Homogenization and corrector for the wave equation

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The wave problem.

For a positive number T, we analyze the asymptotic behavior for the problem

$$\begin{cases} \partial_t (\rho_{\epsilon} \partial_t u_{\epsilon}) - \operatorname{div}_X (A_{\epsilon} \nabla_X u_{\epsilon}) = f_{\epsilon} \text{ en } Q_T \\ u_{\epsilon|t=0} = u_{0,\epsilon}, \ (\rho_{\epsilon} \partial_t u_{\epsilon})_{|t=0} = \vartheta_{\epsilon} \text{ in } \Omega \\ u_{\epsilon} \in L^{\infty}(0, T; H_0^1(\Omega)), \ \partial_t u_{\epsilon} \in L^{\infty}(0, T; L^2(\Omega)). \end{cases}$$
(1)

where $Q_T = (0, T) \times \Omega$ and ε is a parameter which tends to zero.

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Aim of the work

• Computation of an approximation of u_{ε} in the form

$$u_{\epsilon}(t,x) \sim u_0(t,x) + \epsilon u_1(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}) + \epsilon^2 u_2(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}) + \cdots$$

*u*₀(*t*, *x*) + ε*u*₁(*t*, *x*, ^{*t*}/_ε, ^{*x*}/_ε) provides of a corrector (approximation in the strong topology) for *u*_ε,

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• Existence of weak solutions. Counter-examples:

- A_{ε} constant in the two side of a hyperplane, non-parallel to $\{t = 0\}$ ([Hurd-Sattinger, 1968]).
- $A_{\varepsilon} \in C^{0,\alpha}(\overline{\Omega} \times [0, T])$, for every $\alpha \in (0, 1)$ ([Colombini-Spagnolo, 1989]).
- Homogenization of oscillations in the time variable ([Colombini-Spagnolo, 1978]).
- Corrector, well-posed character of the initial data ([BrahaimOsmane-Francfort-Murat, 1992]).

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Regularity Two-scale convergence

We assume:

- ρ_{ε} bounded in $BV(0, T; L^{\infty}(\Omega))$ with $\rho_{\varepsilon} \ge \alpha > 0$,
- A_{ε} bounded in $BV(0, T; L^{\infty}(\Omega; \mathcal{M}_{N}^{H}))$, with $A_{\varepsilon}\xi \cdot \xi \geq \alpha |\xi|^{2}, \forall \xi \in \mathbb{R}^{N}$,
- $u_{0,\varepsilon}$ and ϑ_{ε} are bounded in $H_0^1(\Omega)$ and $L^2(\Omega)$ respectively,
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$u_{\epsilon} \in L^{\infty}(0,T; H^{1}_{0}(\Omega)), \ \partial_{t}u_{\epsilon} \in L^{\infty}(0,T; L^{2}(\Omega))$

and satisfying an energy estimation.

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Regularity Two-scale convergence

Theorem (Homogenization)

The unique solution of (5) satisfies

$$\begin{array}{ll} u_{\epsilon} \stackrel{\star}{\rightharpoonup} u & \text{ in } L^{\infty}(0, T, H_{0}^{1}(\Omega)), \\ \partial_{t} u_{\epsilon} \stackrel{\star}{\rightharpoonup} \partial_{t} u & \text{ in } L^{\infty}(0, T, L^{2}(\Omega)), \end{array}$$

where u is the unique solution of

$$\begin{aligned} \partial_t(\rho\partial_t u) - \operatorname{div}_X(A\nabla_X u_{\epsilon}) &= f \text{ en } Q_T \\ u_{|t=0} &= u_0, \ (\rho\partial_t u)_{|t=0} = \vartheta \quad \text{in } \Omega \\ u \in L^{\infty}(0, T; H^1_0(\Omega)), \ \partial_t u \in L^{\infty}(0, T; L^2(\Omega)). \end{aligned}$$

$$(2)$$

where

$$\begin{split} \rho_{\varepsilon} &\stackrel{\star}{\rightharpoonup} \rho \text{ in } L^{\infty}((0,T) \times \Omega) \\ \mathcal{A}_{\varepsilon}(t,\cdot) &\stackrel{H}{\rightharpoonup} \mathcal{A}(t,\cdot), \forall t \in (0,T) \setminus \mathcal{N} \end{split}$$

