

Modeling and Control of Renewable Resources

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Benasque, 25.08.2017

Introduction: Structured Population Models

u population density

Introduction: Structured Population Models

$u = u(t)$ population density
 t time

Introduction: Structured Population Models

$u = u(t, x)$ population density
 t time
 x age

Introduction: Structured Population Models

$u = u(t, x)$ population density
 t time
 x age

$$\partial_t u + \partial_x u = 0$$

Introduction: Structured Population Models

$u = u(t, x)$ population density

t time

x biological age/size/(trait)

$$\partial_t u + \partial_x ([\text{growth/aging}] u) = 0$$

Introduction: Structured Population Models

$u = u(t, x)$ population density

t time

x biological age/size/(trait)

$$\partial_t u + \partial_x (g(t, x, \int u) u) = 0$$

Introduction: Structured Population Models

$u = u(t, x)$ population density

t time

x biological age/size/(trait)

$$\partial_t u + \partial_x (g(t, x, \int u) u) = [\text{death}]$$

Introduction: Structured Population Models

$u = u(t, x)$ population density

t time

x biological age/size/(trait)

$$\partial_t u + \partial_x (g(t, x, \int u) u) = -d(t, x, u, \int u)$$

Introduction: Structured Population Models

$u = u(t, x)$ population density

t time

x biological age/size/(trait)

$$\begin{aligned}\partial_t u + \partial_x (g(t, x, \int u) u) &= -d(t, x, u, \int u) \\ u(t, 0) &= [\text{birth}]\end{aligned}$$

Introduction: Structured Population Models

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t time

x biological age/size/(trait)

$$\begin{aligned}\partial_t u + \partial_x (g(t, x, \int u) u) &= -d(t, x, u, \int u) \\ u(t, 0) &= b(t, \int u)\end{aligned}$$

Introduction: Structured Population Models

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$$\partial_t u + \partial_x (g(t, x, \int u) u) = -d(t, x, u, \int u)$$

$$u(t, 0) = b(t, \int u)$$

$$u(0, x) = [\text{initial datum}]$$

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Balance Law with **Boundary**

NonLocal flow

NonLocal source

NonLocal boundary data

Introduction: Conservation Laws – Keywords

$$\partial_t u + \operatorname{div}_x f(t, x, u) = g(t, x, u)$$

$$x \in \mathbb{R}^N \quad u \in \mathbb{R}^n$$

$$N = 1, n \geq 1$$

$$N \geq 1, n = 1$$

Norm: $\|\cdot\|_{L^1}$

x regularity: $x \rightarrow u(t, x)$ L^1, L^∞, BV

t regularity: $t \rightarrow u(t)$ L^1 – Lipschitz

u_o dependence: $u_o \rightarrow u(t)$ L^1 – Lipschitz

Introduction: NonLocal Conservation Laws

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ (Chen & Christoforou: PAMS, 2007)
 - ▶ (Christoforou: JHDE, 2007)

Introduction: NonLocal Conservation Laws

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ Granular Materials
 - ▶ (Amadori & Shen: Comm.PDE, 2009)
 - ▶ (Guerra & Shen: JDE, 2014)

Introduction: NonLocal Conservation Laws

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ Granular Materials
 - ▶ Vehicular Traffic
 - ▶ (Colombo, Corli & Rosini: ZAMM, 2007)
 - ▶ (Colombo, Herty & Mercier: COCV, 2011)
 - ▶ (Dong & Tong: NHM, 2011)
 - ▶ (Blandin & Goatin: Numer.Math., 2015)

Introduction: NonLocal Conservation Laws

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ Granular Materials
 - ▶ Vehicular Traffic
 - ▶ Crowd Dynamics
 - ▶ (Colombo, Garavello & Mercier: M3AS, 2011)
 - ▶ (Colombo & Mercier: Acta Math.Sc., 2011)
 - ▶ (Piccoli & Tosin: ARMA, 2011)
 - ▶ (Hoogendoorn et al.: Physica A, 2014)
 - ▶ (Goatin & Rossi: CMS, 2017)

Introduction: NonLocal Conservation Laws

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ Granular Materials
 - ▶ Vehicular Traffic
 - ▶ Crowd Dynamics
 - ▶ Numerical Methods
 - ▶ (Betancourt, Burger, Karlsen & Tory: Nonlin., 2011)
 - ▶ (Amorim, Colombo & Teixeira: M2AN, 2015)
 - ▶ (Aggarwal, Colombo & Goatin: SINUM, 2015)

Introduction: NonLocal Conservation Laws

- ▶ NonLocal Conservation Laws:
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 - ▶ Crowd Dynamics
 - ▶ Numerical Methods
 - ▶ Degasperis–Procesi, Camassa–Holm & Ostrovsky–Hunter
 - ▶ (Gesztesy & Holden: Cambridge Studies, 2003)
 - ▶ (Holden & Xavier: CPDE, 2007)
 - ▶ (Coclite, Ridder & Risebro: Preprint, 2016)

Introduction: Structured Population

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ Granular Materials
 - ▶ Vehicular Traffic
 - ▶ Crowd Dynamics
 - ▶ Numerical Methods
 - ▶ Degasperis–Procesi, Camassa–Holm & Ostrovsky–Hunter
 - ▶ Measure Valued Conservation Laws
 - ▶ (Carrillo, Colombo, Gwiazda & Ulikowska: JDE, 2012)
 - ▶ (Gwiazda, Jamróz & Marciniak-Czochra: SIMA, 2012)
 - ▶ (Canizo, Carrillo & Cuadrado: Acta Appl.Math., 2013)
 - ▶ (Piccoli & Rossi: ARMA, 2014)
 - ▶ (Colombo, Gwiazda & Rosinska: COCV, To appear)

Introduction:

- ▶ NonLocal Conservation Laws:
 - ▶ Elastodynamics
 - ▶ Granular Materials
 - ▶ Vehicular Traffic
 - ▶ Crowd Dynamics
 - ▶ Numerical Methods
 - ▶ Degasperis–Procesi, Camassa–Holm & Ostrovsky–Hunter
 - ▶ Measure Valued Conservation Laws
- ▶ Structured Population
 - ▶ ≈ 2000 items in MathSciNet (190 books)
 - ▶ (Webb: Theory of Nonlinear Age-Dependent Population Dynamics, 1985)
 - ▶ (Diekmann & Heesterbeek: Mathematical Epidemiology of Infectious Diseases, 2000)
 - ▶ (Perthame: Transport Equations in Biology, 2008)
 - ▶ (Broom & Ríčtař: Game-Theor. Models in Biology, 2013)

Structured Population on Graphs

(in collaboration with M.Garavello)

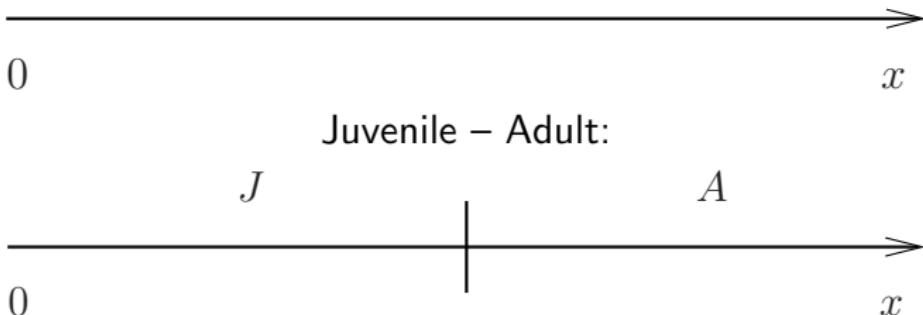
Role of the Graph

The standard setting:



