

Contact Solutions for Nonlinear Systems of PDE and Applications to the ∞ -Laplacian

Nikolaos Katzourakis

BCAM - Basque Center for Applied Mathematics

`nkatzourakis@bcamath.org`

Partial Differential Equations, Optimal Design and Numerics,
Benasque, 08/09/2011

Part of doctoral dissertation

“Nonlinear Systems of Elliptic Partial Differential Equations”

submitted at the Department of Mathematics, University of Athens,
Greece.

What is this talk about?

A new systematic theory of non-differentiable solutions which applies to fully nonlinear PDE systems.

What is this talk about?

A new systematic theory of non-differentiable solutions which applies to fully nonlinear PDE systems.

The model PDE system: ∞ -Laplacian Δ_∞

The ∞ -Laplacian: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,

(tensorial form:)

$$\Delta_\infty u := Du \otimes Du : D^2 u = 0$$

(index form:)

$$D_i u_\alpha D_j u_\beta D_{ij}^2 u_\beta = 0$$

$$1 \leq i, j \leq n, \quad 1 \leq \alpha, \beta \leq N.$$

(condensed form:)

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du$$

The model PDE system: ∞ -Laplacian Δ_∞

The ∞ -Laplacian: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,
(tensorial form:)

$$\Delta_\infty u := Du \otimes Du : D^2 u = 0$$

(index form:)

$$D_i u_\alpha D_j u_\beta D_{ij}^2 u_\beta = 0$$

$$1 \leq i, j \leq n, \quad 1 \leq \alpha, \beta \leq N.$$

(condensed form:)

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du$$

The model PDE system: ∞ -Laplacian Δ_∞

The ∞ -Laplacian: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,
(tensorial form:)

$$\Delta_\infty u := Du \otimes Du : D^2 u = 0$$

(index form:)

$$D_i u_\alpha D_j u_\beta D_{ij}^2 u_\beta = 0$$

$$1 \leq i, j \leq n, \quad 1 \leq \alpha, \beta \leq N.$$

(condensed form:)

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du$$

The model PDE system: ∞ -Laplacian Δ_∞

The ∞ -Laplacian: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,
(tensorial form:)

$$\Delta_\infty u := Du \otimes Du : D^2 u = 0$$

(index form:)

$$D_i u_\alpha D_j u_\beta D_{ij}^2 u_\beta = 0$$

$$1 \leq i, j \leq n, \quad 1 \leq \alpha, \beta \leq N.$$

(condensed form:)

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du$$

The model PDE system: ∞ -Laplacian Δ_∞

Δ_∞ : Quasilinear, 2nd order, Degenerate Elliptic operator in Non-Divergence form.

Δ_∞ arises

- As an “Euler-Lagrange” PDE in Calculus of Variations in L^∞ :

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_\Omega |Du|$$

for Absolute Minimizers, a version of local minimizers

- As the “limit” of p -Laplacian $\Delta_p u = \operatorname{Div}(|Du|^{p-2} Du)$ as $p \rightarrow \infty$:

$$\Delta_\infty + \frac{|Du|^2}{p-2} \Delta u = 0$$

The model PDE system: ∞ -Laplacian Δ_∞

Δ_∞ : Quasilinear, 2nd order, Degenerate Elliptic operator in Non-Divergence form.

Δ_∞ arises

- As an “Euler-Lagrange” PDE in Calculus of Variations in L^∞ :

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_\Omega |Du|$$

for **Absolute Minimizers**, a version of local minimizers

- As the “limit” of p -Laplacian $\Delta_p u = \operatorname{Div}(|Du|^{p-2} Du)$ as $p \rightarrow \infty$:

$$\Delta_\infty + \frac{|Du|^2}{p-2} \Delta u = 0$$

The model PDE system: ∞ -Laplacian Δ_∞

Δ_∞ : Quasilinear, 2nd order, Degenerate Elliptic operator in Non-Divergence form.

Δ_∞ arises

- As an “Euler-Lagrange” PDE in Calculus of Variations in L^∞ :

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_\Omega |Du|$$

for **Absolute Minimizers**, a version of local minimizers

- As the “limit” of p -Laplacian $\Delta_p u = \operatorname{Div}(|Du|^{p-2} Du)$ as $p \rightarrow \infty$:

$$\Delta_\infty + \frac{|Du|^2}{p-2} \Delta u = 0$$

- Implicitly in Geometric Evolution Problems (level-set approach):

$$u_t = \Delta u - \frac{\Delta_\infty u}{|Du|^2}$$

(term of the 1-Laplacian $\text{Div}(Du/|Du|)$)

- In Game Theory,
- In Dynamic Programming,
- In Image Processing,
- In Control Theory,
- ...

- Implicitly in Geometric Evolution Problems (level-set approach):

$$u_t = \Delta u - \frac{\Delta_\infty u}{|Du|^2}$$

(term of the 1-Laplacian $\text{Div}(Du/|Du|)$)

- In Game Theory,
- In Dynamic Programming,
- In Image Processing,
- In Control Theory,
- ...

