

Data Analysis IV

Data Analysis for PTA

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Structure of the lectures

- ▶ DA I: Statistic basis for DA: Likelihood, frequentist/Bayesian
- ▶ GW Obs I: History, response to GW
- ▶ GW Obs II: LISA: LISAPathfinder, noises, ...
- ▶ DA II: 3 main classes of signal, parameter estimations, Fisher Matrix
- ▶ DA III: LISA DA: Global analysis, MBHB, stochastic, ...
- ▶ GW Obs III: LIGO
- ▶ GW Obs IV: PTA
- ▶ DA IV: PTA data analysis

Overview

- ▶ PTA data
- ▶ Fitting the model of the pulsar
- ▶ Continuous Gravitational Wave :
 - Frequentist
 - Bayesian
 - Upper limit
- ▶ Stochastic background
- ▶ Global analysis

Pulsar Timing Array Data

Pulsar model

- Model of the observed arrival time of the pulsar and radio wave propagation:

$$t^{\text{obs}} = t^{\text{PSR}} + \Delta_{\odot} + \Delta_{\text{ISM}} + \Delta_{\text{B}}$$

Observed arrival time

Emission time at pulsar

Barycentering

Propagation delay from pulsar to SSB

Pulsar orbit

PTA data

► Barycentering:

$$\Delta_{\odot} = \Delta_C + \Delta_A + \Delta_{E_{\odot}} + \Delta_{R_{\odot}} + \Delta_{S_{\odot}} + \dots$$

Clock corrections Δ_C , Atmospheric delays Δ_A , Solar system Einstein delay $\Delta_{E_{\odot}}$, SS Roemer delay $\Delta_{R_{\odot}}$, SS Shapiro delay $\Delta_{S_{\odot}}$

► Propagation:

$$\Delta_{ISM} = \Delta_{VP} + \Delta_{ISD} + \Delta_{FDD} + \Delta_{ES} + \dots$$

Vacuum propagation Δ_{VP} , Interstellar dispersion Δ_{ISD} , Additional Frequency dependent delay Δ_{FDD} , Einstein delay Δ_{ES}

► Pulsar orbit:

$$\Delta_B = \Delta_{RB} + \Delta_{AB} + \Delta_{EB} + \Delta_{SB}$$

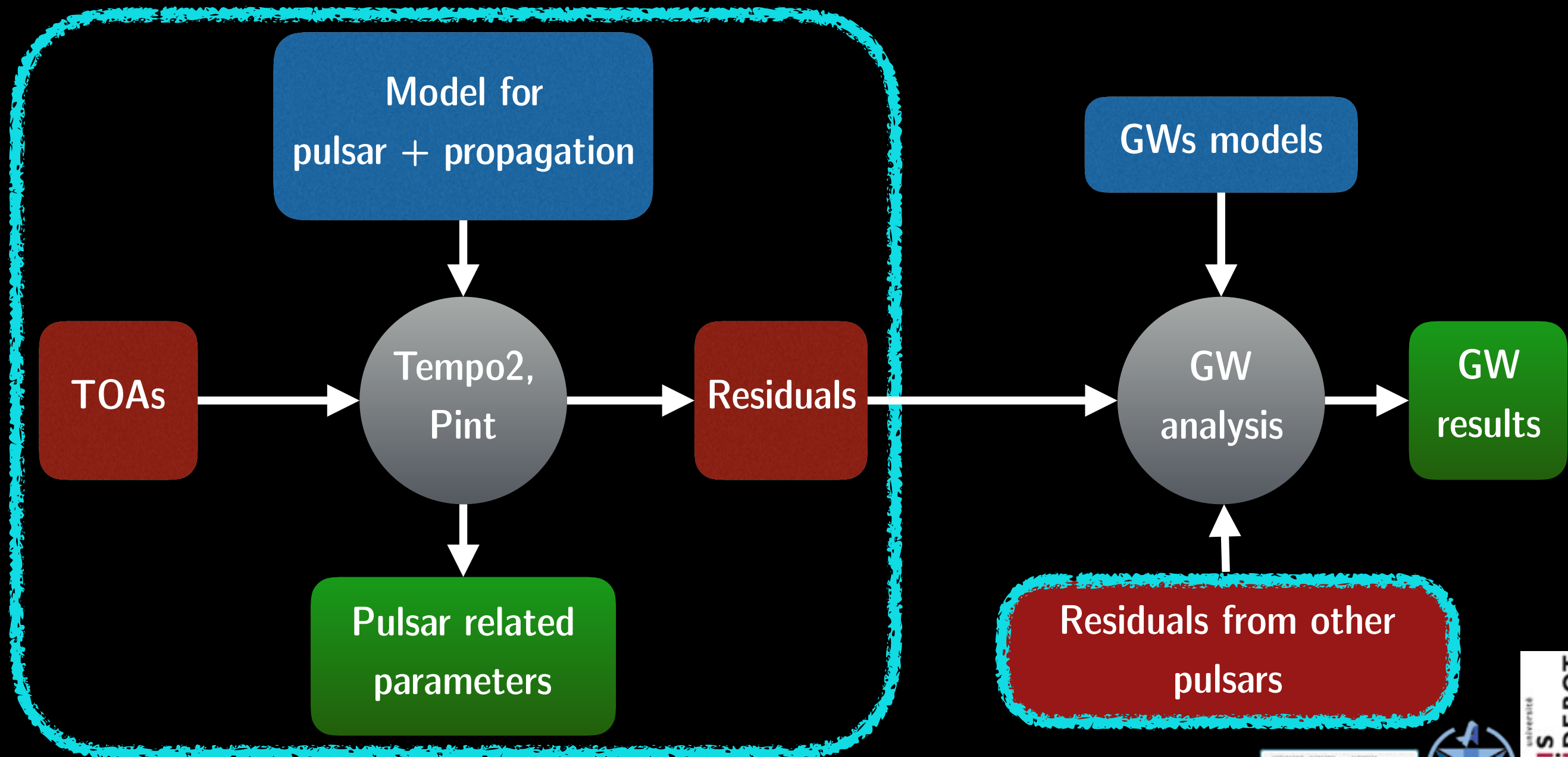
Roemer delay Δ_{RB} , Aberration Δ_{AB} , Einstein delay Δ_{EB} , Shapiro delay Δ_{SB}

► Spin-down:

$$P(t) = P_0 + \dot{P}_0 (t - t_0) + \frac{1}{2} \ddot{P}_0 (t - t_0)^2 + \dots$$

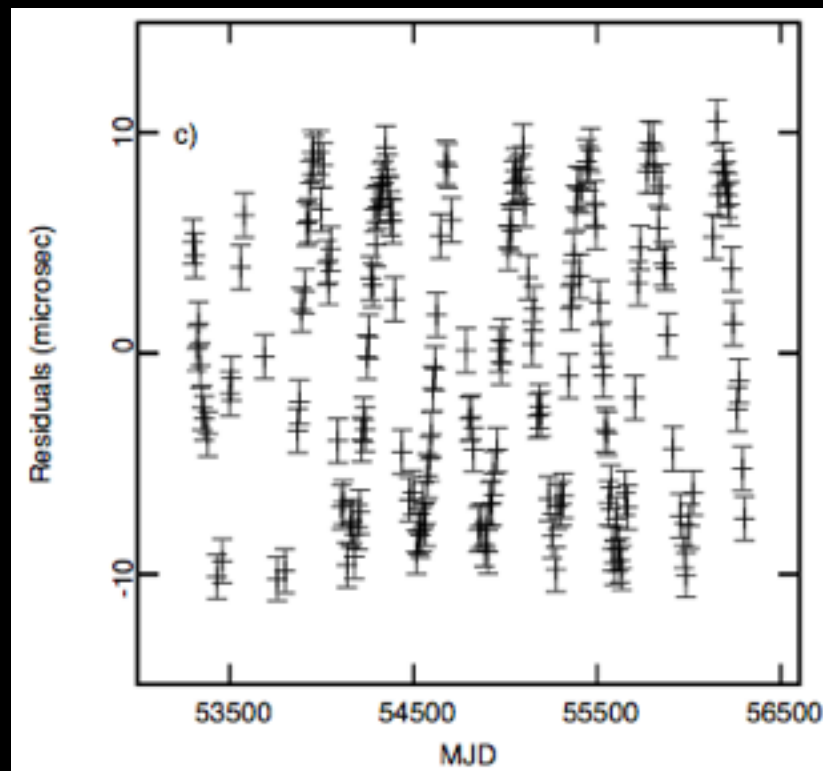
Residuals

- ▶ Time Of Arrivals (TOAs) are used to “fit” a model
- ▶ TOAs - “best model” = residuals \Rightarrow input to GW analysis

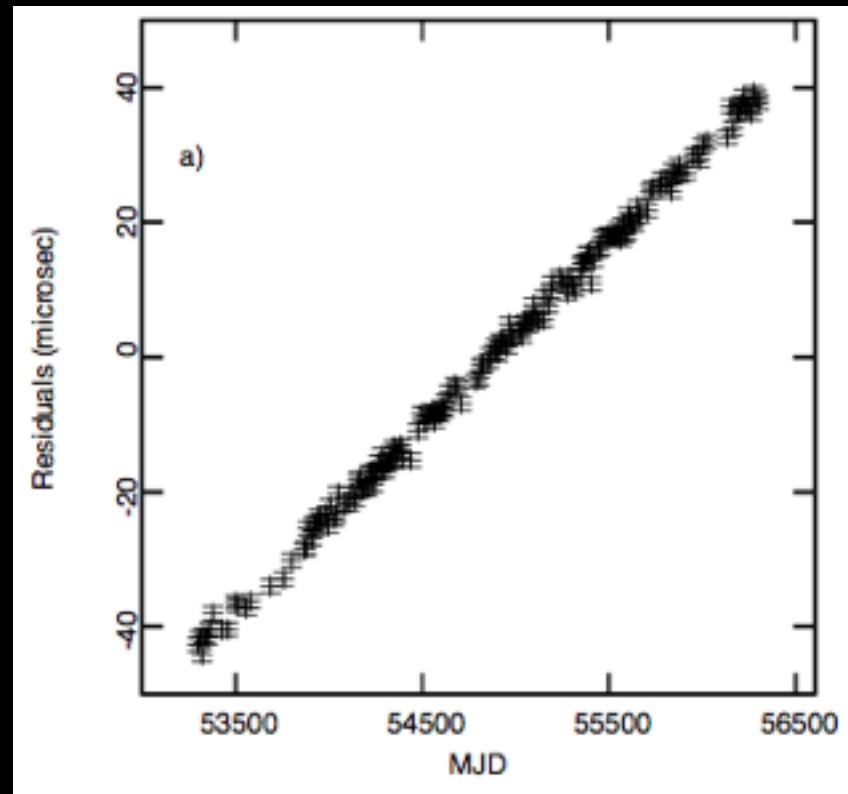


Residuals

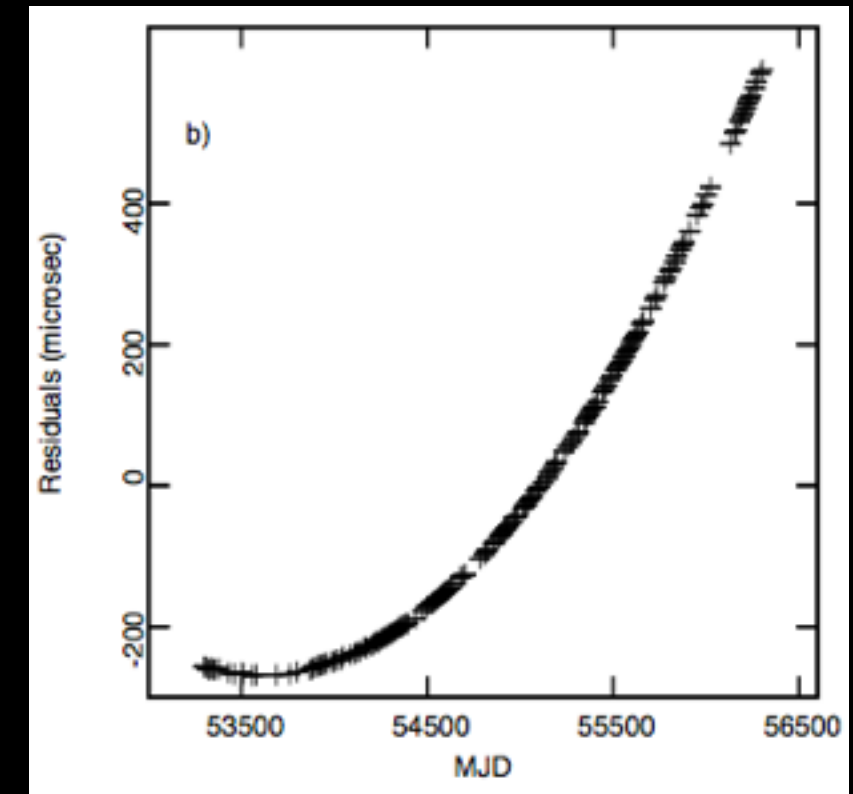
Error in position: annual effect



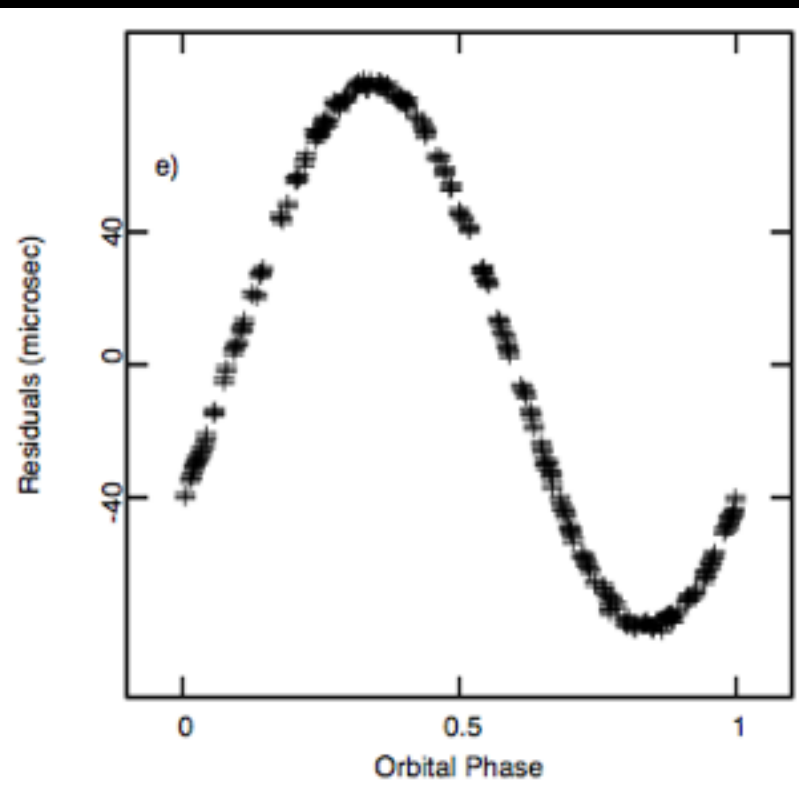
Error in period



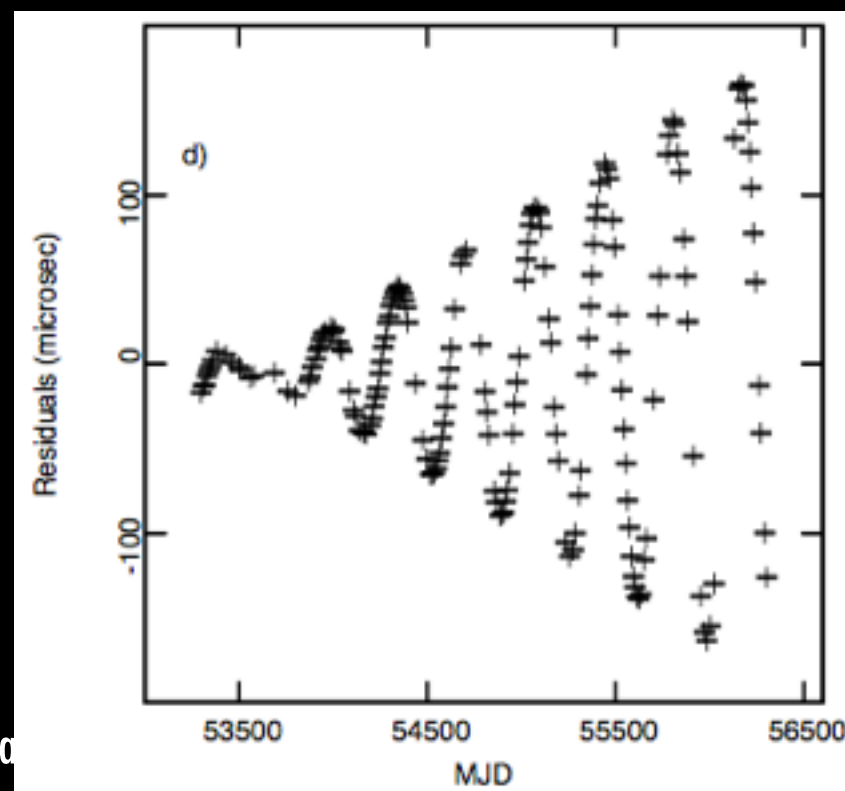
Error in period derivative



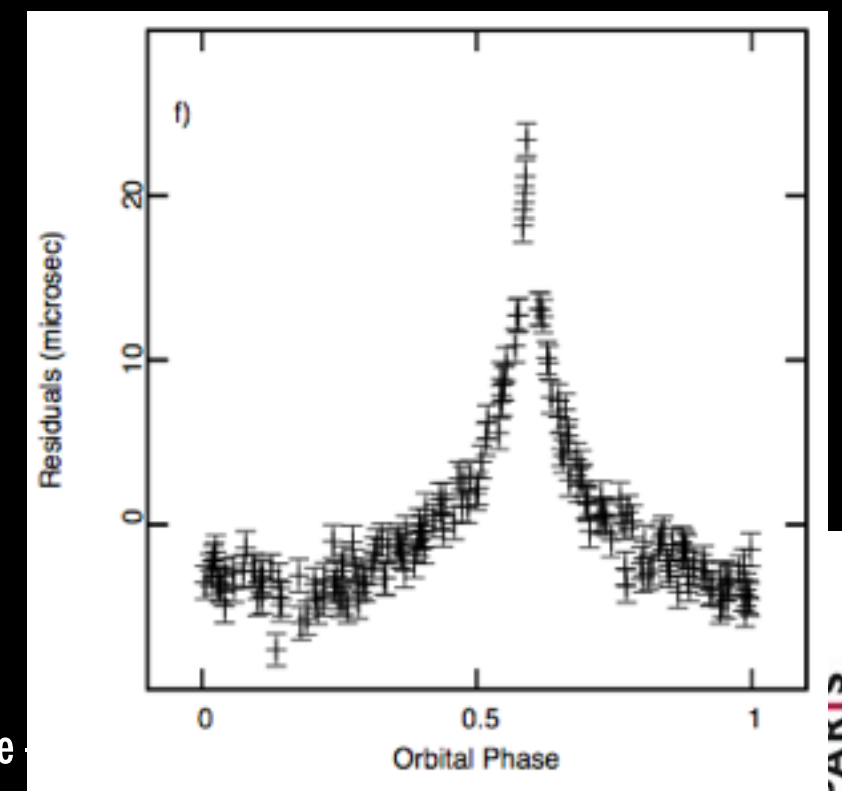
Error in orbital period



Error in proper motion

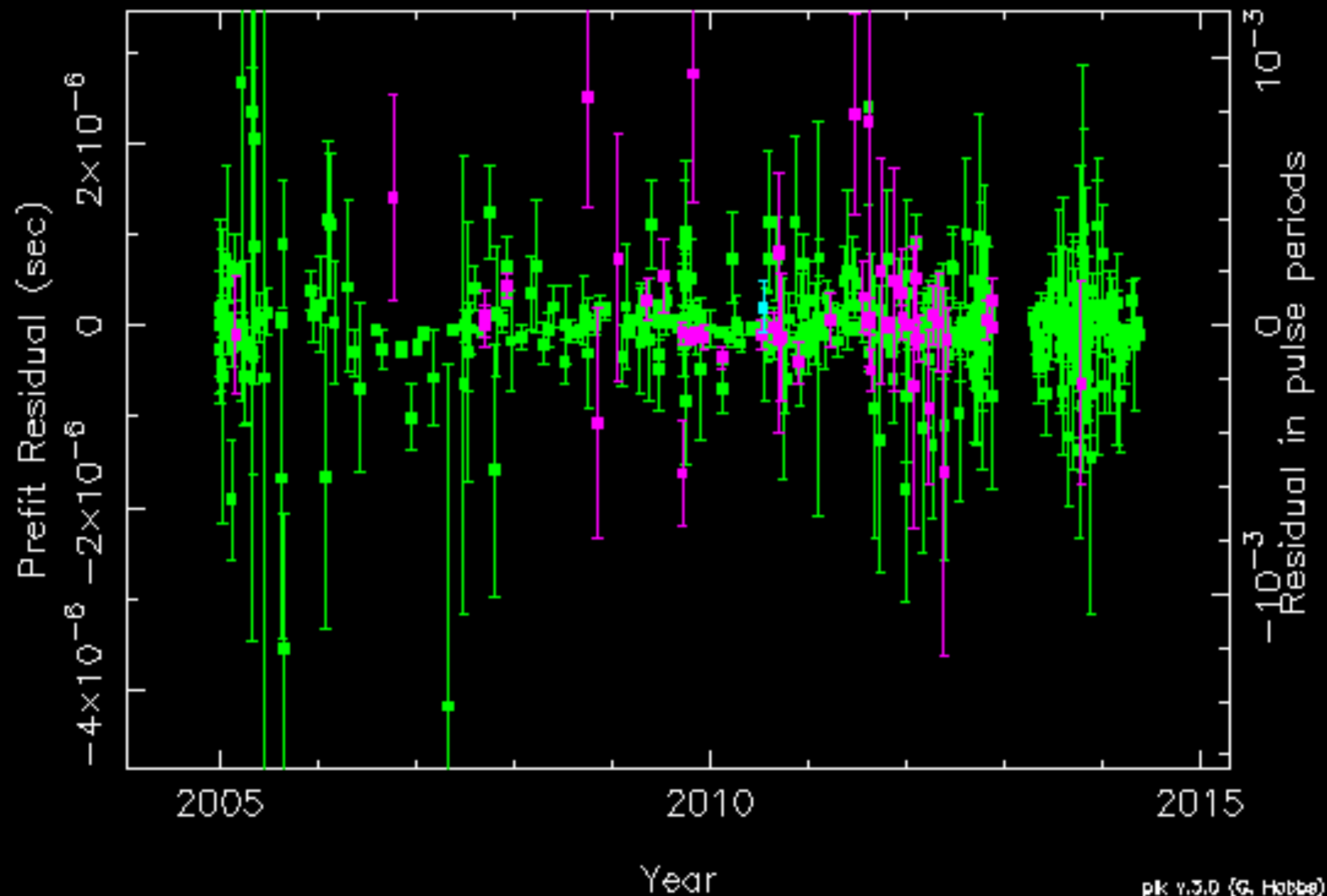


Without correction of Shapiro effect



Residuals

w tim Restart J1909-3744 (Wrms = 0.090 μ s) pre-fit



pk v3.0 (G. Hobbs)