Role of the Graph

The standard setting:



(Carrillo, Cuadrado & Perthame: Math.Biosci., 2007)

(Ackleh & Deng: SIAM Appl.Math., 2009)

(Ackleh & Ma: Numer.Funct.Anal.Opt., 2013)

Role of the Graph

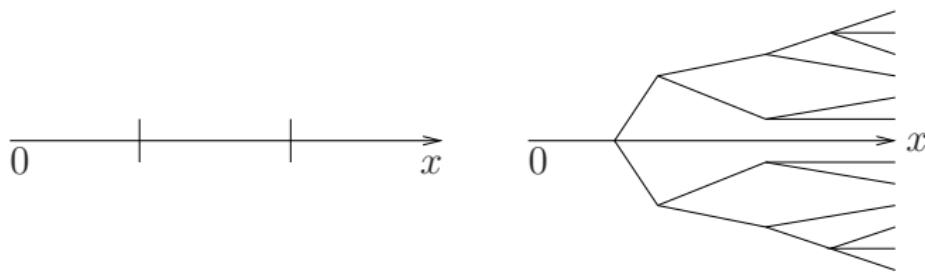
The standard setting:



Juvenile – Adult:



Etc. . .



A General Theorem

$$\begin{cases} \partial_t u_i + \partial_x (g_i(t, x) u_i) = d_i(t, x) u_i \\ g_i(t, 0) u_i(t, 0+) = \mathcal{B}_i(t, u_1(t), \dots, u_n(t)) \\ u_i(0, x) = \bar{u}_i(x) \end{cases}$$

$t \in \mathbb{R}^+$	time	g_i	growth
$x \in \mathbb{R}^+$	age	$-d_i$	death
$u_i \in \mathbb{R}^+$	density	\mathcal{B}_i	birth/change

A General Theorem

$$\begin{cases} \partial_t u_i + \partial_x (g_i(t, x) u_i) = d_i(t, x) u_i \\ g_i(t, 0) u_i(t, 0+) = \mathcal{B}_i(t, u_1(t), \dots, u_n(t)) \\ u_i(0, x) = \bar{u}_i(x) \end{cases}$$

$$\begin{aligned} \mathcal{B}_i(t, u_1, \dots, u_n) &= \alpha_i(t, u_1(\bar{x}_1-), \dots, u_n(\bar{x}_n-)) \\ &\quad + \beta_i \left(\int_{I_1} w_1(x) u_1(x) dx, \dots, \int_{I_n} w_n(x) u_n(x) dx \right) \end{aligned}$$

u_i lives on $[0, \bar{x}_i]$

u_i is fertile for $x \in I_i$

w_i fertility of u_i

α_i transmission

β_i natality

A General Theorem

$$\begin{cases} \partial_t u_i + \partial_x (g_i(t, x) u_i) = d_i(t, x) u_i \\ g_i(t, 0) u_i(t, 0+) = \mathcal{B}_i(t, u_1(t), \dots, u_n(t)) \\ u_i(0, x) = \bar{u}_i(x) \end{cases}$$

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Theorem (Colombo & Garavello: MBE, 2015)

If $g_i \in \mathbf{C}^1$, $\inf g_i > 0$, $\sup_t [\text{TV}(g_i(t)) + \text{TV}(\partial_x g_i(t))] < +\infty$
 $d_i \in (\mathbf{C}^1 \cap \mathbf{L}^\infty)$, $\sup_t \text{TV}(d_i(t, \cdot)) < +\infty$
 $\alpha_i, \beta_i, w_i \in \mathbf{C}^{0,1}$, $\alpha_i(t, 0) = 0$, $\beta_i(0) = 0$, $\inf_x w_i > 0$

A General Theorem

$$\begin{cases} \partial_t u_i + \partial_x (g_i(t, x) u_i) = d_i(t, x) u_i \\ g_i(t, 0) u_i(t, 0+) = \mathcal{B}_i(t, u_1(t), \dots, u_n(t)) \\ u_i(0, x) = \bar{u}_i(x) \end{cases}$$

$$\mathcal{B}_i(t, u_1, \dots, u_n) = \alpha_i(t, u_1(\bar{x}_1-), \dots, u_n(\bar{x}_n-)) + \beta_i \left(\int_{I_1} w_1(x) u_1(x) dx, \dots, \int_{I_n} w_n(x) u_n(x) dx \right)$$

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 $\alpha_i, \beta_i, w_i \in \mathbf{C}^{0,1}$, $\alpha_i(t, 0) = 0$, $\beta_i(0) = 0$, $\inf_x w_i > 0$

Then: *Existence of a solution*

Uniqueness of the solution

Continuous dependence from the initial data

Stability with respect to α_i, β_i, w_i

A General Theorem

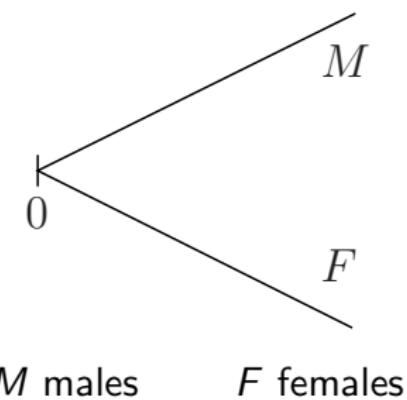
$$\begin{cases} \partial_t u_i + \partial_x (g_i(t, x) u_i) = d_i(t, x) u_i \\ g_i(t, 0) u_i(t, 0+) = \mathcal{B}_i(t, u_1(t), \dots, u_n(t)) \\ u_i(0, x) = \bar{u}_i(x) \end{cases}$$

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Theorem (Colombo & Garavello: MBE, 2015)

$$\begin{aligned} \|u'_i(t) - u''_i(t)\|_{\mathbf{L}^1} &\leq \mathcal{K}(t) \sum_{j=1}^n \left[\|\bar{u}'_j - \bar{u}''_j\|_{\mathbf{L}^1} + t \|\bar{u}'_j - \bar{u}''_j\|_{\mathbf{L}^\infty} \right] \\ &\quad + \mathcal{H}(t) \sum_{j=1}^n \left[\|\alpha'_j - \alpha''_j\|_{\mathbf{C}^0} + \|\beta'_j - \beta''_j\|_{\mathbf{C}^0} + \|w'_j - w''_j\|_{\mathbf{C}^0} \right] \end{aligned}$$

Example: Age & Sex Structured Population



(N. Keyfitz: VI Berkeley Symp. Math. Stat. Prob., 1972)