The general Aronsson PDE system

If $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,

$$\mathcal{A}[u] := H_P(\cdot, u, Du) D(H(\cdot, u, Du)) = 0.$$

Solutions arise as Absolute Minimizers of the **supremal** functional

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_{x \in \Omega} H(x, u(x), Du(x))$$

placed in $L^\infty(\mathbb{R}^n)^N$.

If $H = H(Du)$, then

$$\mathcal{A}[u] = H_P(Du) \otimes H_P(Du) : D^2 u = 0$$

The general Aronsson PDE system

If $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,

$$\mathcal{A}[u] := H_P(\cdot, u, Du) D(H(\cdot, u, Du)) = 0.$$

Solutions arise as Absolute Minimizers of the supremal functional

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_{x \in \Omega} H(x, u(x), Du(x))$$

placed in $L^\infty(\mathbb{R}^n)^N$.

If $H = H(Du)$, then

$$\mathcal{A}[u] = H_P(Du) \otimes H_P(Du) : D^2u = 0$$

The general Aronsson PDE system

If $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,

$$\mathcal{A}[u] := H_P(\cdot, u, Du) D(H(\cdot, u, Du)) = 0.$$

Solutions arise as Absolute Minimizers of the **supremal** functional

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_{x \in \Omega} H(x, u(x), Du(x))$$

placed in $L^\infty(\mathbb{R}^n)^N$.

If $H = H(Du)$, then

$$\mathcal{A}[u] = H_P(Du) \otimes H_P(Du) : D^2 u = 0$$

The general Aronsson PDE system

If $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$,

$$\mathcal{A}[u] := H_P(\cdot, u, Du) D(H(\cdot, u, Du)) = 0.$$

Solutions arise as Absolute Minimizers of the **supremal** functional

$$E_\infty(u, \Omega) = \operatorname{ess\,sup}_{x \in \Omega} H(x, u(x), Du(x))$$

placed in $L^\infty(\mathbb{R}^n)^N$.

If $H = H(Du)$, then

$$\mathcal{A}[u] = H_P(Du) \otimes H_P(Du) : D^2u = 0$$

A startling problem: singular “solutions” of Δ_∞

The **scalar** Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}$ well studied in the last 20 years.

We want to solve the problem of **existence** of $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \subset \subset \mathbb{R}^n, \\ u = g & \text{on } \partial\Omega, \quad g \text{ Lipschitz.} \end{cases}$$

The **vector** Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ can not be studied rigorously!

Example. Let $u : \mathbb{R} \rightarrow \mathbb{R}^2$ be the curve:

$$u(x) := \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^\top dt$$

where $K \in C^0(\mathbb{R})$. Then, u is **Eikonal**:

$$|Du|^2 = 1.$$

Should be “ **∞ -Harmonic**”:

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du.$$

A startling problem: singular “solutions” of Δ_∞

The scalar Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}$ well studied in the last 20 years.

We want to solve the problem of existence of $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \subset\subset \mathbb{R}^n, \\ u = g & \text{on } \partial\Omega, \quad g \text{ Lipschitz.} \end{cases}$$

The vector Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ can not be studied rigorously!

Example. Let $u : \mathbb{R} \rightarrow \mathbb{R}^2$ be the curve:

$$u(x) := \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^\top dt$$

where $K \in C^0(\mathbb{R})$. Then, u is Eikonal:

$$|Du|^2 = 1.$$

Should be “ ∞ -Harmonic”:

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du.$$

A startling problem: singular “solutions” of Δ_∞

The scalar Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}$ well studied in the last 20 years.

We want to solve the problem of existence of $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \subset\subset \mathbb{R}^n, \\ u = g & \text{on } \partial\Omega, \quad g \text{ Lipschitz.} \end{cases}$$

The vector Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ can not be studied rigorously!

Example. Let $u : \mathbb{R} \rightarrow \mathbb{R}^2$ be the curve:

$$u(x) := \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^\top dt$$

where $K \in C^0(\mathbb{R})$. Then, u is Eikonal:

$$|Du|^2 = 1.$$

Should be “ ∞ -Harmonic”:

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du.$$

A startling problem: singular “solutions” of Δ_∞

The scalar Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}$ well studied in the last 20 years.

We want to solve the problem of existence of $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \subset \subset \mathbb{R}^n, \\ u = g & \text{on } \partial\Omega, \quad g \text{ Lipschitz.} \end{cases}$$

The vector Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ can not be studied rigorously!

Example. Let $u : \mathbb{R} \rightarrow \mathbb{R}^2$ be the curve:

$$u(x) := \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^\top dt$$

where $K \in C^0(\mathbb{R})$. Then, u is Eikonal:

$$|Du|^2 = 1.$$

Should be “ ∞ -Harmonic”:

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du.$$

A startling problem: singular “solutions” of Δ_∞

The scalar Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}$ well studied in the last 20 years.

We want to solve the problem of existence of $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \subset \subset \mathbb{R}^n, \\ u = g & \text{on } \partial\Omega, \quad g \text{ Lipschitz.} \end{cases}$$

The vector Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ can not be studied rigorously!

