XVIII International Fall Workshop on Geometry and Physics

WILLMORE SURFACES IN Generalized Robertson-Walker spacetimes and static spacetimes

Magdalena Caballero



This talk is based on

M. Barros, _ and M. Ortega, *Rotational Surfaces in* \mathbb{L}^3 *and Solutions of the Nonlinear Sigma Model.* Commun. Math. Phys. 290, 437–477 (2009).

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_, Willmore surfaces invariant under a 1-parameter group of isometries in Lorentzian 3-manifolds. In progress.

INTRODUCTION

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THE CLASSICAL WILLMORE FUNCTIONAL

The classical Willmore functional is defined as follows

$$\mathfrak{W}(\phi) = \int_{M} H^2 dA,$$

where

 $S \longrightarrow$ compact, boundary free and connected surface

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 $\phi: \mathcal{S} \to \mathbb{R}^3 \longrightarrow \text{immersion}$

 $H \longrightarrow$ mean curvature

 $dA \longrightarrow$ element of area induced on S

Its critical points are called Willmore surfaces.

Its study was proposed by Willmore in 1965.

The Willmore functional in Riemannian setting

$$\mathfrak{W}(\phi) = \int_{\mathcal{S}} (H^2 + \bar{R}) dA + \int_{\partial S} k_g \, ds,$$

where

- $S \longrightarrow$ surface (with boundary)
- $\phi: \mathcal{S} \to \bar{\mathcal{M}} \longrightarrow$ immersion
- $\bar{M} \longrightarrow$ Riemannian 3-manifold
- $H \longrightarrow$ mean curvature of ϕ
- $\bar{R} \longrightarrow$ sectional curvature of $\phi(S)$ in \bar{M}
- $k_g \longrightarrow$ geodesic curvature of ∂S in S

(oriented as in the Stokes theorem).

Proposed by Weiner in 1978.

The Willmore functional in Lorentzian setting

$$\mathfrak{W}(\phi) = \int_{\mathcal{S}} (H^2 + \varepsilon \bar{R}) dA - \int_{\partial S} k_g \, ds,$$

- $S \longrightarrow$ surface (with boundary)
- $\bar{M} \longrightarrow$ Lorentzian 3-manifold
- $\phi: S \to \overline{M} \longrightarrow$ non-degenerate immersion with signature ε
- $H \longrightarrow$ mean curvature of ϕ
- $\bar{R} \longrightarrow$ sectional curvature of $\phi(S)$ in \bar{M}
- $k_g \longrightarrow$ geodesic curvature of ∂S in S (oriented as in the Stokes theorem).

Using the Gauss-Bonnet theorem for surfaces, in its Riemannian and its Lorentzian versions respectively, we get that

 \mathfrak{W} is invariant under conformal changes of the metric of \overline{M} .

 $\phi: S \to \overline{M}$ is a Willmore surface if it is a critical point of \mathfrak{W} under (compact support) variations fixing:

 ∂S and its Gauss map along ∂S

When $\overline{M} = \mathbb{L}^3$, the Gauss map of Willmore surfaces are the solutions of the 2-dimensional nonlinear sigma-model with symmetry O(2, 1).

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Elastic energy:

$$\mathfrak{E}^{\lambda}(lpha) = \int_{lpha} (k^2 + \lambda) \qquad \qquad \lambda \in \mathbb{R}$$

 $(\bar{M}, \bar{g}) \longrightarrow (\text{semi-})$ Riemannian manifold $\alpha : I \to \bar{M} \longrightarrow \text{non-degenerate immersed curve with curvature } k$

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If α has no boundary & is a critical point of $\mathfrak{E}^{\lambda} \rightarrow \mathbf{closed}$ elastic curve

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$$(\bar{M}, \bar{g}) \longrightarrow$$
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When α has boundary, it is called clamped elastic curve if it is a critical point of \mathfrak{E}^{λ} under (compact support) variations fixing:

the boundary points of $\boldsymbol{\alpha}$ and the tangents at them.

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the boundary points of α and the tangents at them.