Example: Age & Sex Structured Population

$$\begin{cases} \partial_t M + \partial_a M = -\kappa \mu M \\ \partial_t F + \partial_a F = -(1 - \kappa) \mu F \\ M(t, 0) + F(t, 0) = \nu \min \left\{ \vartheta \int_{m_1}^{m_2} M(t, a) da, (1 - \vartheta) \int_{f_1}^{f_2} F(t, a) da \right\} \\ \eta M(t, 0) = (1 - \eta) F(t, 0) \end{cases}$$

η relative natality in $[0, 1]$

κ relative mortality in $[0, 1]$

ϑ coupling habits in $[0, 1]$

μ mortality in \mathbb{R}^+

ν natality in \mathbb{R}^+

Example: Age & Sex Structured Population

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$\kappa = 0$ no Male dies

$\kappa = 1$ no Female dies

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$\eta = 0$ no Female is born

$\eta = 1$ no Male is born

Example: Age & Sex Structured Population

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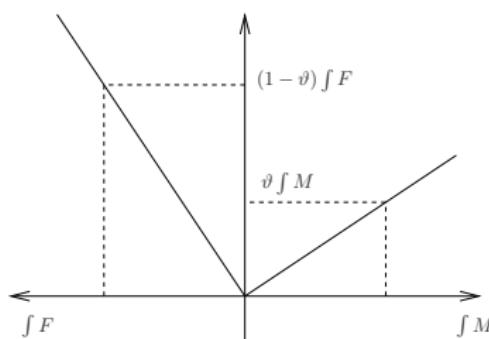
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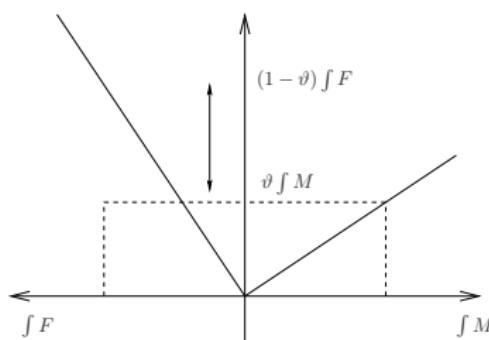
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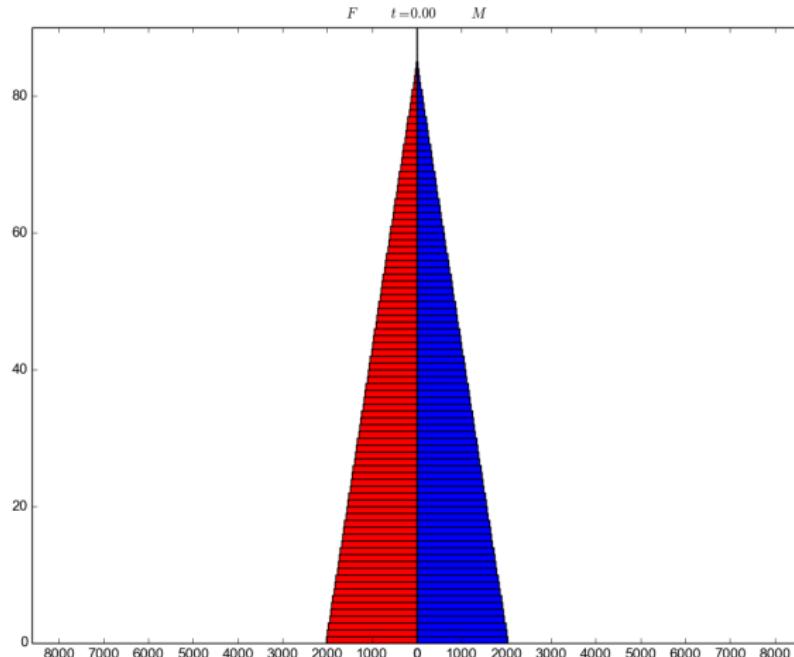


Example: Age & Sex Structured Population

$$\kappa = 0.600$$

$$\eta = 0.485$$

$$\vartheta = 0.7067$$



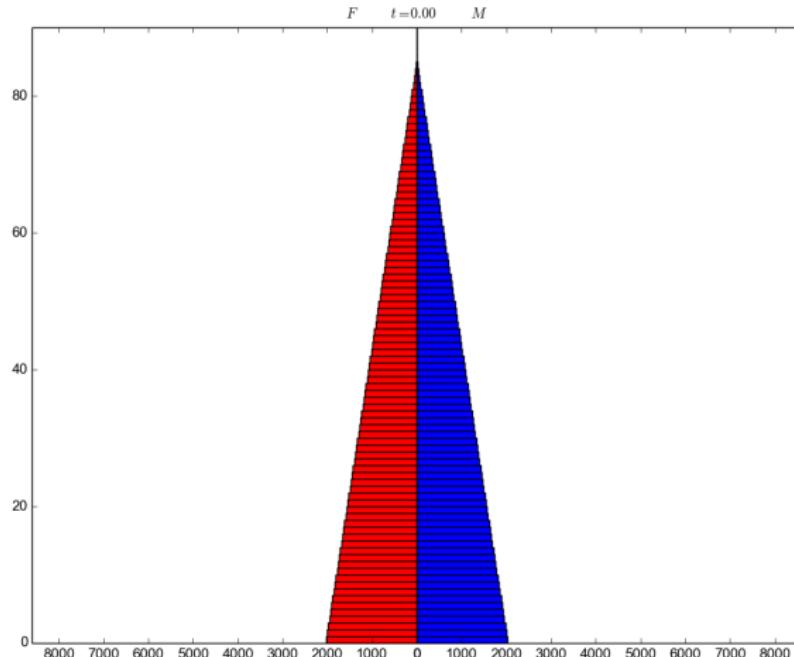
Age pyramid - “slowly” growing

Example: Age & Sex Structured Population

$$\kappa = 0.600$$

$$\eta = 0.300$$

$$\vartheta = 0.7067$$



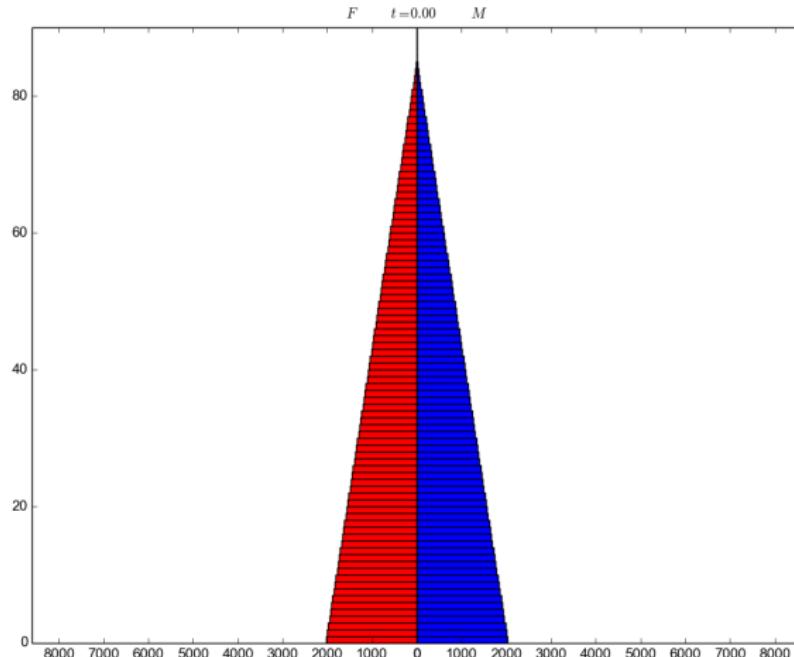
Lower $\eta \Rightarrow$ too many M are born \Rightarrow extinction