Model imperfection

- ▶ The fitting of the model is **not perfect** in particular because we did not consider GWs as the same time as other “pulsars” parameters
- ▶ We need to integrate these imprecisions in GWs data analysis.
 - Global analysis ... many parameters
 - Analytical marginalization based on a [van Haasteren et al. 2009, 2012] (see later)

Data analysis

► The general likelihood is:

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^n \det(C)}} \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T C^{-1} \left(\vec{\delta t} - \vec{h} \right) \right)$$

- n : number of data points
- C : correlation matrix
- $\vec{\delta t}$: residual = data points
- $\vec{\theta}$: parameters

► Unequally sample data

Including pulsar model errors

[van Haasteren et al. 2009, 2012]

- ▶ During the fitting of the pulsar model some residual errors
- ▶ Assumption:
 - random Gaussian process $\delta \vec{t}_i^G$
 - + some contamination by several systematic signals with known functional forms $f_p(t_i)$ but a-priori unknown amplitudes ξ_p :

$$\begin{aligned}\delta \vec{t}_i &= \delta \vec{t}_i^G + \sum_p \xi_p f_p(t_i) \\ &= \delta \vec{t}_i^G + M \vec{\xi}_p\end{aligned}$$

- M : “design matrix” : $n \times m$: m number of pulsar fitting parameters

Data analysis

[van Haasteren et al. 2009, 2012]

► Then the likelihood can be rewritten as

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

- n : number of data points
- C : correlation matrix
- $\vec{\delta t}$: residual = data points
- $\vec{\theta}$: parameters
- G derived from M :
 - $M = U \Sigma V : (n \times n) (n \times m) (m \times m)$
 - $U = (F \ G) : ((n \times m) (n \times (n-m)))$

Likelihood

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \\ \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

Likelihood

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

► GW in

Likelihood

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

► GW in

- h : deterministic GW like binaries

Likelihood

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

► GW in

- h : deterministic GW like binaries
- C : stochastic background as correlation between pulsars

Likelihood

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

► GW in

- h : deterministic GW like binaries
- C : stochastic background as correlation between pulsars

► Noises in C

Gravitational wave signal

► GW signal in the pulsar residual:

$$r(t) = \int_0^t \frac{\delta\nu}{\nu}(t') dt'$$

$$\frac{\delta\nu}{\nu}(t) = \frac{1}{2} \frac{\hat{n}^i \hat{n}^j}{1 + \hat{n} \cdot \hat{k}} \left(\underbrace{h_{ij}(t - L(1 + \hat{n} \cdot \hat{k}))}_{\text{Strain of GW at the pulsar}} - \underbrace{h_{ij}(t)}_{\text{Strain of GW at Earth}} \right)$$

Strain of GW at the pulsar

Strain of GW at Earth

- \hat{n} : direction of the pulsar
- L : distance Earth – pulsar
- \hat{k} : direction of the GW propagation
- h_{ij} : GW strain

Continuous GWs

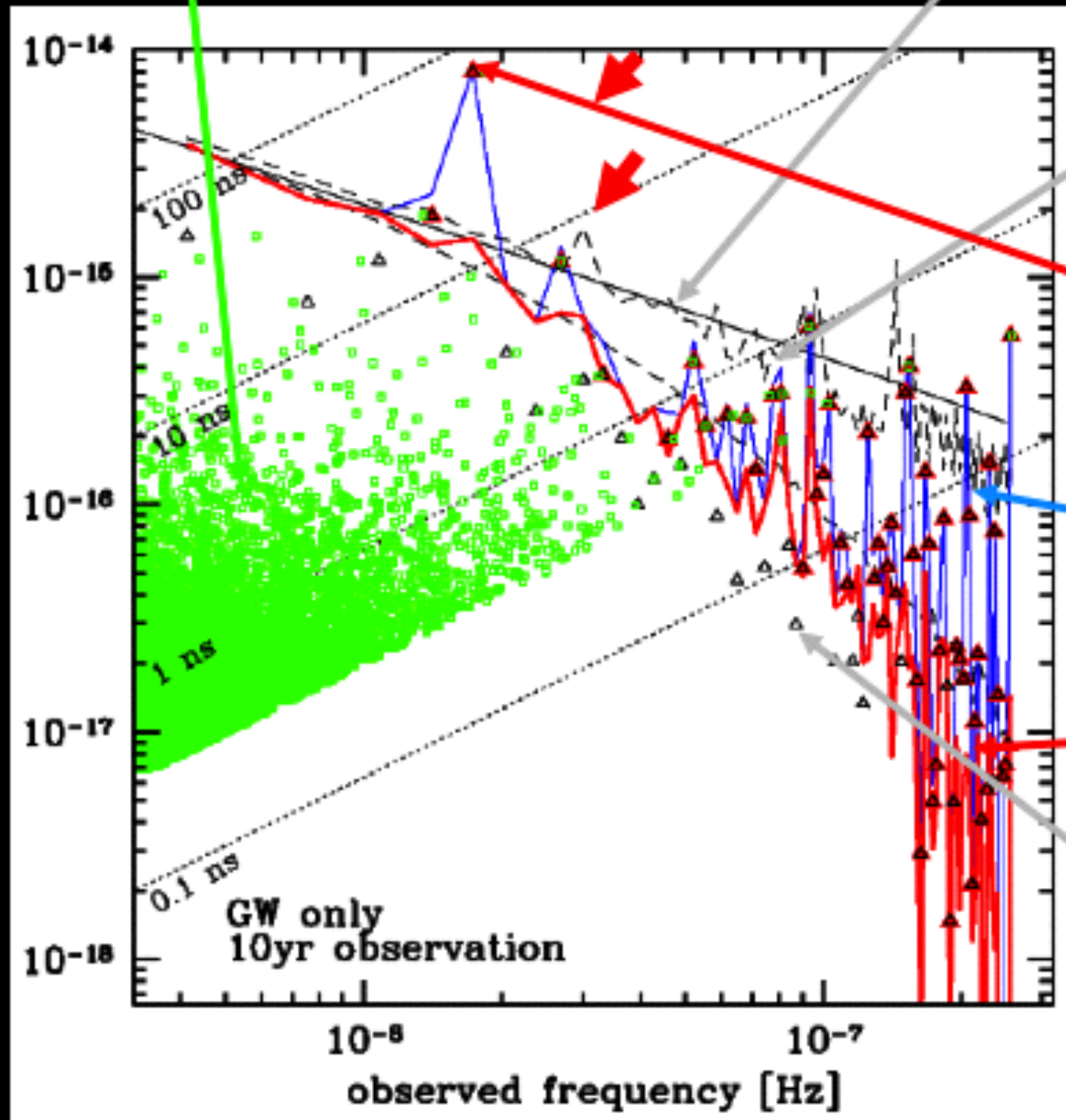
Sources

- ▶ SuperMassive Black Hole Binaries (SMBHB)
 - 10^7 to 10^9 solar masses
 - far from the merger =>
 - quasi-monochromatic sources
 - spins can be neglected
- ▶ Continuous waves: sources that can be resolved individually

Distribution of sources

From A. Sesana

Contribution of individual sources



Theoretical 'average' spectrum

Spectrum averaged over 1000 Monte Carlo realizations

Resolvable systems: i.e. systems whose signal is larger than the sum of all the other signals falling in their frequency bin

Total signal

Unresolved background

Brightest sources in each frequency bin

Model of the signal

► **GW waveform:**

$$h_{+}(t) = \mathcal{A} (1 + \cos^2 i) \cos (\phi(t) + \phi_0)$$
$$h_{\times}(t) = -2\mathcal{A} \cos i \sin (\phi(t) + \phi_0)$$

► **with**

$$\mathcal{A} = 2 \frac{\mathcal{M}_c^{5/3}}{D_L} (\pi f)^{2/3}$$

► **Parameters:**

- \mathcal{M}_c : chirp mass
- D_L : luminosity distance
- $f = 2 \pi \omega$: frequency of GW
- i : inclination
- $\phi(t)$: phase
- ϕ_0 : initial phase

Model of the signal

- GW signal in the residual: 2 terms pulsar term & Earth term

$$r_a(t) = r_a^p(t) - r_a^e(t)$$

$$r_a^e(t) = \frac{\mathcal{A}}{\omega} \left\{ (1 + \cos^2 \iota) F_a^+ [\sin(\omega t + \Phi_0) - \sin \Phi_0] + \right. \\ \left. 2 \cos \iota F_a^\times [\cos(\omega t + \Phi_0) - \cos \Phi_0] \right\},$$

$$r_a^p(t) = \frac{\mathcal{A}_a}{\omega_a} \left\{ (1 + \cos^2 \iota) F_a^+ [\sin(\omega_a t + \Phi_a + \Phi_0) - \right. \\ \left. \sin(\Phi_a + \Phi_0)] + 2 \cos \iota F_a^\times [\cos(\omega_a t + \Phi_a + \Phi_0) - \right. \\ \left. \cos(\Phi_a + \Phi_0)] \right\}.$$

$$F_a^+ = \frac{1}{2} \frac{(\hat{n}^a \cdot \hat{p})^2 - (\hat{n}^a \cdot \hat{q})^2}{1 + \hat{n}^a \cdot \hat{k}}$$

$$F_a^\times = \frac{(\hat{n}^a \cdot \hat{p})(\hat{n}^a \cdot \hat{q})}{1 + \hat{n}^a \cdot \hat{k}}$$

► Parameters

- ϕ_0 : initial phase at Earth
- ϕ_a : initial phase at pulsar
- F_a^+, F_a^\times : beam patterns depending on direction & polarisation

Model of the signal

► Beam patterns F_a^+ , F_a^\times are:

$$F_a^+ = \frac{1}{2} \frac{(\hat{n}^a \cdot \hat{p})^2 - (\hat{n}^a \cdot \hat{q})^2}{1 + \hat{n}^a \cdot \hat{k}}$$

$$F_a^\times = \frac{(\hat{n}^a \cdot \hat{p})(\hat{n}^a \cdot \hat{q})}{1 + \hat{n}^a \cdot \hat{k}}$$

► with $\hat{k} = -\{\sin \theta_S \cos \phi_S, \sin \theta_S \sin \phi_S, \cos \theta_S\}$

$$\hat{p} = \hat{u} \cos \psi + \hat{v} \sin \psi$$

$$\hat{q} = \hat{u} \cos \psi + \hat{v} \sin \psi$$

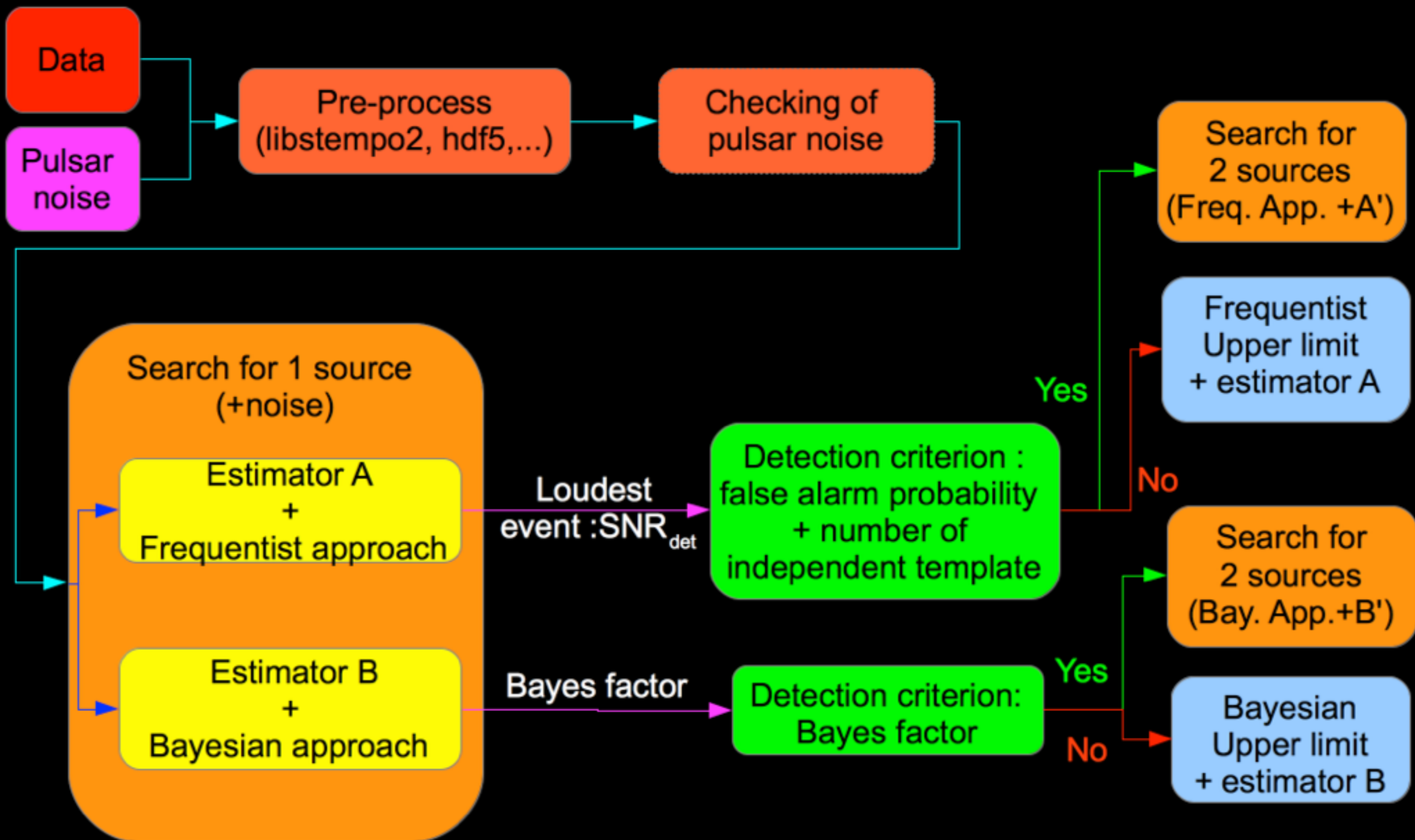
$$\hat{u} = \{\cos \theta_S \cos \phi_S, \cos \theta_S \sin \phi_S, -\sin \theta_S\}$$

$$\hat{v} = \{\sin \phi_S, -\cos \phi_S, 0\}$$

► Parameters:

- θ_S, ϕ_S : equatorial sky position of GW source
- ψ : polarisation
- p^a : direction of the pulsar

DA pipeline (EPTA)



Continuous GWs

Frequentist analysis

F-statistic Earth term only

- ▶ We consider only the Earth term which is the coherent term between all pulsars
- ▶ To apply F-statistic we want to rewrite the signal in the form

$$r_a^E(t) = \sum_j a_{(j)} h_{(j)}^a$$

Model of the signal

- Beam patterns F_a^+ , F_a^\times can be rewritten in the form:

$$F_a^+ = F_c^a \cos(2\psi) + F_s^a \sin(2\psi)$$

$$F_a^\times = -F_s^a \cos(2\psi) + F_c^a \sin(2\psi)$$

- with

$$F_c^a = \left\{ \frac{1}{4}(\sin^2(\theta_a) - 2\cos^2(\theta_a))\sin^2(\theta_S) - \frac{1}{2}\cos(\theta_a)\sin(\theta_a)\sin(2\theta_S)\cos(\phi_S - \phi_a) + \frac{1}{4}(1 + \cos^2(\theta_S))\sin^2(\theta_a)\cos(2\phi_S - 2\phi_a) \right\} \frac{1}{1 + \hat{n}^a \cdot \hat{k}}$$

$$F_s^a = \left\{ \cos(\theta_a)\sin(\theta_a)\sin(\theta_S)\sin(\phi_S - \phi_a) + \frac{1}{2}\sin^2(\theta_a)\cos(\theta_S)\sin(2\phi_a - 2\phi_S) \right\} \frac{1}{1 + \hat{n}^a \cdot \hat{k}}.$$

F-statistic Earth term only

► Thus, we have $r_a^E(t) = \sum_j a_{(j)} h_{(j)}^a$

► with

$$\begin{aligned} h_{(1)} &= F_c^a \sin(\Phi(t)), & h_{(2)} &= F_s^a \sin(\Phi(t)), \\ h_{(3)} &= F_c^a \cos(\Phi(t)), & h_{(4)} &= F_s^a \cos(\Phi(t)), \end{aligned}$$

► and

$$\begin{aligned} a_{(1)} &= \frac{\mathcal{A}}{2\pi f} [(1 + \cos^2 \iota) \cos(2\psi) \cos(\Phi_0) - 2 \cos \iota \sin(2\psi) \sin(\Phi_0)], \\ a_{(2)} &= \frac{\mathcal{A}}{2\pi f} [(1 + \cos^2 \iota) \sin(2\psi) \cos(\Phi_0) + 2 \cos \iota \cos(2\psi) \sin(\Phi_0)], \\ a_{(3)} &= \frac{\mathcal{A}}{2\pi f} [(1 + \cos^2 \iota) \cos(2\psi) \sin(\Phi_0) + 2 \cos \iota \sin(2\psi) \cos(\Phi_0)], \\ a_{(4)} &= \frac{\mathcal{A}}{2\pi f} [(1 + \cos^2 \iota) \sin(2\psi) \sin(\Phi_0) - 2 \cos \iota \cos(2\psi) \cos(\Phi_0)]. \end{aligned}$$

F-statistic Earth term only

- We parametrize only the deterministic signal h , not the noises and the stochastic background

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{r} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{r} \right) \right)$$

=> the log likelihood is:

$$\log \mathcal{L} = \langle \vec{\delta t}_a | \vec{r}_a \rangle - \frac{1}{2} \langle \vec{r}_a | \vec{r}_a \rangle$$

with inner product: $\langle \vec{x} | \vec{y} \rangle = \vec{x}^T G (G^T C G)^{-1} G^T \vec{y}$

F-statistic Earth term only

► Analytic maximisation of the likelihood over $a_{(j)}$: $\frac{\partial \log(\mathcal{L})}{\partial a_{(j)}} = 0$

► Solution: $a_{(j)} = M_{kj}^{-1} X_j$

with $X_j \equiv \sum_{\alpha=1}^P \langle x_{\alpha} | h_{(j)}^{\alpha} \rangle$ and $M_{jk} \equiv \sum_{\alpha=1}^P \langle h_{(j)}^{\alpha} | h_{(k)}^{\alpha} \rangle$

► New statistic: $\mathcal{F}_e = \{\log(\mathcal{L})\}_{max} = \frac{1}{2} X_k M_{jk}^{-1} X_j$

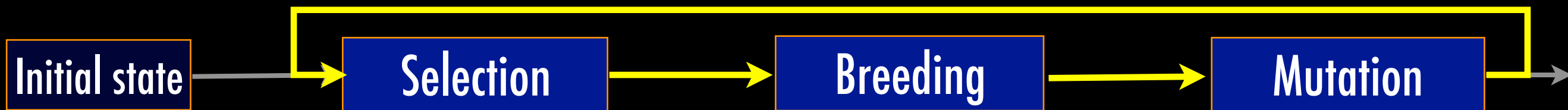
► To be maximized over the 3 remaining parameters (intrinsic):

- Equatorial latitude: θ_S ,
- Equatorial latitude: ϕ_S
- Frequency: f

Search algorithm MS-GA: Genetic Algorithm

Description : gene ↔ parameter : binary representation (binary or Grey code):
 parameter value ↔ 0 1 1 1 0 0 1 0 1 0 0 1

Evolution : organism ↔ template described by a set of genes



Selection : Selection of parents for the breeding

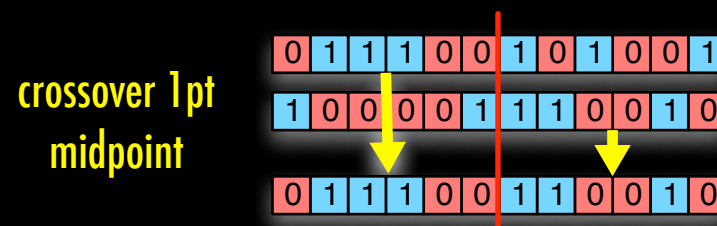
Probability of selecting one organism depend on Quality.

1. Quality $Q_i = \text{Maximized Likelihood}$,
2. Sort organisms by decreasing normalized quality
3. Roulette selection : Select one organism with probability equal to $Q_{Ni} / \sum_j^N Q_{Nj}$

Breeding : Making 1 child from the 2 selected parents

Mixing parts of corresponding parental genes. Several types of breeding :

- Crossover one point randomly chosen. Example :



- Others possibilities ...

Mutation : Change few bits in gene

Probability of change described by the 'Probability Mutation Rate' (PMR) $\in [0,1]$.