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Regularity Two-scale convergence

Definition (Two-scale convergence)

We say that a sequence $v_{\varepsilon} \in L^2(Q_T)$ two-scale converges to a function $v \in L^2(Q_T; L^2_{\sharp}(\mathbb{R} \times Y))$ and we write $v_{\varepsilon} \stackrel{2e}{\rightharpoonup} v$, if for every $\psi \in C^0_c(Q_T; C_{\sharp}(\mathbb{R} \times Y))$ we have

$$\lim_{\varepsilon \to 0} \int_{Q_{\tau}} v_{\varepsilon} \psi(t, x, \frac{t}{\varepsilon}, \frac{x}{\varepsilon}) \, dt dx = \int_{Q_{\tau}} M_{s, y}(v\psi) \, dt dx.$$
(3)

We say that $v_{\varepsilon} \in L^{2}(Q_{T})$ two-scale converges strongly to $v \in L^{2}(Q_{T}; L^{2}_{\sharp}(\mathbb{R} \times Y))$ and we write $v_{\varepsilon} \stackrel{2e}{\rightarrow} v$ if for every bounded sequence z_{ε} in $L^{2}(Q_{T})$, which two-scale converges to a function $z \in L^{2}(Q_{T}; L^{2}_{\sharp}(\mathbb{R} \times Y))$, we have

$$\lim_{\varepsilon \to 0} \int_{Q_{\tau}} v_{\varepsilon} z_{\varepsilon} \, dt dx = \int_{Q_{\tau}} M_{s,y}(vz) \, dt dx. \tag{4}$$

Regularity Two-scale convergence

Theorem (Compactness)

If v_{ε} is a bounded sequence in $L^2(Q_T)$, then there exists a subsequence of ε , still denoted by ε , and there exists $v \in L^2(Q_T; L^2_{\sharp}(\mathbb{R} \times Y))$ such that v_{ε} two-scales converges to v. Moreover, if v_{ε} is bounded in $H^1(Q_T)$, then, for a subsequence of ε , there exist $v_0 \in H^1(Q_T)$ and $v_1 \in L^2(Q_T; H^1_{\sharp}(\mathbb{R} \times Y))$, such that $v_{\varepsilon} \rightharpoonup v_0$ in $H^1(Q_T)$

$$\nabla_{t,x} \mathbf{v}_{\varepsilon} \stackrel{2e}{\rightharpoonup} \nabla_{t,x} \mathbf{v}_{0} + \nabla_{s,y} \mathbf{v}_{1}.$$

In our case

Proposition

If v_{ε} is bounded in $L^{\infty}(0, T; L^{2}(\Omega))$, then in the above Theorem the function v is in $L^{\infty}(0, T; L^{2}(\Omega; L^{2}_{*}(\mathbb{R} \times Y)))$

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The wave problem.

$$\begin{aligned} \partial_t(\rho_\epsilon \partial_t u_\epsilon) - \operatorname{div}_x(A_\epsilon \nabla_x u_\epsilon) + B_\epsilon \cdot \nabla_{t,x} u_\epsilon &= f_\epsilon \text{ en } Q_T \\ u_{\epsilon|t=0} &= u_{0,\epsilon}, \ (\rho_\epsilon \partial_t u_\epsilon)_{|t=0} = \vartheta_\epsilon \text{ in } \Omega \\ u_\epsilon &\in L^\infty(0, T; H^1_0(\Omega)), \ \partial_t u_\epsilon \in L^\infty(0, T; L^2(\Omega)). \end{aligned}$$
(5)

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Case:
$$\Omega = \mathbb{R}^N$$

Case: $\Omega = (\alpha, \beta)$
SSUMPTIONS

The problem data have the following structure:

$$\rho_{\epsilon}(t,x) = \rho^{0}(\frac{x}{\epsilon}) + \epsilon \rho^{1}(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}), \quad A_{\epsilon}(t,x) = A^{0}(\frac{x}{\epsilon}) + \epsilon A^{1}(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon})$$
$$B_{\epsilon}(t,x) = B(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}), \quad f_{\epsilon}(t,x) = f(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon})$$
$$u_{0,\epsilon}(x) = u^{0}(x) + \epsilon u^{1}(x,\frac{x}{\epsilon}), \quad \theta_{\epsilon}(x) = \theta(x,\frac{x}{\epsilon}).$$

Assuming that the functions are periodic in the unit cube $Y = (0, 1)^N$ with respect to the spatial microscopic variable $y = x/\varepsilon$ and quasi-periodic in the time microscopic variable $s = t/\varepsilon$.