Example: Age & Sex Structured Population

$$\kappa = 0.400$$

$$\eta = 0.485$$

$$\vartheta = 0.7067$$



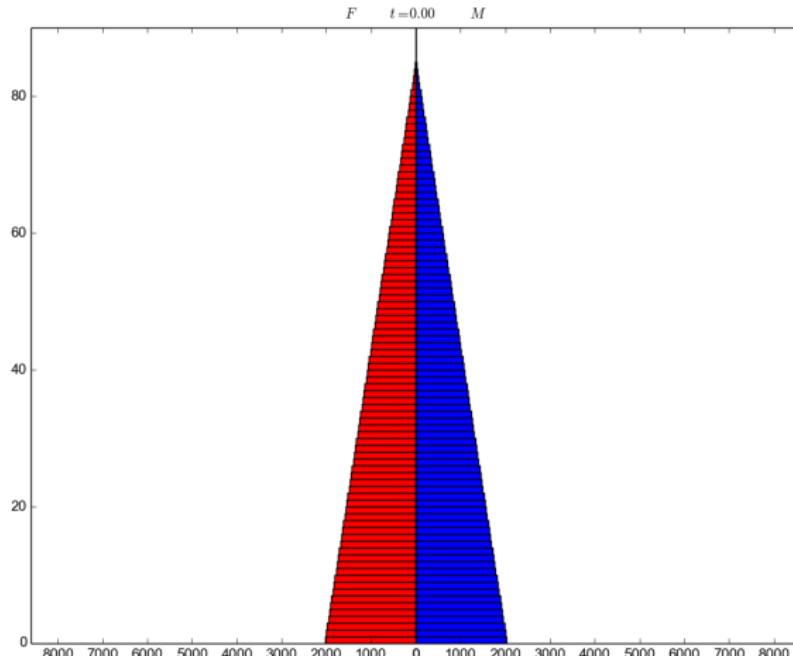
Lower $\kappa \Rightarrow$ too many F die \Rightarrow extinction

Example: Age & Sex Structured Population

$$\kappa = 0.600$$

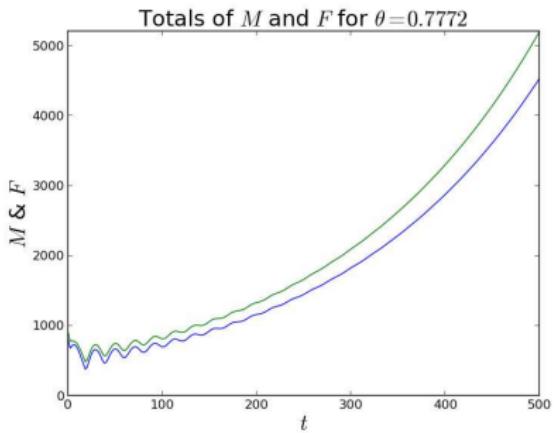
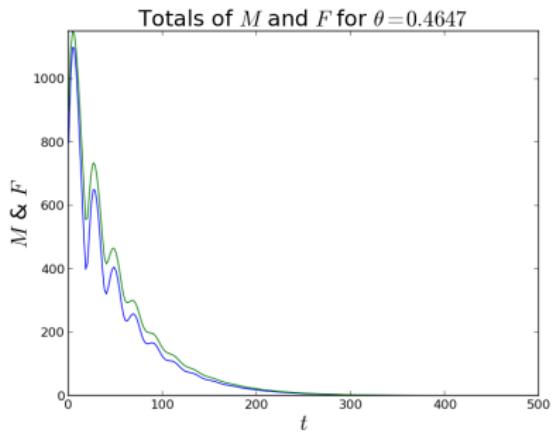
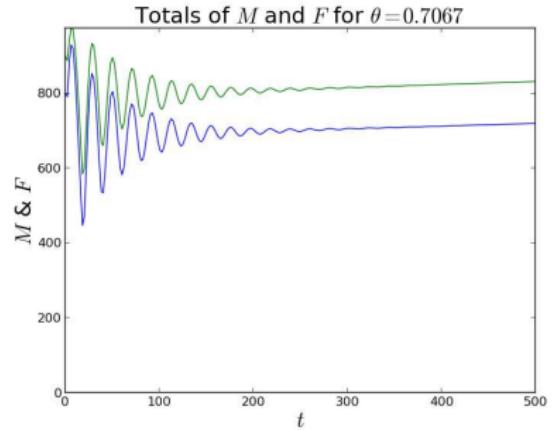
$$\eta = 0.485$$

$$\vartheta = 0.5000$$



Lower $\vartheta \Rightarrow$ extinction

Example: Age & Sex Structured Population



Example: Age & Sex Structured Population

Optimal Mating Ratio:

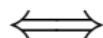
$$\vartheta(t) = \frac{\int_{f_1}^{f_2} F(t, a) da}{\int_{m_1}^{m_2} M(t, a) da + \int_{f_1}^{f_2} F(t, a) da}$$

Optimal Fertility Rate:

$$\frac{\nu}{\frac{1}{\int_{m_1}^{m_2} M(t, a) da} + \frac{1}{\int_{f_1}^{f_2} F(t, a) da}}$$

(Colombo & Garavello: MBE, 2015)

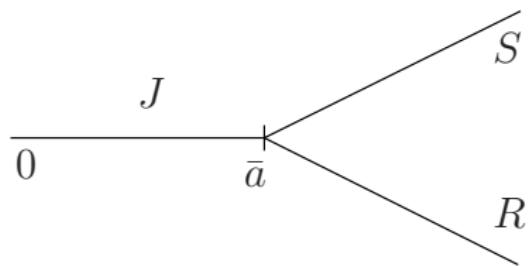
Control



Management of a Biological Resource

(in collaboration with M. Garavello)

Management of a Biological Resource



J Juveniles $a \in [0, \bar{a}]$

S Sold $a \in [\bar{a}, +\infty[$

R Reproduction $a \in [\bar{a}, a_{\max}]$

Management of a Biological Resource

$$\begin{cases} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \\ g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta) g_J(t, \bar{a}) J(t, \bar{a}) \end{cases}$$

J Juveniles $a \in [0, \bar{a}]$

S Sold $a \in [\bar{a}, +\infty[$

R Reproduction $a \in [\bar{a}, a_{\max}]$

Management of a Biological Resource

$$\begin{aligned} & \text{0} \quad J \\ & \quad \bar{a} \end{aligned}$$
$$S \left\{ \begin{array}{l} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \end{array} \right.$$
$$R \left\{ \begin{array}{l} g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta) g_J(t, \bar{a}) J(t, \bar{a}) \end{array} \right.$$

Profit = [income from S] – [costs of J, S, R]