Several types of mutation :

- Mutate all the gene : If a random value $\alpha < PMR$, mutate the gene. Several types :
 - Choose randomly N bits and flip them.
 - Complete random value
- Mutate bits independently : for each bit compare PMR to a random value α . If $\alpha < PMR$, flip bit (0 \rightarrow 1 or 1 \rightarrow 0).

Search algorithm MS-GA: Genetic Algorithm

Description : gene \longleftrightarrow parameter : binary representation (binary or Grey code):
 parameter value \longleftrightarrow 0 1 1 1 0 0 1 0 1 0 0 1

Evolution : organism \longleftrightarrow template described by a set of genes

Initial state

Selection : Sele
the breeding

Probability
organism depe

1. Quality $Q_i =$
Likelihood,

2. Sort organisms by decreasing
normalized quality

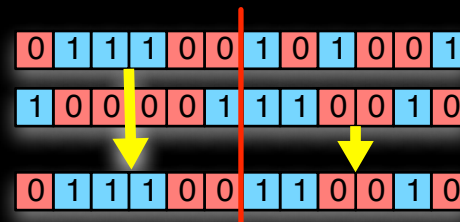
3. Roulette selection : Select one
organism with probability equal to
 $Q_{Ni} / \sum_j^N Q_{Nj}$

GA can be seen as a method for clustering templates
around the best one.

GA has several possibilities of tuning which allows local
or global searches.

chosen. Example :

crossover 1pt
midpoint



Others possibilities ...

Choose randomly N bits and flip them.

Complete random value

Mutate bits independently : for each bit
compare PMR to a random value α . If
 $\alpha < PMR$, flip bit ($0 \rightarrow 1$ or $1 \rightarrow 0$).

gene

the
 $\in [0,1]$.

value α
types :

Search algorithm MS-GA: Multi Search

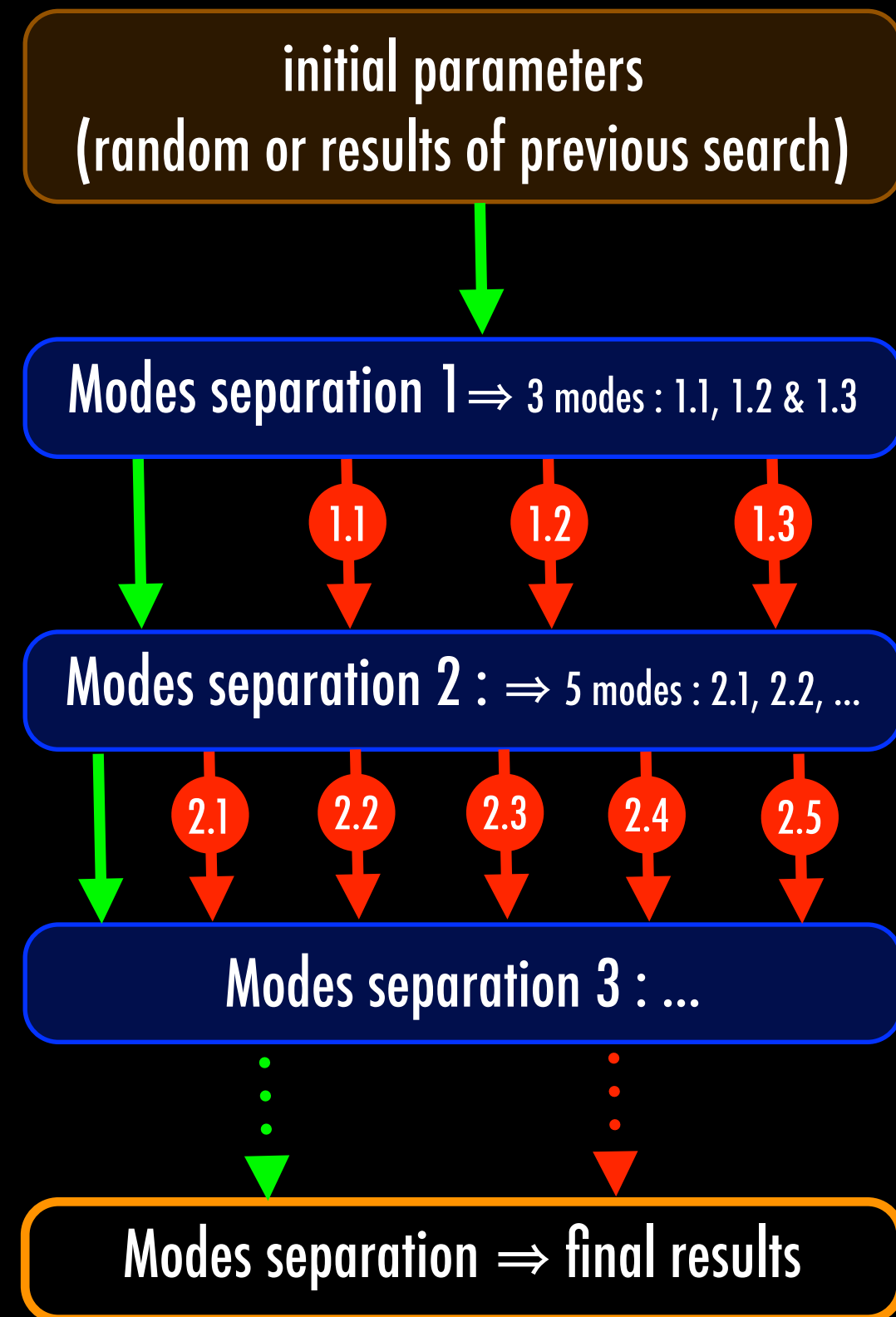
Framework to run in parallel several dedicated search methods :

→ "Global searches" looks for new good candidates avoiding the ones already found.

→ "Local searches" explores in details the best candidates found at the previous step.

"Modes separation" : the results are combined to find a new set of best candidates using some criterions (high SNR and not too close to the others).

Each search is done by a GA with a special tuning or a parallel MCMC (EMCEE)



Individual sources and data

[Template :

- Several individual sources : Earth term only, non-eccentric, fixed frequencies.

- Fstatistic : analytic maximisation over 4 parameters (Petiteau & al. 2012 , Babak & Sesana 2012, Ellis & al. 2012) \Rightarrow search for $N_{\text{src}} \times 3$ parameters (sky positions & frequencies).

- GW background (GWB) and red-noise on pulsars (RN) can be taken into account in likelihood computation (use of design matrix based on Van Hasterren & Levin 2012) ...

- MS-GA can search for GWB + RN + individual source parameters (ex. in Stas Babak's talk).

[Search :

- MS-GA coupled with several technics for removing «ghost detections» (checking of correlation between pulsars, high-pass filtering, cyclic removing of pulsars).

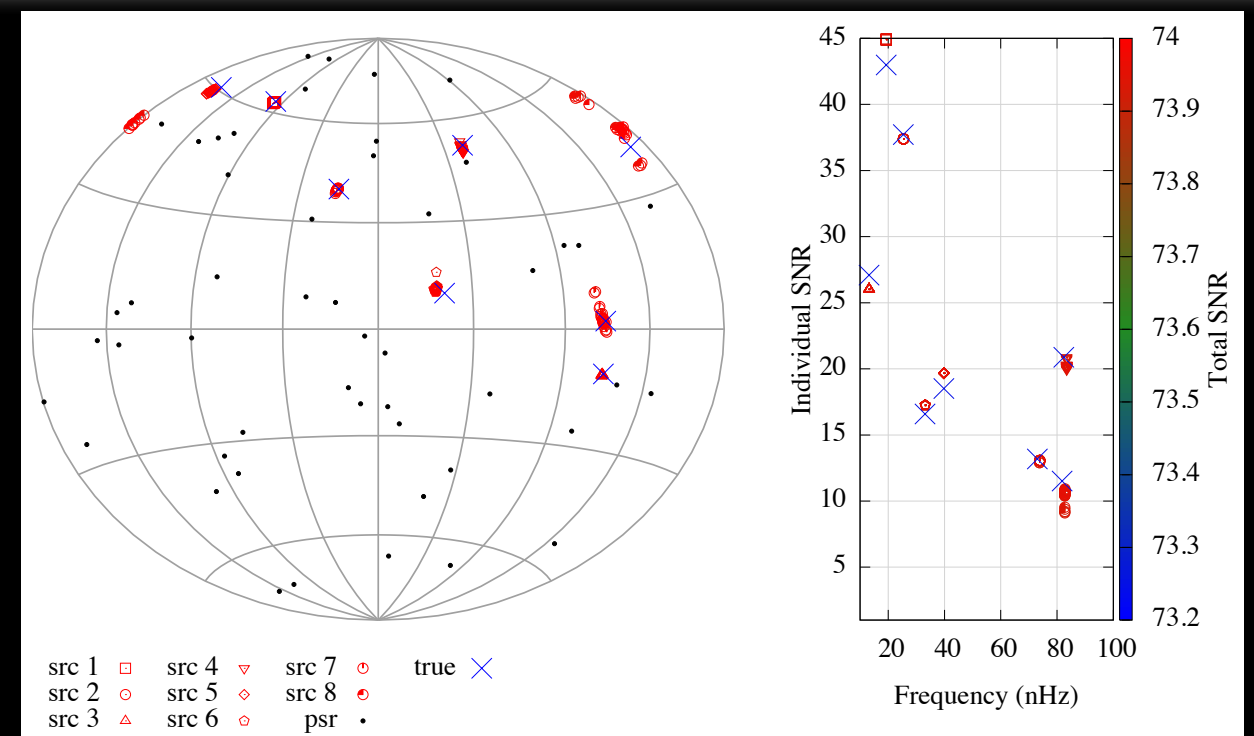
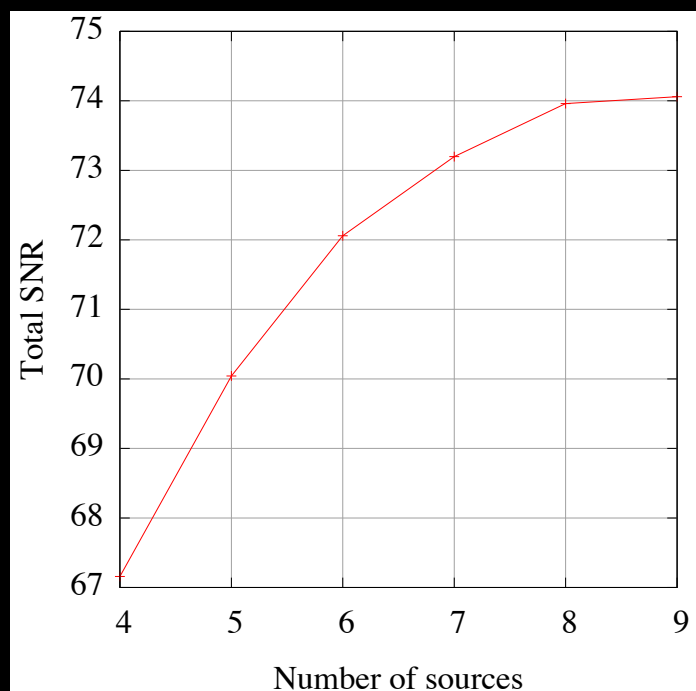
- Characterisation of errors and likelihood distribution via MCMC (Antoine Lassus's talk).

[Data : simplified dataset or par/tim dataset (\Rightarrow MS-GA can work with real dataset).

Results on simulated data

Npulsars	noise	dataset	Nsrc	ind. src SNR	signal	Results
30-50	noiseless or white 50-100 ns	simplified	1-5	> 10	earth term, same frequency	Pilot study Babak & Sesana 2012
30-50	white 30-200 ns	simplified	3-8	> 10	earth term, \neq freq.	OK Petiteau & al. 2012

- MS-GA successfully identified **all** the injected sources in all datasets
- MS-GA **found all source parameters** : sky position offset by less than few degrees and frequencies found with precision better than 0.1 nHz (errors characterisation : **Antoine Lassus' talk**)



Statistics of \mathcal{F}_e

- $2\mathcal{F}_e$ is distributed as χ^2 with n degrees of freedom
[Janaroski & Krolak LRR, 15 (2012)]

$$p'_0(\mathcal{F}) = p_{\chi^2}(2\mathcal{F}) = \frac{(2\mathcal{F})^{n/2-1} e^{-(2\mathcal{F})/2}}{2^{n/2} \Gamma(n/2)} = \frac{(\mathcal{F})^{n/2-1} e^{-\mathcal{F}}}{2 \Gamma(n/2)}$$

- After normalization and approximations:

$$p_0(\mathcal{F}) = e^{-\mathcal{F}} \frac{\mathcal{F}^{n/2-1}}{(n/2 - 1)!} \left(\text{exact : } e^{-\mathcal{F}} \frac{\mathcal{F}^{n/2-1}}{\Gamma(n/2)} \right)$$

Statistics of \mathcal{F}_e

- The false alarm probability, P_F that \mathcal{F}_e exceed \mathcal{F}_{th} when there is no signal is

$$P_F(\mathcal{F}_{th}) = \int_{\mathcal{F}_{th}}^{\infty} p_0(\mathcal{F}) d\mathcal{F}$$

$$= e^{-\mathcal{F}_{th}} \sum_{k=0}^{n/2-1} \frac{\mathcal{F}_{th}^k}{k!} \left(\text{exact : } \frac{\Gamma(n/2, \mathcal{F}_{th})}{\Gamma(n/2)} \right)$$

- Probability that $\mathcal{F} < \mathcal{F}_{th}$ for one template is: $1 - P_F(\mathcal{F}_{th})$
- Probability that $\mathcal{F} < \mathcal{F}_{th}$ for one template is: $[1 - P_F(\mathcal{F}_{th})]^{N_{cell}}$
- Finally, probability that $\mathcal{F} > \mathcal{F}_{th}$ for at least one template is the total false alarm probability:

$$P_F^T(\mathcal{F}_{th}) = 1 - [1 - P_F(\mathcal{F}_{th})]^{N_{cell}}$$

Statistics of Fe

- In the case of Fe , we marginalize over 4 parameters per source so $N = 4 N_{src}$ then :

$$P_F(\mathcal{F}_{e,th}) = e^{-\mathcal{F}_{e,th}} \sum_{k=0}^{2N_{src}-1} \frac{\mathcal{F}_{e,th}^k}{k!}$$

- The total false alarm probability is than

$$P_F^T = 1 - \left[1 - e^{-\mathcal{F}_{e,th}} \sum_{k=0}^{2N_{src}-1} \frac{\mathcal{F}_{e,th}^k}{k!} \right]^{N_{cell}}$$

- We need N_{cell} the total number of templates ?

Statistics of Fe

- ▶ We need N_{cell} the total number of templates:
 - criterion for considering that 2 templates defined by parameters ξ and ξ' are independent is that the autocovariance function is

$$C(\xi, \xi') \leq \rho C(\xi, \xi) = \rho \frac{n}{2}$$

- with $\rho = 0.5$
 - Stochastic template bank
- ▶ 1 source: False Alarm Probability

$$P_F^T = 1 - [1 - e^{-\mathcal{F}_{e,th}} (1 + \mathcal{F}_{e,th})]^{N_{cell,1}}$$

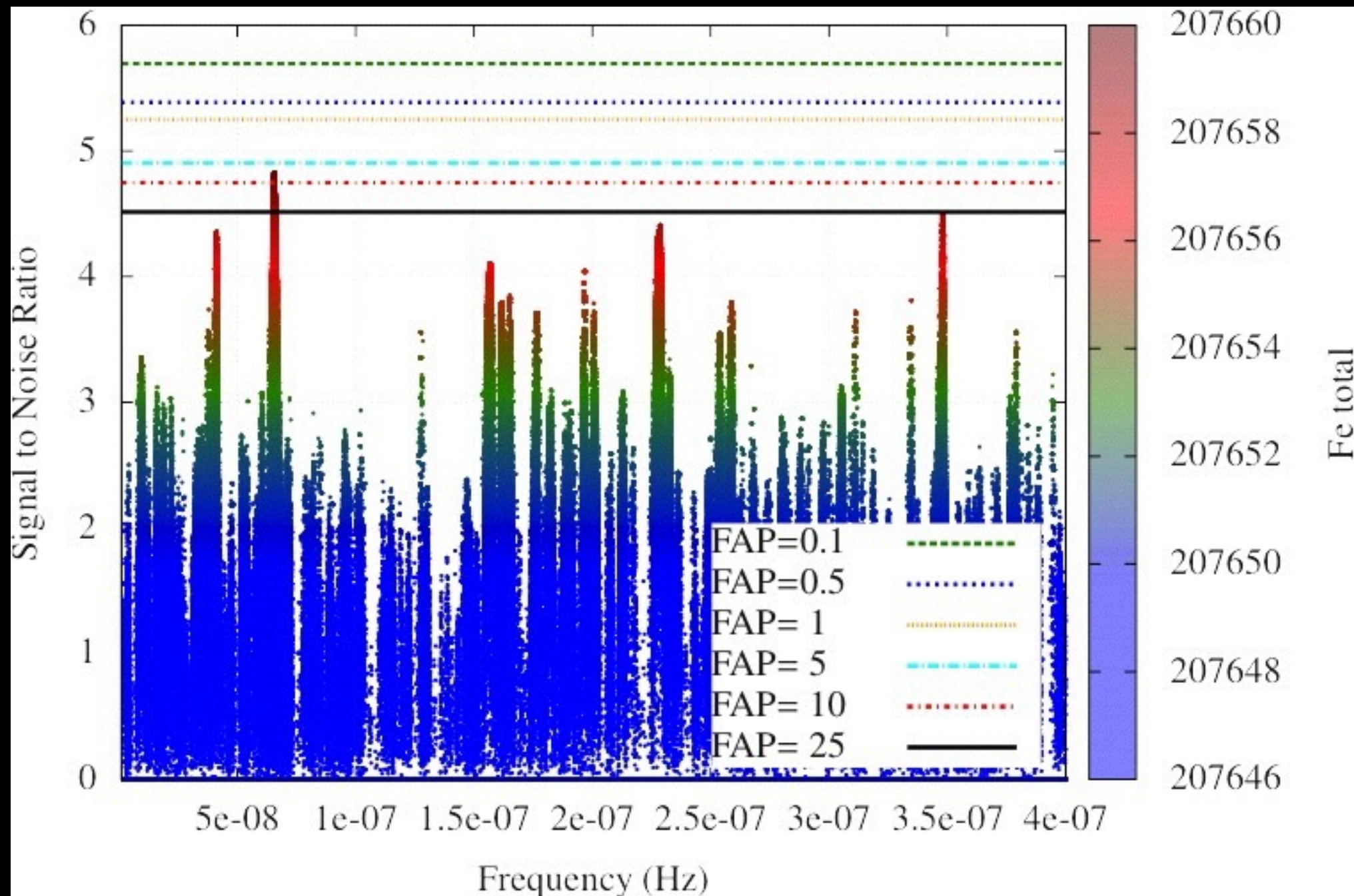
- ▶ By inverting, we got the threshold corresponding to the false alarm probability

Apply on real-data

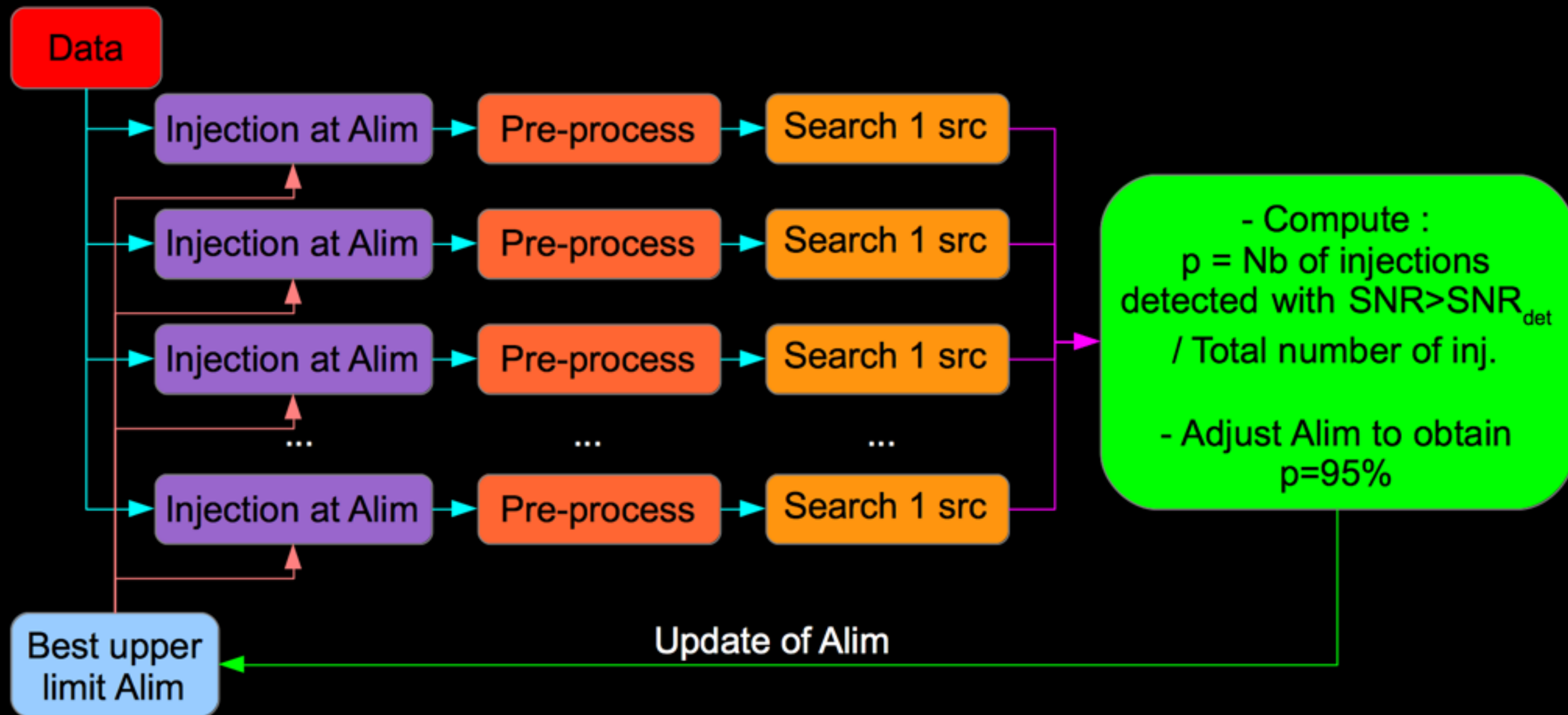
- ▶ Data: EPTA data release 2
 - 10- of 41 millisecond pulsars
- ▶ Noises analysis:
 - Hardest part: estimate C
 - Estimation of the noise contribution for each pulsar using various technics:
 - Red noise
 - Dispersion measurements
 - White noise component per back-end per pulsar
 - EFAC
 - EQUAD