Assumptions

• $\rho^0 \in L^{\infty}_{\sharp}(Y), A^0 \in L^{\infty}_{\sharp}(Y; \mathcal{M}^H_N)$ Hermitian and coercitive.

• $\rho^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y)), A^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y; \mathcal{M}_N^H))$, with

 $\partial_t \rho^1, \partial_s \rho^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y)), \ \partial_t A^1, \partial_s A^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y; \mathcal{M}_N^H)).$

- $B \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y)^{N+1})$
- $f \in L^1(0, T; L^2(\mathbb{R}^N; C_{\sharp}(\mathbb{R} \times Y))).$
- $u_{0,\varepsilon}$ and ϑ_{ε} bounded in $H^1(\mathbb{R}^N)$ and $L^2(\mathbb{R}^N)$ respectively.

Then, the two-scale compactness result provides $u^0 \in H^1(\mathbb{R}^N)$, $u^1 \in L^2(\mathbb{R}^N; H^1_{\sharp}(Y))$ and $\vartheta \in L^2(\mathbb{R}^N; L^2_{\sharp}(Y))$ such that, up to a subsequence, we have

 $u_{0,\varepsilon} \rightharpoonup u^0$ in $H^1(\mathbb{R}^N)$, $\nabla_x u_{0,\varepsilon} \stackrel{2e}{\rightharpoonup} \nabla_x u^0 + \nabla_y u^1$, $\vartheta_{\varepsilon} \stackrel{2e}{\rightharpoonup} \vartheta$. (6)

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• $\rho^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y)), A^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y; \mathcal{M}_N^H))$, with

 $\partial_t \rho^1, \partial_s \rho^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y)), \ \partial_t A^1, \partial_s A^1 \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y; \mathcal{M}_N^H)).$

- $B \in L^{\infty}(Q_T; C_{\sharp}(\mathbb{R} \times Y)^{N+1})$
- $f \in L^1(0, T; L^2(\mathbb{R}^N; C_{\sharp}(\mathbb{R} \times Y))).$

• $u_{0,\varepsilon}$ and ϑ_{ε} bounded in $H^1(\mathbb{R}^N)$ and $L^2(\mathbb{R}^N)$ respectively.

Then, the two-scale compactness result provides $u^0 \in H^1(\mathbb{R}^N)$, $u^1 \in L^2(\mathbb{R}^N; H^1_{\sharp}(Y))$ and $\vartheta \in L^2(\mathbb{R}^N; L^2_{\sharp}(Y))$ such that, up to a subsequence, we have

 $u_{0,\varepsilon} \rightharpoonup u^0$ in $H^1(\mathbb{R}^N)$, $\nabla_x u_{0,\varepsilon} \stackrel{2e}{\rightharpoonup} \nabla_x u^0 + \nabla_y u^1$, $\vartheta_{\varepsilon} \stackrel{2e}{\rightharpoonup} \vartheta$. (6)

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 $\partial_t \rho^1, \partial_s \rho^1 \in L^{\infty}(Q_T; C_{\mathfrak{t}}(\mathbb{R} \times Y)), \partial_t A^1, \partial_s A^1 \in L^{\infty}(Q_T; C_{\mathfrak{t}}(\mathbb{R} \times Y; \mathcal{M}_N^H)).$

•
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Theorem (Part I)

We assume the above hypothesis, then the sequence u_{ε} satisfies

$$u_{arepsilon}\stackrel{*}{
ightarrow} u_{0} \; \; {\it in} \; L^{\infty}(0,\,T;\, H^{1}(\mathbb{R}^{N}))$$

Limit system

$$\nabla_{t,x} u_{\varepsilon} \stackrel{2e}{\rightharpoonup} \nabla_{t,x} u_0 + \nabla_{s,y} u_1,$$

where u_0 , u_1 are the unique solutions of the variational system

$$u_0 \in L^{\infty}(0, T; H^1(\mathbb{R}^N)), \quad \partial_t u_0 \in L^{\infty}(0, T; L^2(\mathbb{R}^N)),$$

