

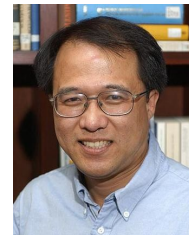
Loop optimization for tensor network renormalization

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Zheng-Cheng Gu
(PI, CUHK)

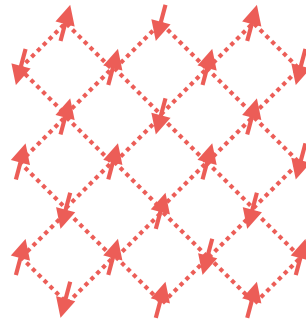


Xiao-Gang Wen
(MIT, PI)

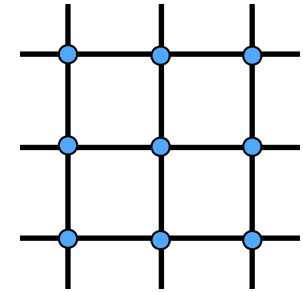
Overview

tensor network + renormalization group = tensor network renormalization

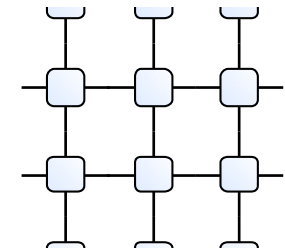
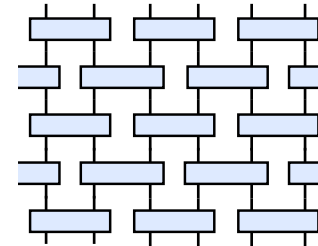
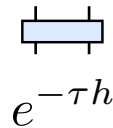
Partition function of
classical statistical system



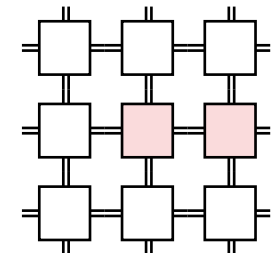
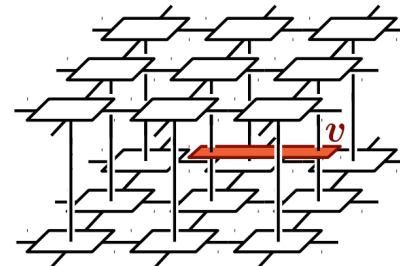
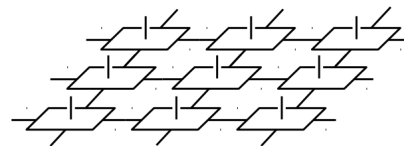
$$Z = \sum_{\{\sigma\}} \exp(\beta \sum_{\langle ij \rangle} \sigma_i \sigma_j)$$



Euclidean path integral of
1D quantum system



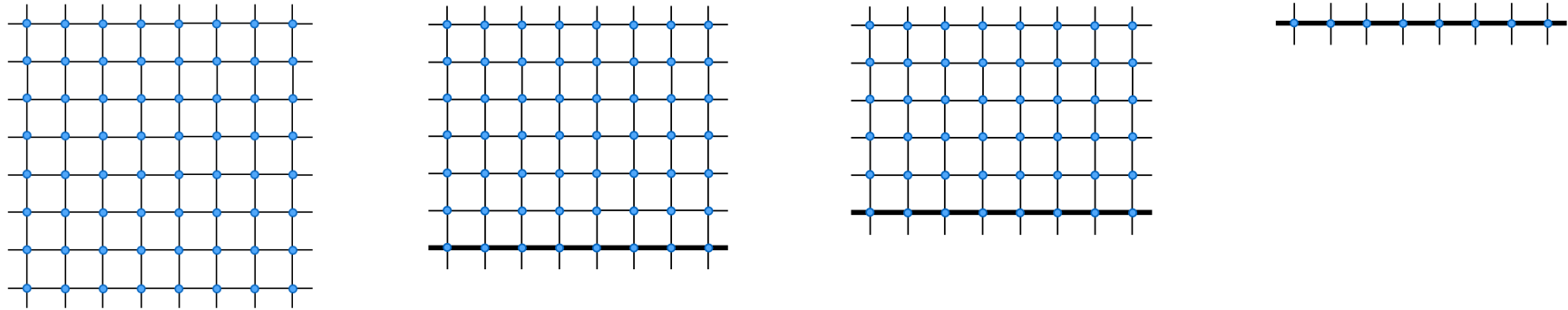
Physical properties of 2D
quantum system



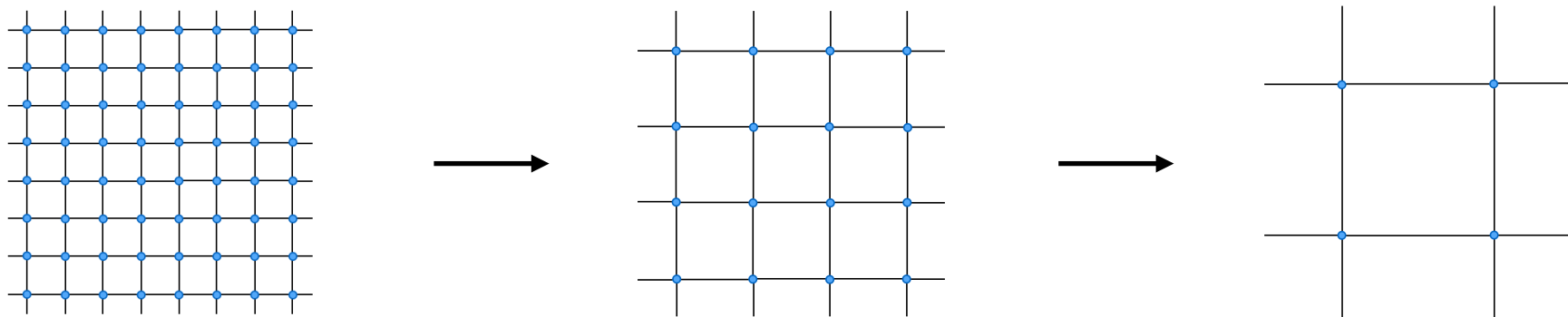
Overview

tensor network + renormalization group = tensor network renormalization

■ boundary MPS



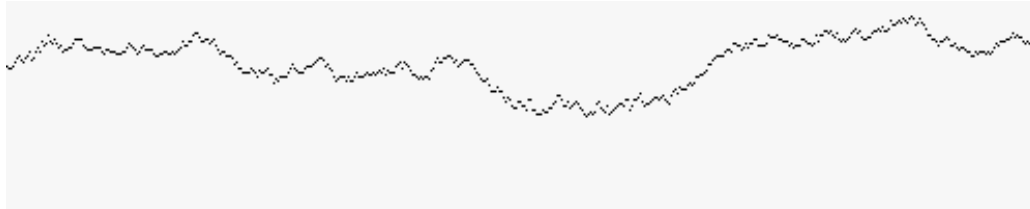
■ fully isotropic coarse-graining



Overview

tensor network + renormalization group = tensor network renormalization

How the physics change with scale



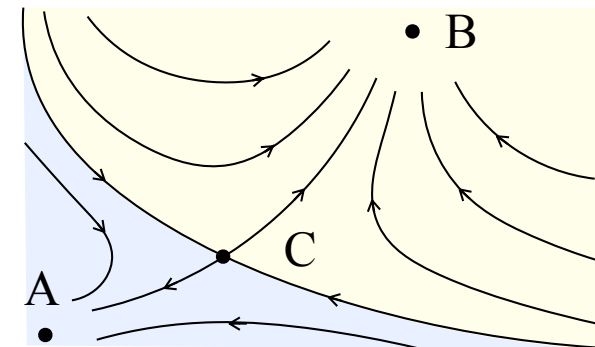
← scale transformation

- Non-perturbative approach, suitable for strongly correlated systems
- Reproduce long-range physics

Aim

- Remove short-range entanglement / correlations
- Generate proper RG flow & correct fixed points
- Recover scale invariance at criticality

RG flow

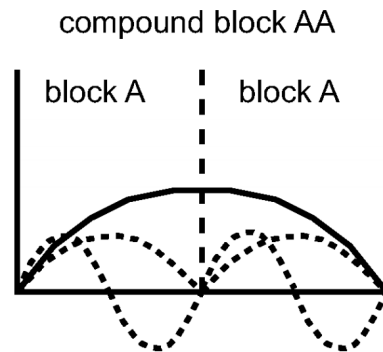


Real space renormalization group

1D quantum:

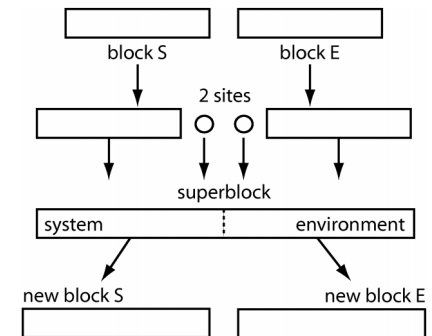
Real space analogue of NRG
Wilson (1975)
breakdown for “particle in a box” problem

real space NRG



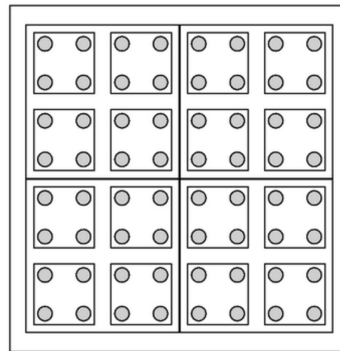
entanglement

DMRG S. White (1992)



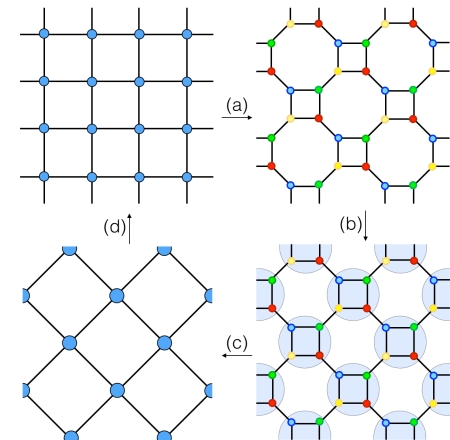
2D classical:

block spin



entanglement

TRG Levin & Nave (2007)



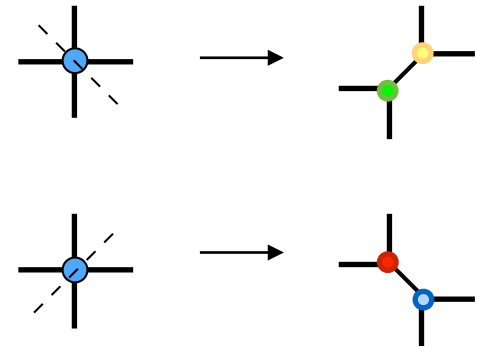
L.P. Kadanoff (1966)