Apply on real-data

► Detection results of Fp on real data

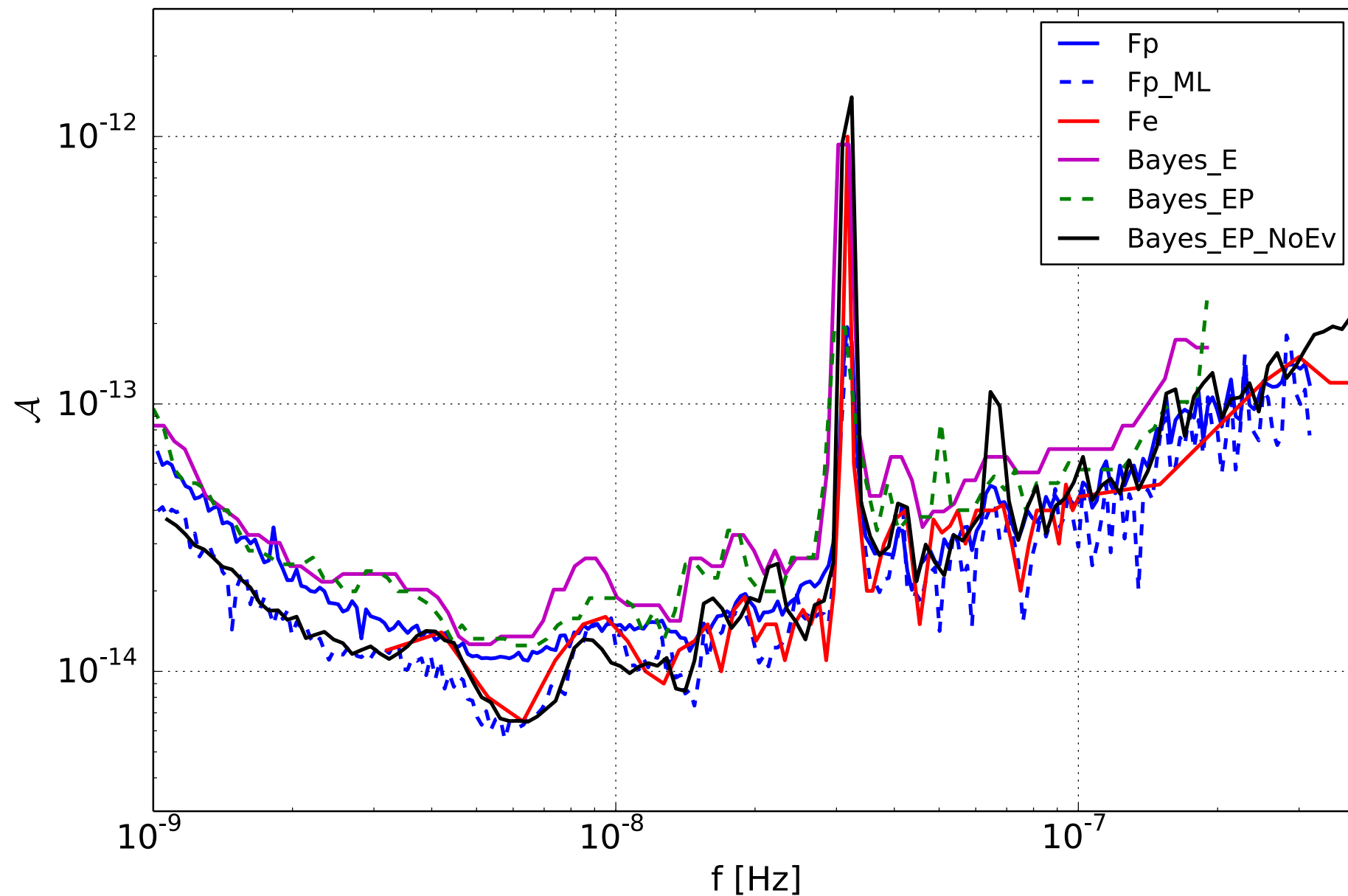


Upper limit



Results

Babak et al. EPTA MNRAS 455.2 (2016)



Fp statistic

Ellis et al. (2012)

- ▶ Excess power in which we basically search for extra power at a given frequency in each pulsar data
- ▶ Maximisation over all parameters except frequency f

$$r_a(t) = \sum_{j=1}^2 b_{(j,a)}(\mathcal{A}, \theta_S, \phi_S, \Psi, \iota, \Phi_0, \Phi_a) \kappa_{(j)}(\omega, t)$$

- ▶ Distribution of Fp statistic:

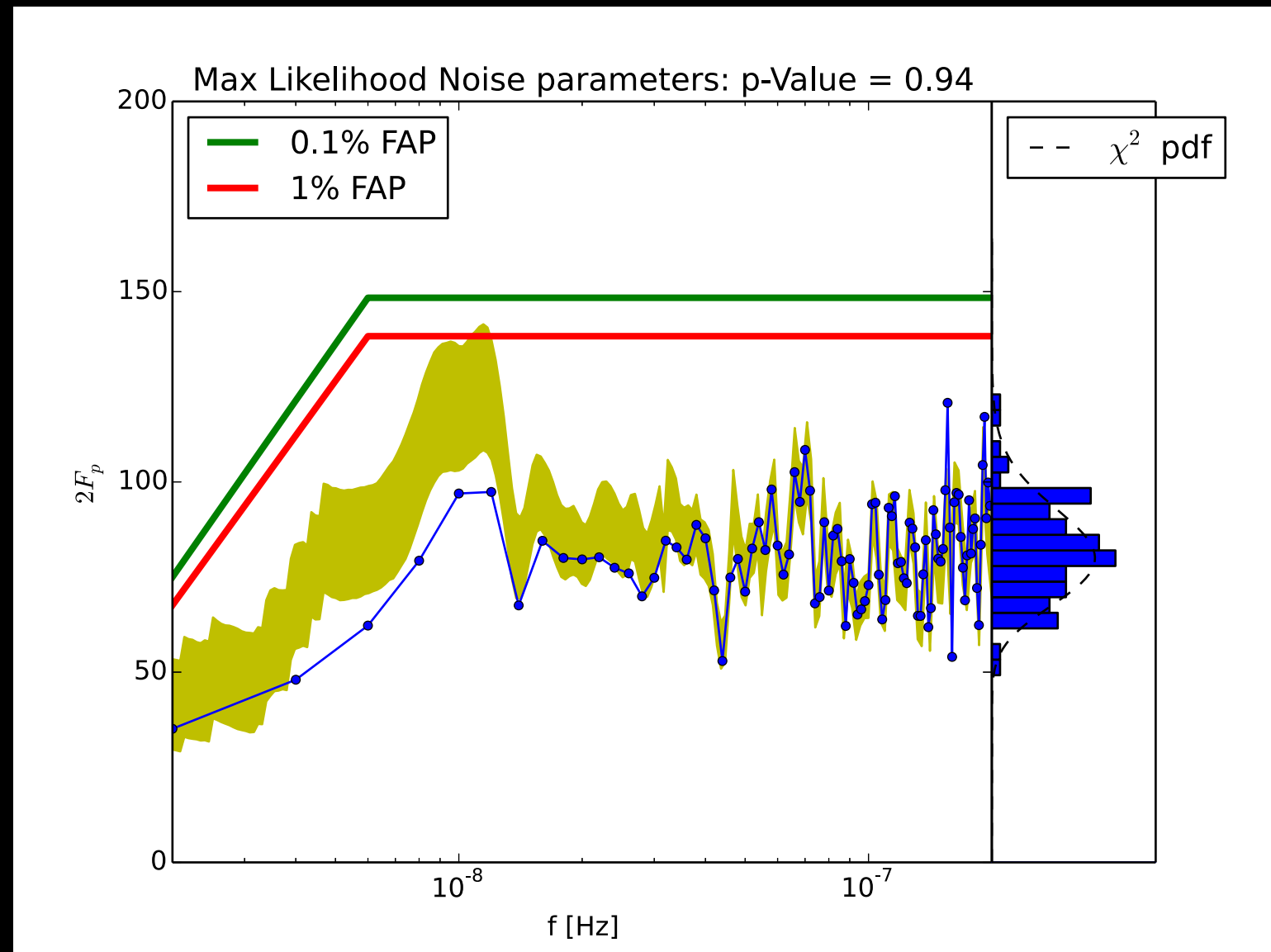
- Gaussian noise: central : $p_0(\mathcal{F}_p) = \frac{\mathcal{F}_p^{n/2-1}}{(n/2-1)!} \exp(-\mathcal{F}_p)$
- Signal: non-central with optimal SNR ρ :

$$p_1(\mathcal{F}_p, \rho) = \frac{(2\mathcal{F}_p)^{(n/2-1)/2}}{\rho^{n/2-1}} I_{n/2-1}(\rho\sqrt{2\mathcal{F}_p}) e^{-\mathcal{F}_p - \frac{1}{2}\rho}$$

Fe detection results

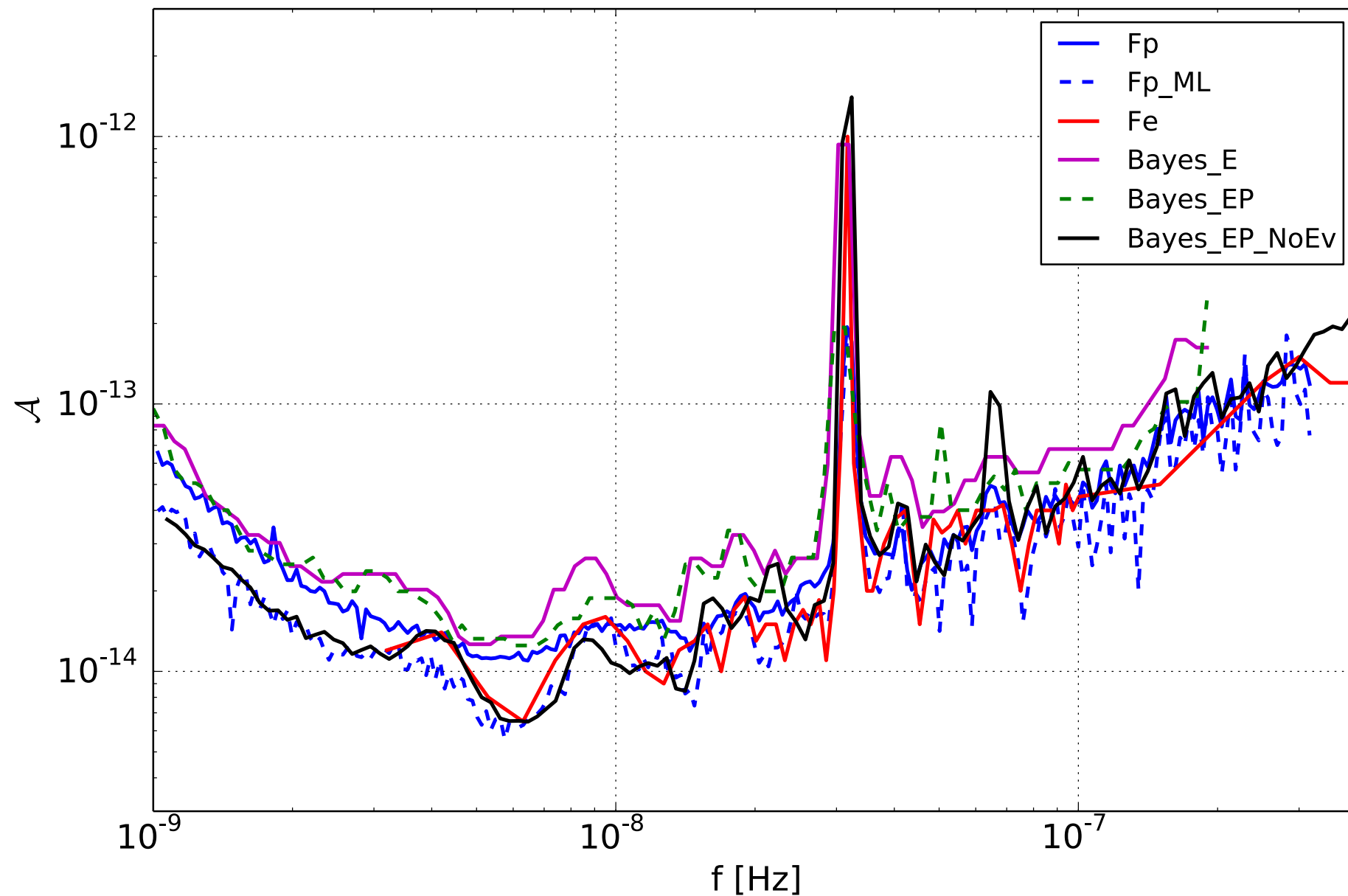
Babak et al. EPTA MNRAS 455.2 (2016)

- ▶ F_p evaluated at 99 independent frequencies
- ▶ $p\text{-value} = 0.93$
- ▶ Take into account the uncertainty in the noise parameters by sampling from their posterior distribution derived from the single pulsar analysis



Results

Babak et al. EPTA MNRAS 455.2 (2016)



Continuous GWs

Bayesian analysis

Bayesian analysis 1

► No evolving sources: frequency at the pulsar is the same as the earth frequency.

- we should sample on $7+N_{\text{pulsar}}$ parameters

$$(\mathcal{A}, \theta_S, \phi_S, \Psi, \iota, \omega, \Phi_0, \Phi_a)$$

- numerical marginalization over the pulsar phase ϕ_a [Taylor et al., 2014]
- MultiNest
- Analysis:
 - 41 pulsars with fixed noise
 - 6 pulsars with varying noise

Bayesian analysis 2

► Full response:

- $7 + 2 N_{\text{pulsar}}$ parameter space
- Parallel tempering MCMC
- Analysis:
 - 41 pulsars with Earth term only
 - 6 pulsars with pulsar and Earth terms

Results

► Bayes factor

$$\mathcal{B} = \frac{\int \mathcal{L}(\vec{\theta}, \vec{\lambda} | \vec{\delta t}) \pi(\vec{\theta}, \vec{\lambda}) d\vec{\theta} d\vec{\lambda}}{\int \mathcal{L}(\vec{\theta} | \vec{\delta t}) \pi(\vec{\theta}) d\vec{\theta}}.$$

- Non evolving: $\log(\mathcal{B}) = -0.27$
- Earth term only: $\log(\mathcal{B}) = -0.31$

=> no detection

=> upper limit

Upper limit

$$0.95 = \int_0^{\tilde{A}} d\mathcal{A} \int d\vec{\lambda}' \mathcal{L}(\mathcal{A}, \vec{\lambda}' | \delta\vec{t}) \pi(\mathcal{A}) \pi(\vec{\lambda}')$$

Data

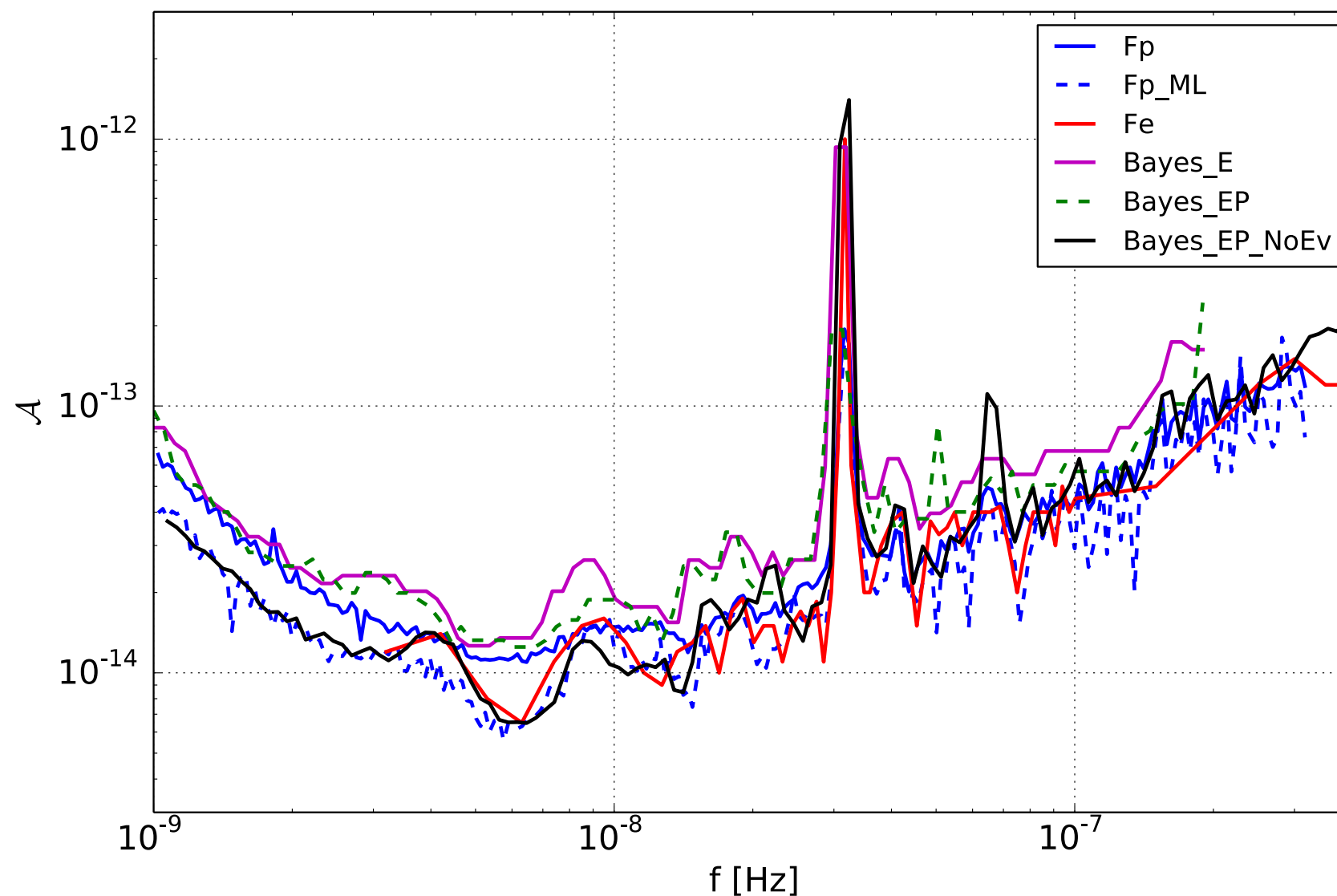
Pre-process

Full exploration of all parameters within the box in frequency (+sky)

On amplitude distribution, take the value of A including 95% of the distribution

Upper limit Alim

Results EPTA

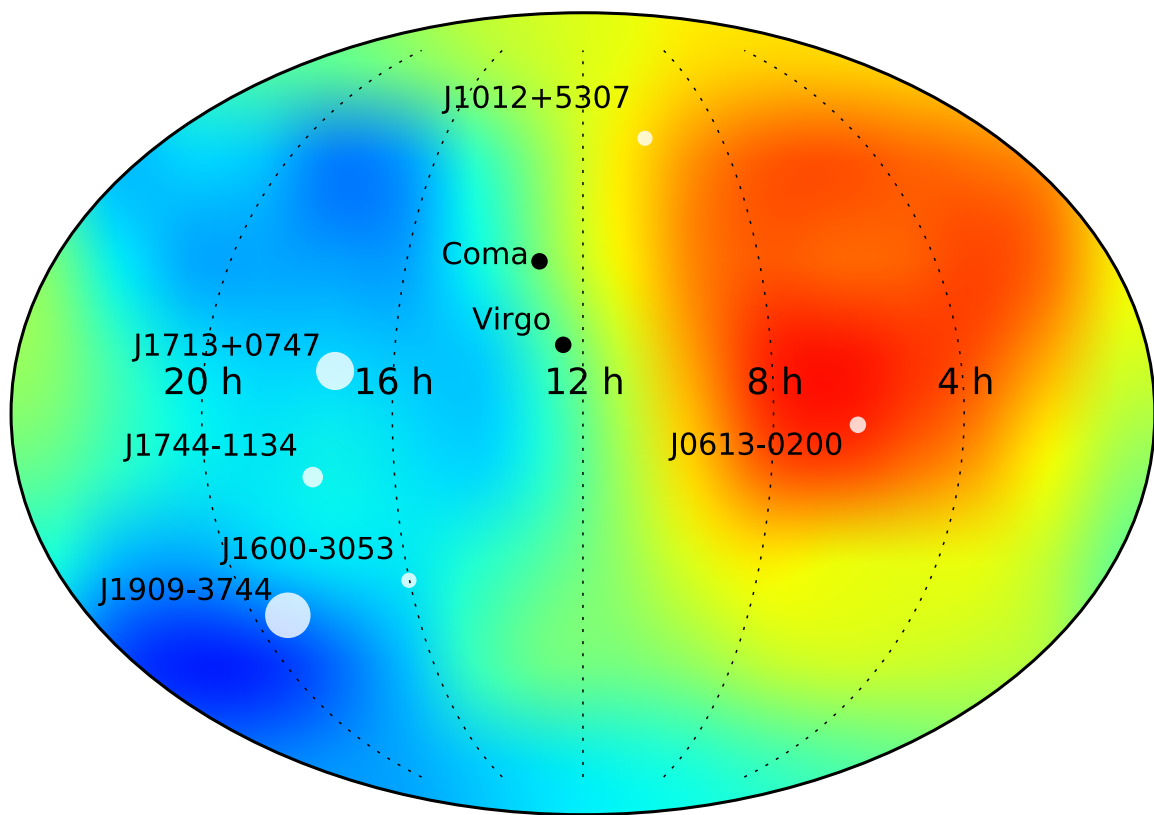


Search ID	Noise treatment	pulsars (N)	parameters	Signal model	Likelihood
<i>Fp_ML</i>	Fixed ML	41	1	E+P NoEv	Maximization over $2N$ constant amplitudes
<i>Fp</i>	Sampling posterior	41	1	E+P NoEv	Maximization over $2N$ constant amplitudes
<i>Fe</i>	Fixed ML	41	3	E	Maximization over 4 constant amplitudes
<i>Bayes_E</i>	Fixed ML	41	7	E	Full
<i>Bayes_EP</i>	Fixed ML	6	$7 + 2 \times 6$	E+P Ev	Full
<i>Bayes_EP_NoEv</i>	Fixed ML	41	7	E+P NoEv	Marginalization over pulsar phases
<i>Bayes_EP_NoEv_noise</i>	Searched over	6	$7 + 5 \times 6$	E+P NoEv	Marginalization over pulsar phases