Example. Let $u : \mathbb{R} \rightarrow \mathbb{R}^2$ be the curve:

$$u(x) := \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^\top dt$$

where $K \in C^0(\mathbb{R})$. Then, u is **Eikonal**:

$$|Du|^2 = 1.$$

Should be “ ∞ -Harmonic”:

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du.$$

A startling problem: singular “solutions” of Δ_∞

The scalar Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}$ well studied in the last 20 years.

We want to solve the problem of existence of $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \subset\subset \mathbb{R}^n, \\ u = g & \text{on } \partial\Omega, \quad g \text{ Lipschitz.} \end{cases}$$

The vector Δ_∞ for $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ can not be studied rigorously!

Example. Let $u : \mathbb{R} \rightarrow \mathbb{R}^2$ be the curve:

$$u(x) := \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^\top dt$$

where $K \in C^0(\mathbb{R})$. Then, u is **Eikonal**:

$$|Du|^2 = 1.$$

Should be “ ∞ -Harmonic”:

$$\Delta_\infty u = D \left(\frac{1}{2} |Du|^2 \right) Du.$$

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has no classical solutions,
- Δ_∞ has no strong a.e. solutions,
- Δ_∞ has no weak solutions,
- Δ_∞ has no measure-theoretic solutions,
- Δ_∞ has no distributional solutions, and
- Δ_∞ has no viscosity solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has no classical solutions,
- Δ_∞ has no strong a.e. solutions,
- Δ_∞ has no weak solutions,
- Δ_∞ has no measure-theoretic solutions,
- Δ_∞ has no distributional solutions, and
- Δ_∞ has no viscosity solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has no classical solutions,
- Δ_∞ has no strong a.e. solutions,
- Δ_∞ has no weak solutions,
- Δ_∞ has no measure-theoretic solutions,
- Δ_∞ has no distributional solutions, and
- Δ_∞ has no viscosity solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has no classical solutions,
- Δ_∞ has no strong a.e. solutions,
- Δ_∞ has no weak solutions,
- Δ_∞ has no measure-theoretic solutions,
- Δ_∞ has no distributional solutions, and
- Δ_∞ has no viscosity solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the **vectorial** Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the vectorial Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

4. Contact Solutions for Fully Nonlinear Systems of PDE

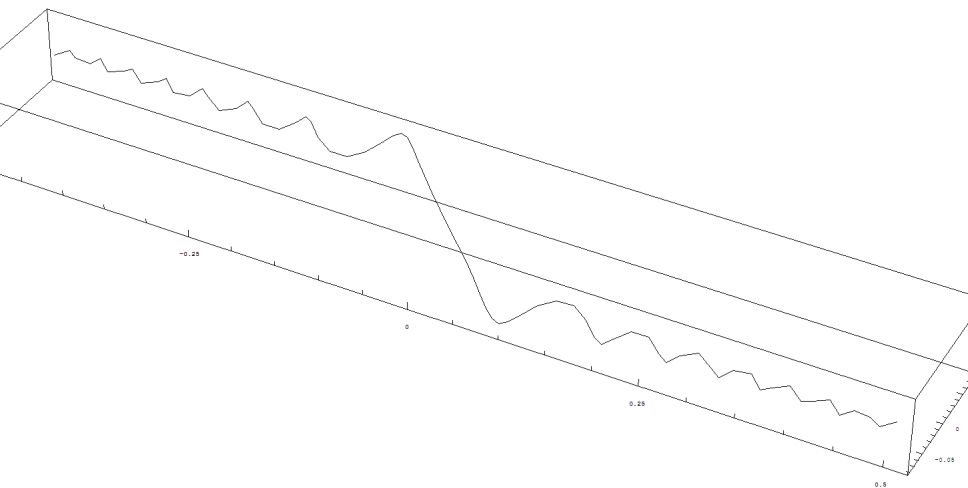
However, for appropriate K :

- $\nexists D^2u$ anywhere on \mathbb{R} !
- $\nexists D^2u$ as a Radon measure !
- $\exists D^2u$ only in \mathcal{D}' !

Generally, the **vectorial** Δ_∞ :

- Δ_∞ has **no classical** solutions,
- Δ_∞ has **no strong a.e.** solutions,
- Δ_∞ has **no weak** solutions,
- Δ_∞ has **no measure-theoretic** solutions,
- Δ_∞ has **no distributional** solutions, and
- Δ_∞ has **no viscosity** solutions.

A startling problem: singular “solutions” of Δ_∞



Simulation of the ∞ -Harmonic curve $u(x) = \int_0^x \left(\cos(K(t)), \sin(K(t)) \right)^T dt, u : \mathbb{R} \rightarrow \mathbb{R}^2$.

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Scalar PDE ($N = 1$): if $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $\Delta_\infty u = D_i u D_j u D_{ij}^2 u = 0$.

Well studied in the context of Viscosity Solutions ('90 - , existence and uniqueness for the Dirichlet problem, C^1 -regularity, ...).

Example (Aronsson '1984). Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be:

$$u(x, y) := |x|^{4/3} - |y|^{4/3}.$$

Then, u is $C^{1, \frac{1}{3}}$ and solves $\Delta_\infty u = 0$ only in the viscosity sense ($\nexists D^2 u$ on the axes).