Tensor renormalization group

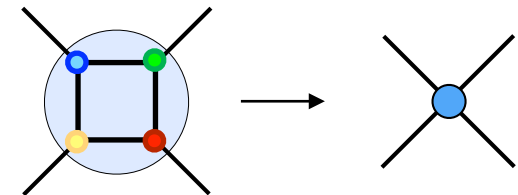
Levin & Nave (2007) LN-TNR

Three steps

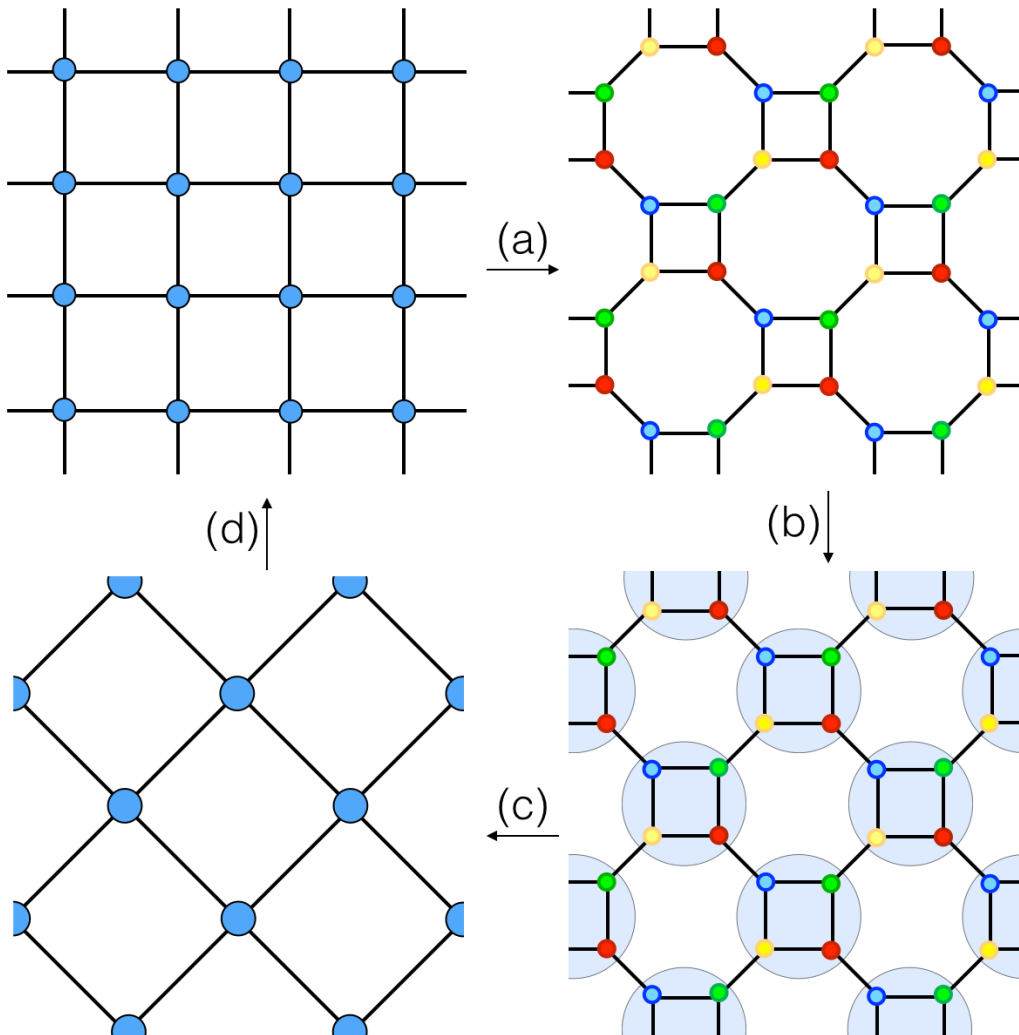
1. Deform tensors, make a truncation



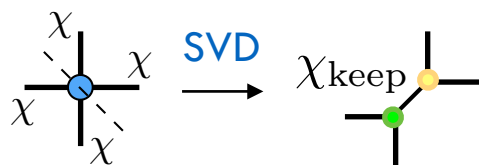
2. Coarse graining



3. Renormalize tensors
(multiply tensor by a constant factor)



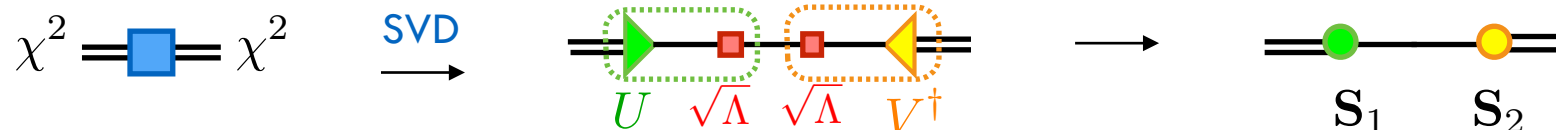
Tensor renormalization group



singular value decomposition (SVD)
only keep the largest χ_{keep} singular values

$$\left\| \begin{array}{c} \chi \\ \chi \end{array} \begin{array}{c} \chi \\ \chi \end{array} - \begin{array}{c} \chi_{\text{keep}} \\ 1 \end{array} \begin{array}{c} 2 \end{array} \right\|^2$$

cost function
 $\|\mathbf{T} - \mathbf{S}_1 \cdot \mathbf{S}_2\|^2$



original

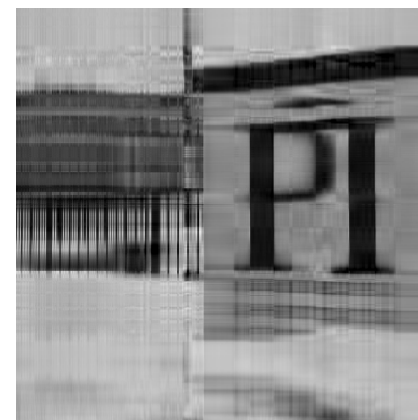
$$\chi_{\text{keep}} = \chi^2$$



$$\chi_{\text{keep}} = 2\chi$$



$$\chi_{\text{keep}} = \chi$$



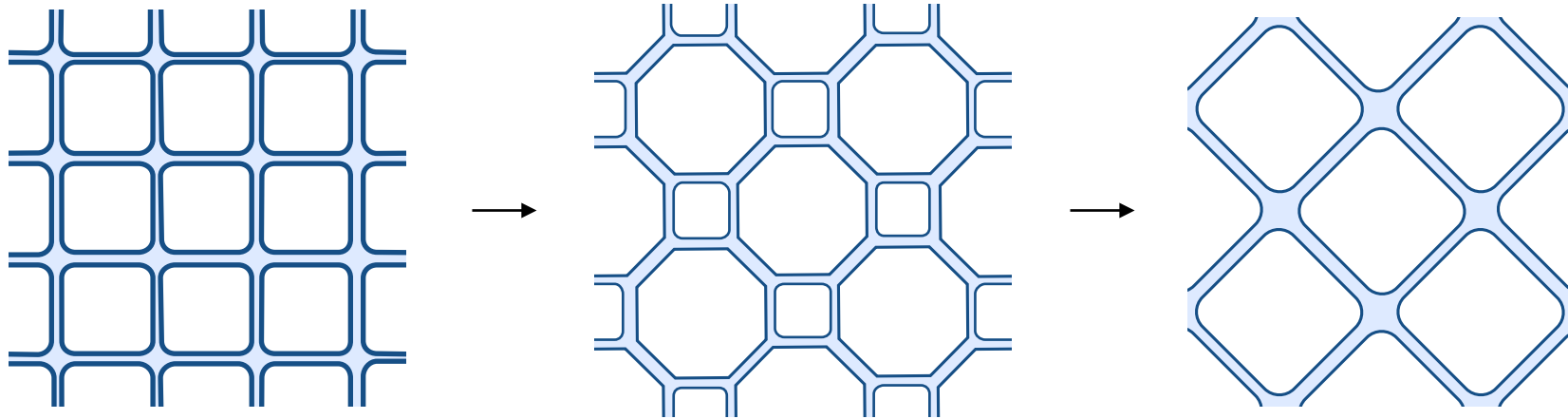
$$\chi_{\text{keep}} = \chi/4$$

Drawbacks of LN-TNR

Off criticality

cannot remove conner-double-line (CDL) tensors

cannot give the correct structures of fixed points

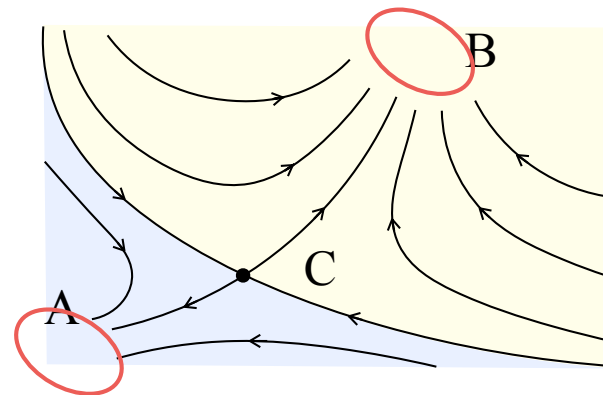


$$\begin{array}{c} D^2 \\ \text{---} \text{---} \text{---} \\ D^2 \end{array}$$

$$\chi = D^2$$

$$\begin{array}{c} D \\ \text{---} \text{---} \text{---} \\ D \end{array}$$

$$\begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_D \end{pmatrix}$$



Drawbacks of LN-TNR

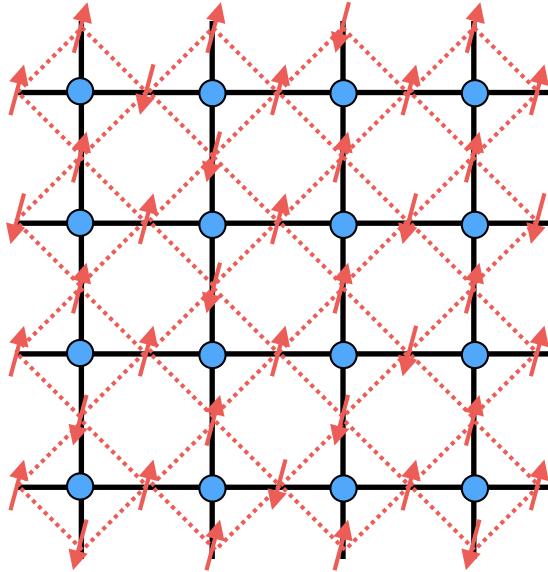
At criticality

cannot explicitly recover scale invariance

cannot completely remove short-range entanglement

Example

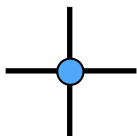
classical Ising model



partition function

$$Z = \sum_{\{\sigma\}} \exp(\beta \sum_{\langle ij \rangle} \sigma_i \sigma_j)$$

local tensor

 $\mathbf{T} = T_{u,l,d,r}^{\text{Ising}}$

$$T_{1,2,1,2}^{\text{Ising}} = e^{-4\beta}, \quad T_{2,1,2,1}^{\text{Ising}} = e^{-4\beta},$$

$$T_{1,1,1,1}^{\text{Ising}} = e^{4\beta}, \quad T_{2,2,2,2}^{\text{Ising}} = e^{4\beta},$$

others = 1.