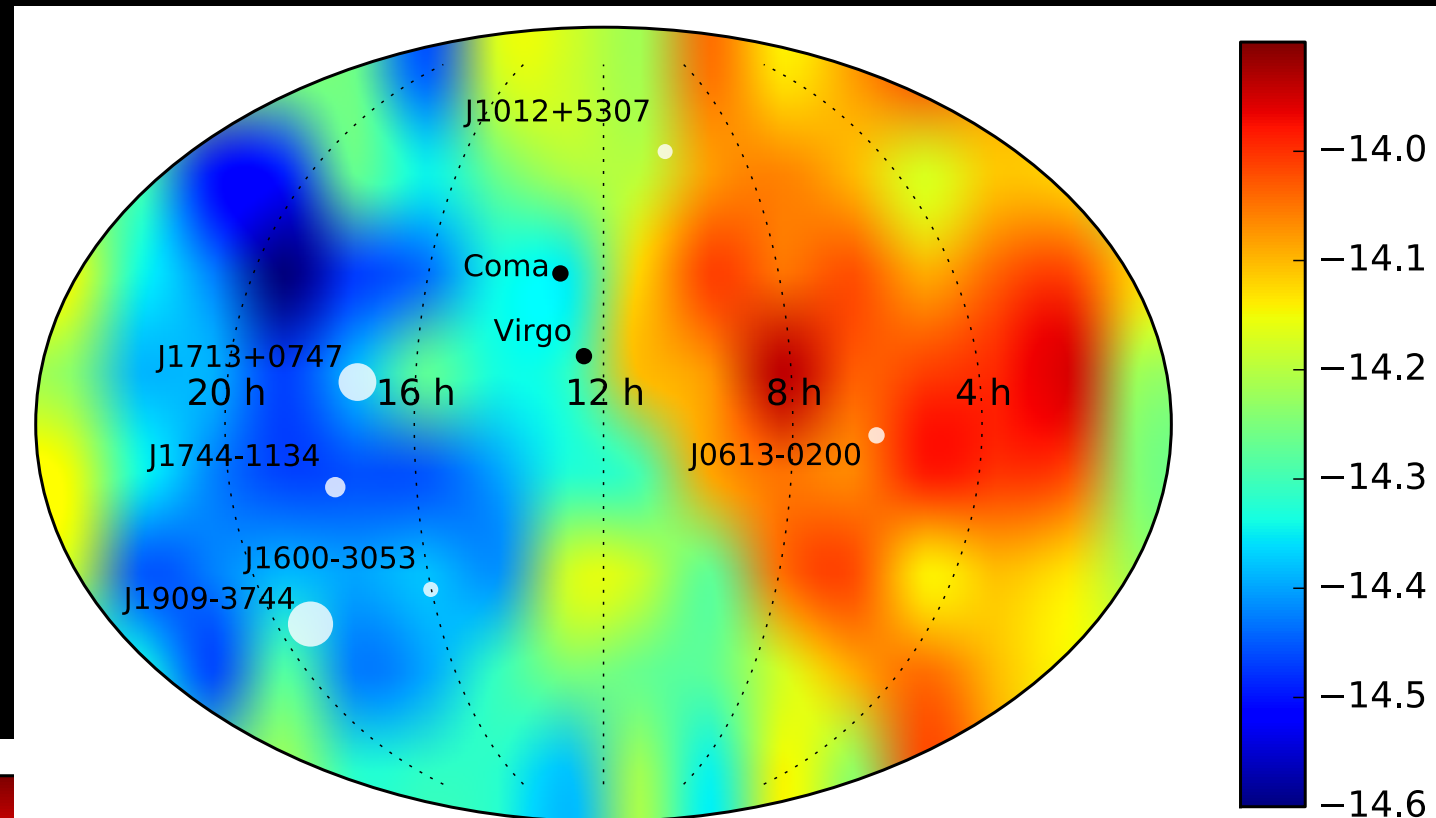
Upper limit

► Sky map upper limit at 7nHz

Frequentist



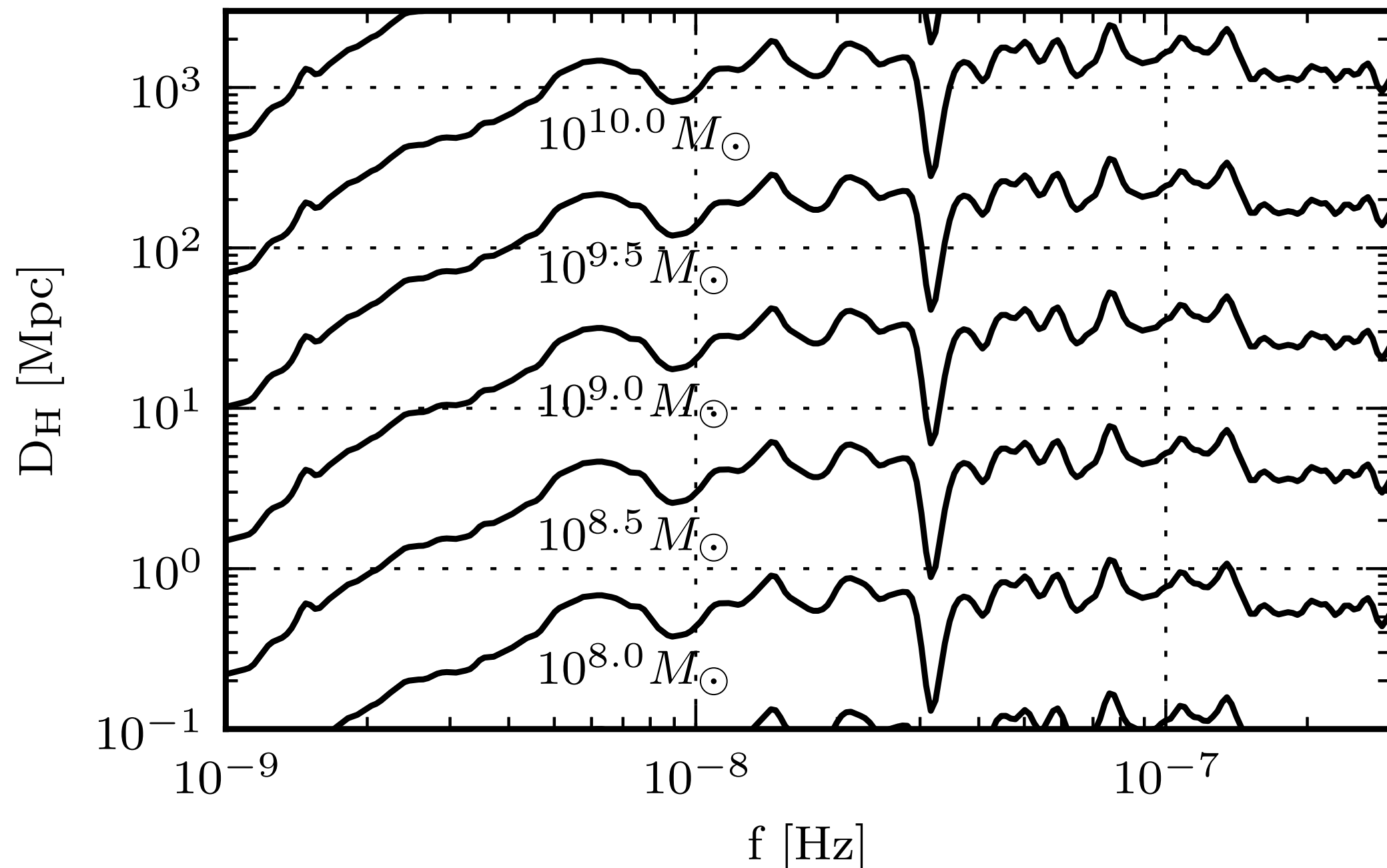
Bayesian



Horizon

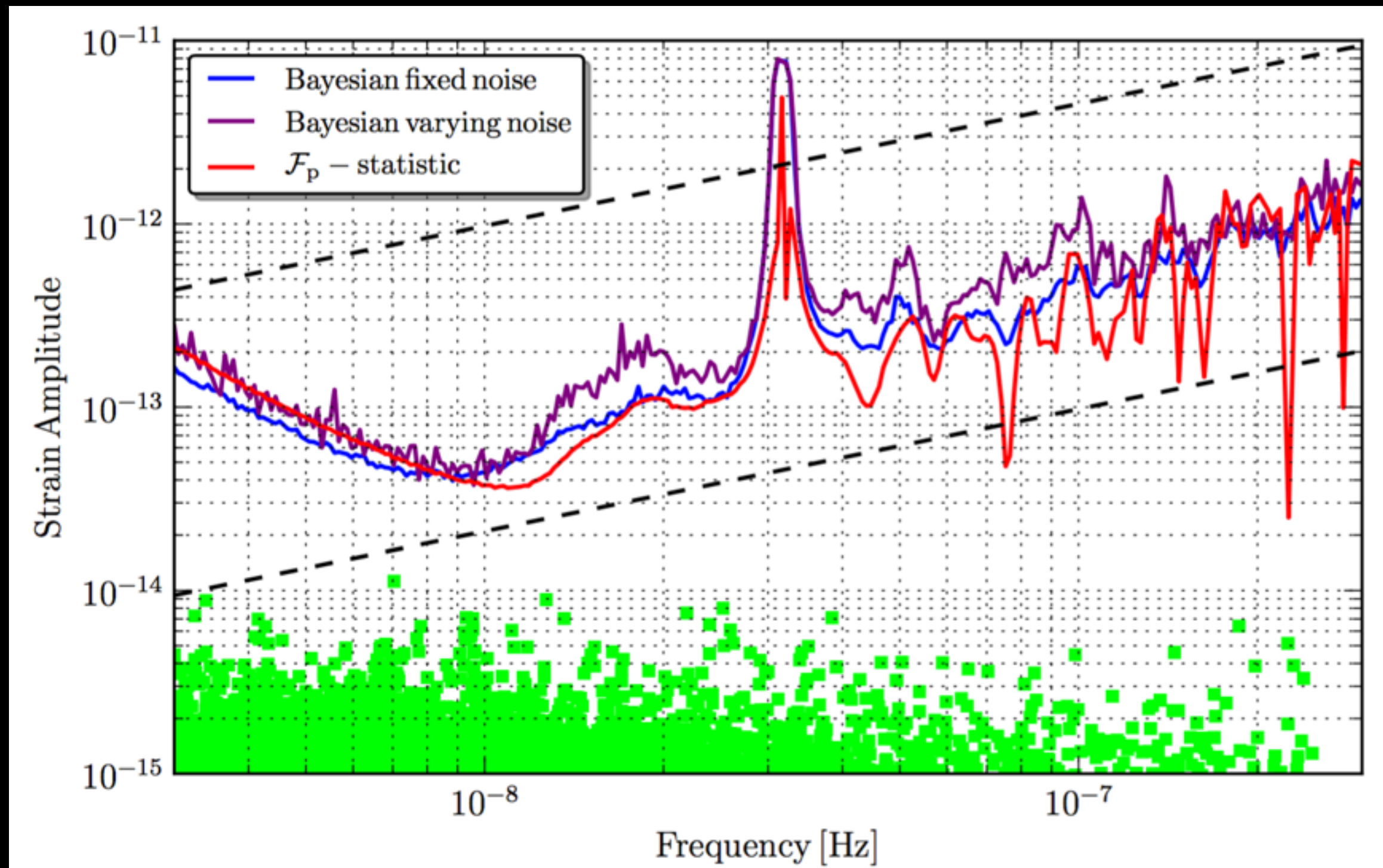
► Invert amplitude

$$\mathcal{A} = 2 \frac{\mathcal{M}_c^{5/3}}{D_L} (\pi f)^{2/3}$$



Results from NANOGrav

Arzoumanian et al. NANOGrav (2014)



Stochastic background

DA stochastic background

► Likelihood:

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

► Stochastic background shape: power-law

► Parametrization of the correlation matrix:

$$C_{GWB} = \zeta_{\alpha\beta} A^2 \left(\frac{1yr^{-1}}{f_L} \right)^{\gamma-1} \left[\Gamma(1-\gamma) \sin \frac{\pi\gamma}{2} (f_L \tau_{ij})^{\gamma-1} - \sum_{n=0}^{\infty} \frac{(f_L \tau_{ij})^{2n}}{(2n)!(2n+1-\gamma)} \right]$$
$$\zeta_{\alpha\beta} = \frac{3}{2} y \ln y - \frac{1}{4} y + \frac{1}{2} + \frac{1}{2} \delta_{\alpha\beta} , \quad y = \frac{1 - \cos \theta_{\alpha\beta}}{2} , \quad \tau_{ij} = 2\pi |t_i - t_j|$$

DA stochastic background

► Likelihood:

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

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► Likelihood:

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$$\zeta_{\alpha\beta} = \frac{3}{2} y \ln y - \frac{1}{4} y + \frac{1}{2} + \frac{1}{2} \delta_{\alpha\beta} , \quad y = \frac{1 - \cos \theta_{\alpha\beta}}{2} , \quad \tau_{ij} = 2\pi |t_i - t_j|$$

DA stochastic background

► Likelihood:

$$p(\vec{\delta t}|\vec{\theta}) = \frac{1}{\sqrt{(2\pi)^{n-m} \det(G^T C G)}} \times \exp \left(-\frac{1}{2} \left(\vec{\delta t} - \vec{h} \right)^T G (G^T C G)^{-1} G^T \left(\vec{\delta t} - \vec{h} \right) \right)$$

► Stochastic background shape: power-law

► Parametrization of the correlation matrix:

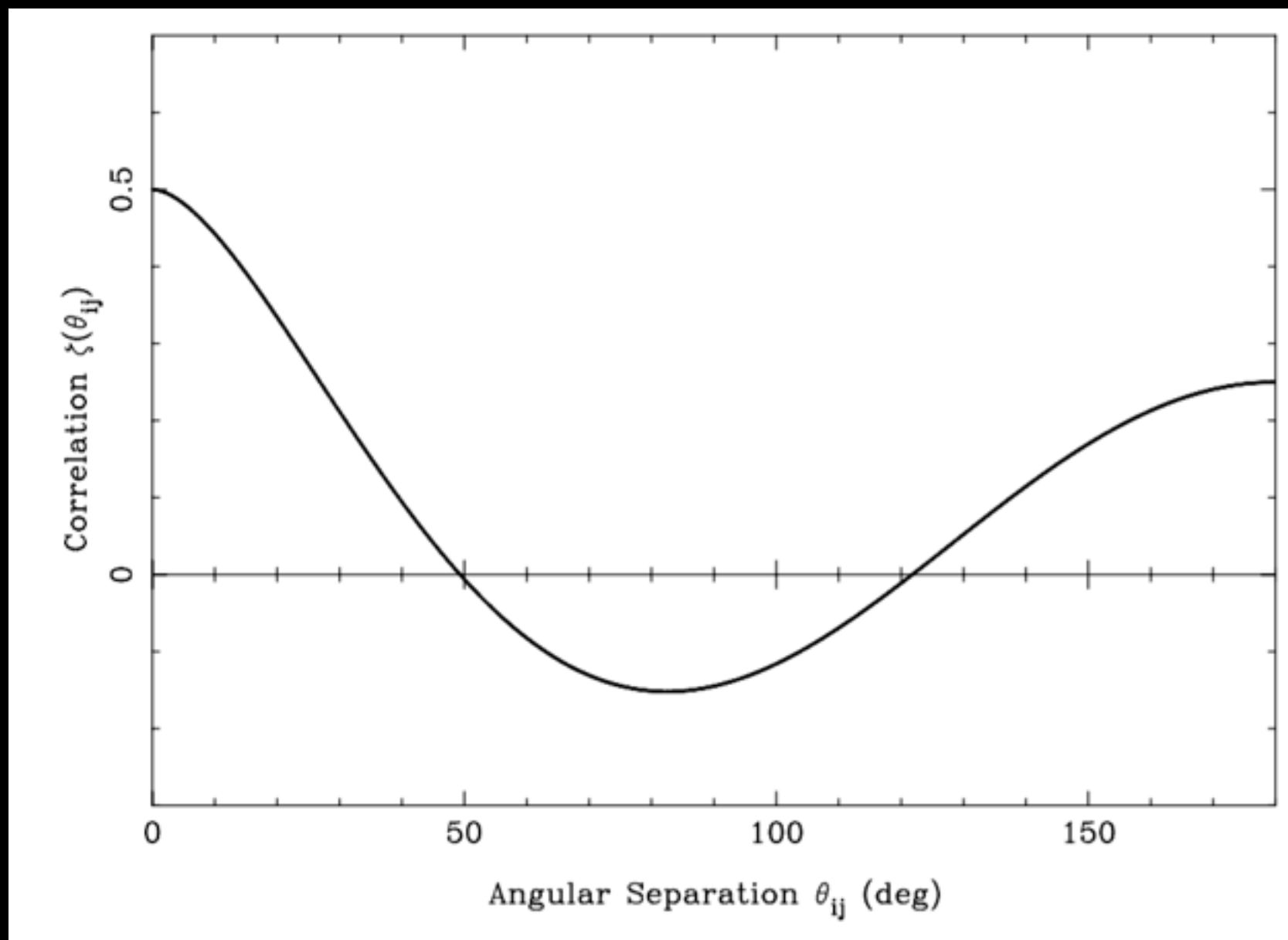
$$C_{GWB} = \zeta_{\alpha\beta} A^2 \left(\frac{1yr^{-1}}{f_L} \right)^{\gamma-1} \left[\Gamma(1-\gamma) \sin \frac{\pi\gamma}{2} (f_L \tau_{ij})^{\gamma-1} - \sum_{n=0}^{\infty} \frac{(f_L \tau_{ij})^{2n}}{(2n)!(2n+1-\gamma)} \right]$$

$$\zeta_{\alpha\beta} = \frac{3}{2} y \ln y - \frac{1}{4} y + \frac{1}{2} + \frac{1}{2} \delta_{\alpha\beta}, \quad y = \frac{1 - \cos \theta_{\alpha\beta}}{2}, \quad \tau_{ij} = 2\pi |t_i - t_j|$$

Hellings Downs curve

Hellings Downs curve

- Overlap reduction function: expected correlation in pulsar timing residuals due to an isotropic stochastic GW background



Search for stochastic background

- ▶ Parameterization of C and inverting C is time consuming because its a matrix $n \times n$, with n the total number of measurements.
- ▶ Several methods:
 - Bayesian / Frequentist
 - Fixed noise / varying noise
 - Fixed slope / varying slope
 - Various samplers

Search for stochastic background

► Bayesian:

- Use the likelihood previously define
- Sampling algorithm:
 - MultiNest [EPTA]
 - parallel tempering MCMC [Ellis]
- Inputs: priors
- Results: posterior distribution for:
 - amplitude and slope of the background
 - noises parameters for individual pulsars
 - common noises

Search for stochastic background

► Bayesian:

Lentati et al. EPTA (2015)