Management of a Biological Resource

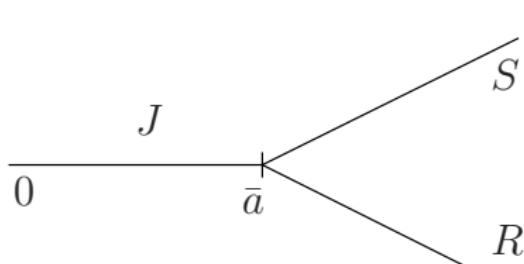
$$\left\{ \begin{array}{l} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \\ g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta) g_J(t, \bar{a}) J(t, \bar{a}) \end{array} \right.$$

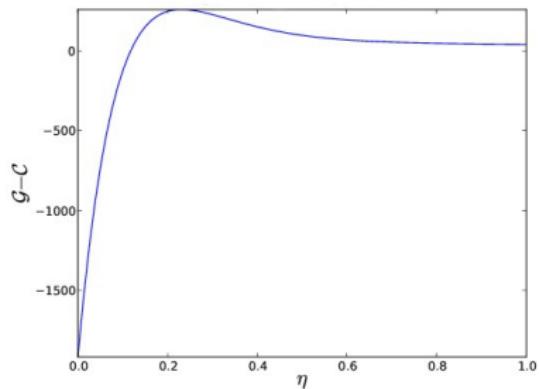
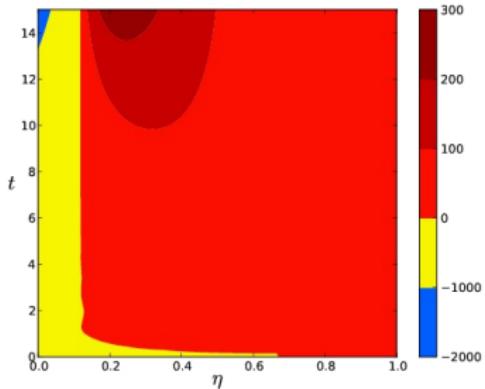
Profit = [income from S] – [costs of J, S, R]

Find η to maximize the profit

Stability estimates \Rightarrow existence of an optimal η

Management of a Biological Resource


$$\begin{cases} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \\ g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta) g_J(t, \bar{a}) J(t, \bar{a}) \end{cases}$$



(Colombo & Garavello: MBE, 2015)

RMColombo

Management of a Biological Resource

$$\left. \begin{array}{l} J \\ 0 \\ \bar{a} \\ S \\ R \end{array} \right\} \begin{cases} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \\ g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta) g_J(t, \bar{a}) J(t, \bar{a}) \end{cases}$$

Profit = [income from S] – [costs of J, S, R]

Find η to maximize the profit

Stability estimates \Rightarrow existence of an optimal η

The Profit is Differentiable w.r.t η !

Management of a Biological Resource

$$\left. \begin{array}{l} J \\ 0 \\ \bar{a} \\ S \\ R \end{array} \right\} \begin{cases} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \\ g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta(\mathbf{t}) g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta(\mathbf{t})) g_J(t, \bar{a}) J(t, \bar{a}) \end{cases}$$

Management of a Biological Resource

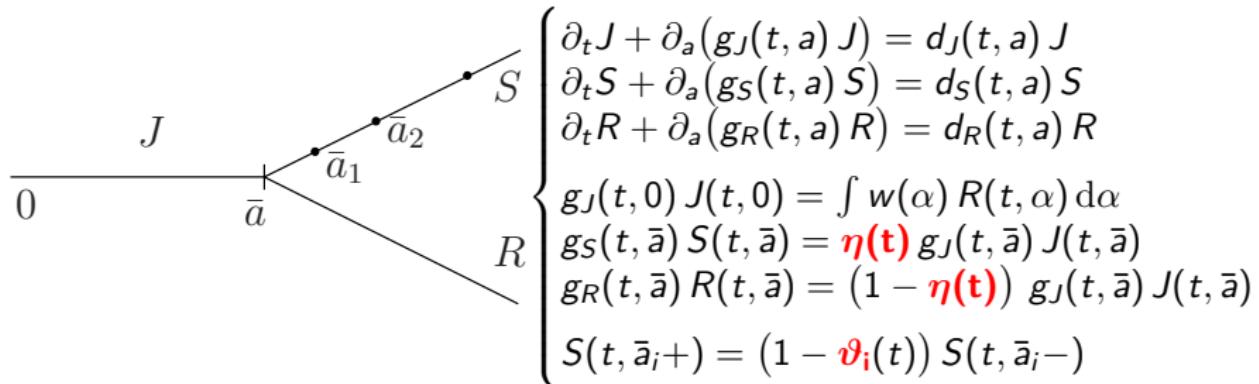
$$\left\{ \begin{array}{l} \partial_t J + \partial_a (g_J(t, a) J) = d_J(t, a) J \\ \partial_t S + \partial_a (g_S(t, a) S) = d_S(t, a) S \\ \partial_t R + \partial_a (g_R(t, a) R) = d_R(t, a) R \\ g_J(t, 0) J(t, 0) = \int w(\alpha) R(t, \alpha) d\alpha \\ g_S(t, \bar{a}) S(t, \bar{a}) = \eta(\mathbf{t}) g_J(t, \bar{a}) J(t, \bar{a}) \\ g_R(t, \bar{a}) R(t, \bar{a}) = (1 - \eta(\mathbf{t})) g_J(t, \bar{a}) J(t, \bar{a}) \end{array} \right.$$

$$\mathcal{C}_J = \iint C_J(t, a, J(t, a)) da dt$$

$$\mathcal{C}_S = \iint C_S(t, a, S(t, a)) da dt$$

$$\mathcal{C}_R = \iint C_R(t, a, R(t, a)) da dt$$

Management of a Biological Resource



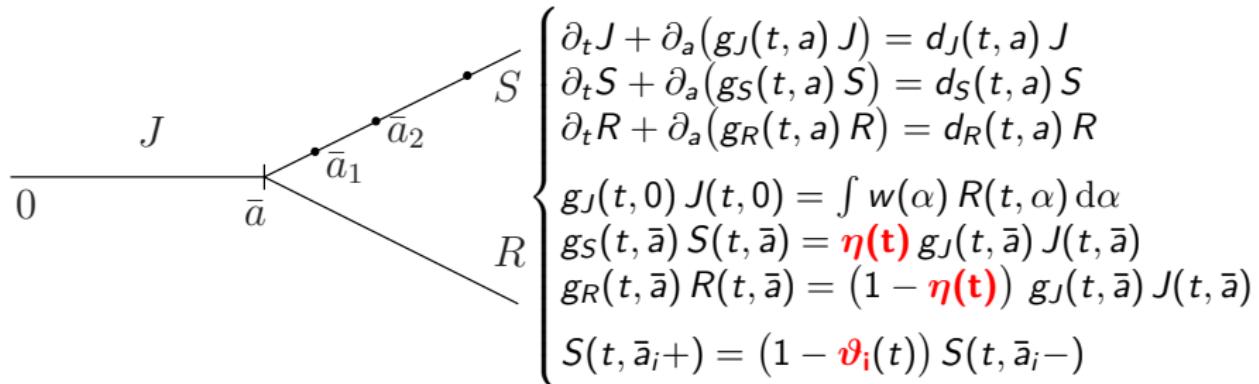
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$$\mathcal{I} = \int \sum_i \vartheta_i(\mathbf{t}) P_i(t) S(t, \bar{a}_i-) dt$$