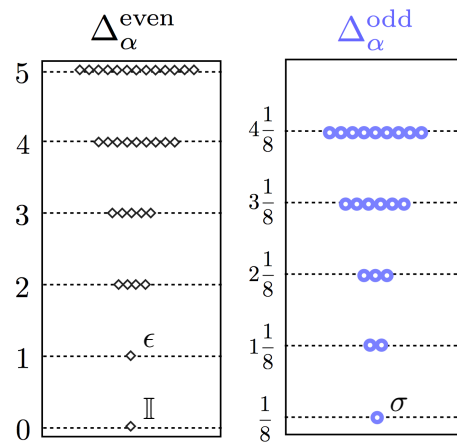
Drawbacks of LN-TNR

Ising CFT

central charge

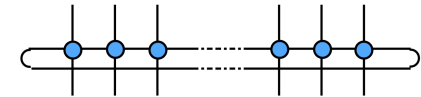
$$c = 1/2$$

scaling
dimensions $\rightarrow$



Calculate scaling dimensions

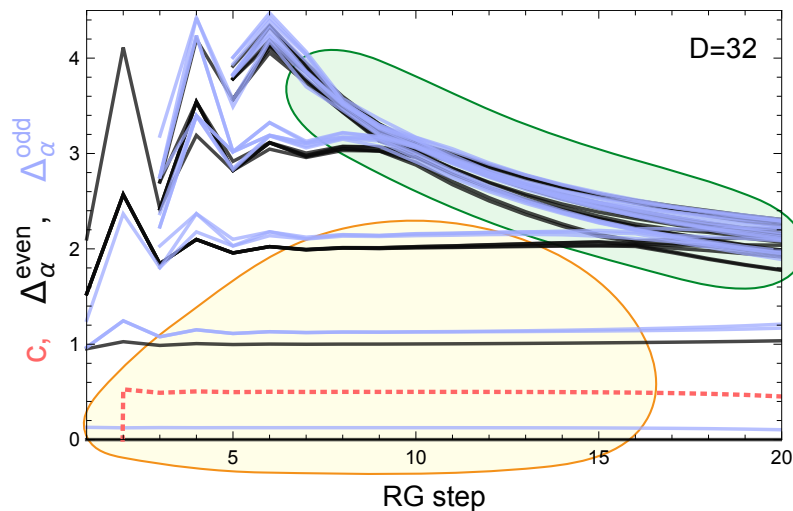
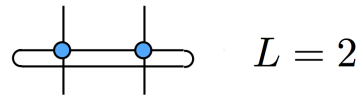
transfer matrix



eigenvalues of the transfer matrix $\rightarrow c, \Delta_\alpha$

Zheng-Cheng Gu and Xiao-Gang Wen,
Phys. Rev. B **80**, 155131 (2009).

LN-TNR

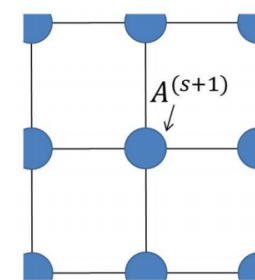
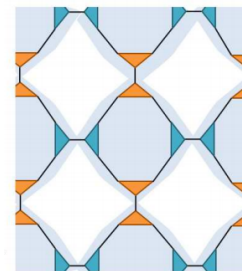
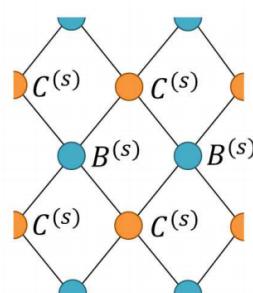
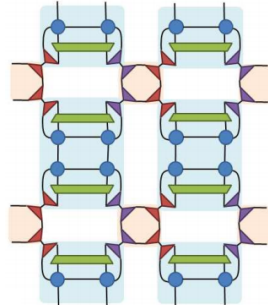
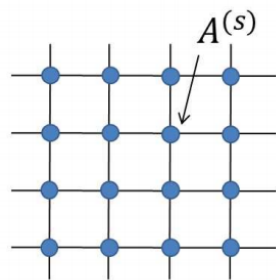


scaling dimensions change with RG step
cannot explicitly recover scale invariance

high-index parts will destroy low-index parts
accuracy is fine, stability is bad

Improvements of LN-TNR

	off-critical	critical
LN-TNR (TRG) (Levin & Nave, 2006)	😐	😞
SRG (Xie, Jiang, Weng, Xiang, 2008)	😊	😐
GW-TNR (TEFR) (Gu & Wen, 2009)	😄	😐
EV-TNR (Evenbly & Vidal, 2014)	😄	😄



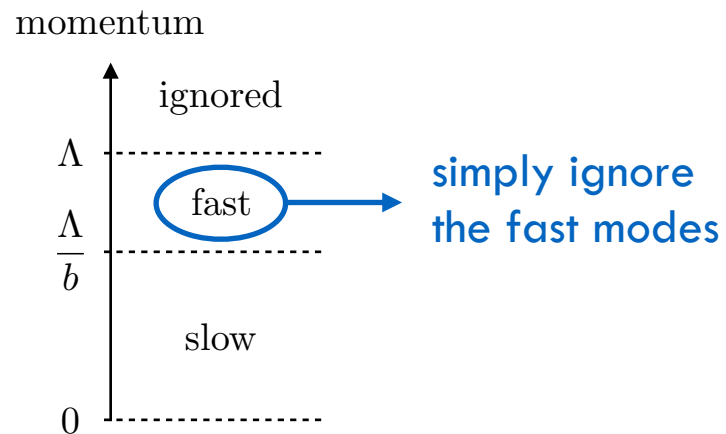
Improvements of LN-TNR

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GW-TNR (TEFR) (Gu & Wen, 2009)		
EV-TNR (Evenbly & Vidal, 2014)		
Loop-TNR (current)		

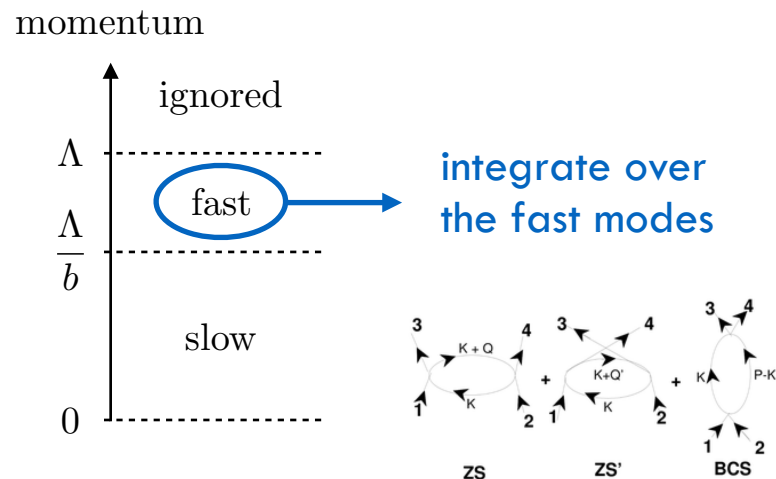
Renormalization Group

Momentum space

- Tree level approximation — no loop

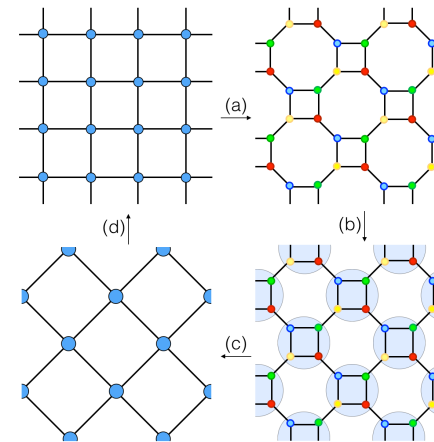


- Beyond tree level — one loop



Real space

- Tree level approximation — no loop



LN-TNR

remove short-range entanglement by a local SVD

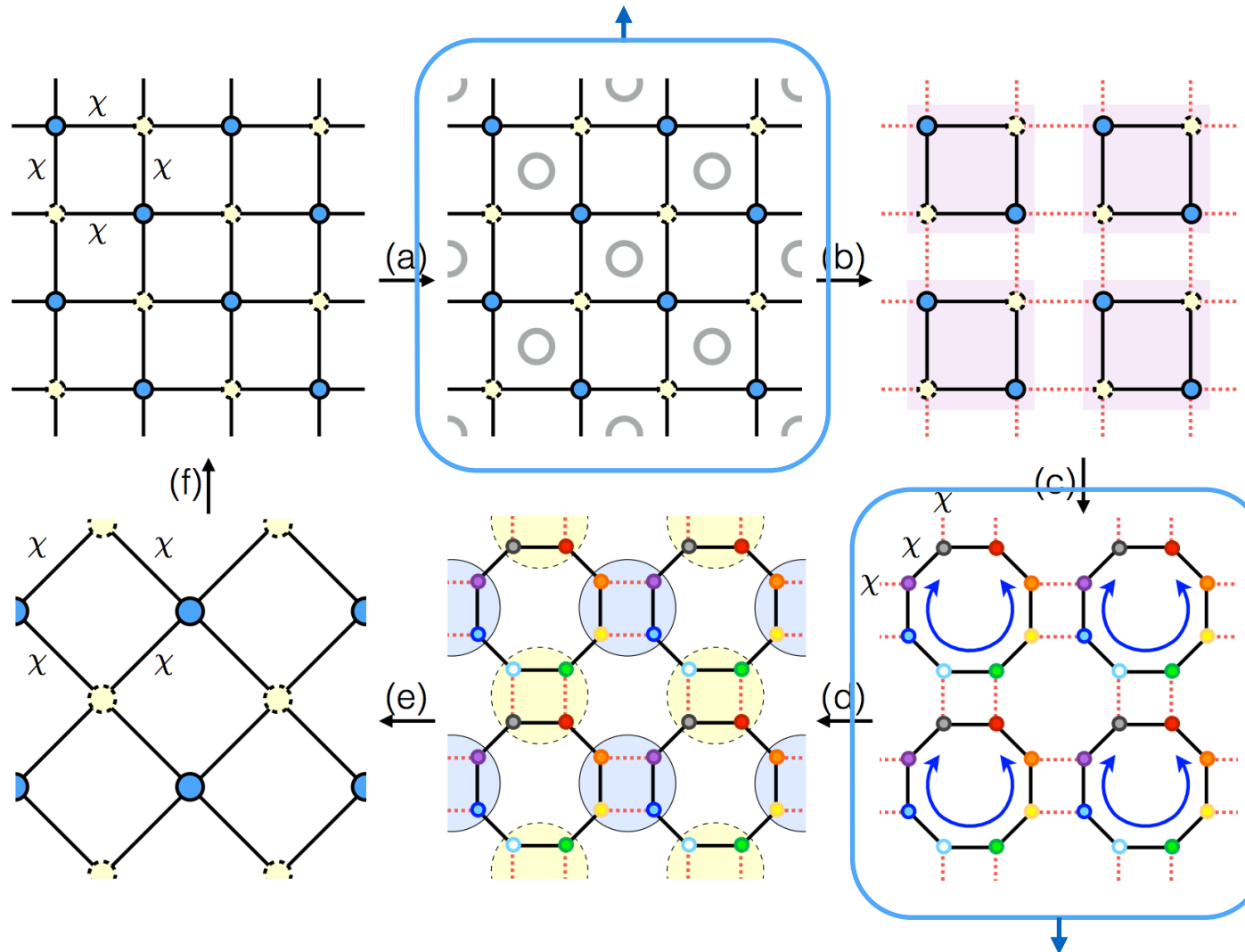
- Beyond tree level — one loop

LN-TNR + loop optimization
further remove short-range entanglement inside a loop

This work !