Example (K. '2010). Let $H \in C^1(\mathbb{R}^n)$ be constant along $[a, b]$. Then:

$$u(x) := \frac{b + a^\top}{2} x + f\left(\frac{b - a^\top}{2} x\right).$$

is for all $f \in W_{loc}^{1, \infty}(\mathbb{R})$, $\|f\|_{L^\infty(\mathbb{R})} < 1$ a non- C^1 solution of $\mathcal{A}[u] = 0$ in the viscosity sense ($\nexists D^2 u$ anywhere).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Scalar PDE ($N = 1$): if $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $\Delta_\infty u = D_i u D_j u D_{ij}^2 u = 0$.

Well studied in the context of **Viscosity Solutions** ('90 - , existence and uniqueness for the Dirichlet problem, C^1 -regularity, ...).

Example (Aronsson '1984). Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be:

$$u(x, y) := |x|^{4/3} - |y|^{4/3}.$$

Then, u is $C^{1, \frac{1}{3}}$ and solves $\Delta_\infty u = 0$ only in the viscosity sense ($\nexists D^2 u$ on the axes).

Example (K. '2010). Let $H \in C^1(\mathbb{R}^n)$ be constant along $[a, b]$. Then:

$$u(x) := \frac{b + a^\top}{2} x + f\left(\frac{b - a^\top}{2} x\right).$$

is for all $f \in W_{loc}^{1, \infty}(\mathbb{R})$, $\|f\|_{L^\infty(\mathbb{R})} < 1$ a **non- C^1 solution** of $\mathcal{A}[u] = 0$ in the viscosity sense ($\nexists D^2 u$ anywhere).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Scalar PDE ($N = 1$): if $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $\Delta_\infty u = D_i u D_j u D_{ij}^2 u = 0$.

Well studied in the context of **Viscosity Solutions** ('90 - , existence and uniqueness for the Dirichlet problem, C^1 -regularity, ...).

Example (Aronsson '1984). Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be:

$$u(x, y) := |x|^{4/3} - |y|^{4/3}.$$

Then, u is $C^{1, \frac{1}{3}}$ and solves $\Delta_\infty u = 0$ only in the viscosity sense ($\nexists D^2 u$ on the axes).

Example (K. '2010). Let $H \in C^1(\mathbb{R}^n)$ be constant along $[a, b]$. Then:

$$u(x) := \frac{b + a^\top}{2} x + f\left(\frac{b - a^\top}{2} x\right).$$

is for all $f \in W_{loc}^{1, \infty}(\mathbb{R})$, $\|f\|_{L^\infty(\mathbb{R})} < 1$ a **non- C^1 solution** of $\mathcal{A}[u] = 0$ in the viscosity sense ($\nexists D^2 u$ anywhere).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Scalar PDE ($N = 1$): if $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $\Delta_\infty u = D_i u D_j u D_{ij}^2 u = 0$.

Well studied in the context of **Viscosity Solutions** ('90 - , existence and uniqueness for the Dirichlet problem, C^1 -regularity, ...).

Example (Aronsson '1984). Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be:

$$u(x, y) := |x|^{4/3} - |y|^{4/3}.$$

Then, u is $C^{1, \frac{1}{3}}$ and solves $\Delta_\infty u = 0$ only in the viscosity sense ($\nexists D^2 u$ on the axes).

Example (K. '2010). Let $H \in C^1(\mathbb{R}^n)$ be constant along $[a, b]$. Then:

$$u(x) := \frac{b + a^\top}{2} x + f\left(\frac{b - a^\top}{2} x\right).$$

is for all $f \in W_{loc}^{1, \infty}(\mathbb{R})$, $\|f\|_{L^\infty(\mathbb{R})} < 1$ a **non- C^1 solution** of $\mathcal{A}[u] = 0$ in the viscosity sense ($\nexists D^2 u$ anywhere).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Scalar PDE ($N = 1$): if $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $\Delta_\infty u = D_i u D_j u D_{ij}^2 u = 0$.

Well studied in the context of **Viscosity Solutions** ('90 - , existence and uniqueness for the Dirichlet problem, C^1 -regularity, ...).

Example (Aronsson '1984). Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be:

$$u(x, y) := |x|^{4/3} - |y|^{4/3}.$$

Then, u is $C^{1, \frac{1}{3}}$ and solves $\Delta_\infty u = 0$ only in the viscosity sense ($\nexists D^2 u$ on the axes).

Example (K. '2010). Let $H \in C^1(\mathbb{R}^n)$ be constant along $[a, b]$. Then:

$$u(x) := \frac{b + a^\top}{2} x + f\left(\frac{b - a^\top}{2} x\right).$$

is for all $f \in W_{loc}^{1, \infty}(\mathbb{R})$, $\|f\|_{L^\infty(\mathbb{R})} < 1$ a **non- C^1 solution** of $\mathcal{A}[u] = 0$ in the viscosity sense ($\nexists D^2 u$ anywhere).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Scalar PDE ($N = 1$): if $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $\Delta_\infty u = D_i u D_j u D_{ij}^2 u = 0$.

Well studied in the context of **Viscosity Solutions** ('90 - , existence and uniqueness for the Dirichlet problem, C^1 -regularity, ...).