Management of a Biological Resource



$$\mathcal{C}_J = \iint C_J(t, a, J(t, a)) da dt$$

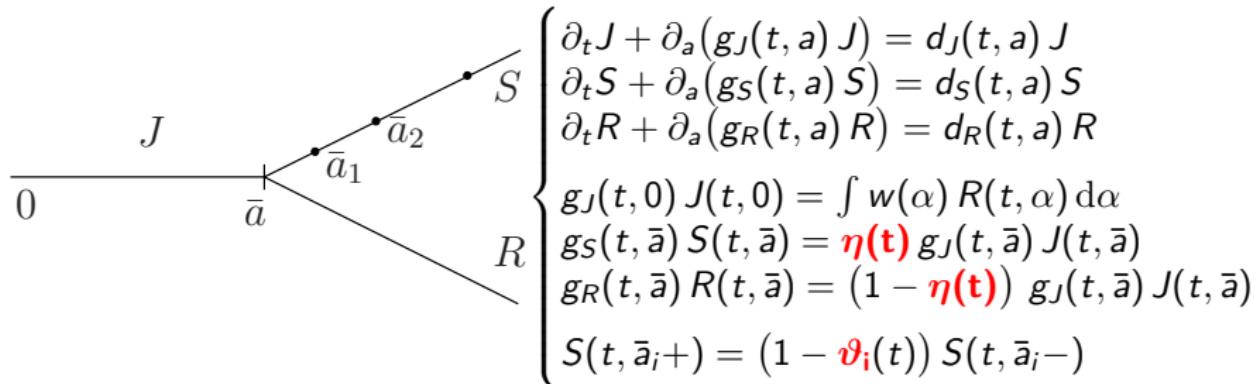
$$\mathcal{C}_S = \iint C_S(t, a, S(t, a)) da dt$$

$$\mathcal{C}_R = \iint C_R(t, a, R(t, a)) da dt$$

$$\mathcal{I} = \int \sum_i \vartheta_i(\mathbf{t}) P_i(t) S(t, \bar{a}_i-) dt$$

$$\mathcal{P} = \mathcal{I} - (\mathcal{C}_J + \mathcal{C}_S + \mathcal{C}_R)$$

Management of a Biological Resource



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$$\mathcal{P} = \mathcal{I} - (\mathcal{C}_J + \mathcal{C}_S + \mathcal{C}_R)$$

\mathcal{P} is Gateaux
differentiable
w.r.t. η and ϑ

Management of a Biological Resource

How to find the
optimal control?
maximal profit?

Management of a Biological Resource

How to find the optimal control?
maximal profit?

Gateaux differentiability \Rightarrow gradient methods

Management of a Biological Resource

How to find the optimal control?
maximal profit?

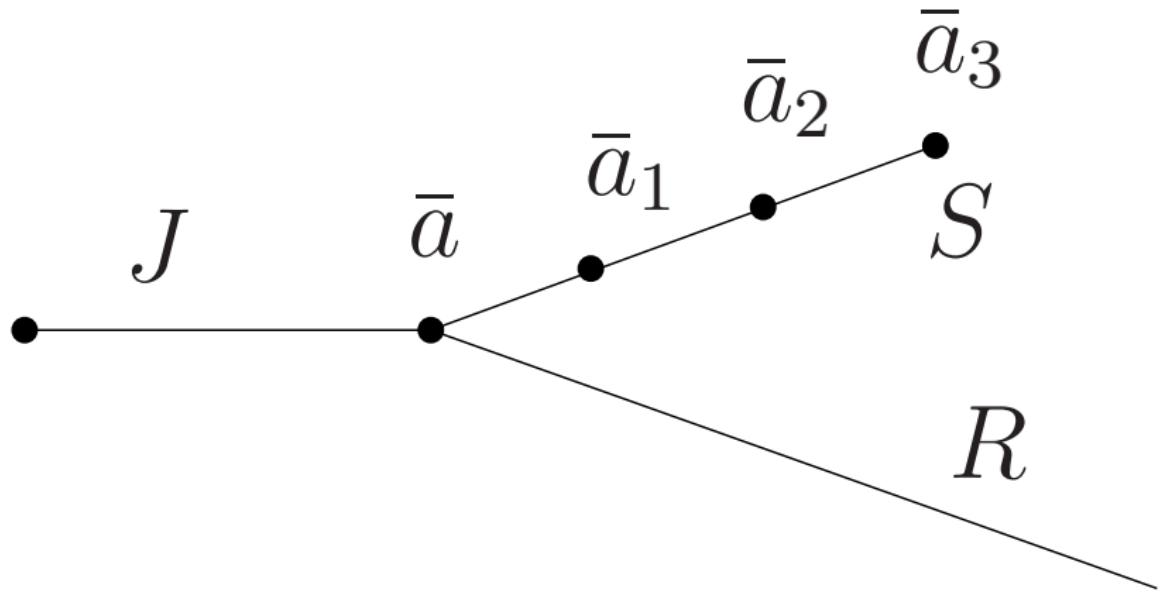
Bang–Bang controls

Theorem (Colombo & Garavello: ESAIM – COCV, 2017)

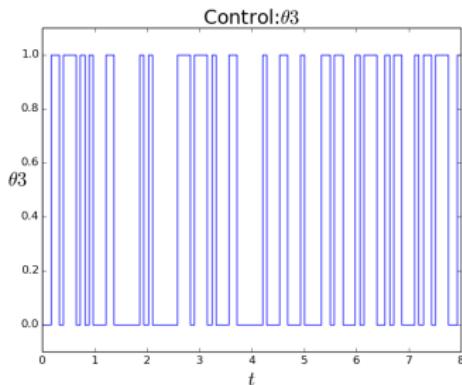
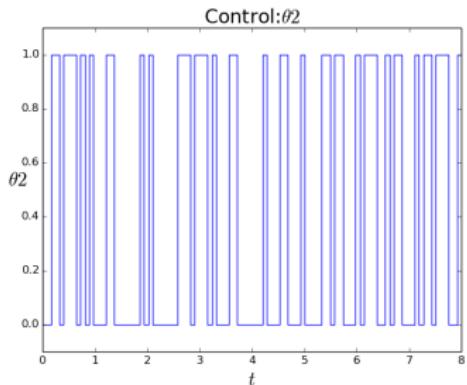
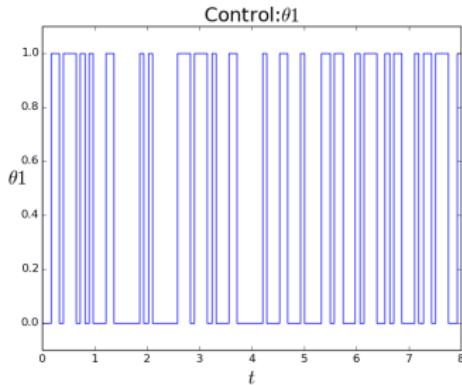
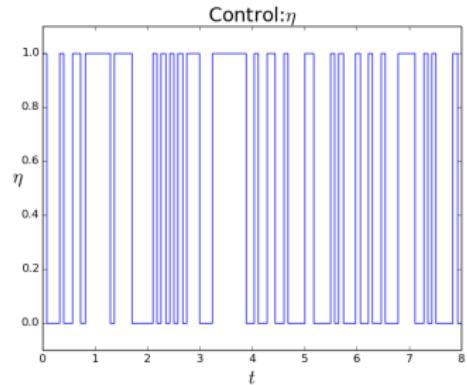
For any $\varepsilon > 0$ there exists a bang–bang control $(\eta_\varepsilon, \vartheta_\varepsilon)$ such that

$$\mathcal{P}(\eta_\varepsilon, \vartheta_\varepsilon) \geq \sup \mathcal{P}(\eta, \vartheta) - \varepsilon$$

