Geometric analysis issues in uncompressible fluid mechanics

Yann BRENIER CNRS-Université de Nice-Sophia

Benasque september 2011

Yann Brenier (CNRS)

Geometric analyisi and fluid mechanics

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Benasque september 2011

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The Euler equations of incompressible fluid mechanics

Yann Brenier (CNRS)

Geometric analyisi and fluid mechanics

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The Euler equations of incompressible fluid mechanics

2 Least action principles

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- Geometric analysis issues

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- The Euler equations of incompressible fluid mechanics
- 2 Least action principles
- Geometric analysis issues
- Minimizing geodesics: existence and uniqueness results for the pressure gradient

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- Abridged bibliography

EULER'S EQUATIONS: GEOMETRIC DEFINITION

One can describe the motion of an incompressible fluid inside a bounded domain D in R^d by a time-dependent family t \rightarrow M_t of maps, in the Hilbert space H = L²(D, R^d), valued in the subset VPM(D) of all Lebesgue measure-preserving maps

$$VPM(D) = \{M \in H, \ \int_D q(M(x))dx = \int_D q(x)dx, \ \forall q \in C(R^d)\}$$

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$$\mathsf{VPM}(\mathsf{D}) = \{\mathsf{M} \in \mathsf{H}, \ \int_{\mathsf{D}} \mathsf{q}(\mathsf{M}(x)) \mathsf{d}x = \int_{\mathsf{D}} \mathsf{q}(x) \mathsf{d}x, \ \forall \mathsf{q} \in \mathsf{C}(\mathsf{R}^{\mathsf{d}})\}$$

Solutions of the Euler equations, introduced in 1755, correspond to those curves $t \to M_t \in VPM(D)$ for which there exists a time dependent scalar function p_t , called 'pressure field', defined on D, such that

$$\frac{d^2 M_t}{dt^2} + (\nabla p_t) \circ M_t = 0$$

where ∇ is the gradient operator on R^d (with respect to the Euclidean norm $|\cdot|$).

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THEOREM Assume D to be convex. Let (M_t, p_t) a solution of the Euler equations, with a constant λ such that

$$\sum_{i,j=1}^{d} \frac{\partial^2 p_t(\boldsymbol{x})}{\partial \boldsymbol{x}_i \partial \boldsymbol{x}_j} \xi_i \xi_j \leq \lambda |\xi|^2, \ \forall \xi \in \boldsymbol{\mathsf{R}^d}, \ \forall \boldsymbol{x} \in \boldsymbol{\mathsf{D}}, \ \forall t$$

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Then, for every $t_0 < t_1$ so that $(t_1 - t_0)^2 \lambda < \pi^2$, M_t is the unique minimizer, among all curves along VPM(D) that coincide with M_t at $t = t_0$, $t = t_1$, of the following ACTION

$$\frac{1}{2}\int_{t_0}^{t_1}\int_D|\frac{dM_t(x)}{dt}|^2\,dxdt$$

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In other words, such a curve is nothing but a (constant speed) geodesic along VPM(D) , with respect to the metric induced by $H=L^2(D,R^d)$

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see Arnold 1966, Ebin-Marsden 1970, Arnold-Khesin book 1998.

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THE DUAL ACTION

Minimizing the action can be written as a saddle point problem, just by using a time-dependent Lagrange multiplier to relax the constraint for M_t to belong to VPM(D)

$$\inf_{M} \sup_{p} \int_{t_0}^{t_1} \int_{D} \{ \frac{1}{2} |\frac{dM_t(x)}{dt}|^2 - p_t(M_t(x)) + p_t(x) \} dx dt$$

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This is trivially bounded from below by

$$\sup_p \ \inf_M \ \int_{t_0}^{t_1} \int_D \{\frac{1}{2} |\frac{dM_t(x)}{dt}|^2 - p_t(M_t(x)) + p_t(x)\} dx dt$$

which naturally leads to a dual least action principle

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THEOREM Under exactly the same conditions (D convex and $(t_1 - t_0)^2 \lambda < \pi^2$), the pressure p is the unique maximizer of the CONCAVE DUAL ACTION

$$\textbf{I}[\textbf{p}] = \int_{\textbf{D}} \textbf{J}_{\textbf{p}}(\textbf{M}_{t_0}(\textbf{x}), \textbf{M}_{t_1}(\textbf{x})) \textbf{d}\textbf{x} + \int_{t_0}^{t_1} \int_{\textbf{D}} \textbf{p}_t(\textbf{x}) \textbf{d}\textbf{x} \textbf{d}t$$

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$$J_p(\boldsymbol{y},\boldsymbol{z}) = \inf \int_{t_0}^{t_1} (\frac{1}{2} |\frac{d\xi_t}{dt}|^2 - p_t(\xi_t)) \ dt$$

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As for the previous theorem, the proof is elementary and directly follows from the 1D Poincaré inequality, which explains the role of constant π . Notice that M_t is never assumed to be smooth or one-to-one and the case d = 1 is fine.

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GEOMETRIC ANALYSIS ISSUES I 1) DENSITY OF DIFFEOMORPHISMS IN VPM(D) It is customary to consider the subset SDiff(D) of VPM(D) made of Lebesgue-measure preserving maps that are, in addition, orientation preserving diffeomorphisms. For $d \ge 2$, VPM(D) is precisely the L² closure of SDiff(D). This is a relatively easy result.