 $u_{1} \in L^{\infty}(0, T; L^{2}(\mathbb{R}^{N}; H^{1}_{\sharp}(\mathbb{R} \times Y))), \quad M_{s,y}(u_{1}) = 0 \text{ a.e. in } Q_{T},$ $u_{0|t=0} = u^{0}, \ (M_{y}(\rho^{0})\partial_{t}u_{0})_{|t=0} = M_{y}(\vartheta),$

$$\left(\rho^{0}\left(\partial_{t}u_{0}+\partial_{s}u_{1}\right)\right)_{|t=s=0}=\vartheta, \ \nabla_{y}u_{1|t=s=0}=\nabla_{y}u^{1},$$

Limit system Corrector

Theorem (Part II)

$$\begin{cases} \int_{Q_{T}} M_{s,y} (-\rho^{0}(\partial_{t}u_{0}\partial_{t}v_{0} + \partial_{s}u_{1}\partial_{s}v_{1}) \\ \int_{Q_{T}} +A^{0}(\nabla_{x}u_{0} + \nabla_{y}u_{1}) \cdot (\nabla_{x}v_{0} + \nabla_{y}v_{1})) dtdx \\ + \int_{Q_{T}} M_{s,y} (B \cdot (\nabla_{t,x}u_{0} + \nabla_{s,y}u_{1})v_{0}) dtdx \\ = \int_{Q_{T}} M_{s,y} (fv_{0} + F^{0} \cdot (\nabla_{x}v_{0} + \nabla_{y}v_{1})) dtdx \\ \forall v_{0} \in W_{0}^{1,1}(0, T; L^{2}(\mathbb{R}^{N})) \cap L^{1}(0, T; H^{1}(\mathbb{R}^{N})), \\ \forall v_{1} \in L^{1}(0, T; L^{2}(\mathbb{R}^{N}; H^{1}_{\sharp}(\mathbb{R} \times Y))) \end{cases}$$

$$(7)$$

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Theorem (Part III)

$$\begin{cases} \int_{Q_{T}} M_{s,y} (-2\rho^{0}\partial_{s}u_{1}\partial_{t}\psi + A^{0}\nabla_{y}u_{1} \cdot \nabla_{x}\psi - \operatorname{div}_{x}(\overline{A^{0}}\nabla_{y}\psi)u_{1}) dtdx \\ + \int_{Q_{T}} M_{s,y} (-\rho^{1}(\partial_{t}u_{0} + \partial_{s}u_{1})\partial_{s}\psi + A^{1}(\nabla_{x}u_{0} + \nabla_{y}u_{1}) \cdot \nabla_{y}\psi) dtdx \\ + \int_{Q_{T}} M_{s,y} (B \cdot (\nabla_{t,x}u_{0} + \nabla_{s,y}u_{1})\psi) dtdx \\ = \int_{Q_{T}} M_{s,y} (f\psi + F^{1} \cdot \nabla_{y}\psi) dtdx, \\ \forall \psi \in H^{1}(Q_{T}; \overline{W}^{1}), \quad \psi_{|t=0} = \psi_{|t=T} = 0. \end{cases}$$

$$(8)$$

Limit system

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Formally,

$$\begin{split} \rho^0 \partial_{ss}^2 u_1 - \operatorname{div}_y (\mathcal{A}^0 (\nabla_x u_0 + \nabla_y u_1)) &= -\operatorname{div}_y \mathcal{F}^0 \quad \text{in } \mathbb{R} \times \mathbb{R}^N, \\ \text{a.e. } (t, x) \in (0, T) \times \mathbb{R}^N, \end{split}$$

$$\begin{split} \rho^{0}\partial_{tt}^{2}u_{0} &-\operatorname{div}_{x}(\mathcal{A}^{0}\nabla_{x}u_{0})+2\rho^{0}\partial_{st}^{2}u_{1}-\operatorname{div}_{x}(\mathcal{A}^{0}\nabla_{y}u_{1})-\operatorname{div}_{y}(\mathcal{A}^{0}\nabla_{x}u_{1})\\ &+\partial_{s}\big(\rho^{1}(\partial_{t}u_{0}+\partial_{s}u_{1})\big)-\operatorname{div}_{y}\big(\mathcal{A}^{1}(\nabla_{x}u_{0}+\nabla_{y}u_{1})\big)\\ &+B\cdot(\nabla_{t,x}u_{0}+\nabla_{s,y}u_{1})+\rho^{0}\partial_{ss}^{2}u_{2}-\operatorname{div}_{y}(\mathcal{A}^{0}\nabla_{y}u_{2})\\ &=f-\operatorname{div}_{x}F^{0}-\operatorname{div}_{y}F^{1}, \text{ a.e. }(t,x)\in(0,T)\times\mathbb{R}^{N}. \end{split}$$