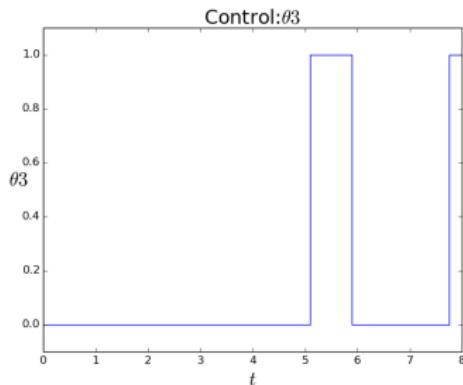
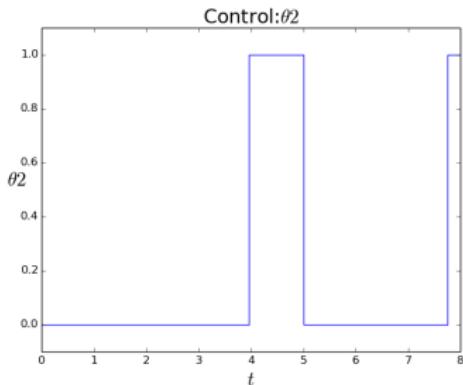
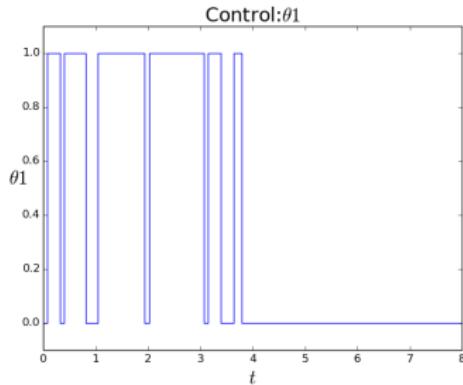
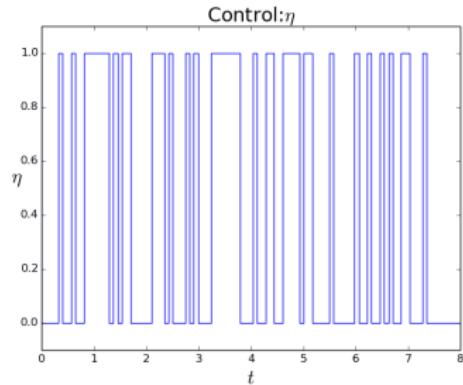
Management of a Biological Resource



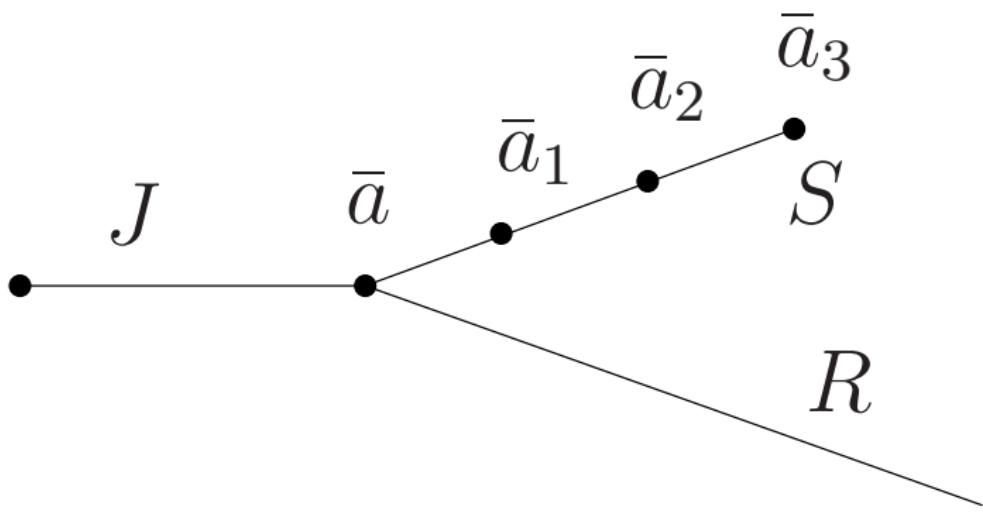
Management of a Biological Resource



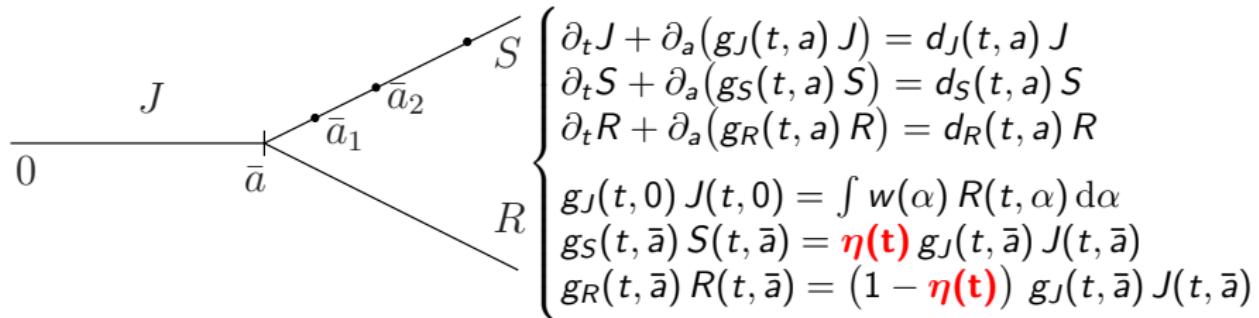
Management of a Biological Resource



Management of a Biological Resource



Management of a Biological Resource



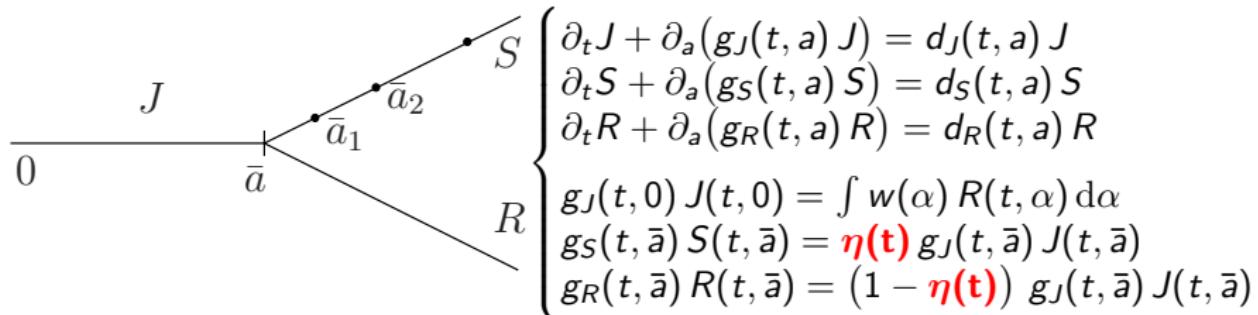
$$\begin{aligned} \mathcal{C}_J &= \iint c_J(t, a) J(t, a) da dt \\ \mathcal{C}_S &= \iint c_S(t, a) S(t, a) da dt \\ \mathcal{C}_R &= \iint c_R(t, a) R(t, a) da dt \end{aligned}$$