 $\lambda = \mathbf{0} \longrightarrow \text{free elastic curve}$

Link

Willmore surfaces	generated by	free elastic curves	
of revolution in \mathbb{R}^3		hyperbolic plane	Barros
of revolution in \mathbb{L}^3 with spacelike axis		anti de Sitter plane	Barros, and Ortega
of revolution in \mathbb{L}^3 with null axis		anti de Sitter plane	Barros, and Ortega

LINK

Barros

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(M,g) \longrightarrow Riemannian or Lorentzian surface

- $\gamma \longrightarrow$ nondegenerate curve immersed in (M, g)
- $f: \mathbb{S}^1 \to \mathbb{R}^+ \longrightarrow \text{smooth function}$

$$\mathbb{S}^1 \times \gamma$$
 is Willmore in $(\mathbb{S}^1 \times M, \varepsilon dt^2 + f^2 g)$
 \uparrow
 γ is a free elastic curve in (M, g)

NATURAL QUESTION

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Given:

- $(\bar{M}, \bar{g}) \longrightarrow$ semi-Riemannian 3-manifold
- $G \longrightarrow 1$ -parameter group of isometries

What must $(\overline{M}, \overline{g})$ and G satisfy to obtain that G-invariant Willmore surfaces in $(\overline{M}, \overline{g})$ are generated by

elastic curves in certain surface

?



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In all the previous results

G is COMPACT

Except for:

Rotational Willmore surfaces in \mathbb{L}^3 with null axis

IDEA

Extend the technique to get results for

Lorentzian product manifolds of dimension 3,

G being a non necessarily compact 1-parameter group of isometries

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1st variation of \mathfrak{W}

IN A SEMI-RIEMANNIAN SETTING

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THEOREMBARROS, _ AND ORTEGA
$$\phi: S \rightarrow \overline{M}$$
 is a Willmore surface if and only if $\int_{S} \overline{g}(\mathfrak{R}(\mathbb{H}) + N(\overline{R}^{\mathbf{V}})N, \mathbf{V}^{\perp}) dA = 0,$

for any variational field V compatible with the boundary conditions.

1st variation of \mathfrak{W}

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for any variational field V compatible with the boundary conditions.

 $\mathbb{H} \longrightarrow$ mean curvature vector field

$$\mathfrak{R} = \varepsilon(\bigtriangleup + \tilde{A}) + (\operatorname{Ric}(N, N) - 2(H^2 + \varepsilon \bar{R}))\mathbf{I}$$

is a kind of Schrödinger operator, being

- $riangle \longrightarrow$ Laplacian respect to the normal conection
- $\tilde{A} \longrightarrow$ Simons' operator
- *Ric Ricci curvature*

1st variation of $\mathfrak W$

IN A SEMI-RIEMANNIAN SETTING

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THEOREM BARROS, _ AND ORTEGA

 $\phi: S \rightarrow \overline{M}$ is a Willmore surface if and only if

$$\int_{\mathcal{S}} ar{g}(\mathfrak{R}(\mathbb{H}) + \mathcal{N}(ar{R}^{\mathbf{V}})\mathcal{N}, \mathbf{V}^{\perp}) dA = 0,$$

for any variational field V compatible with the boundary conditions.

 $N \longrightarrow$ Gauss map along ϕ

 $\overline{R}^{\mathbf{V}}(m, \mathbf{v}) \rightarrow$ sectional curvature of \overline{M} restricted to the level surface \mathbf{v} , at the point m

 $(M^1, ds^2) \longrightarrow 1$ -dimensional Riemannian manifold $(M, g) \longrightarrow Riemannian or Lorentzian surface$

$$(\bar{M}, \bar{g}) = (M \times M^1, g + \bar{\varepsilon} ds^2), \qquad \bar{\varepsilon} = \begin{cases} -1 & \text{if } g \text{ Riemannian} \\ 1 & \text{if } g \text{ Lorentzian} \end{cases}$$

 ${m S}=\gamma imes {m M}^1, \qquad \qquad \gamma$ non-degenerate curve in M

Is $\gamma \times M^1$ Willmore?

$$N(\mathbf{R}^{\mathbf{V}}) = \mathbf{0},$$

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 $N(\bar{R}^{V})=0,$

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so $\gamma \times M^1$ is Willmore if and only if

$$\int_{\gamma imes M^1} ar{g}(\mathfrak{R}(\mathbb{H}), \mathbf{V}^\perp) d\mathbf{A} = 0,$$

if and only if

 $\mathfrak{R}(\mathbb{H}) = 0$

if and only if

$$\tilde{\varepsilon}k'' + \varepsilon k^3 + 2R\,k = 0$$

where $\tilde{\varepsilon}$ is the signature of γ and R is the sectional curvature of M

