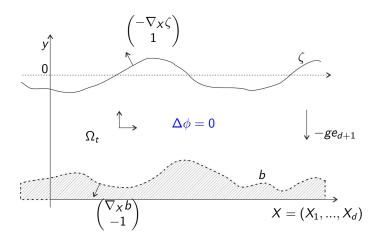
# BOTTOM DETECTION AND OPTIMAL CONTROL PROBLEM ON WATER WAVES

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Partial differential equations, optimal design and numerics

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We are considering an incompressible, inviscid fluid + irrotational.



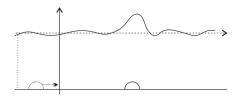
# WATER-WAVES EQUATION

The general water-waves formulation for  $(X,y) \in \mathbb{R}^d \times \mathbb{R}$ , with d=1,2,  $V=\nabla \phi$ 

(1) 
$$\begin{cases} \Delta_{X,y}\phi = 0, & b \leq y \leq \zeta, \\ \partial_t \zeta + \nabla \zeta \cdot \nabla \phi = \partial_y \phi, & y = \zeta, \\ \partial_t \phi + \frac{1}{2} |\nabla_{X,y} \phi|^2 + g\zeta = 0, & y = \zeta, \\ \frac{\partial \phi}{\partial n} = 0, & y = b. \end{cases}$$

# Some phenomena involving water-waves

► Waves generation by bottom disturbances (Zuazua '14, Peregrine '67, Wu '84)



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- ► Tsunamis (generated by displacement of plates, (Iguchi '11, Wu '84)

Falla de deslizamiento oblicuo



Other CORET Program

### Some phenomena involving water-waves

- Waves generation by bottom disturbances (Zuazua '14, Peregrine '67, Wu '84)
- ➤ Tsunamis (generated by displacement of plates, (Iguchi '11, Wu '84)
- ► Bottom detection through surface measurements (Taroudakis '01, Nicholls-Taber '08, Vasan-Deconinck '13)



# ZAKHAROV 1967; CRAIG, SULEM 1992

- $\blacktriangleright \psi(t,X) := \phi(t,X,\zeta(t,X))$
- ▶ If at time t one knows  $\psi$ , it is possible to solve on  $\Omega_t$

$$\begin{cases} \Delta_{X,y}\phi = 0, & \Omega_t \\ \phi|_{y=\zeta} = \psi, & \partial_n\phi|_{y=b} = 0 \end{cases}$$

$$G(\zeta, b)\psi = \sqrt{1 + |\nabla \zeta|^2} \partial_n \phi \big|_{y=\zeta}$$

# System (1) becomes

(2) 
$$\begin{cases} \partial_t \zeta - G(\zeta, b)\psi = 0, \\ \partial_t \psi + g\zeta + \frac{1}{2} |\nabla \psi|^2 - \frac{1}{2(1 + |\nabla \zeta|^2)} (G(\zeta, b)\psi + \nabla \zeta \cdot \nabla \psi)^2 = 0. \end{cases}$$

#### Well-posedness within a sobolev class

- Nalimov '74, Yosihara '82, Craig '85: Existence 1-D locally in time with almost flat bottom, around small perturbations of still water.
- ▶ S. Wu '97, '99, '11: Local existence 1-D, 2-D and global existence 2-D in the case of a layer of fluid of infinite depth.
- ▶ Lannes '05, '13: Local existence in time, 1,2-D, uneven fixed bottom.
- ► Germain, Masmoudi, Shatah '12: Global existence in time, 2-D with infinite depth, small initial data.

# Theorem, well-posedness of (2) (Lannes 2013)

Let  $d_0>\frac{d}{2}$  and  $N\geq d_0+\max\{d_0,2\}+3/2$ . Then let  $U_0=(\zeta_0,\psi_0)\in H^{d_0+2}\times H^2$ ,  $\mathcal{E}^N\in L^\infty$ ,  $b\in H^{N+\max\{d_0,1\}+1}(\mathbb{R}^d)$ . Moreover assume that

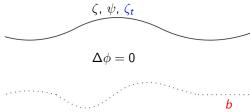
$$\exists h_{min}>0, \ \exists a_0>0, \quad \zeta_0(X)-b(X)\geq h_{min} \ \mathrm{and} \ \mathfrak{a}(U_0)\geq a_0.$$

Then there exists T > 0 and a unique solution  $U \in C([0, T]; H^{d_0+2} \times H^2)$ ,  $\mathcal{E}^N \in L^{\infty}$ , to (2) with initial data  $U_0$ .