Algorithms of Loop-TNR

Part One: Entanglement filtering



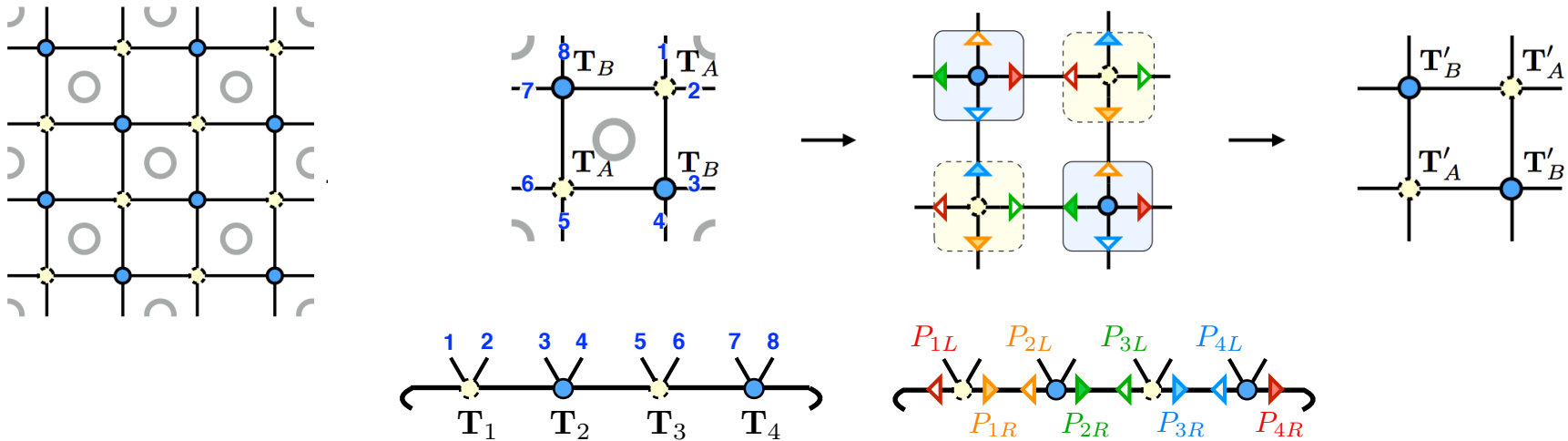
Together: Complete remove short-range entanglement

Part Two: Optimizing tensors on a loop

Part One — Entanglement filtering

How

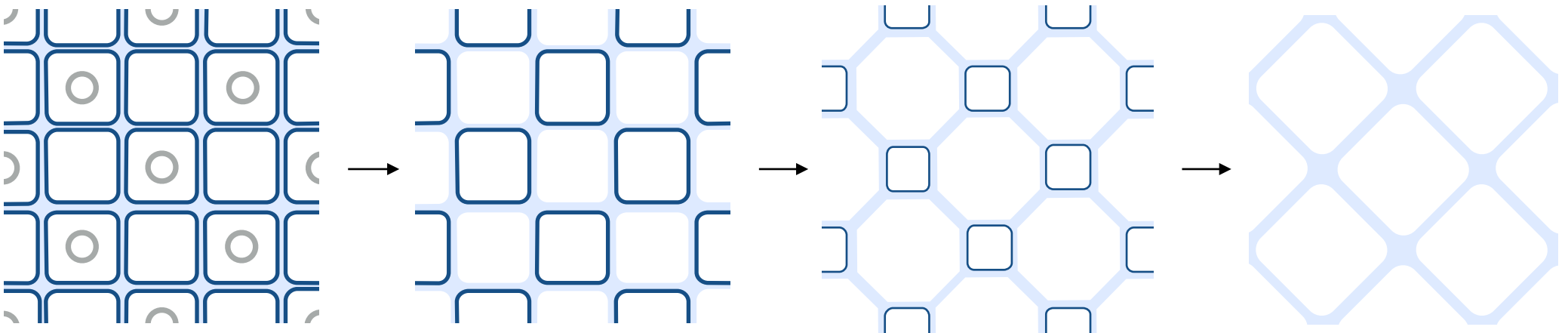
1. Find & insert projectors
2. Define new tensors



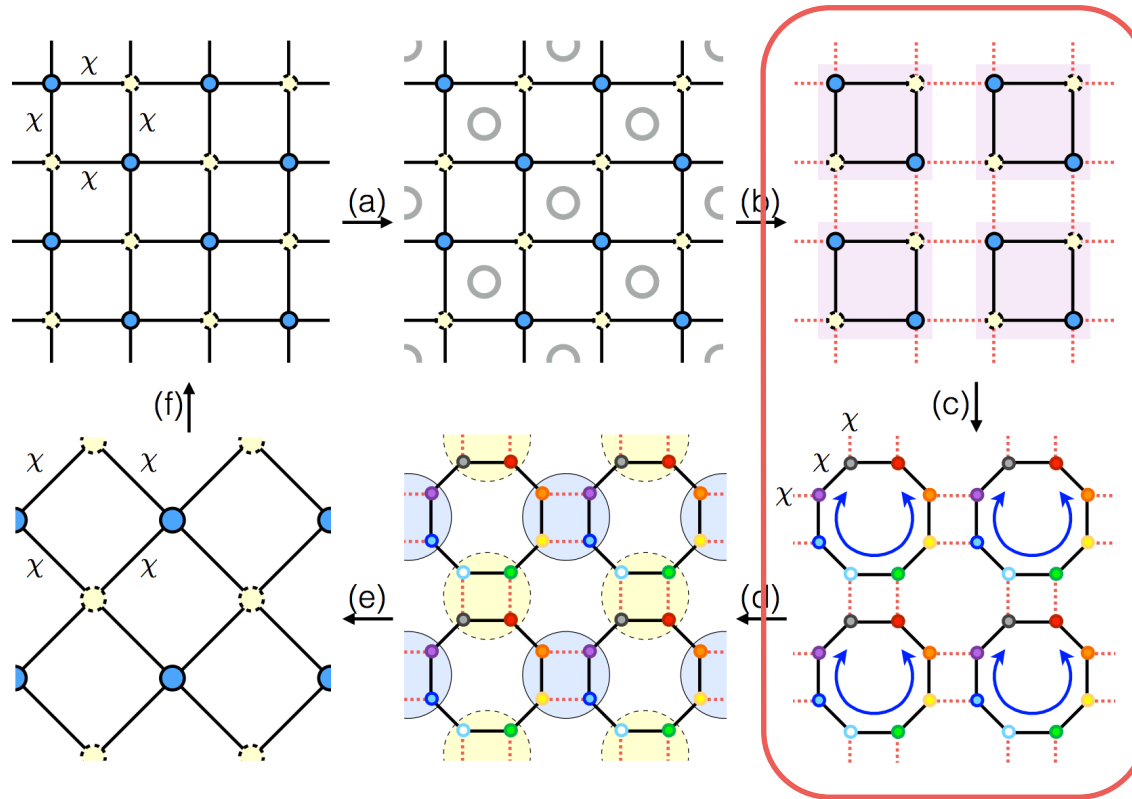
Aim

Remove corner double line (CDL) tensors
Generate local canonical gauge

Zheng-Cheng Gu and Xiao-Gang Wen,
Phys. Rev. B **80**, 155131 (2009).



Part Two — Optimizing tensors on a loop



■ LN-TNR

$$\left\| \begin{array}{c} \chi \\ \chi \end{array} \begin{array}{c} \chi \\ \chi \end{array} - \begin{array}{c} \chi \\ 1 \\ 2 \end{array} \right\|^2, \quad \left\| \begin{array}{c} \chi \\ \chi \end{array} \begin{array}{c} \chi \\ \chi \end{array} - \begin{array}{c} \chi \\ 3 \\ 4 \end{array} \right\|^2$$

cost function

■ Loop-TNR

$$\left\| \begin{array}{c} T_4 \\ T_3 \end{array} \begin{array}{c} T_1 \\ T_2 \end{array} - \begin{array}{c} 8 \\ 7 \\ 6 \\ 5 \\ 4 \\ 3 \\ 2 \\ 1 \end{array} \right\|^2 = \left\| \begin{array}{c} \text{---} \end{array} \begin{array}{c} \text{---} \end{array} \right\|^2$$

Part Two — Optimizing tensors on a loop

(a) $\left\| \begin{array}{c} \text{Square diagram} \\ - \\ \text{Octagon diagram} \end{array} \right\|^2 = \left\| \begin{array}{c} \text{Tensor network } |\Psi_A\rangle \\ - \\ \text{Tensor network } |\Psi_B\rangle \end{array} \right\|^2$

$= \langle \Psi_A | \Psi_A \rangle + \langle \Psi_B | \Psi_B \rangle - \langle \Psi_A | \Psi_B \rangle - \langle \Psi_B | \Psi_A \rangle$

$= \mathcal{C} + \mathcal{N}_i \mathbf{T}_i^\dagger \mathbf{T}_i - \mathcal{W}_i^\dagger \mathbf{T}_i - \mathbf{T}_i^\dagger \mathcal{W}_i$

$$f(\mathbf{T}_i) = \left\| |\Psi_A\rangle - |\Psi_B\rangle \right\|^2 = \langle \Psi_A | \Psi_A \rangle + \langle \Psi_B | \Psi_B \rangle - \langle \Psi_A | \Psi_B \rangle - \langle \Psi_B | \Psi_A \rangle$$