Example (Aronsson '1984). Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be:

$$u(x, y) := |x|^{4/3} - |y|^{4/3}.$$

Then, u is $C^{1, \frac{1}{3}}$ and solves $\Delta_\infty u = 0$ only in the viscosity sense ($\nexists D^2 u$ on the axes).

Example (K. '2010). Let $H \in C^1(\mathbb{R}^n)$ be constant along $[a, b]$. Then:

$$u(x) := \frac{b + a^\top}{2} x + f\left(\frac{b - a^\top}{2} x\right).$$

is for all $f \in W_{loc}^{1, \infty}(\mathbb{R})$, $\|f\|_{L^\infty(\mathbb{R})} < 1$ a **non- C^1 solution of $\mathcal{A}[u] = 0$** in the viscosity sense ($\nexists D^2 u$ anywhere).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Idea behind Viscosity Solutions $u : \mathbb{R}^n \rightarrow \mathbb{R}$ of

$$F(x, u(x), Du(x), D^2u(x)) = 0 :$$

Use

Extremals min/max

and

Ellipticity of $F(\cdot, u, Du, D^2u) = 0$

to

“pass the derivatives” from u to a smooth test function ψ

via the

“Maximum Principle” Calculus

(a sort of “Nonlinear Distribution” theory).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Idea behind Viscosity Solutions $u : \mathbb{R}^n \rightarrow \mathbb{R}$ of

$$F(x, u(x), Du(x), D^2u(x)) = 0 :$$

Use

Extremals min/max

and

Ellipticity of $F(\cdot, u, Du, D^2u) = 0$

to

“pass the derivatives” from u to a smooth test function ψ

via the

“Maximum Principle” Calculus

(a sort of “Nonlinear Distribution” theory).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Idea behind Viscosity Solutions $u : \mathbb{R}^n \rightarrow \mathbb{R}$ of

$$F(x, u(x), Du(x), D^2u(x)) = 0 :$$

Use

Extremals min/max

and

Ellipticity of $F(\cdot, u, Du, D^2u) = 0$

to

“pass the derivatives” from u to a smooth test function ψ

via the

“Maximum Principle” Calculus

(a sort of “Nonlinear Distribution” theory).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Idea behind Viscosity Solutions $u : \mathbb{R}^n \rightarrow \mathbb{R}$ of

$$F(x, u(x), Du(x), D^2u(x)) = 0 :$$

Use

Extremals min/max

and

Ellipticity of $F(\cdot, u, Du, D^2u) = 0$

to

“pass the derivatives” from u to a smooth test function ψ

via the

“Maximum Principle” Calculus

(a sort of “Nonlinear Distribution” theory).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Idea behind Viscosity Solutions $u : \mathbb{R}^n \rightarrow \mathbb{R}$ of

$$F(x, u(x), Du(x), D^2u(x)) = 0 :$$

Use

Extremals min/max

and

Ellipticity of $F(\cdot, u, Du, D^2u) = 0$

to

“pass the derivatives” from u to a smooth test function ψ

via the

“Maximum Principle” Calculus

(a sort of “Nonlinear Distribution” theory).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Idea behind Viscosity Solutions $u : \mathbb{R}^n \rightarrow \mathbb{R}$ of

$$F(x, u(x), Du(x), D^2u(x)) = 0 :$$

Use

Extremals min/max

and

Ellipticity of $F(\cdot, u, Du, D^2u) = 0$

to

“pass the derivatives” from u to a smooth test function ψ

via the

“Maximum Principle” Calculus

(a sort of “Nonlinear Distribution” theory).

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Motivation of Viscosity Solutions: if $u : \mathbb{R}^n \rightarrow \mathbb{R}$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0, \quad (\text{PDE})$$

then if $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$ and $u - \psi$ has vanishing max at x :

$$u - \psi \leq (u - \psi)(x) = 0,$$

then

$$\begin{aligned} Du(x) &= D\psi(x), \\ D^2u(x) &\leq D^2\psi(x). \end{aligned}$$

Hence, if

$$X \mapsto F(\cdot, \cdot, \cdot, X) \text{ is monotone}$$

then

$$(\text{PDE}) \implies 0 \leq F(x, \psi(x), D\psi(x), D^2\psi(x)).$$

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Motivation of Viscosity Solutions: if $u : \mathbb{R}^n \rightarrow \mathbb{R}$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0, \quad (\text{PDE})$$

then if $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$ and $u - \psi$ has vanishing max at x :

$$u - \psi \leq (u - \psi)(x) = 0,$$

then

$$\begin{aligned} Du(x) &= D\psi(x), \\ D^2u(x) &\leq D^2\psi(x). \end{aligned}$$

Hence, if

$$X \mapsto F(\cdot, \cdot, \cdot, X) \text{ is monotone}$$

then

$$(\text{PDE}) \implies 0 \leq F(x, \psi(x), D\psi(x), D^2\psi(x)).$$

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Motivation of Viscosity Solutions: if $u : \mathbb{R}^n \rightarrow \mathbb{R}$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0, \quad (\text{PDE})$$

then if $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$ and $u - \psi$ has vanishing max at x :

$$u - \psi \leq (u - \psi)(x) = 0,$$

then

$$\begin{aligned} Du(x) &= D\psi(x), \\ D^2u(x) &\leq D^2\psi(x). \end{aligned}$$