$$\begin{aligned} \mathcal{I} &= \int \sum_i \vartheta_i(\mathbf{t}) P_i(t) S(t, \bar{a}_i-) dt \\ \mathcal{P} &= \mathcal{I} - (\mathcal{C}_J + \mathcal{C}_S + \mathcal{C}_R) \end{aligned}$$

Theorem (Colombo & Garavello: Nonlinear An. RWA, 2017)

If $\eta(\mathbf{t}) = \sum_i \eta_i \chi_{[\tau_{i-1}, \tau_i[}$ and $\vartheta(\mathbf{t}) = \sum_i \vartheta_i \chi_{[\tau_{i-1}, \tau_i[}$, then

Management of a Biological Resource



$$\mathcal{C}_J = \iint c_J(t, a) J(t, a) da dt$$

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\mathcal{P} is a **polynomial** in $\eta_1, \eta_2, \dots, \vartheta_1, \vartheta_2, \dots$

(+ bounds on the degree)

Management of a Biological Resource – Example

$$g_J(t, a) = 1.00 \quad d_J(t, a) = 1.50 \quad c_J(t, a) = 0.25 \quad J_o(a) = 1.00$$

$$g_S(t, a) = 1.00 \quad d_S(t, a) = 0.50 \quad c_S(t, a) = 0.00 \quad S_o(a) = 0.00$$

$$g_R(t, a) = 1.00 \quad d_R(t, a) = 0.75 \quad c_R(t, a) = 0.00 \quad R_o(a) = 0.00$$

$$\bar{a} = 1.00 \quad \bar{a}_1 = 1.50 \quad N = 1$$

$$p(a) = 0.00 \quad p_1(t) = 8.00 \quad w(a) = 120.00 \chi_{[1.00, 4.00]}(a)$$

Management of a Biological Resource – Example

$$g_J(t, a) = 1.00 \quad d_J(t, a) = 1.50 \quad c_J(t, a) = 0.25 \quad J_o(a) = 1.00$$

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$$\bar{a} = 1.00$$

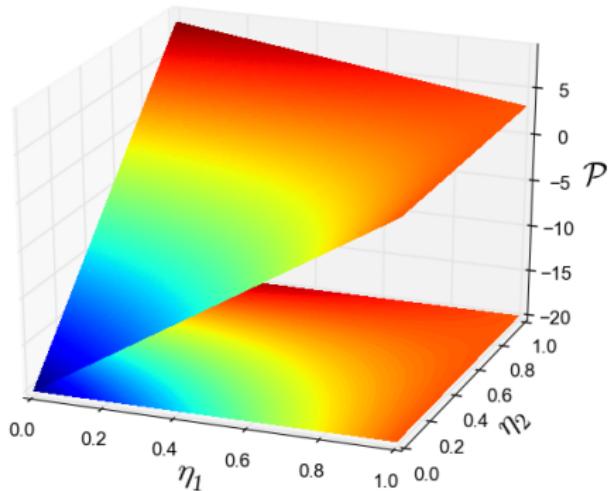
$$\bar{a}_1 = 1.50$$

$$N = 1$$

$$p(a) = 0.00 \quad p_1(t) = 8.00 \quad w(a) = 120.00 \chi_{[1.00, 4.00]}(a)$$

$$\eta = \eta_1 \chi_{[0,1]} + \eta_2 \chi_{[1,2]}$$

$$\begin{aligned}\mathcal{P} = & -19.97 + 23.10 \eta_1 \\ & + 28.18 \eta_2 - 28.18 \eta_1 \eta_2\end{aligned}$$

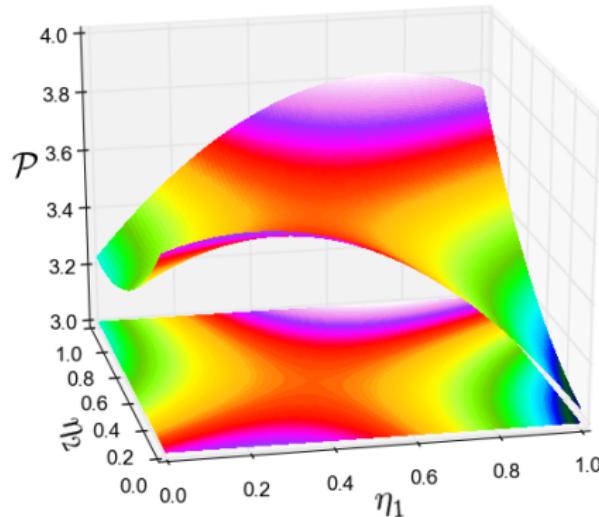


Management of a Biological Resource – Example

$$\begin{array}{lllll} \bar{a} = 1.00 & d_J(t, a) = 0.50 & c_J(t, a) = 0.25 & p(a) = 1.00 & J_o(a) = 1.00 \\ N = 1 & d_S(t, a) = 1.00 & c_S(t, a) = 0.25 & p_1(t) = 8.20 & S_o(a) = 0.00 \\ \bar{a}_1 = 1.50 & d_R(t, a) = 1.50 & c_R(t, a) = 0.25 & w(a) = 10.00 & R_o(a) = 0.00 \end{array}$$

$$\eta = \eta_1 \chi_{[0,0.5]} + \eta_2 \chi_{[0.5,1]} + \eta_1 \chi_{[1,1.5]} + \eta_2 \chi_{[1.5,2]}$$

$$\mathcal{P}(\eta_1, \eta_2) = 3.65 + 0.46 \eta_1 - 0.88 \eta_2 + 1.11 \eta_1 \eta_2 - 1.06 \eta_1^2 + 0.46 \eta_2^2$$



R.M. Colombo, M. Garavello

Polynomial Profit in Renewable Resources Management

Nonlinear Analysis RWA, 37, 374-386, 2017

R.M. Colombo, M. Garavello

Control of Biological Resources on Graphs

ESAIM – COCV, 23, 3, 1073-1097, 2017

R.M. Colombo, M. Garavello

Stability and Optimization in Structured Population Models on Graphs

Mathematical Biosciences and Engineering, 12, 2, 311-335, 2015