$$u_{\epsilon}(t,x) \sim u_0(t,x) + \epsilon u_1(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}) + \epsilon^2 u_2(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}) + \cdots$$

 u_1 non locally depends on u_0 , u_1 ,

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Formally,

$$\begin{split} \rho^0 \partial_{ss}^2 u_1 - \operatorname{div}_y (\mathcal{A}^0 (\nabla_x u_0 + \nabla_y u_1)) &= -\operatorname{div}_y \mathcal{F}^0 \quad \text{in } \mathbb{R} \times \mathbb{R}^N, \\ \text{a.e. } (t, x) \in (0, T) \times \mathbb{R}^N, \end{split}$$

$$\begin{split} \rho^0 \partial_{tt}^2 u_0 &-\operatorname{div}_x(A^0 \nabla_x u_0) + 2\rho^0 \partial_{st}^2 u_1 - \operatorname{div}_x(A^0 \nabla_y u_1) - \operatorname{div}_y(A^0 \nabla_x u_1) \\ &+ \partial_s \left(\rho^1 (\partial_t u_0 + \partial_s u_1) \right) - \operatorname{div}_y \left(A^1 (\nabla_x u_0 + \nabla_y u_1) \right) \\ &+ B \cdot (\nabla_{t,x} u_0 + \nabla_{s,y} u_1) + \rho^0 \partial_{ss}^2 u_2 - \operatorname{div}_y (A^0 \nabla_y u_2) \\ &= f - \operatorname{div}_x F^0 - \operatorname{div}_y F^1, \text{ a.e. } (t,x) \in (0,T) \times \mathbb{R}^N. \\ &u_{\epsilon}(t,x) \sim u_0(t,x) + \epsilon u_1(t,x,\frac{t}{2},\frac{x}{2}) + \epsilon^2 u_2(t,x,\frac{t}{2},\frac{x}{2}) + \cdots \end{split}$$

$$u_1, x_1 \sim u_0(t, x_1) + \epsilon u_1(t, x_1, \frac{1}{\epsilon}, \frac{1}{\epsilon}) + \epsilon u_2(t, x_1, \frac{1}{\epsilon}, \frac{1}{\epsilon}) + \cdots$$

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$$u_{\epsilon}(t,x) \sim u_0(t,x) + \epsilon u_1(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}) + \epsilon^2 u_2(t,x,\frac{t}{\epsilon},\frac{x}{\epsilon}) + \cdots$$

 u_1 non locally depends on u_0 ,

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Limit system Corrector

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Limit system Corrector

We would like to improve the convergence of the $\nabla_{t,x} u_{\varepsilon}$

Theorem

Assume that convergence for initial data holds in the two-scale strong convergence sense. Then, for every $\Gamma_{\varepsilon} \in L^2(Q_T)^{N+1}$ which two-scale converges strongly to $\nabla_{s,y} u_1$, we have

$$\lim_{\varepsilon \to 0} \int_{Q_T} |\nabla_{t,x} (u_\varepsilon - u_0) - \Gamma_\varepsilon|^2 \, dx dt = 0, \tag{9}$$

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Limit system Corrector

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Limit system Corrector

Remark

If $\nabla_{s,y}u_1$ belongs to $L^2(Q_T; C^0_{\sharp}(\mathbb{R} \times Y)^{N+1})$, we can take in (11)

$$\Gamma_{\varepsilon} = \nabla_{s,y} u_1(t,x,\frac{t}{\varepsilon},\frac{x}{\varepsilon}).$$

Then Theorem asserts

$$abla_{t,x}u_{\varepsilon} -
abla_{t,x}u_0 -
abla_{s,y}u_1(t,x,rac{t}{\varepsilon},rac{x}{\varepsilon}) o 0 \quad \text{in } L^2(Q_T)^{N+1},$$

which assuming further regularity in u1 implies

$$u_{\varepsilon} - u_0 - \varepsilon u_1(t, x, \frac{t}{\varepsilon}, \frac{x}{\varepsilon}) \to 0 \text{ in } H^1(Q_T).$$