• Prior on parameters

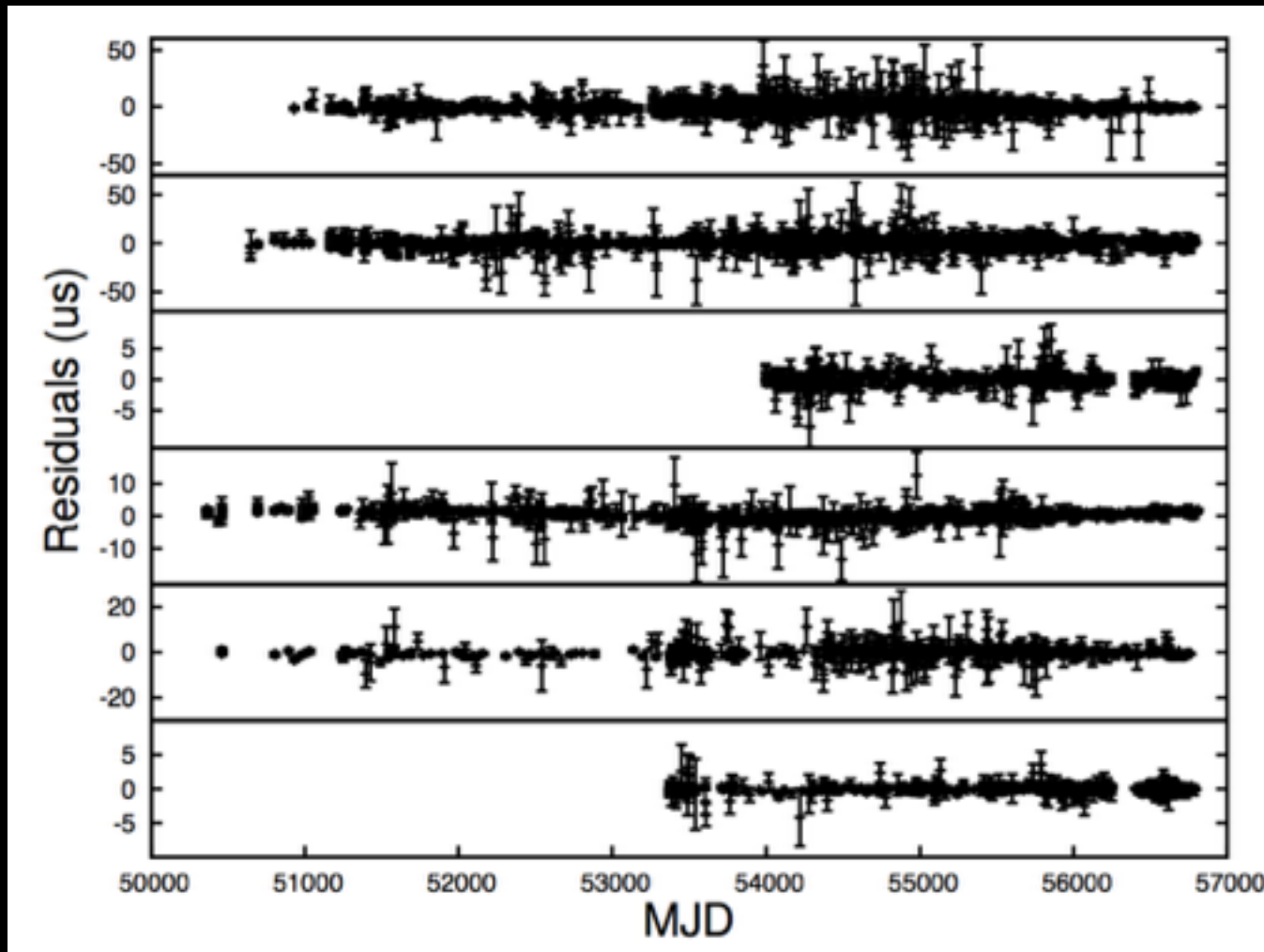
Parameter	Description	Prior range	
White noise α	Global EFAC	uniform in $[0.5, 1.5]$	1 parameter per pulsar (total 6)
Spin-noise A_{SN} γ_{SN}	Spin-noise power law amplitude Spin-noise power law spectral index	uniform in $[10^{-20}, 10^{-10}]$ uniform in $[0, 7]$	1 parameter per pulsar (total 6) 1 parameter per pulsar (total 6)
DM variations A_{DM} γ_{DM}	DM variations power law amplitude DM variations power law spectral index	uniform in $[10^{-20}, 10^{-10}]$ uniform in $[0, 7]$	1 parameter per pulsar (total 6) 1 parameter per pulsar (total 6)
Common noise A_{CN} γ_{CN} A_{clk} γ_{clk} A_{eph} γ_{eph}	Uncorrelated common noise power law amplitude Uncorrelated common noise power law spectral index Clock error power law amplitude Clock error power law spectral index Solar System ephemeris error power law amplitude Solar System ephemeris error power law spectral index	uniform in $[10^{-20}, 10^{-10}]$ uniform in $[0, 7]$ uniform in $[10^{-20}, 10^{-10}]$ uniform in $[0, 7]$ uniform in $[10^{-20}, 10^{-10}]$ uniform in $[0, 7]$	1 parameter for the array 1 parameter for the array 1 parameter for the array 1 parameter for the array 3 parameters for the array (x, y, z) 3 parameters for the array (x, y, z)
Stochastic GWB A γ ρ_i	GWB power law amplitude GWB power law spectral index GWB power spectrum coefficient at frequency i/T	uniform in $[10^{-20}, 10^{-10}]$ uniform in $[0, 7]$ uniform in $[10^{-20}, 10^0]$	1 parameter for the array 1 parameter for the array 1 parameter for the array per frequency in unparameterised GWB power spectrum model (total 20)
Stochastic background angular correlation function $c_{1...4}$ Γ_{IJ}	Chebyshev polynomial coefficient Correlation coefficient between pulsars (I,J)	uniform in $[-1, 1]$ uniform in $[-1, 1]$	see Eq. (36) 1 parameter for the array per unique pulsar pair (total 15)

Search for stochastic background

► Example: EPTA

Lentati et al. EPTA (2015)

• data

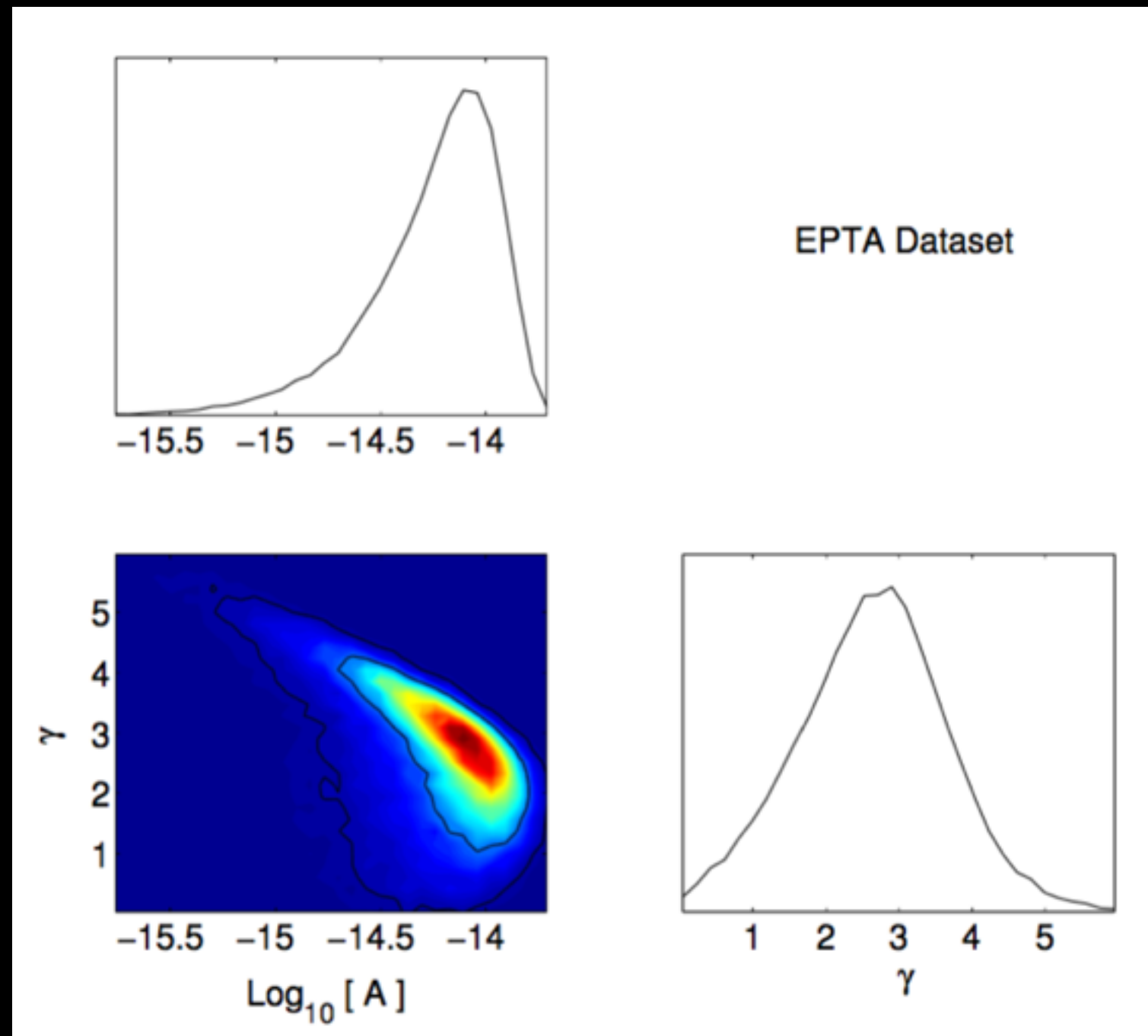
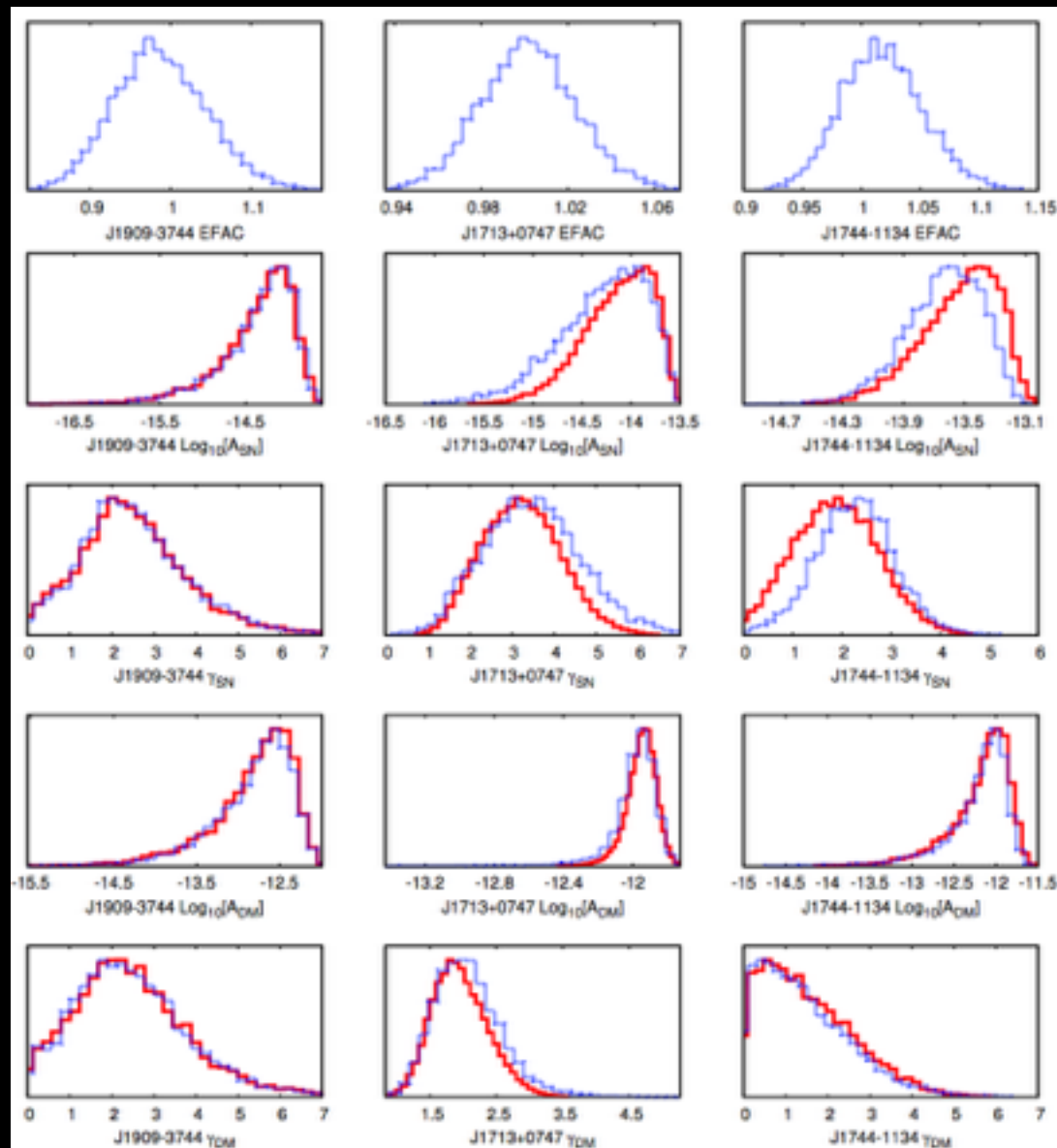


Pulsar	J0613–0200	J1012+5307	J1600–3053	J1713+0747	J1744–1134	J1909–3744
Dataspan (yr)	16.05	16.83	7.66	17.66	17.25	9.38
$N_{\text{sys}}^{\text{a}}$	14	15	4	14	9	3
$\sigma(\mu\text{s})^{\text{b}}$	1.691	1.610	0.563	0.679	0.801	0.131
$\text{Log}_{10} A_{\text{SN}}$	-13.58 ± 0.40 (-13.41)	-13.05 ± 0.09 (-13.04)	-13.71 ± 0.54 (-13.42)	-14.31 ± 0.46 (-14.20)	-13.63 ± 0.27 (-13.60)	-14.22 ± 0.42 (-13.98)
γ_{SN}	2.50 ± 0.99 (2.09)	1.56 ± 0.37 (1.56)	1.91 ± 1.05 (1.38)	3.50 ± 1.16 (3.51)	2.21 ± 0.82 (2.16)	2.23 ± 0.89 (2.17)
$\text{Log}_{10} A_{\text{DM}}$	-11.61 ± 0.12 (-11.57)	-12.25 ± 0.47 (-11.92)	-11.75 ± 0.39 (-11.67)	-11.97 ± 0.14 (-11.90)	-12.19 ± 0.38 (-11.93)	-12.76 ± 0.53 (-12.51)
γ_{DM}	1.36 ± 0.48 (1.11)	1.26 ± 0.97 (0.27)	1.64 ± 0.80 (1.46)	2.03 ± 0.55 (1.82)	1.41 ± 1.09 (0.36)	2.23 ± 1.07 (2.16)
Global EFAC	1.01 ± 0.02 (1.01)	0.98 ± 0.02 (0.98)	1.03 ± 0.04 (1.03)	1.00 ± 0.02 (1.00)	1.01 ± 0.03 (1.00)	1.02 ± 0.04 (1.01)
95% upper limit ^c	9.7×10^{-15}	8.3×10^{-15}	2.1×10^{-14}	4.4×10^{-15}	7.0×10^{-15}	5.2×10^{-15}

Search for stochastic background

► Example: EPTA

Lentati et al. EPTA (2015)

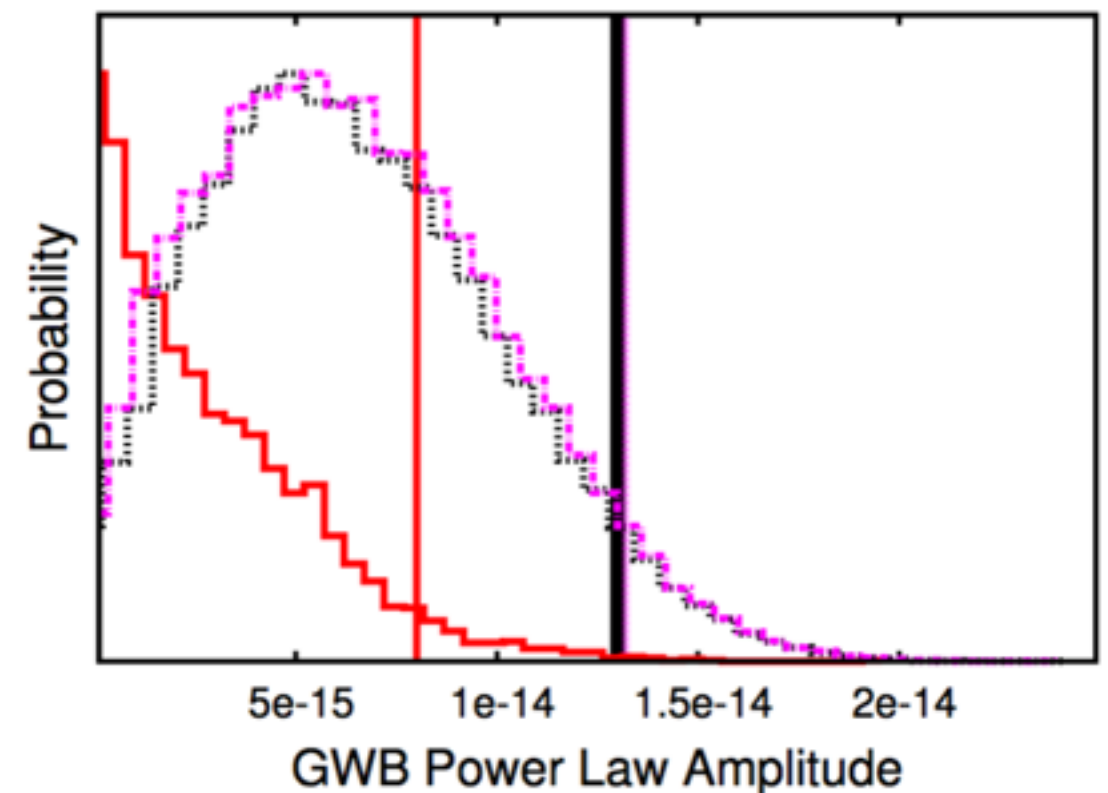
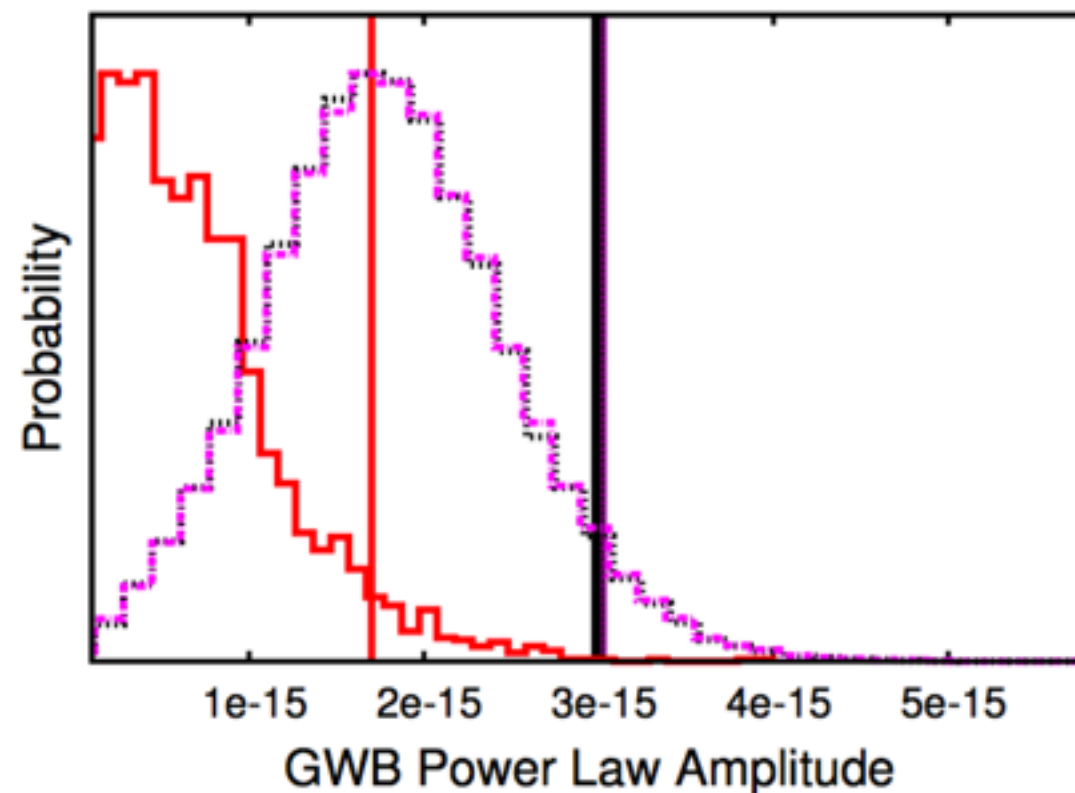


Search for stochastic background

► Example: EPTA

Lentati et al. EPTA (2015)

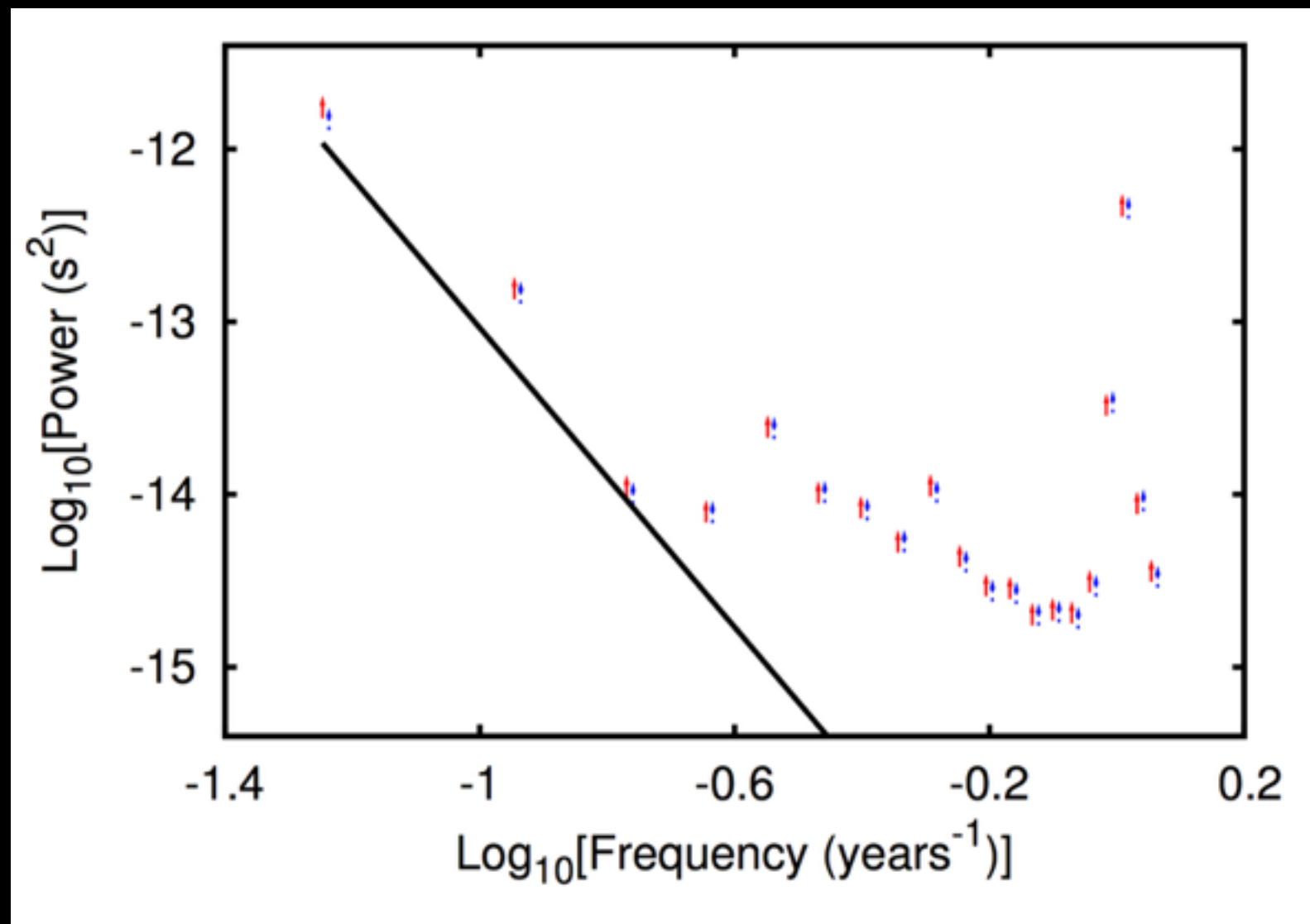
Model	95% upper limit ($\times 10^{-15}$)
Bayesian Analysis	
Fixed Noise - Fixed Spectral Index	1.7
Varying Noise - Fixed Spectral Index	3.0
Additional Common Signals - Fixed Spectral Index	3.0
Fixed Noise - Varying Spectral Index	8.0
Varying Noise - Varying Spectral Index	13
Additional Common Signals - Varying Spectral Index	13