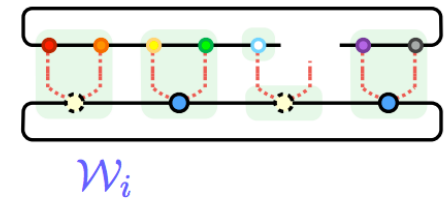
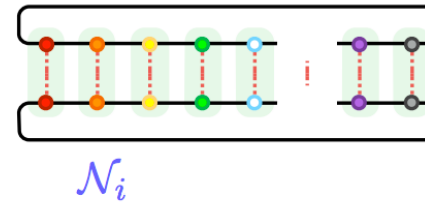
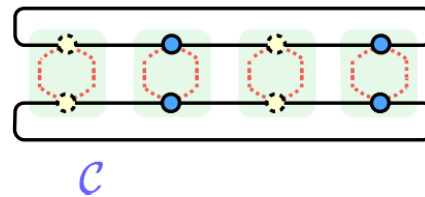
$$= \mathcal{C} + \mathbf{T}_i^\dagger \mathcal{N}_i \mathbf{T}_i - \mathcal{W}_i^\dagger \mathbf{T}_i - \mathbf{T}_i^\dagger \mathcal{W}_i,$$

solve the linear equation

$$\mathcal{N}_i \mathbf{T}_i = \mathcal{W}_i.$$

Part Two — Optimizing tensors on a loop

(b) contraction order



computational cost

$$\mathcal{O}(7\chi^6)$$

$$\mathcal{O}(6\chi^6 + 7\chi^5)$$

$$\mathcal{O}(6\chi^6 + 4\chi^5)$$

memory cost

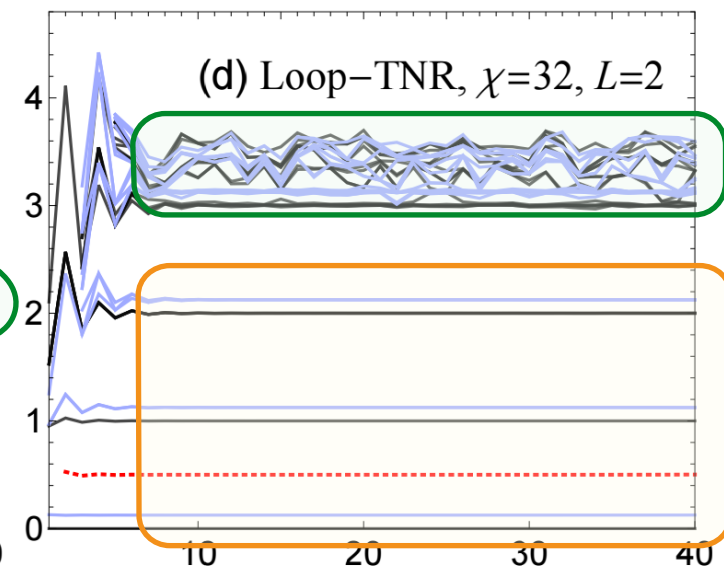
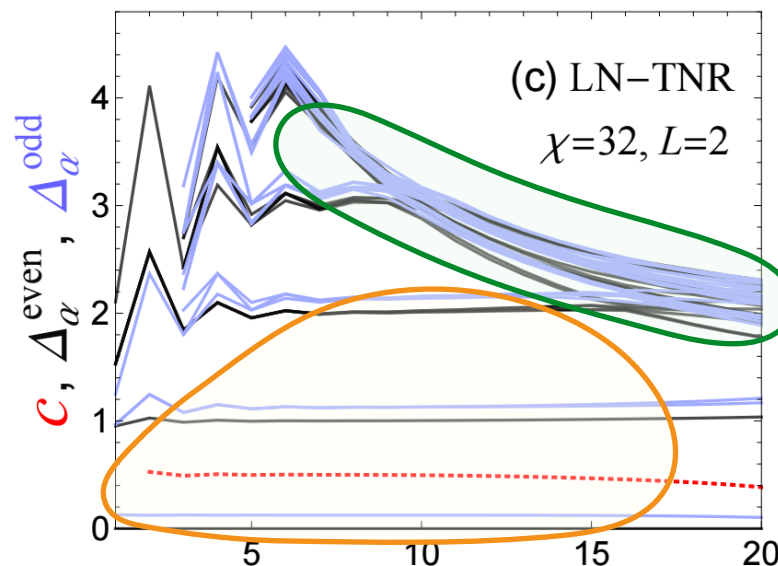
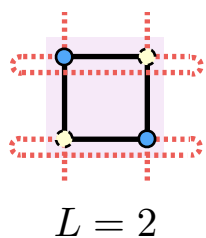
$$\mathcal{O}(\chi^4)$$

$$\mathcal{O}(\chi^4)$$

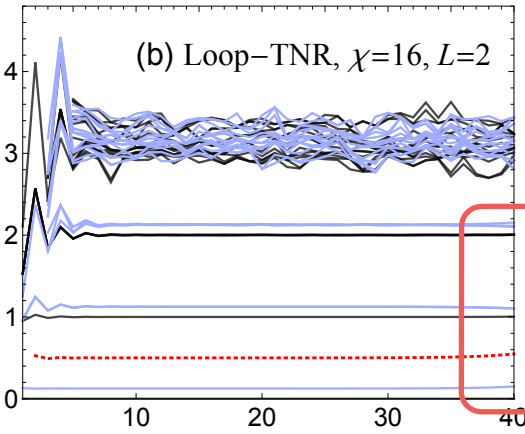
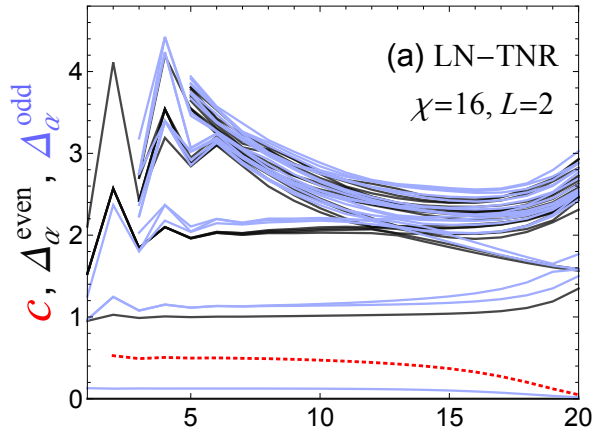
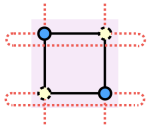
$$\mathcal{O}(\chi^4)$$

Loop-TNR Results

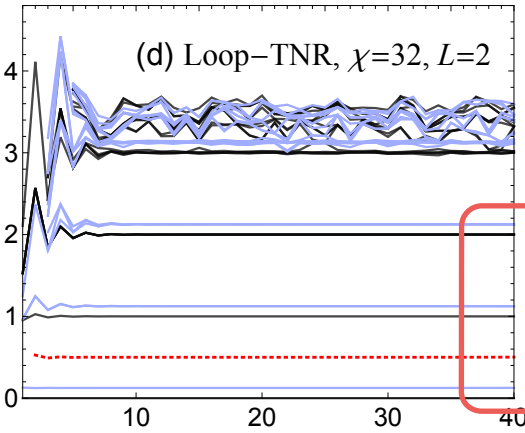
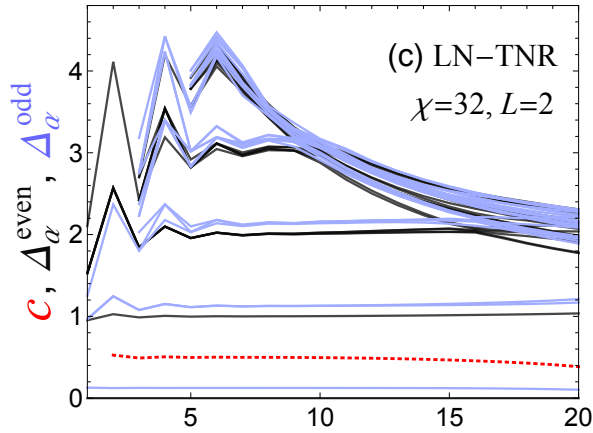
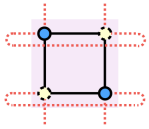
- scaling dimensions does not change with scale $\sim$ scale invariance
- a clear gap between high-level parts and low-level parts



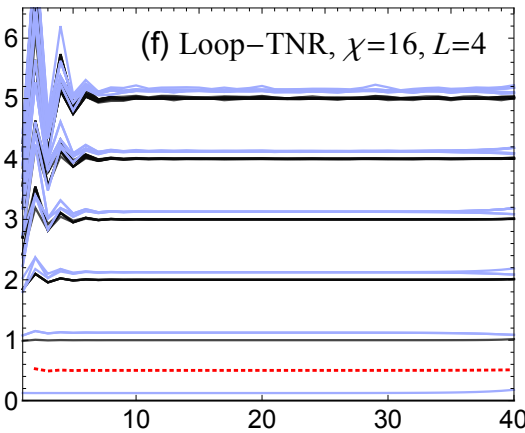
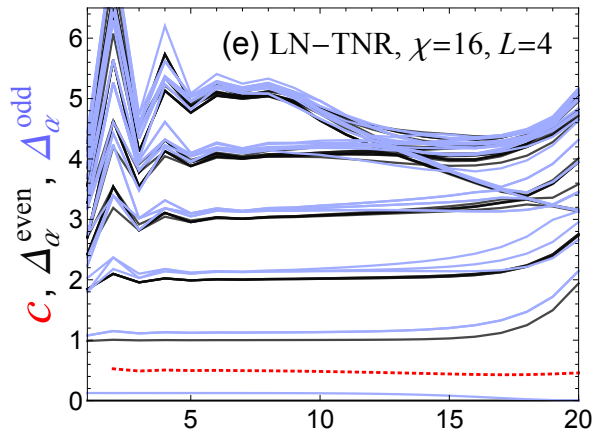
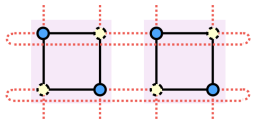
Stability