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We consider $I = (\alpha, \beta), Q_T = (0, T) \times I$

$$\begin{cases} \partial_t (\rho_{\epsilon} \partial_t u_{\epsilon}) - \partial_x (a_{\epsilon} \partial_x u_{\epsilon}) + B_{\epsilon} \cdot \nabla_{t,x} u_{\epsilon} = f_{\epsilon} \text{ in } Q_T \\ (-c_{\alpha} a_{\epsilon} \partial_x u_{\epsilon} + d_{\alpha} u_{e} p)_{|x=\alpha} = 0 \text{ in } (0, T) \\ (c_{\beta} a_{\epsilon} \partial_x u_{\epsilon} + d_{\beta} u_{e} p)_{|x=\beta} = 0 \text{ in } (0, T) \\ u_{\epsilon|t=0} = u_{0,\epsilon}, \ (\rho_{\epsilon} \partial_t u_{\epsilon})_{|t=0} = \vartheta_{\epsilon} \text{ in } \Omega \\ u_{\epsilon} \in L^{\infty}(0, T; H^1(I)), \ \partial_t u_{\epsilon} \in L^{\infty}(0, T; L^2(I)). \end{cases}$$
(10)

where $c_{\alpha}, d_{\alpha}, c_{\beta}, d_{\beta}$ are non-negative constants such that

$$c_{\alpha} + d_{\alpha} > 0, \quad c_{\beta} + d_{\beta} > 0.$$

Boundary conditions for u_0 and u_1 ???

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(10)

where $c_{\alpha}, d_{\alpha}, c_{\beta}, d_{\beta}$ are non-negative constants such that

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Boundary conditions for u_0 and u_1 ???

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Theorem ($\Omega = I$ **, Part I)**

For a subsequence of ε , still denoted by ε , u_{ε} satisfies $u_{\varepsilon} \stackrel{*}{\rightharpoonup} u_{0}$ in $L^{\infty}(0, T; H^{1}(I))$

$$\nabla_{t,x} u_{\varepsilon} \stackrel{2e}{\rightharpoonup} \nabla_{t,x} u_0 + \nabla_{s,y} u_1,$$

where u_0 , u_1 are the unique solutions of the variational system $u_0 \in L^{\infty}(0, T; V)$, $\partial_t u_0 \in L^{\infty}(0, T; L^2(I))$

 $u_1 \in L^{\infty}(0, T; L^2(I; H^1_{\sharp}(\mathbb{R} \times Y))), \quad M_{s,y}(u_1) = 0 \text{ a.e. in } Q_T$

$$u_{0|t=0} = u^{0}, \ \partial_{t} u_{0|t=0} = \frac{M_{y}(\rho^{0}\vartheta)}{M_{y}(\rho^{0})}$$
$$\left(\partial_{t} u_{0} + \partial_{s} u_{1}\right)_{|t=s=0} = \vartheta, \ \partial_{y} u_{1|t=s=0} = \partial_{y} u^{1}$$

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Theorem ($\Omega = I$ **, Part II)**

$$\begin{cases} \int_{Q_T} M_{s,y} (-\rho^0 (\partial_t u_0 \partial_t v_0 + \partial_s u_1 \partial_s v_1) \\ +a^0 (\partial_x u_0 + \partial_y u_1) (\partial_x v_0 + \partial_y v_1)) dt dx \\ + \frac{d_\alpha}{c_\alpha} \int_{\{x=\alpha\}} M_y(a^0) u_0 v_0 dt + \frac{d_\beta}{c_\beta} \int_{\{x=\beta\}} M_y(a^0) u_0 v_0 dt \\ + \int_{Q_T} M_{s,y} (B \cdot (\nabla_{t,x} u_0 + \nabla_{s,y} u_1) v_0) dt dx = \int_{Q_T} M_{s,y}(f v_0) dt dx \\ \forall v_0 \in W_0^{1,1}(0, T; L^2(I)) \cap L^1(0, T; V), \quad \forall v_1 \in L^2(Q_T; H^1_{\sharp}(\mathbb{R} \times Y)) \end{cases}$$