$$\begin{split} \mathfrak{a} &= g + w_t + V \cdot \nabla w, \quad \mathcal{E}^N = |B\psi|_{H^{d_0+3/2}}^2 + \sum_{\alpha \in \mathbb{N}^d, |\alpha| \le N} |\zeta_{(\alpha)}|_2^2 + |B\psi_{(\alpha)}|_2^2, \\ \zeta_{(\alpha)} &= \partial^\alpha \zeta, \quad \psi_{(\alpha)} = \partial^\alpha \psi - \underline{\omega} \partial^\alpha \zeta, \quad B = \frac{|D|}{(1+|D|)^{1/2}}. \\ &\underline{\omega} = \frac{G(\zeta)\psi + \nabla_X \zeta \cdot \nabla_X \psi}{1 + |\nabla_X \zeta|^2}. \end{split}$$

### Identifiability of the bottom

What measurements can be made on the free surface to detect the bottom uniquely?



$$\begin{cases} \partial_t \zeta = G(\zeta, b)\psi = \sqrt{1 + |\nabla \zeta|^2} \partial_n \phi \Big|_{y=\zeta}, \\ \partial_t \psi + g\zeta + \frac{1}{2} |\nabla \psi|^2 - \frac{1}{2(1 + |\nabla \zeta|^2)} (G(\zeta, b)\psi + \nabla \zeta \cdot \nabla \psi)^2 = 0. \end{cases}$$

#### THEOREM

Let T>0 and  $d_0>\frac{d}{2}$ . Assume that for j=1,2,  $(\zeta_j,\psi_j)\in C^1([0,T];H^{d_0+1}(\mathbb{R}^d)\times H^2(\mathbb{R}^d))$  are solutions of (2), with  $b_1,b_2\in H^{N+\max\{d_0,1\}+1}(\mathbb{R}^d)$ , such that there exists  $h_{min}>0$ , such that, for all  $X\in\mathbb{R}^d$  and  $t\in(0,T)$ ,

$$\zeta_j(t,X)-b_j(X)\geq h_{min},\quad j=1,2.$$

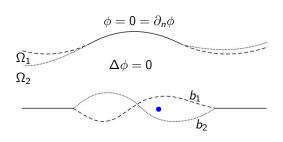
Let S be an open subset of  $\mathbb{R}^d$  and  $t_0 \in (0, T)$  a single time. If  $\forall X \in S$ ,

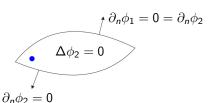
$$\zeta_1(t_0,X)=\zeta_2(t_0,X),\quad \psi_1(t_0,X)=\psi_2(t_0,X),\quad \partial_t\zeta_1(t_0,X)=\partial_t\zeta_2(t_0,X),$$

then

$$b_1(X) = b_2(X) \quad \forall X \in \mathbb{R}^d.$$

$$\phi = \phi_1 - \phi_2$$





One gets,  $\phi_2 = C = \phi_1$ , which we exclude (Still water).

# OPTIMAL CONTROL PROBLEM

Given a target function  $\tau(X) \in L^2(\mathbb{R}^d)$ , we are considering  $F: H^{N+\max\{d_0,1\}+2}(\mathbb{R}^d) \to \mathbb{R}$ 

$$F(b) = \frac{1}{2} \int_{\mathbb{R}^d} |\partial_t \zeta(X)|_{t=t_0} - \tau(X)|^2 dX$$

#### PROBLEM

To find  $b^{min} \in \mathcal{B}_{ad}$ , such that,

$$F(b^{min}) = \min_{b \in \mathcal{B}_{ad}} F(b).$$

 $\blacktriangleright \ \mathcal{B}_{ad} = \{b \in H^{N+\max\{d_0,1\}+2}(\mathbb{R}^d) : \operatorname{supp}(b) \subset K, |b|_{H^{N+\max\{d_0,1\}+2}(\mathbb{R}^d)} \leq C\}$ 

## THEOREM, EXISTENCE OF MINIMIZERS

Let  $\zeta \in H^{d_0+2}(\mathbb{R}^d)$  and  $\psi \in H^2(\mathbb{R}^d)$ . Assume that  $\tau(X) \in L^2(\mathbb{R}^d)$ . Then the minimization problem,

$$\min_{b\in\mathcal{B}_{ad}}F(b),$$

has one minimizer  $b^m \in \mathcal{B}_{ad}$ .