Hence, if

$$X \mapsto F(\cdot, \cdot, \cdot, X) \text{ is monotone}$$

then

$$(\text{PDE}) \implies 0 \leq F(x, \psi(x), D\psi(x), D^2\psi(x)).$$

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Motivation of Viscosity Solutions: if $u : \mathbb{R}^n \rightarrow \mathbb{R}$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0, \quad (\text{PDE})$$

then if $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$ and $u - \psi$ has vanishing max at x :

$$u - \psi \leq (u - \psi)(x) = 0,$$

then

$$\begin{aligned} Du(x) &= D\psi(x), \\ D^2u(x) &\leq D^2\psi(x). \end{aligned}$$

Hence, if

$$X \mapsto F(\cdot, \cdot, \cdot, X) \text{ is monotone}$$

then

$$(\text{PDE}) \implies 0 \leq F(x, \psi(x), D\psi(x), D^2\psi(x)).$$

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Motivation of Viscosity Solutions: if $u : \mathbb{R}^n \rightarrow \mathbb{R}$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0, \quad (\text{PDE})$$

then if $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$ and $u - \psi$ has vanishing max at x :

$$u - \psi \leq (u - \psi)(x) = 0,$$

then

$$\begin{aligned} Du(x) &= D\psi(x), \\ D^2u(x) &\leq D^2\psi(x). \end{aligned}$$

Hence, if

$$X \mapsto F(\cdot, \cdot, \cdot, X) \text{ is monotone}$$

then

$$(\text{PDE}) \implies 0 \leq F(x, \psi(x), D\psi(x), D^2\psi(x)).$$

Motivation of Viscosity Solutions: if $u : \mathbb{R}^n \rightarrow \mathbb{R}$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0, \quad (\text{PDE})$$

then if $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$ and $u - \psi$ has vanishing max at x :

$$u - \psi \leq (u - \psi)(x) = 0,$$

then

$$\begin{aligned} Du(x) &= D\psi(x), \\ D^2u(x) &\leq D^2\psi(x). \end{aligned}$$

Hence, if

$$X \mapsto F(\cdot, \cdot, \cdot, X) \text{ is monotone}$$

then

$$(\text{PDE}) \implies 0 \leq F(x, \psi(x), D\psi(x), D^2\psi(x)).$$

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Definition of Viscosity Solutions: The function $u \in C^0(\mathbb{R}^n)$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0,$$

if for $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$

$$u - \psi \leq (u - \psi)(x) = 0,$$

$$u - \psi \geq (u - \psi)(x) = 0,$$

implies

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \geq 0,$$

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \leq 0.$$

Advantage:

Merely $C^0(\mathbb{R}^n)$ functions as PDE solutions!

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Definition of Viscosity Solutions: The function $u \in C^0(\mathbb{R}^n)$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0,$$

if for $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$

$$u - \psi \leq (u - \psi)(x) = 0,$$

$$u - \psi \geq (u - \psi)(x) = 0,$$

implies

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \geq 0,$$

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \leq 0.$$

Advantage:

Merely $C^0(\mathbb{R}^n)$ functions as PDE solutions!

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Definition of Viscosity Solutions: The function $u \in C^0(\mathbb{R}^n)$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0,$$

if for $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$

$$u - \psi \leq (u - \psi)(x) = 0,$$

$$u - \psi \geq (u - \psi)(x) = 0,$$

implies

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \geq 0,$$

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \leq 0.$$

Advantage:

Merely $C^0(\mathbb{R}^n)$ functions as PDE solutions!

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Definition of Viscosity Solutions: The function $u \in C^0(\mathbb{R}^n)$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0,$$

if for $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$

$$u - \psi \leq (u - \psi)(x) = 0,$$

$$u - \psi \geq (u - \psi)(x) = 0,$$

implies

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \geq 0,$$

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \leq 0.$$

Advantage:

Merely $C^0(\mathbb{R}^n)$ functions as PDE solutions!

A scalar digression: Δ_∞ for $N = 1$ & Viscosity Solutions

Definition of Viscosity Solutions: The function $u \in C^0(\mathbb{R}^n)$ solves

$$F(x, u(x), Du(x), D^2u(x)) = 0,$$

if for $x \in \mathbb{R}^n$, $\psi \in C^2(\mathbb{R}^n)$

$$u - \psi \leq (u - \psi)(x) = 0,$$

$$u - \psi \geq (u - \psi)(x) = 0,$$

implies

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \geq 0,$$

$$F(x, \psi(x), D\psi(x), D^2\psi(x)) \leq 0.$$

Advantage:

Merely $C^0(\mathbb{R}^n)$ functions as PDE solutions!

Exists a theory of non-differentiable solutions which applies to fully nonlinear systems of PDEs

$$F(\cdot, u, Du, D^2u) = 0, \quad u : \mathbb{R}^n \longrightarrow \mathbb{R}^N,$$

and

extends scalar Viscosity Solutions

to

$N > 1$

(without monotonicity, componentwise arguments, weak coupling, ...).