Others bayesian methods

- ▶ Measure power in frequency bins [Lentati et al.]
- ▶ Unparameterised power spectrum analysis for a correlated Gravitational Wave Background

95% upper limits from an unparameterised power spectrum analysis for a correlated GWB (red points), and uncorrelated common red noise process (blue points) for the 6 pulsar



DA stochastic background

- ▶ Example of frequentist method used: *Optimal statistic*
 - weak signal maximum likelihood for GWB spectral amplitude (Anholm et al. 2009; Siemens et al. 2013; Chamberlin et al. 2014)
 - The statistic is:

$$\hat{A}^2 = \frac{\sum_{IJ} \delta \mathbf{t}_I^T \mathbf{P}_I^{-1} \tilde{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \delta \mathbf{t}_J}{\sum_{IJ} \text{tr} \left[\mathbf{P}_I^{-1} \tilde{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \tilde{\mathbf{S}}_{JI} \right]},$$

- with:
 - autocovariance of the post-fit residuals $\mathbf{P}_I = \langle \delta \mathbf{t}_I \delta \mathbf{t}_I^T \rangle$
 - signal term $A^2 \tilde{\mathbf{S}}_{IJ} = \langle \delta \mathbf{t}_I \delta \mathbf{t}_J^T \rangle = \mathbf{S}_{IJ}$

DA stochastic background

- ▶ Example of frequentist method used: *Optimal statistic*
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- with:
 - autocovariance of the post-fit residuals $\mathbf{P}_I = \langle \delta \mathbf{t}_I \delta \mathbf{t}_I^T \rangle$
 - signal term $A^2 \tilde{\mathbf{S}}_{IJ} = \langle \delta \mathbf{t}_I \delta \mathbf{t}_J^T \rangle = \mathbf{S}_{IJ}$

DA stochastic background

► Example of frequentist method used: *Optimal statistic*

- SNR is:
$$\rho = \frac{\hat{A}^2}{\sigma_0} = \frac{\sum_{IJ} \delta \mathbf{t}_I^T \mathbf{P}_I^{-1} \tilde{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \delta \mathbf{t}_J}{\left(\sum_{IJ} \text{tr} \left[\mathbf{P}_I^{-1} \tilde{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \tilde{\mathbf{S}}_{JI} \right] \right)^{1/2}}$$

measures how likely it is that we have found a cross-correlated signal in our data rather than an uncorrelated signal

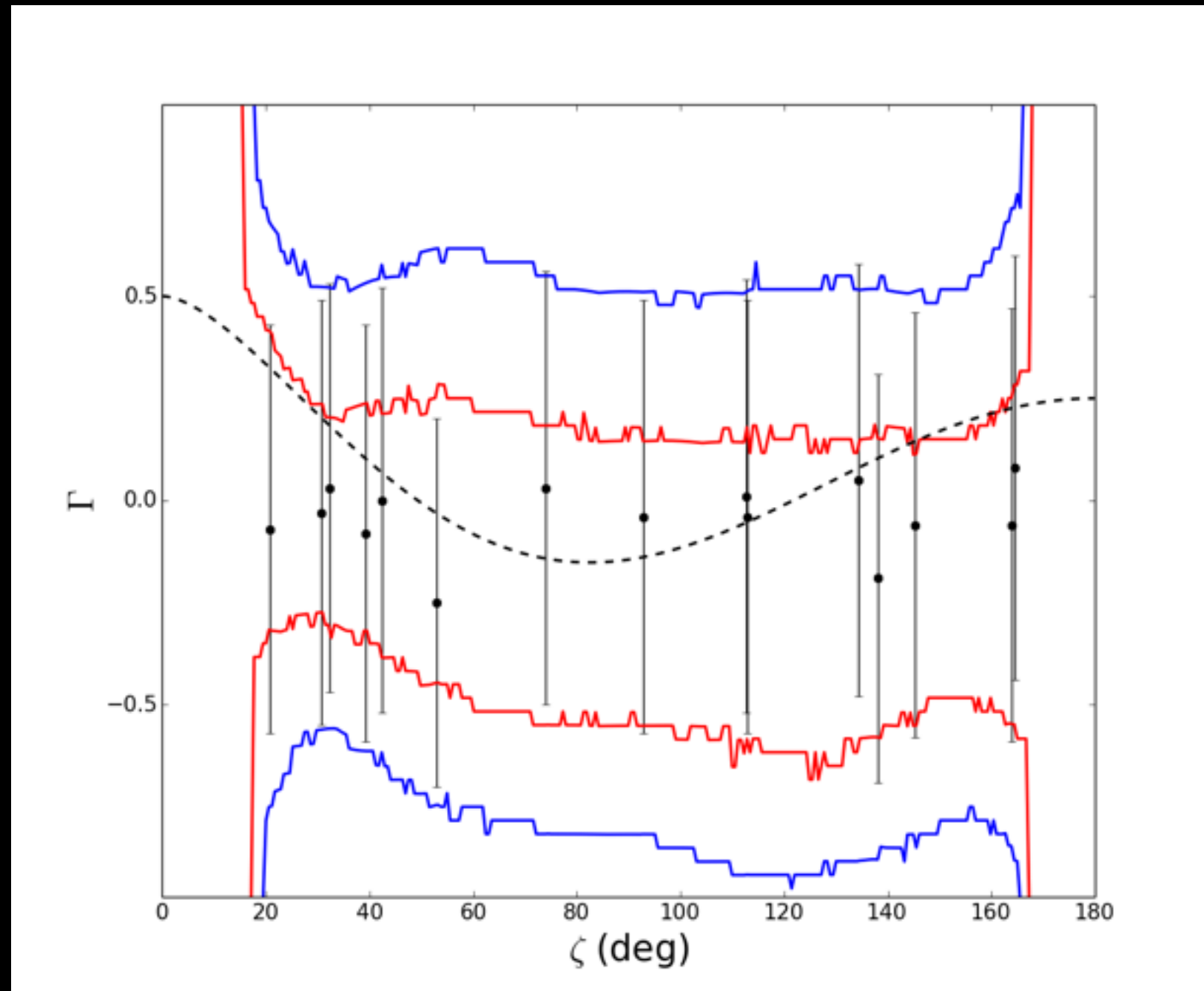
- Measurement of cross-power values
$$\chi_{IJ} = \frac{\delta \mathbf{t}_I^T \mathbf{P}_I^{-1} \hat{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \delta \mathbf{t}_J}{\text{tr} \left[\mathbf{P}_I^{-1} \hat{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \hat{\mathbf{S}}_{JI} \right]}$$

with $\mathbf{S}_{IJ} = A^2 \zeta_{IJ} \hat{\mathbf{S}}_{IJ}$ and error $\sigma_{0,IJ} = \left(\text{tr} \left[\mathbf{P}_I^{-1} \hat{\mathbf{S}}_{IJ} \mathbf{P}_J^{-1} \hat{\mathbf{S}}_{JI} \right] \right)^{-1/2}$

=> high SNR limit: cross-power values = Hellings Downs curve

Results

► Results of optimal-statistic on EPTA data

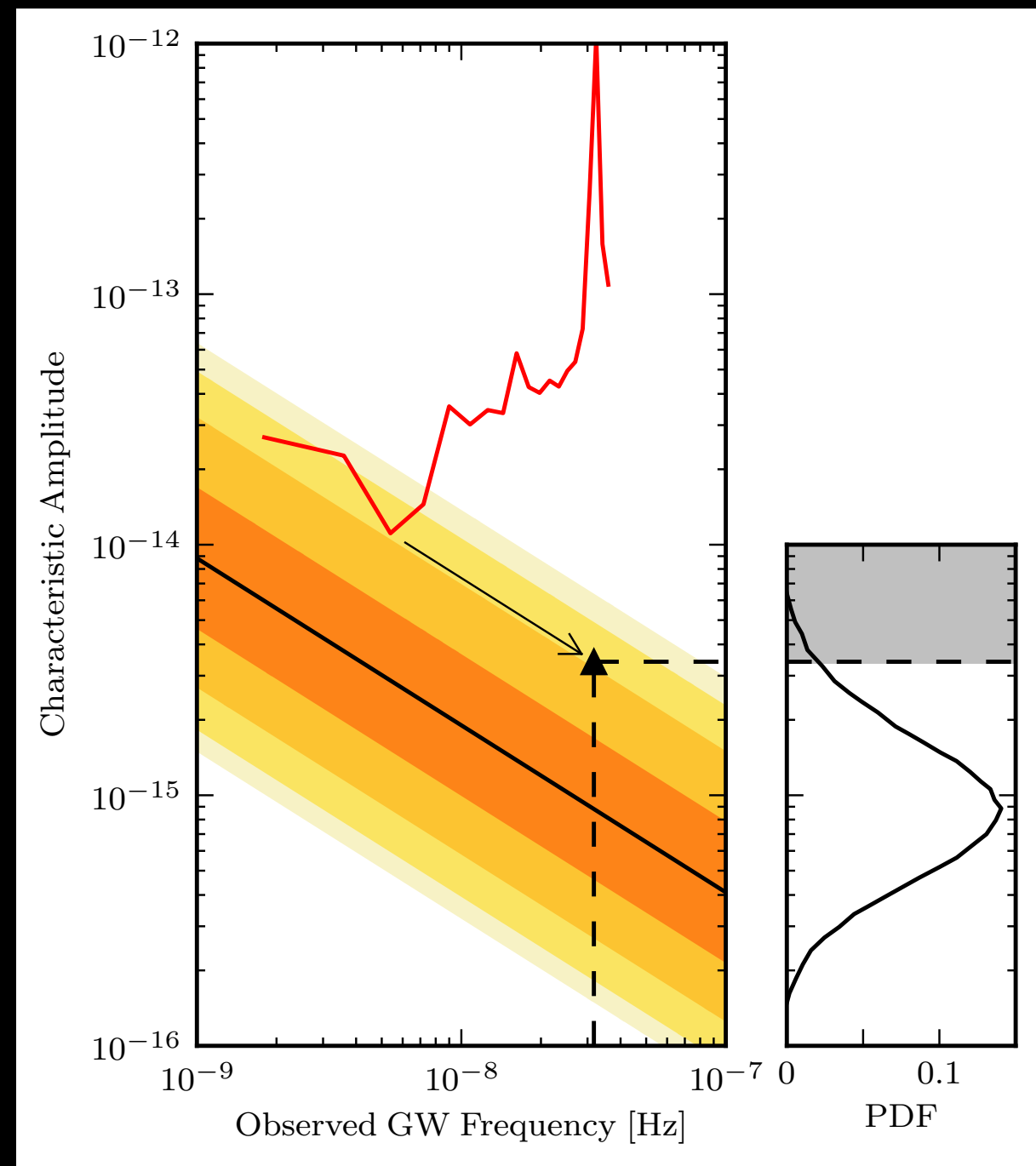
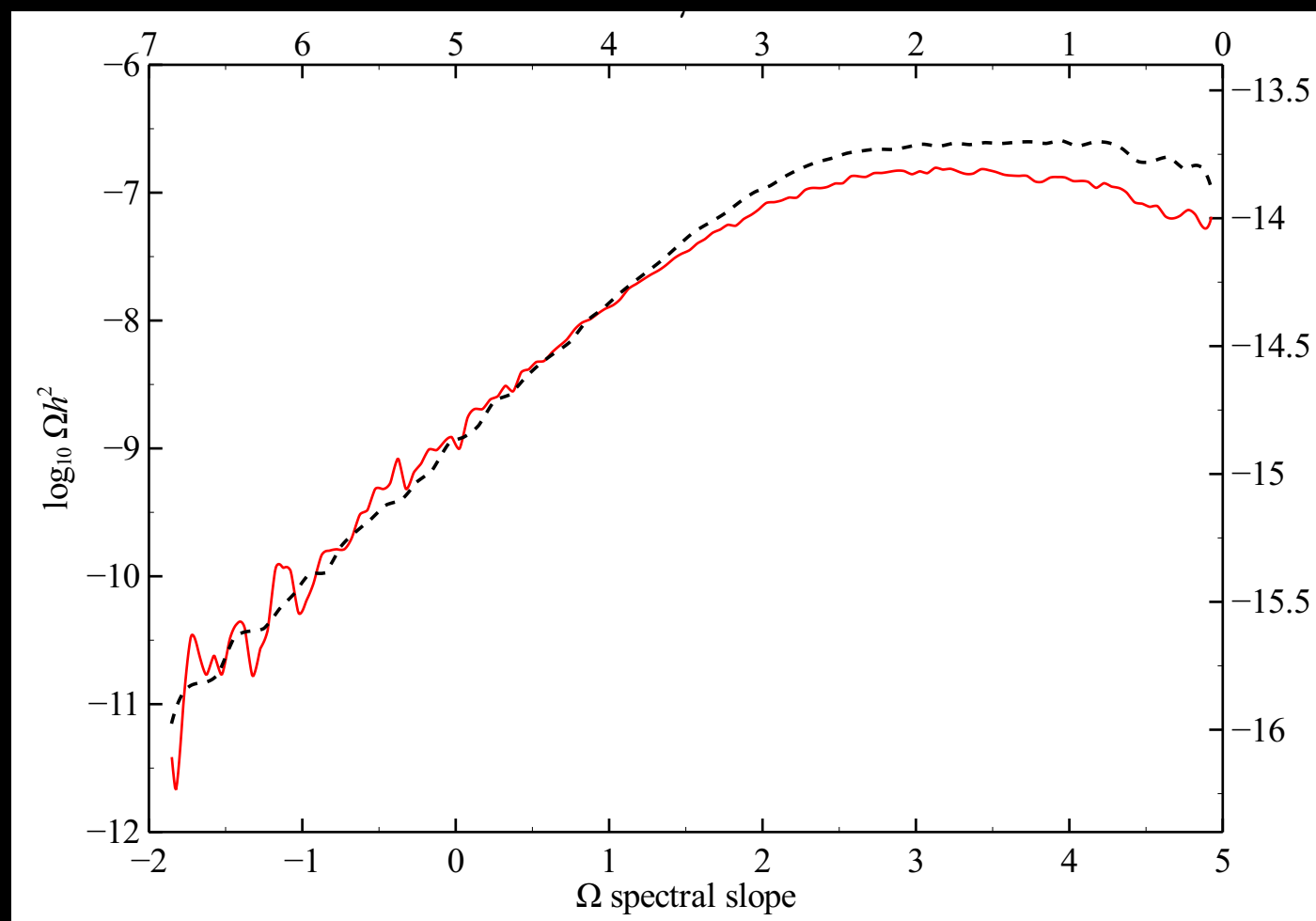


Lentati et al. EPTA (2015)

Upper limit result

► EPTA data

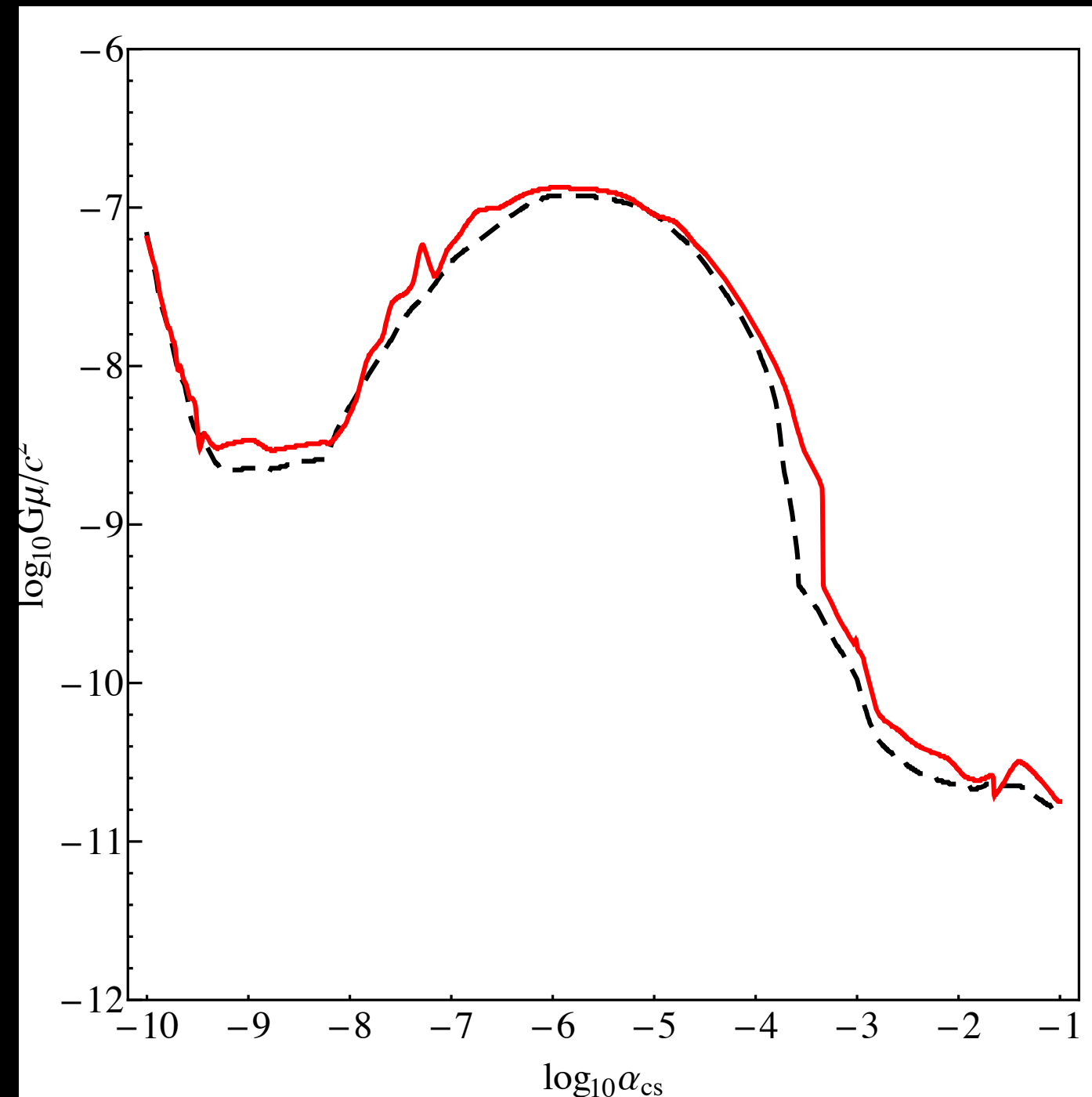
Lentati et al. EPTA (2015)



Upper limit on cosmic strings

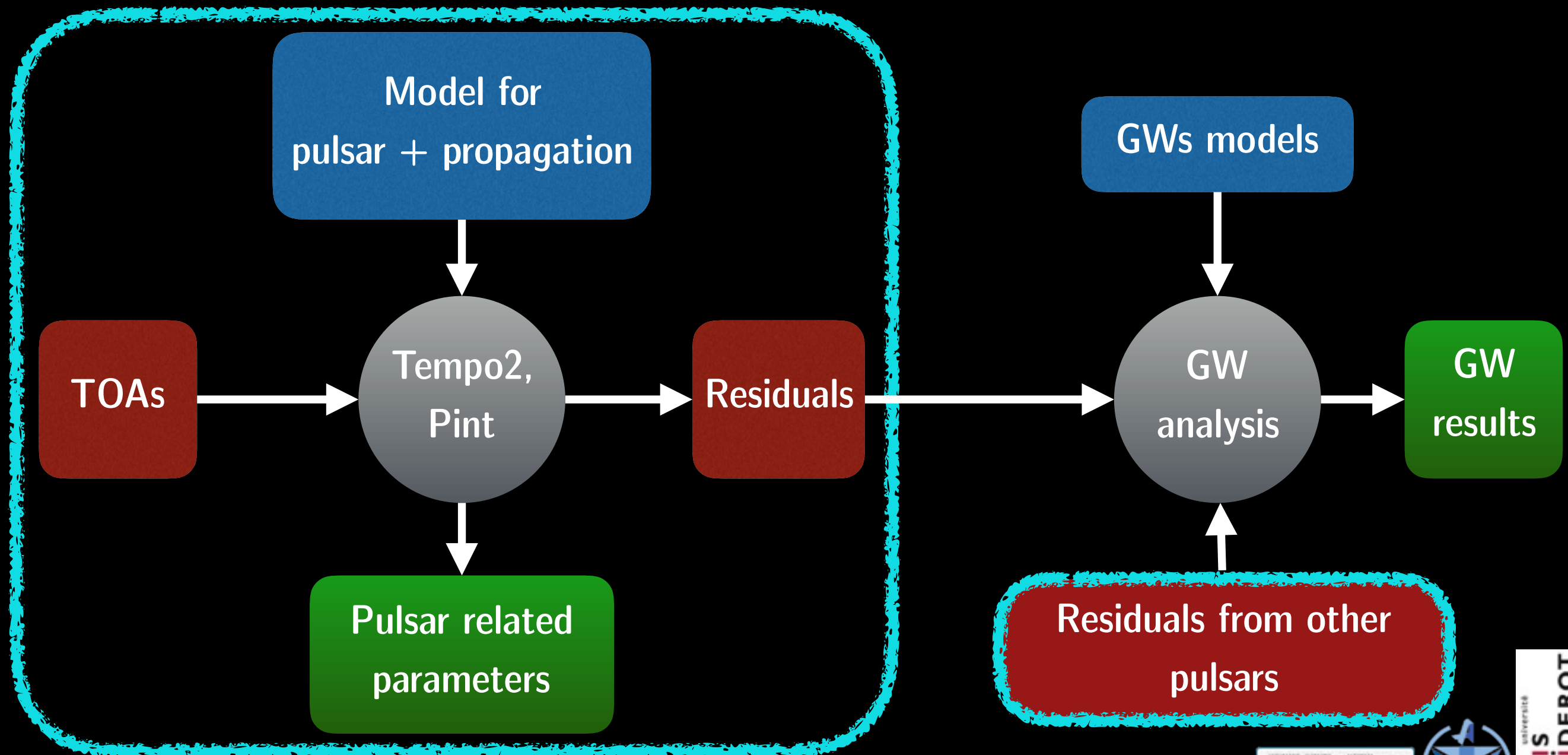
Lentati et al. EPTA (2015)

- ▶ Background from cosmic string network.
- ▶ Parameters
 - string tension $G\mu/c^2$,
 - α_{cs} : the birth-scale of loops relative to the horizon.
 - ...