- ▶ Let  $\{b_n\}$   $\subset \mathcal{B}_{ad}$  be a minimizing sequence of F
- lacktriangledown  $\exists$  subsequence, such that  $b_n 
  ightharpoonup ar b$  in  $H^{N+max\{d_0,1\}+2}(\mathbb{R}^d)$ , with  $ar b \in \mathcal{B}_{ad}$
- $b_n \to \bar{b}$  strongly in  $H^{N+\max\{d_0,1\}+1}(\mathbb{R}^d)$
- Let  $\phi_n$  and  $\bar{\phi}$  the corresponding solutions with bottom  $b_n$  and  $\bar{b}$
- $G(\zeta, b_n)\psi \to G(\zeta, \bar{b})\psi$ , strongly in  $L^2(\mathbb{R}^d)$
- $ightharpoonup \inf_{b\in\mathcal{B}_{ad}}F(b)=\lim_{n\to\infty}F(b_n)=F(\bar{b})$
- ▶ Uniqueness of this minimum follows from the identifiability.

# Shape derivative of F

Given  $\zeta_0$ ,  $\psi_0$ 

$$F(b) = \frac{1}{2} \int_{\mathbb{R}^d} \left| \partial_t \zeta(X) \right|_{t=t_0} - \tau(X) \right|^2 dX = \frac{1}{2} \int_{\mathbb{R}^d} \left| G(\zeta_0, b) \psi_0 - \tau(X) \right|^2 dX$$

For all  $h \in H^{N+max\{d_0,1\}+2}(\mathbb{R}^d)$ , one has

$$F'(b) \cdot h = -\int_{\Gamma_b} h \frac{\nabla \phi \cdot \nabla \psi}{\sqrt{1 + |\nabla_X b|^2}}$$

with  $\phi$  and  $\psi$  being the solutions of

$$\left\{ \begin{array}{ll} \Delta\phi = 0, \quad \Omega, \\ \phi = \psi_0, \quad \Gamma_{\zeta_0} \\ \frac{\partial\phi}{\partial n} = 0, \quad \Gamma_b, \end{array} \right. \qquad \begin{array}{ll} \Delta\psi = 0, \quad \Omega, \\ \psi = G - \tau, \quad \Gamma_{\zeta_0} \\ \frac{\partial\psi}{\partial n} = 0, \quad \Gamma_b. \end{array}$$

$$\phi_{\delta} = \phi(\Omega + \delta u)$$
 is the solution of the problem

$$\left\{ \begin{array}{ccc} \Delta\phi_{\delta}=0, & \Omega_{\delta} \\ \phi_{\delta}=\psi_{0}, & \Gamma_{\zeta_{0}} \\ \frac{\partial\phi_{\delta}}{\partial\textit{n}^{\delta}}=0, & \Gamma_{\textit{b}}^{\delta}, \end{array} \right.$$

$$\phi' = lim_{\delta o 0} rac{\phi_{\delta} - \phi_{0}}{\delta}$$
 one has

$$\begin{cases} & \Delta \phi' = 0, \quad \Omega \\ & \phi' = 0, \quad \Gamma_{\zeta_0} \\ & \frac{\partial \phi'}{\partial n} = \nabla u_n \cdot \nabla \phi - u_n \frac{\partial^2 \phi}{\partial n^2}, \quad \Gamma_b. \end{cases}$$

Then

$$F'(b) \cdot h = \int_{\mathbb{R}^d} (G(\zeta_0, b)\psi_0 - \tau) \sqrt{1 + |\nabla_X \zeta_0|^2} \frac{\partial \phi'}{\partial n} \Big|_{\zeta_0} dX$$

$$= \int_{\Gamma_{\zeta_0}} (G - \tau) \frac{\partial \phi'}{\partial n} dA,$$

$$= -\int_{\Gamma_b} \psi \frac{\partial \phi'}{\partial n} dA$$

$$= \int_{\Gamma_b} \psi \left[ \nabla \left( \frac{h}{\sqrt{1 + |\nabla_X b|^2}} \right) \cdot \nabla_X \phi - \frac{h}{\sqrt{1 + |\nabla_X b|^2}} \frac{\partial^2 \phi}{\partial n^2} \right] dA$$

After some calculations

$$F'(b) \cdot h = -\int_{\Gamma_b} h \frac{\nabla \phi \cdot \nabla \psi}{\sqrt{1 + |\nabla_X b|^2}}.$$

# **Thanks**