Exists a theory of non-differentiable solutions which applies to fully nonlinear systems of PDEs

$$F(\cdot, u, Du, D^2u) = 0, \quad u : \mathbb{R}^n \longrightarrow \mathbb{R}^N,$$

and

extends scalar Viscosity Solutions

to

$N > 1$

(without monotonicity, componentwise arguments, weak coupling, ...).

Exists a theory of non-differentiable solutions which applies to fully nonlinear systems of PDEs

$$F(\cdot, u, Du, D^2u) = 0, \quad u : \mathbb{R}^n \longrightarrow \mathbb{R}^N,$$

and

extends scalar Viscosity Solutions

to

$N > 1$

(without monotonicity, componentwise arguments, weak coupling, ...).

Exists a theory of non-differentiable solutions which applies to fully nonlinear systems of PDEs

$$F(\cdot, u, Du, D^2u) = 0, \quad u : \mathbb{R}^n \longrightarrow \mathbb{R}^N,$$

and

extends scalar Viscosity Solutions

to

$N > 1$

(without monotonicity, componentwise arguments, weak coupling, ...).

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

preserving working philosophy and most of flexibility of scalar theory.

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

preserving working philosophy and most of flexibility of scalar theory.

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

preserving working philosophy and most of flexibility of scalar theory.

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

preserving working philosophy and most of flexibility of scalar theory.

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

preserving working philosophy and most of flexibility of scalar theory.

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

preserving working philosophy and most of flexibility of scalar theory.

Key ingredient in the vector case $N > 1$:

exists an

Extremality Principle

applying to

Vector Functions $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$

which

Extends min/max to $N > 1$

and carries a

“Maximum Principle” calculus.

This allows to

develop a “Viscosity type” theory for PDE systems

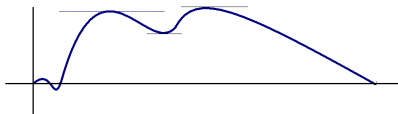
preserving working philosophy and most of flexibility of scalar theory.

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the Extremality Principle of Contact:

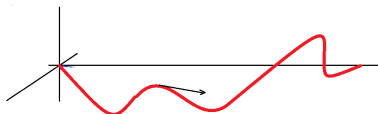
Functional notion, not pointwise!

Fact: If $u \in C_0^1(\Omega)$ and $u \not\equiv 0$, then u has interior extremum and $Du = 0$ there.



Example. If $\gamma \in C_0^1((-1, 1))^N$ unit speed curve $\gamma : (-1, 1) \rightarrow \mathbb{R}^N$, then

$$|\dot{\gamma}| \equiv 1 \neq 0.$$

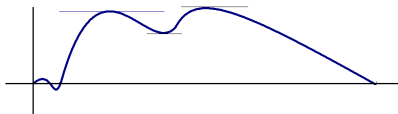


Hence, Vector Functions can NOT have classical "extrema"!

Peculiarities of the Extremality Principle of Contact:

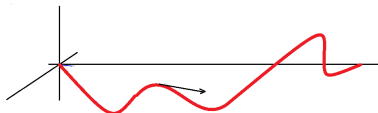
Functional notion, not pointwise!

Fact: If $u \in C_0^1(\Omega)$ and $u \not\equiv 0$, then u has interior extremum and $Du = 0$ there.



Example. If $\gamma \in C_0^1((-1, 1))^N$ unit speed curve $\gamma : (-1, 1) \rightarrow \mathbb{R}^N$, then

$$|\dot{\gamma}| \equiv 1 \neq 0.$$



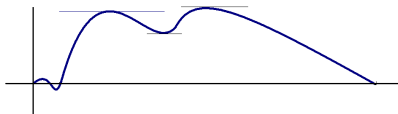
Hence, Vector Functions can NOT have classical "extrema"!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the Extremality Principle of Contact:

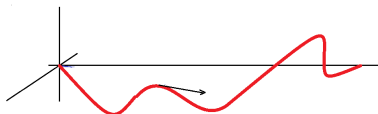
Functional notion, not pointwise!

Fact: If $u \in C_0^1(\Omega)$ and $u \not\equiv 0$, then u has interior extremum and $Du = 0$ there.



Example. If $\gamma \in C_0^1((-1, 1))^N$ unit speed curve $\gamma : (-1, 1) \rightarrow \mathbb{R}^N$, then

$$|\dot{\gamma}| \equiv 1 \neq 0.$$

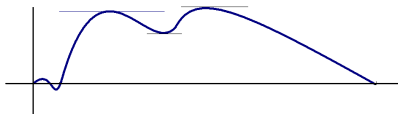


Hence, Vector Functions can NOT have classical "extrema"!

Peculiarities of the Extremality Principle of Contact:

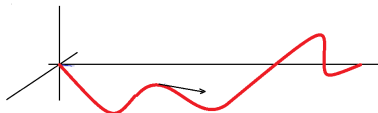
Functional notion, not pointwise!

Fact: If $u \in C_0^1(\Omega)$ and $u \not\equiv 0$, then u has interior extremum and $Du = 0$ there.