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$$\mathbf{M}(\mathbf{x}) = (\mathbf{h}(\mathbf{x_1}), \mathbf{x_2}, \mathbf{x_3})$$

where h is any Lebesgue-measure preserving map of the unit interval, are in the closure of $SDiff([0, 1]^3)$.

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GEOMETRIC ANALYSIS ISSUES II

2) DENSITY OF PERMUTATIONS IN VPM(D) Another interesting subset of $VPM([0, 1]^3)$ is made of all "permutations" of all dyadic divisions of the unit cube in sub-cubes of equal volumes.

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GEOMETRIC ANALYSIS ISSUES II

2) DENSITY OF PERMUTATIONS IN VPM(D) Another interesting subset of VPM($[0, 1]^3$) is made of all "permutations" of all dyadic divisions of the unit cube in sub-cubes of equal volumes. The set of all such permutations, denoted P(D) turns out to be L² dense in VPM($[0, 1]^3$) for all dimensions.

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GEOMETRIC ANALYSIS ISSUES III

3) GEODESIC COMPLETENESS This amounts to globally solving the initial value problem for the Euler equations. This is an outstanding problem for nonlinear evolution PDEs, which will not be discussed here.

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4) MINIMIZING GEODESICS Shnirelman has proven (Math USSR Sb 1986) that existence of minimizing geodesics along SDiff(D) may fail when d \geq 3. Remarkably enough, as we will see, the case d \geq 3 turns out to be "easy", with a crucial use of the convex structure of the dual problem.

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The case d = 2 is clearly linked to symplectic geometry and seems extremely difficult: a fascinating strategy has been developed by Shnirelman, by adding braid constraints to the minimization problem, which certainly deserves further investigations.

APPROXIMATE MINIMIZING GEODESICS

DEFINITION Let us assume D to be convex, fix $t_0=0,\ t_1=1$ and consider two maps $M_0, M_1\in VPM(D).$ We say that $(M_t^\varepsilon)\in SDiff(D)$ is an ϵ -minimizing geodesic if

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$$\int_{\mathsf{D}}\int_{t_0}^{t_1}|\frac{\mathsf{d}\mathsf{M}^\epsilon_\mathsf{t}(x)}{\mathsf{d}\mathsf{t}}|^2\;\mathsf{d}\mathsf{t}\mathsf{d}\mathsf{x}\leq\mathsf{d}(\mathsf{M}_0,\mathsf{M}_1)^2+\epsilon$$

$$\int_{\mathbf{D}} |\mathbf{M}_{\mathbf{1}}^{\epsilon}(\mathbf{x}) - \mathbf{M}_{\mathbf{1}}(\mathbf{x})|^{2} \mathbf{d}\mathbf{x} + \int_{\mathbf{D}} |\mathbf{M}_{\mathbf{0}}^{\epsilon}(\mathbf{x}) - \mathbf{M}_{\mathbf{0}}(\mathbf{x})|^{2} \mathbf{d}\mathbf{x} \leq \epsilon$$

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where $\frac{1}{2}d(M_0, M_1)^2$ denotes the maximal dual action. The existence of such approximations is in no way trivial and is a consequence of a key density results due to Shnirelman (GAFA 1994) that we will use later.

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MAIN THEOREM Let us assume D to be convex, with $d \ge 3$, fix $t_0 = 0$, $t_1 = 1$ and consider two maps $M_0, M_1 \in VPM(D)$. Then, there is a UNIQUE pressure-gradient ∇p_t such that for all $(M_t^{\epsilon}) \epsilon$ -minimizing geodesics, we have in the sense of distributions

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In addition p belongs to the functional space $L_t^2(BV_x)_{loc}$

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In addition p belongs to the functional space $L_t^2(BV_x)_{loc}$ This result essentially goes back to YB CPAM 1999, with important improvements in Ambrosio-Figalli ARMA 2008. It is a combination of solving the dual least action problem and using Shnirelman's density result for "generalized flows", GAFA 1994.

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MINIMIZING GEODESICS: FINAL COMMENTS 1) UNIQUENESS OF THE PRESSURE GRADIENT This is a remarkable feature of the theory. There is no equivalent result for finite dimensional configuration spaces such as SO(3), on which geodesic curves (for appropriate metrics) correspond to the motion of solid bodies in classical mechanics. We believe this strange phenomenon to be the consequence of the "hidden convexity" of the problem in dimension 3 and more. Of course thr case d=2 is completely different.

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2) LIMITED REGULARITY OF THE PRESSURE GRADIENT The pressure gradient was proven first (YB CPAM 1999) to be a locally bounded measure. Recently, Ambrosio and Figalli have shown a better L^2 integrability with respect to the time variable (with measure values in space). Recently, I found an explicit example (that goes back to Duchon and Robert) of solutions with a pressure field semi-concave in the space variable and not more. The optimal regularity, and its dependence on the data, are clearly challenging analytic issues.

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1) The Euler equations

L. Euler, opera omnia, seria secunda 12, p. 274 (in french, english translation available)

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Shirelman's papers: Math Sb USSR 1987, GAFA 1994,

Neretin, Math. Sb 1992, Brenier-Gangbo, Calc. Var. PDE 2003

4) Global theory of minimizing geodesics

Brenier's papers: JAMS 1990, ARMA 1993, CPAM 1999, Physica D 2008, arXiv 2010,

Duchon-Robert, Qu. Appl. M. 1992, Ambrosio-Figalli, Arma 2008