$\chi = 16$
remain accurate up to 40
iteration steps



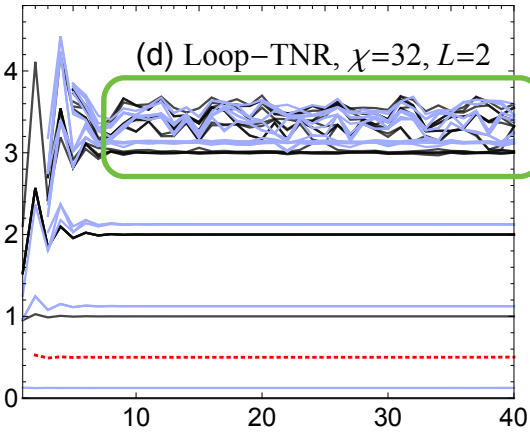
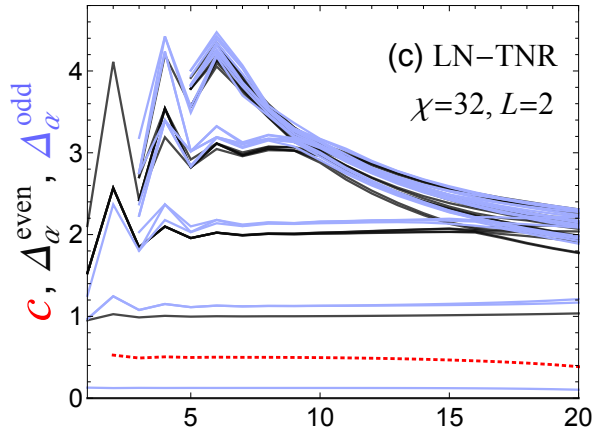
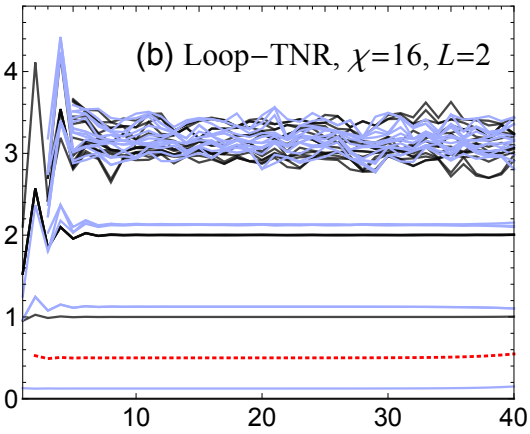
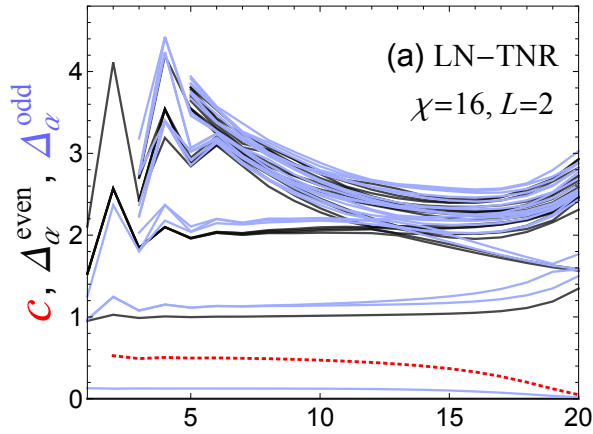
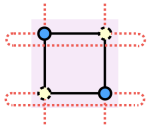
even longer for $\chi = 32$
the proper RG flow last
longer for larger χ



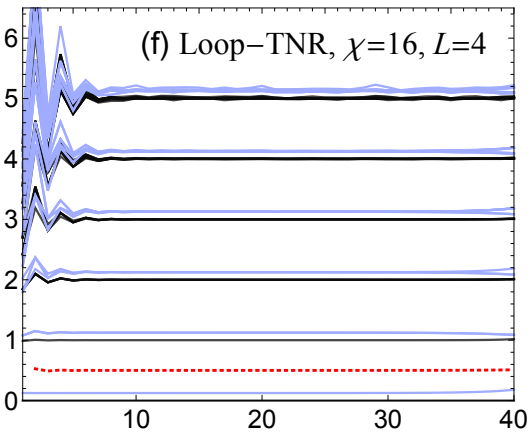
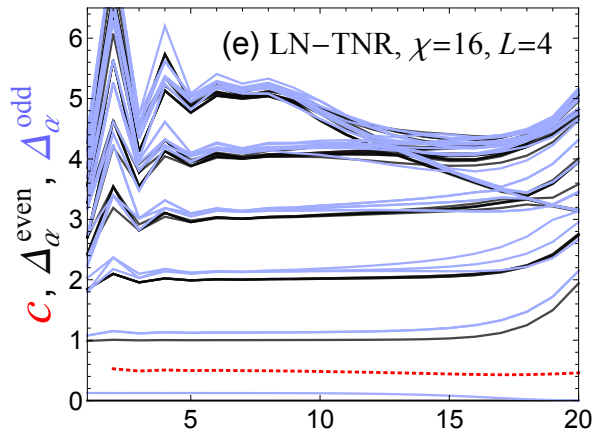
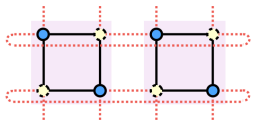
Iteration step

Iteration step

Stability



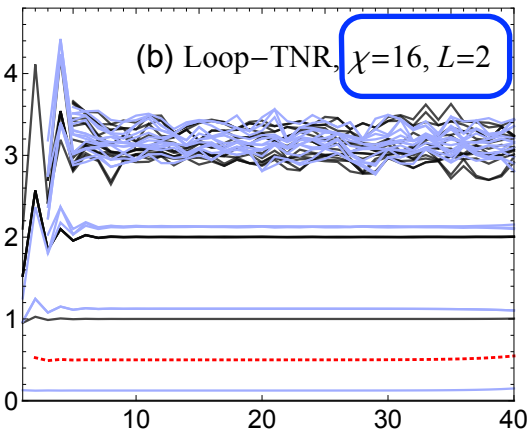
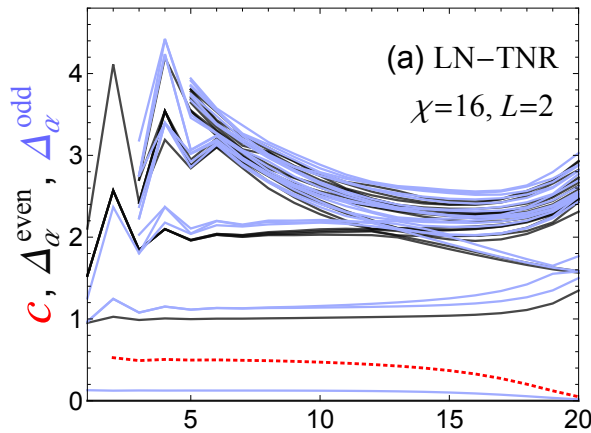
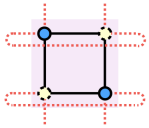
increasing χ , more scaling dimensions can be resolved



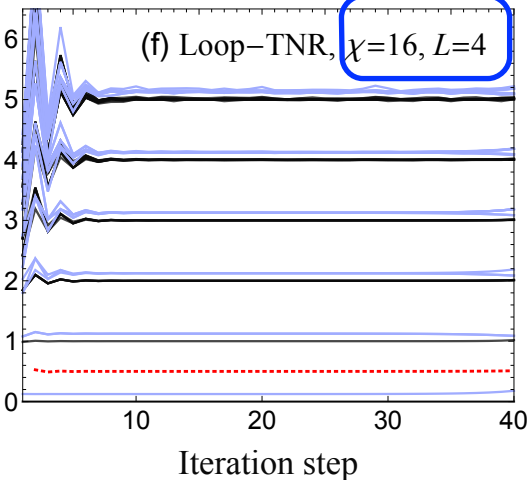
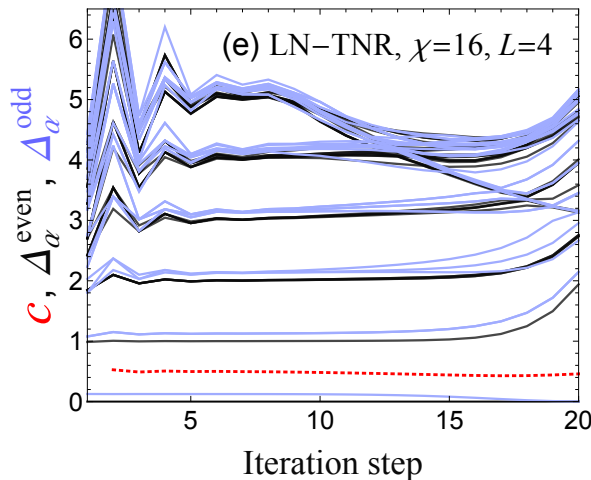
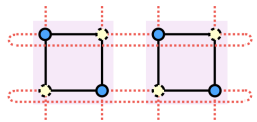
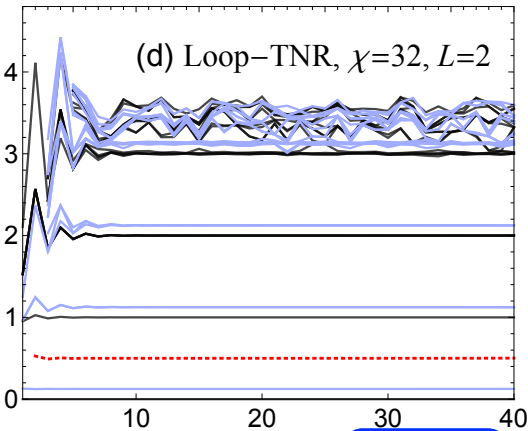
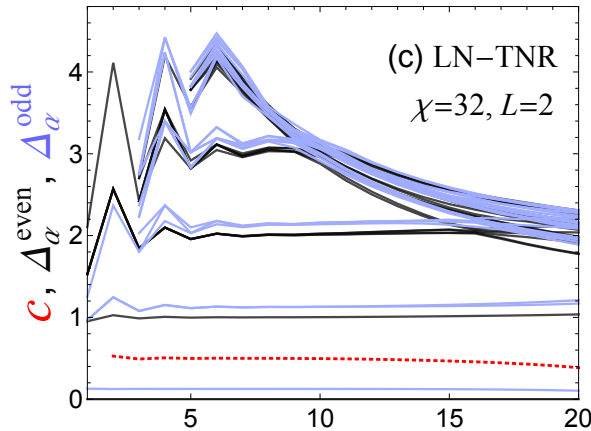
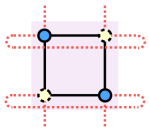
Iteration step