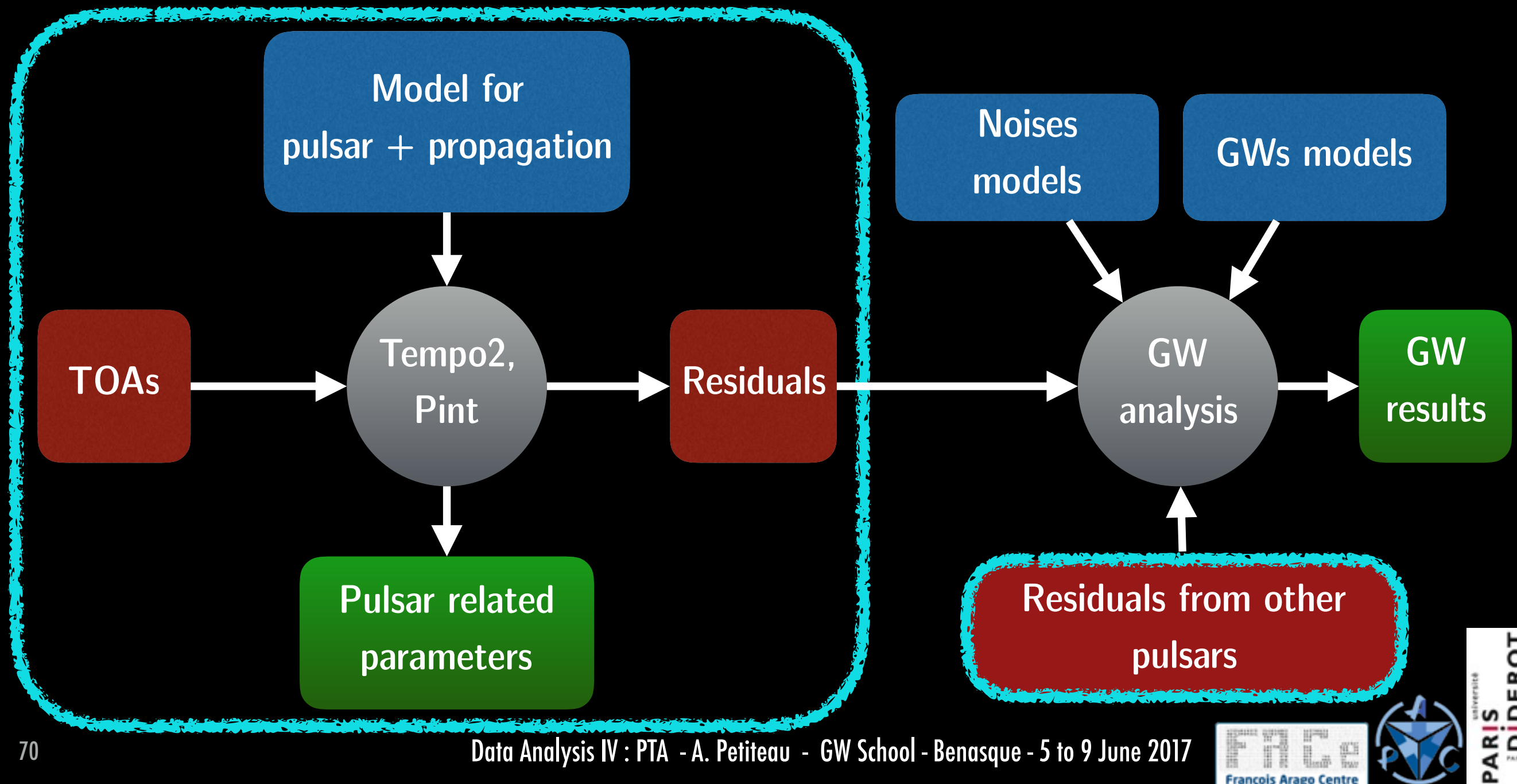
Global analysis

► Separated approach ...



Global analysis

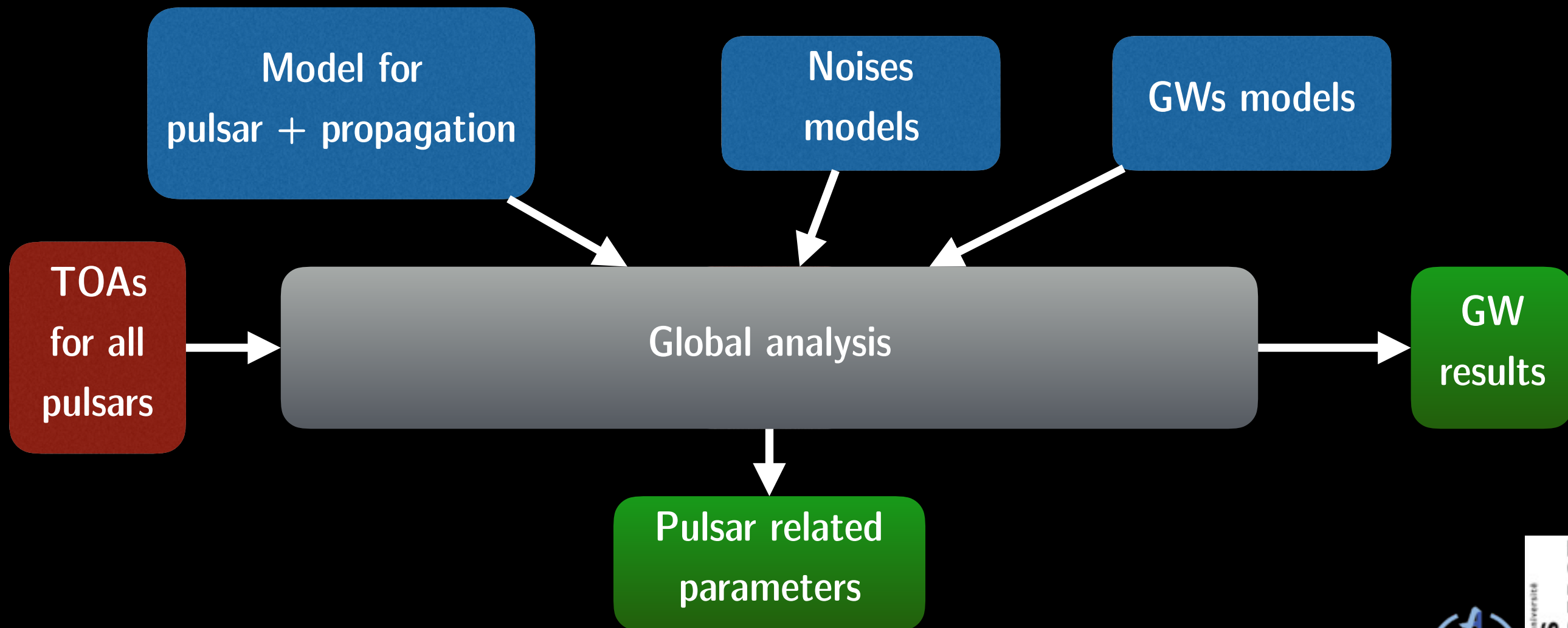
► Separated approach including noises



Global analysis

► Global analysis including:

- Pulsar + propagation parameters
- Noises
- GWs: continuous wave sources + backgrounds



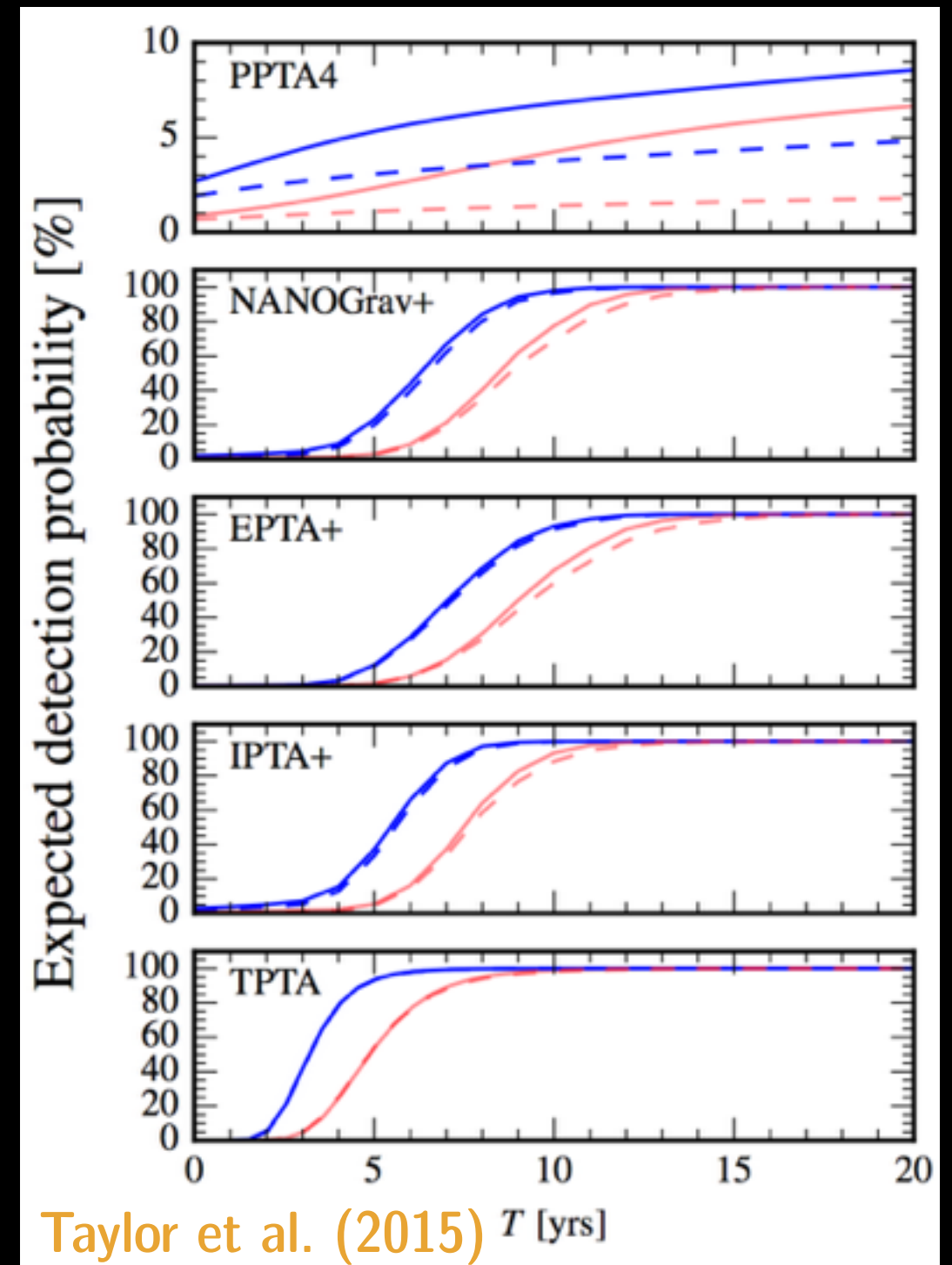
Global analysis

- ▶ Global analysis including:
 - Pulsar + propagation parameters
 - Noises
 - GWs: continuous wave sources + backgrounds
- ▶ Could also include the pulse template matching
- ▶ Work in progress

Future

► More data:

- Continue to observe the pulsar
- Group all data in IPTA: EPTA, NANOGrav, PPTA
- Use more pulsars
- New instruments: SKA and it's precursor



Nancay RT



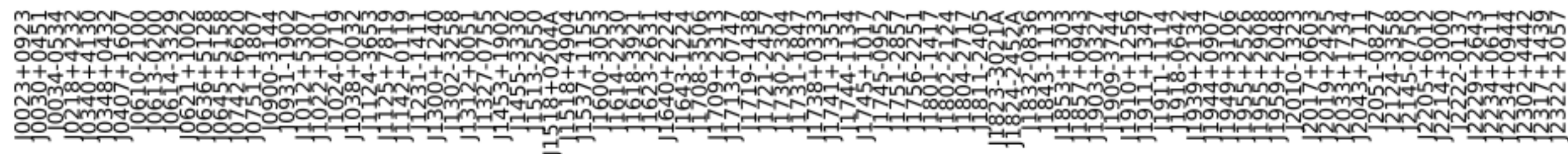
RMS (us)

100

10

1

0.1



0.0

0.4

0.8

1.2

1.6

2.0

2.4

2.8

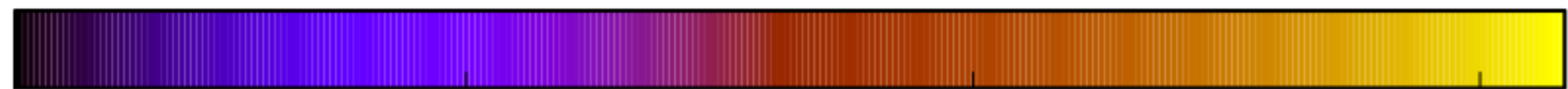
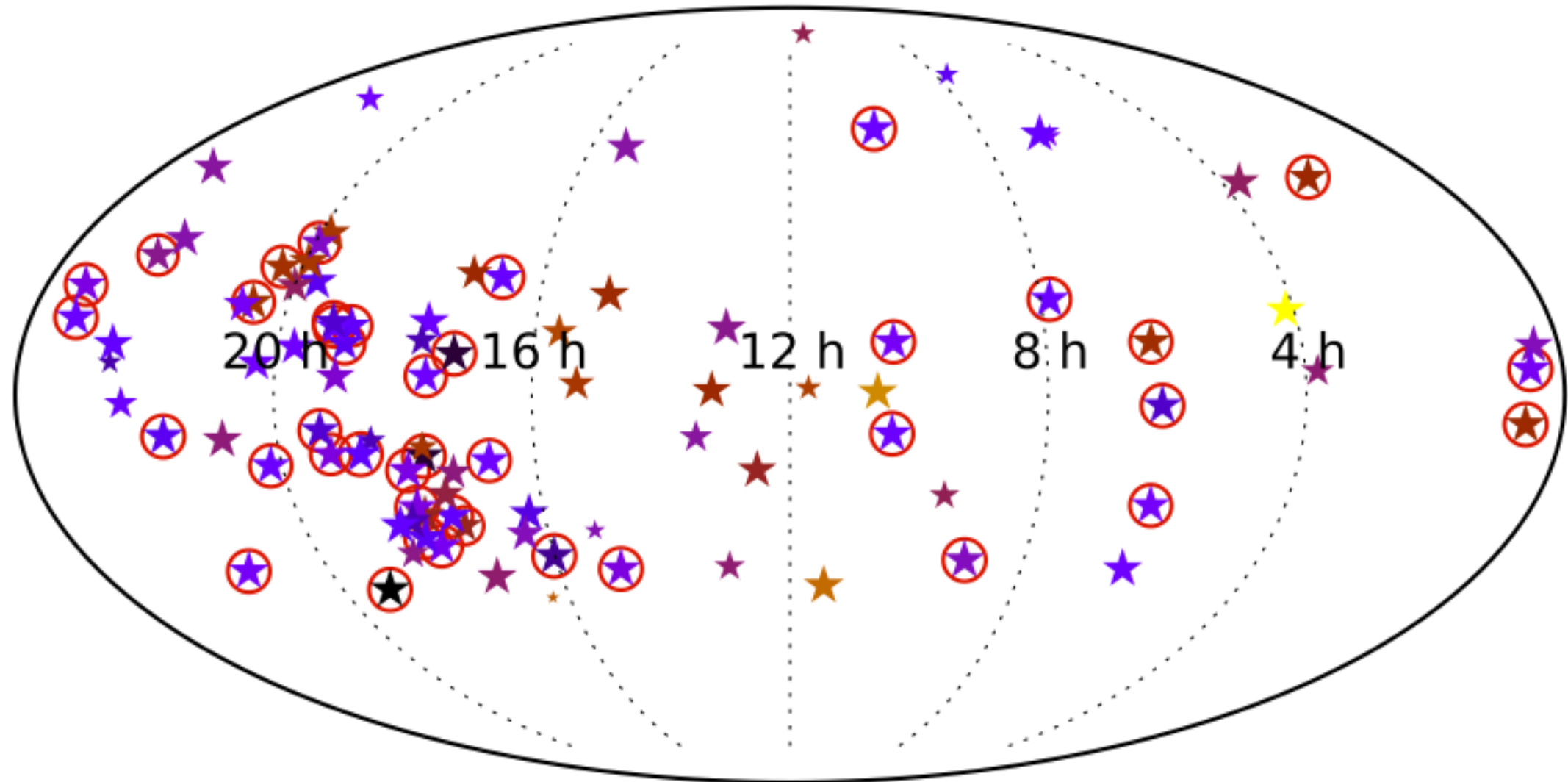
3.2

3.6

Observation time (years)

Future

► M



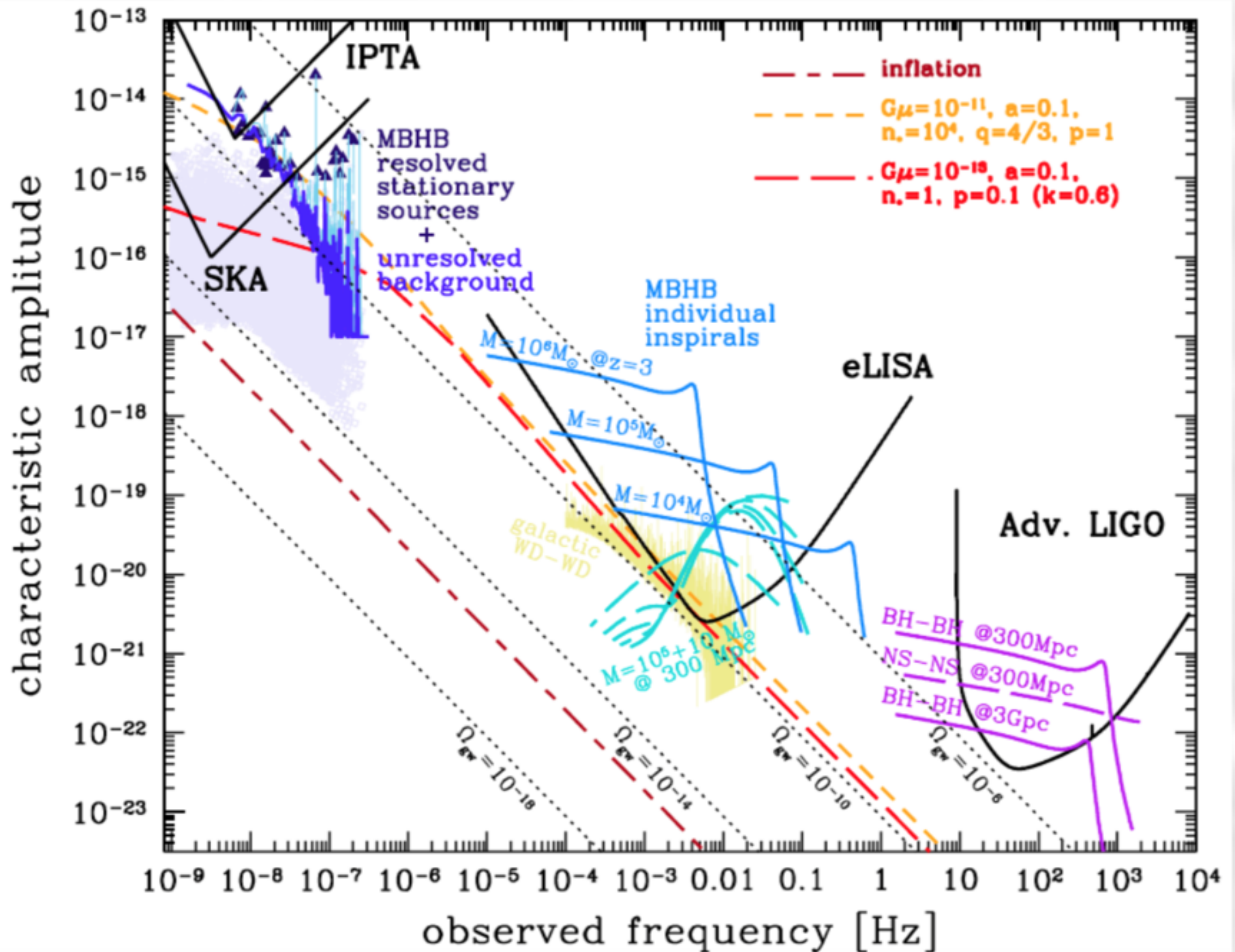
10⁰ 10¹ 10²
colorscale = RMS (us) , size = duration

Future

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Thank you