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if and only if

$$\mathfrak{R}(\mathbb{H})=0$$

if and only if

 $\tilde{\varepsilon}k'' + \varepsilon k^3 + 2Rk = 0$ elastic curves equation

where $\tilde{\varepsilon}$ is the signature of γ and R is the sectional curvature of M

THEOREM _____ $\gamma \times M^1$ is a Willmore surface in $(M \times M^1, g + \bar{\varepsilon} ds^2)$ \uparrow γ is a free elastic curve in (M, g)

IN A **3-**DIM WARPED PRODUCT

Consider the warped product spacetimes

 $M^1 \times_f M = (M^1 \times M, \bar{\varepsilon} ds^2 + f^2 g)$ and $M \times_h M^1 = (M^1 \times M, \bar{\varepsilon} h^2 ds^2 + g)$, where $f : M^1 \longrightarrow \mathbb{R}^+$ and $h : M \longrightarrow \mathbb{R}^+$ are smooth

Since \mathfrak{W} is invariant under conformal changes of the metric

COROLLARY $M^1 \times \gamma$ is Willmore in $M^1 \times_f M$ \uparrow \uparrow γ is free elastic in (M, g) $M^1 \times \gamma$ is Willmore in $M \times_h M^1$ \uparrow \uparrow γ is free elastic in (M, g)

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Since \mathfrak{W} is invariant under conformal changes of the metric

COROLLARY

 $\begin{array}{c} M^{1} \times \gamma \text{ is Willmore in } M^{1} \times_{f} M \\ \uparrow \\ \gamma \text{ is free elastic in } (M,g) \end{array} \qquad \begin{array}{c} M^{1} \times \gamma \text{ is Willmore in } M \times_{h} M^{1} \\ \uparrow \\ \gamma \text{ is free elastic in } (M,\frac{1}{h^{2}}g) \end{array}$

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WILLMORE SURFACES IN GENERALIZED ROBERTSON-WALKER AND STATIC SPACETIMES

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IN GENERALIZED ROBERTSON-WALKER SPACETIMES

A GENERALIZED ROBERTSON-WALKER SPACETIME IS

 $I \times_f M = (I \times M, -dt^2 + f^2g)$

where (M, g) is Riemannian and $f : I \longrightarrow \mathbb{R}^+$

When dimM = 2



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STANDARD STATIC AND STATIC SPACETIMES

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A timelike Killing vector field ξ in a Lorentzian manifold $(\overline{M}, \overline{g})$ is

- static: if it is irrotational
- standard static: if static and there exists an isometry

$$\chi: (\bar{M}, \bar{g}) \longrightarrow (\mathbb{R} \times M, -h^2 dt^2 + g),$$

where $d\chi(\xi) = \partial_t$, $\xi(h \circ \chi) = 0$ and (M, g) is Riemannian

A STANDARD STATIC SPACETIME IS

A spacetime admiting a standard static vector field.

A STATIC SPACETIME IS

A spacetime admiting a static vector field. Locally, it is a standard static one.

IN STANDARD STATIC SPACETIMES

COROLLARY

 $I \times \gamma$ is Willmore in the standard static spacetime $M \times_h I$

$$\gamma$$
 is a free elastic curve in $(M, \frac{1}{h^2}g)$

Given $G \longrightarrow 1$ -parameter group of isometries with timelike Killing vector field ξ

COROLLARY

If ξ is standard static,

G-invariant Willmore surfaces in $(\overline{M}, \overline{g})$ are generated by elastic curves in $(M, \frac{-1}{\overline{g}(\xi, \xi)}\overline{g})$

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Applying

LEMMA M.SÁNCHEZ

Let ξ be a complete static vector field in $(\overline{M}, \overline{g})$. Its lift to the universal covering of $(\overline{M}, \overline{g})$ is standard static.

We get

THEOREM

If ξ is static,

G-invariant Willmore surfaces are generated by elastic curves in $(M, \frac{-1}{g(\xi,\xi)}g)$

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THEOREM

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With similar techniques, the following result is obtained

Given $G \longrightarrow 1$ -parameter subgroup of isometries with spacelike Killing vector field ξ .

THEOREM

If ξ has no zero and it is irrotational, then

G-invariant Willmore surfaces are generated by elastic curves in
$$(M, \frac{1}{g(\xi, \xi)}g)$$

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THE END