Iteration step

Stability



effectively, $\chi = 16$



effectively, $\chi = 16^2 = 256$

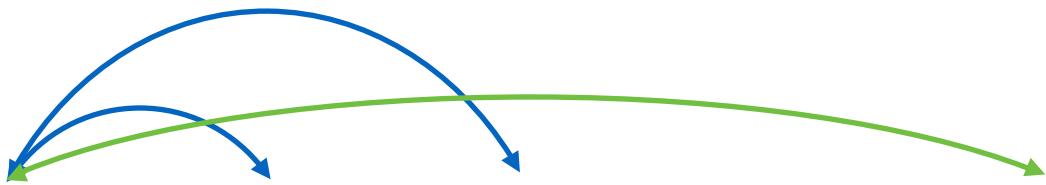
much more scaling

dimensions can be read off
accuracy is higher

infinite $\chi \sim$ infinite

dimensional fixed point tensor
described by Ising CFT

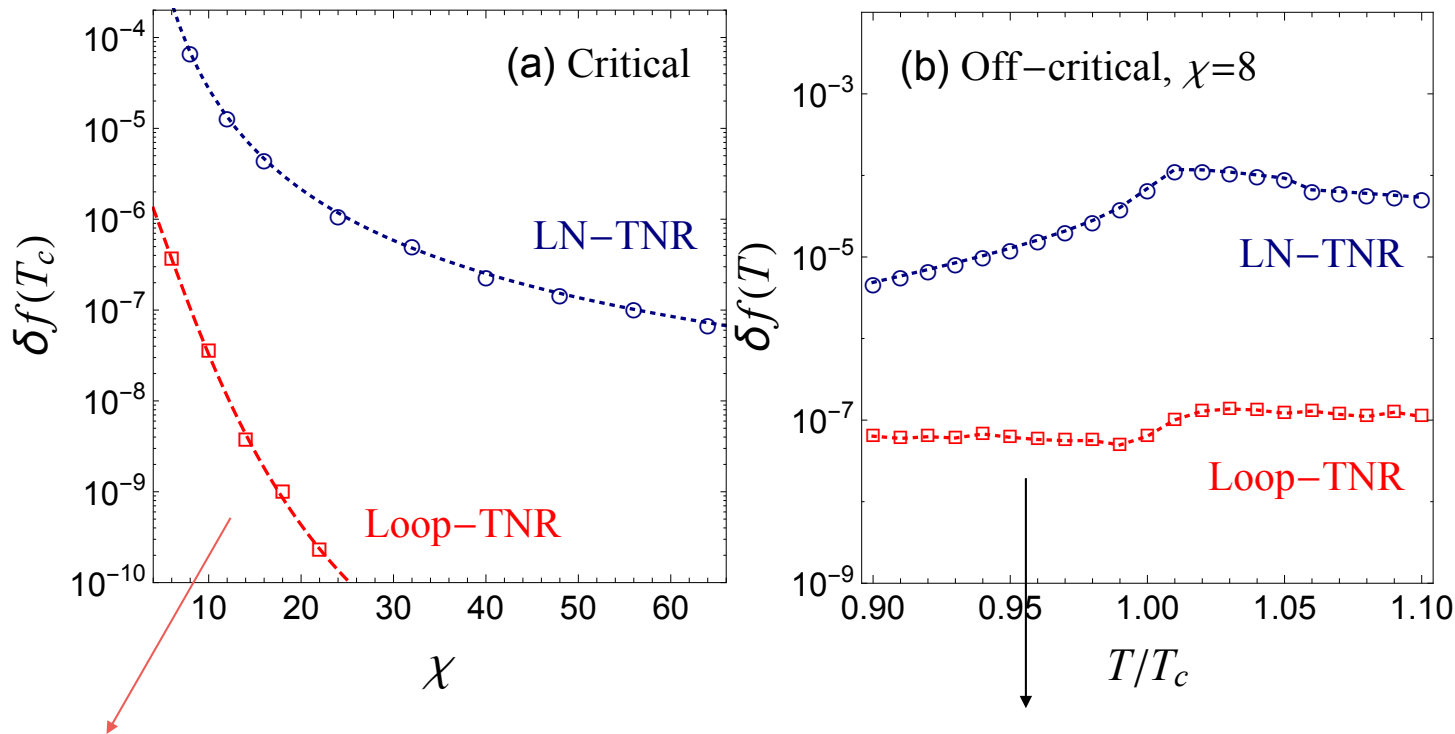
Accuracy



Exact		LN-TNR $\chi = 64$ $L = 1$ 2^{11} spins	LN-TNR $\chi = 64$ $L = 2$ 2^{11} spins	Loop-TNR $\chi = 16$ $L = 2$ 2^{18} spins	Loop-TNR $\chi = 24$ $L = 2$ 2^{18} spins	Loop-TNR $\chi = 16$ $L = 4$ 2^{18} spins	Loop-TNR $\chi = 24$ $L = 4$ 2^{18} spins	EV-TNR [50] $\chi = 24$ $L = 2$ 2^{18} spins
c	0.5	0.49946958	0.49970058	0.50001491	0.50000165	0.50009255	0.50008794	0.50001
σ	0.125	0.12504027	0.12500837	0.12500528	0.12500011	0.12501117	0.12499789	0.1250004
ϵ	1	1.00028269	0.99996784	1.00000566	1.00000601	0.99999403	1.00000507	1.00009
	1.125	1.12368834	1.12444247	1.12495187	1.12499400	1.12498755	1.12500559	1.12492
	1.125	1.12394625	1.12450246	1.12510600	1.12500464	1.12498755	1.12500559	1.12510
	2	1.92334948	1.99811859	2.00000743	1.99970911	1.99999517	2.00000985	1.99922
	2	1.96264143	1.99815644	2.00066117	2.00016629	1.99999517	2.00000985	1.99986
	2	1.97496787	1.99868822	2.00066117	2.00031103	2.00002744	2.00001690	2.00006
	2	2.00274974	1.99948966	2.00586886	2.00131384	2.00006203	2.00002745	2.00168

Relative error of the free energy per site

- At critical point, the error of Loop-TNR decays much faster than the error of LN-TNR



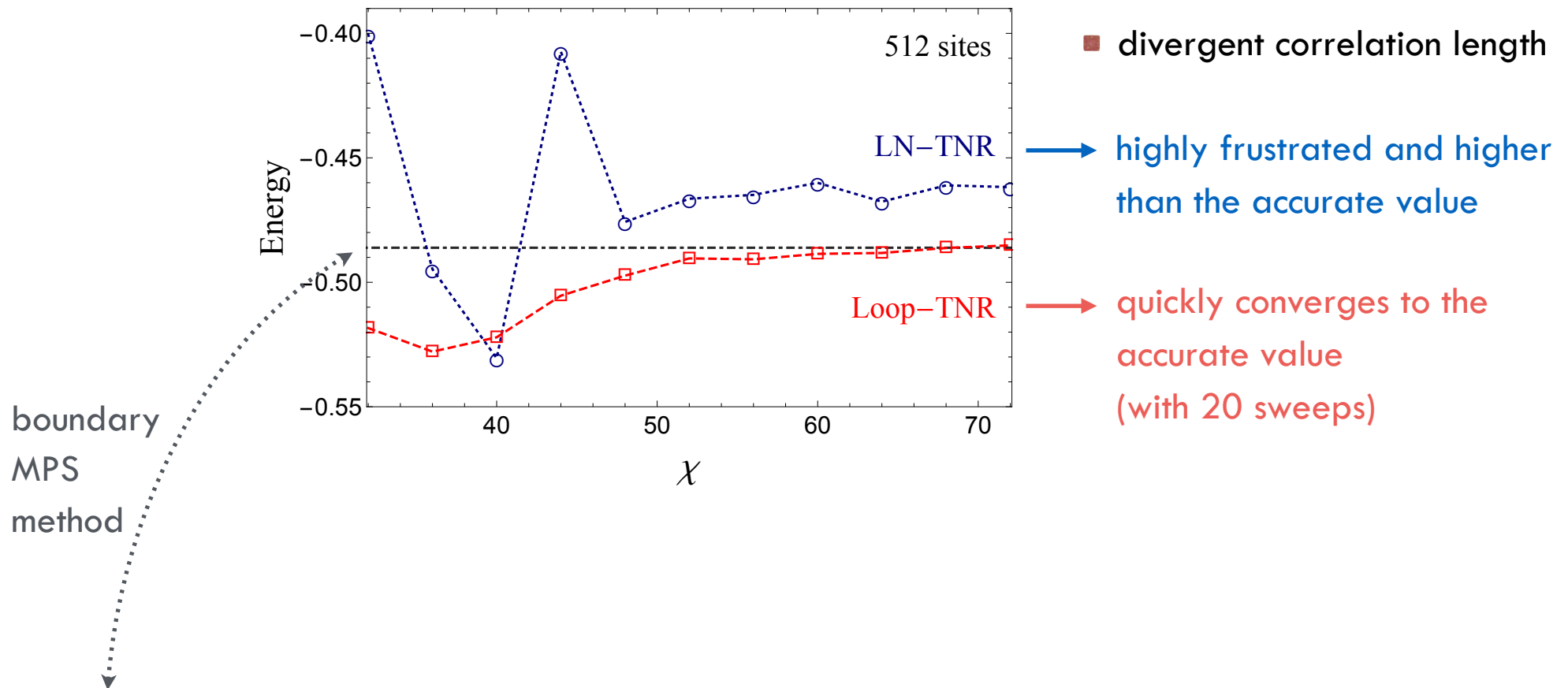
almost decays exponentially with bond dimension

- At off-critical points, the errors almost remains a constant for all temperatures near the critical point

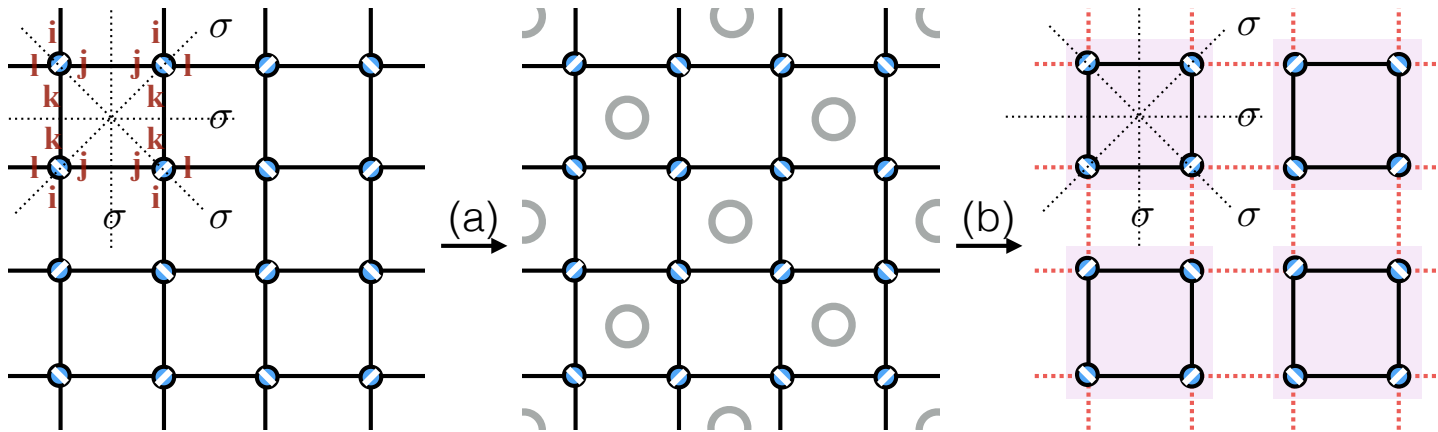
Variational energy for a 2D quantum model