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Theorem ($\Omega = I$ **, Part III)**

$$\begin{cases} \int_{Q_T} M_{s,y} (-2\rho^0 \partial_s u_1 \partial_t \psi - \rho^1 (\partial_t u_0 + \partial_s u_1) \partial_s \psi \\ +a^1 (\partial_x u_0 + \partial_y u_1) \partial_y \psi) dt dx \\ + \int_{Q_T} M_{s,y} (B \cdot (\nabla_{t,x} u_0 + \nabla_{s,y} u_1) \psi) dt dx = \int_{Q_T} M_{s,y} (f\psi) dt dx \\ \forall \psi \in H_0^1(0, T; L^2(I; P_1(\mathcal{W}^1))) \end{cases}$$

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Theorem ($\Omega = I$, Part IV)

$$\begin{split} \int_{Q_T} M_{s,y} \Big(-2\rho^0 \partial_s u_1 \partial_t \psi + a^0 \partial_y u_1 \partial_x \psi - a^0 \partial_{x,y}^2 \psi \, u_1 \Big) \, dt dx \\ &+ \int_{Q_T} M_{s,y} \Big(-\rho^1 (\partial_t u_0 + \partial_s u_1) \partial_s \psi + a^1 (\partial_x u_0 + \partial_y u_1) \partial_y \psi \Big) \, dt dx \\ &+ \int_{Q_T} M_{s,y} \Big(B \cdot (\nabla_{t,x} u_0 + \nabla_{s,y} u_1) \psi \Big) \, dt dx = \int_{Q_T} M_{s,y} (f\psi) \, dt dx, \\ &\forall \psi \in H^1(Q_T; P_2(\mathcal{W}^1)), \quad \psi_{|t=0} = \psi_{|t=T} = 0 \\ &(a^0 \partial_y \psi)_{|x=\alpha,y=\bar{\alpha}} = 0 \quad \text{if } c_\alpha \neq 0, \quad \psi_{|x=\alpha,y=\bar{\alpha}} = 0 \quad \text{if } c_\alpha = 0 \\ &(a^0 \partial_y \psi)_{|x=\beta,y=\bar{\beta}} = 0 \quad \text{if } c_\beta \neq 0, \quad \psi_{|x=\beta,y=\bar{\beta}} = 0 \quad \text{if } c_\beta = 0. \end{split}$$

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Boundary conditions

Proposition

In the conditions of the above Theorem ($\Omega = I$), one has

$$(a^0 \partial_y P_2 u_1)_{|x=\alpha,y=\bar{\alpha}} = 0 \quad \text{if } c_\alpha \neq 0, \quad P_2 u_1_{|x=\alpha,y=\bar{\alpha}} = 0 \quad \text{if } c_\alpha = 0 \\ (a^0 \partial_y P_2 u_1)_{|x=\beta,y=\bar{\beta}} = 0 \quad \text{if } c_\beta \neq 0, \quad P_2 u_1_{|x=\beta,y=\bar{\beta}} = 0 \quad \text{if } c_\beta = 0$$

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Introduction

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- Difficulties
- Pramework and tools
 - Regularity
 - Two-scale convergence
- 3 Periodic Case
- 4 Case: $\Omega = \mathbb{R}^N$
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5 Case: $\Omega = (\alpha, \beta)$

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- The boundary conditions
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Theorem

We assume that in previous Theorem (Ω =I), the sequences $u_{0,\varepsilon}$ and ϑ_{ε} converge in two-scale in strong sense, then, for every sequence $\Gamma_{\varepsilon} \in L^2(Q_T)^2$ which two-scale strongly converges to $\nabla_{s,y}u_1$, we have

$$\lim_{\varepsilon\to 0}\int_{Q_T}|\nabla_{t,x}(u_\varepsilon-u_0)-\Gamma_\varepsilon|^2\,dxdt=0.$$

Assuming regularity enough for u_1 the above Theorem asserts

$$u_{\varepsilon} - u_0 - \varepsilon u_1(t, x, \frac{t}{\varepsilon}, \frac{x}{\varepsilon}) \to 0 \text{ in } H^1(Q_T).$$

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THANK YOU VERY MUCH, FOR YOUR ATTENTION!!!

Faustino Maestre, et al. Homogenization wave equation

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