D=3 PEPS ansatz

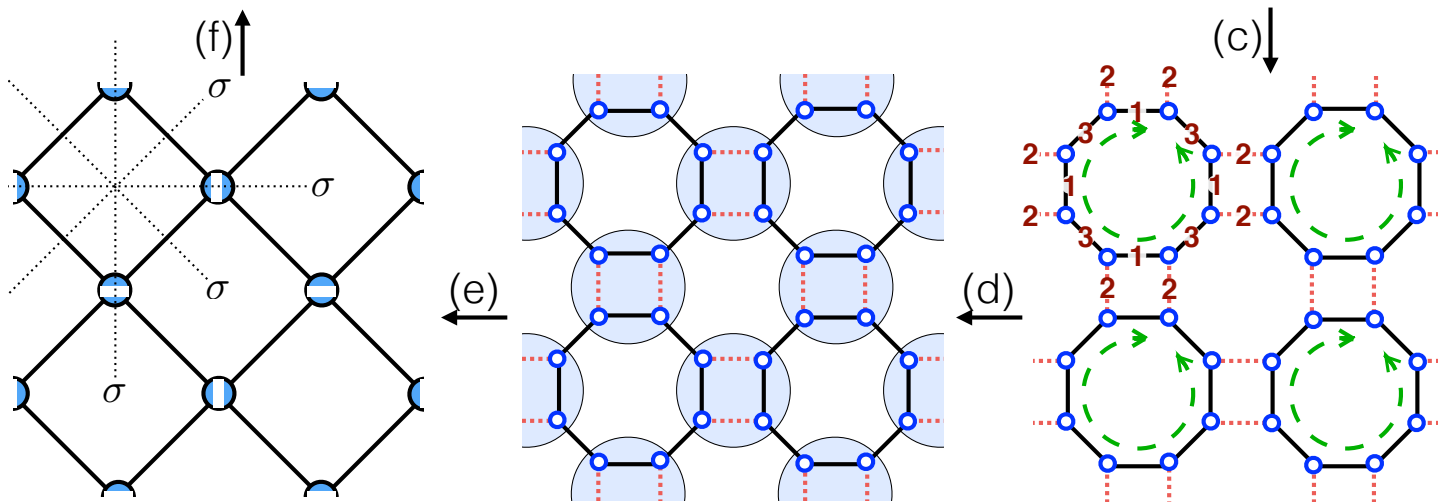
variational RVB ansatz for the $J_1 - J_2$ antiferromagnetic Heisenberg model on a square lattice at $J_2 = 0.5J_1$



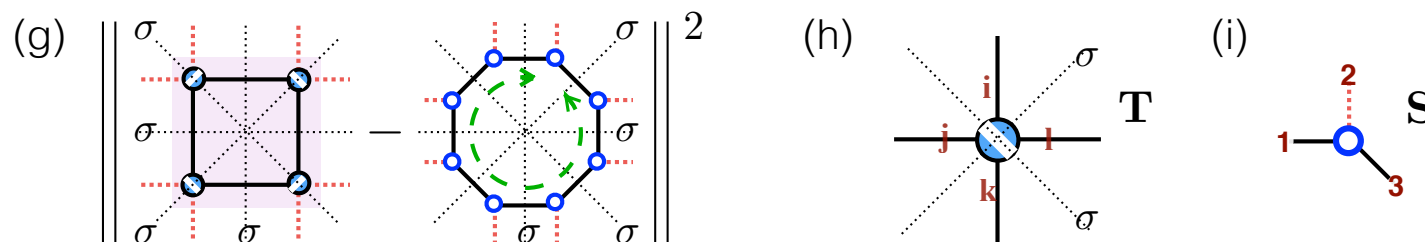
Loop TRG with reflection symmetry



4 axis of symmetry
global C4 symmetry

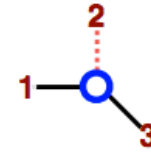


fix the gauge

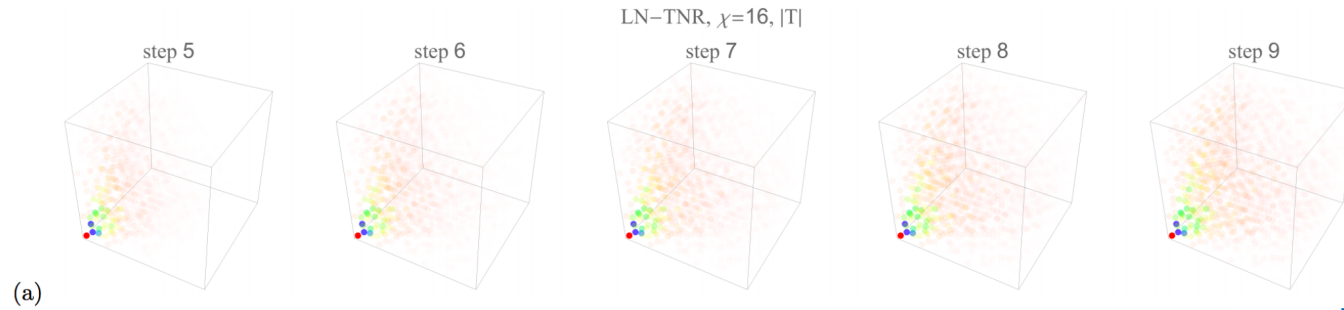


ideal case:
explicitly
invariant fixed
point tensor S

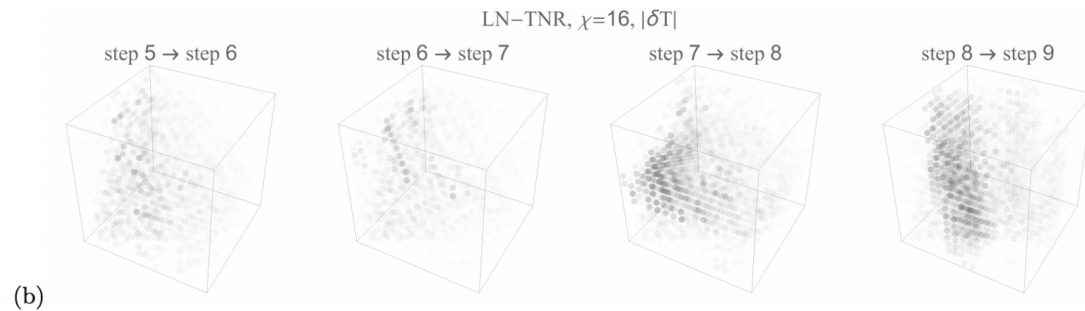
Fixed point tensors



LN-TNR
absolute value

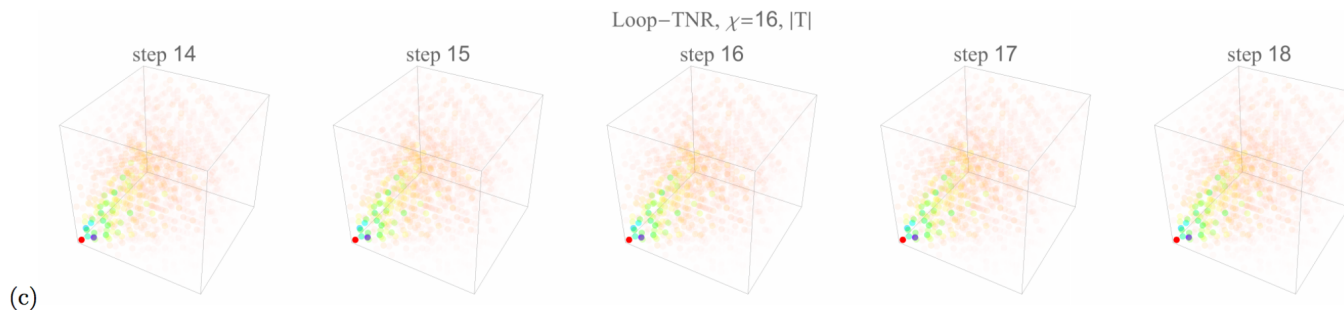


LN-TNR
absolute difference

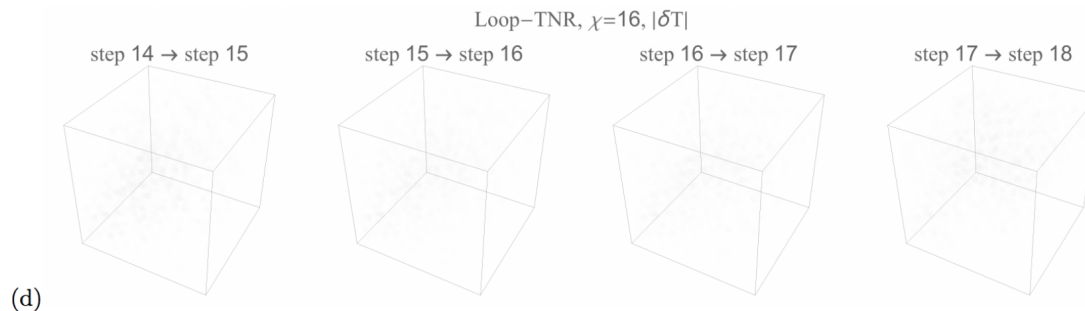


low-index parts
are approximately
invariant

Loop-TNR
absolute value



Loop-TNR
absolute difference



all tensor elements
are nearly invariant
~ scale invariance

Summary

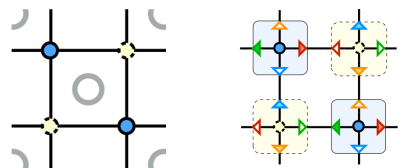
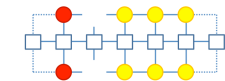
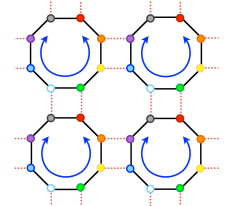
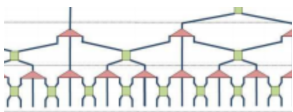
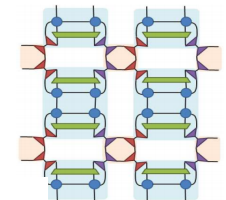
Real space TNR

■ Tree level: LN-TNR (Levin & Nave, 2007)

■ One loop: GW-TNR, EV-TNR, Loop-TNR

$$\left\| \begin{array}{c} x \\ \diagup \quad \diagdown \\ x \end{array} - \begin{array}{c} x \\ \diagdown \quad \diagup \\ x \end{array} \right\|^2, \quad \left\| \begin{array}{c} x \\ \diagup \quad \diagdown \\ x \end{array} - \begin{array}{c} x \\ \diagdown \quad \diagup \\ x \end{array} \right\|^2$$

$$\left\| \begin{array}{c} \text{Square Loop} - \text{Octagon Loop} \end{array} \right\|^2$$

1D algorithm	LN-TNR + 1D algorithm
 iTEBD	GW-TNR (Gu & Wen, 2009) Loop-TNR Part One 
 DMRG Variational MPS	Loop-TNR Part Two 
 MERA	EV-TNR (Evenbly & Vidal, 2014) 

Thank you!