Example. If $\gamma \in C_0^1((-1, 1))^N$ unit speed curve $\gamma : (-1, 1) \rightarrow \mathbb{R}^N$, then

$$|\dot{\gamma}| \equiv 1 \neq 0.$$



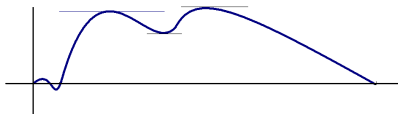
Hence, Vector Functions can NOT have classical "extrema"!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the Extremality Principle of Contact:

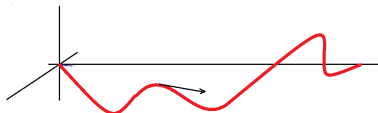
Functional notion, not pointwise!

Fact: If $u \in C_0^1(\Omega)$ and $u \not\equiv 0$, then u has interior extremum and $Du = 0$ there.



Example. If $\gamma \in C_0^1((-1, 1))^N$ unit speed curve $\gamma : (-1, 1) \rightarrow \mathbb{R}^N$, then

$$|\dot{\gamma}| \equiv 1 \neq 0.$$



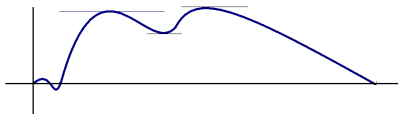
Hence, Vector Functions can NOT have classical "extrema"!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the Extremality Principle of Contact:

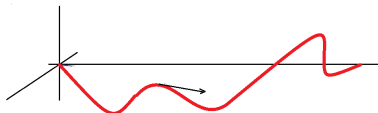
Functional notion, not pointwise!

Fact: If $u \in C_0^1(\Omega)$ and $u \not\equiv 0$, then u has interior extremum and $Du = 0$ there.



Example. If $\gamma \in C_0^1((-1, 1))^N$ unit speed curve $\gamma : (-1, 1) \rightarrow \mathbb{R}^N$, then

$$|\dot{\gamma}| \equiv 1 \neq 0.$$

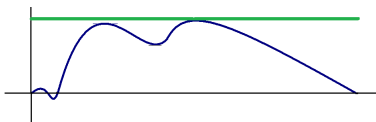


Hence, **Vector Functions can NOT have classical "extrema"!**

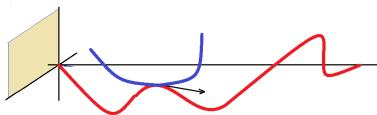
Peculiarities of the **Extremality Principle of Contact**:

Extremals are functions, not points!

Scalar case $N = 1$: Extremum at x is the point $u(x)$:



Vector case $N > 1$: Extremum at x is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$ passing through the point $u(x)$:

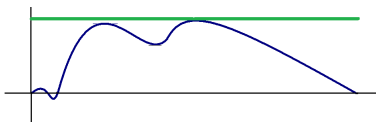


In the scalar case $\psi \equiv \text{constant}$.

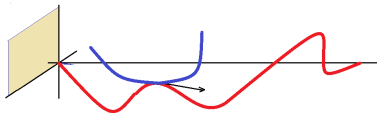
Peculiarities of the **Extremality Principle of Contact**:

Extremals are functions, not points!

Scalar case $N = 1$: Extremum at x is the point $u(x)$:



Vector case $N > 1$: Extremum at x is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$ passing through the point $u(x)$:

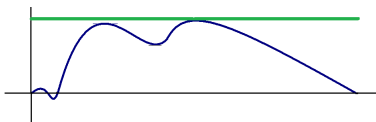


In the scalar case $\psi \equiv \text{constant}$.

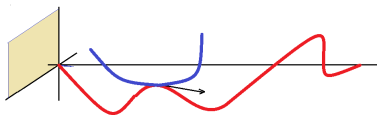
Peculiarities of the **Extremality Principle of Contact**:

Extremals are functions, not points!

Scalar case $N = 1$: Extremum at x is the point $u(x)$:



Vector case $N > 1$: Extremum at x is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$ passing through the point $u(x)$:

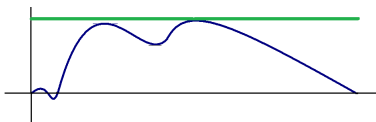


In the scalar case $\psi \equiv \text{constant}$.

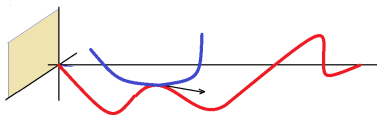
Peculiarities of the **Extremality Principle of Contact**:

Extremals are functions, not points!

Scalar case $N = 1$: Extremum at x is the point $u(x)$:



Vector case $N > 1$: Extremum at x is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$ passing through the point $u(x)$:

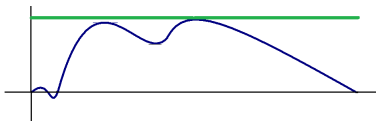


In the scalar case $\psi \equiv \text{constant}$.

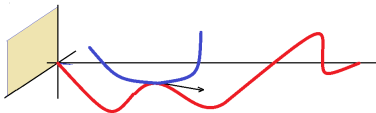
Peculiarities of the **Extremality Principle of Contact**:

Extremals are functions, not points!

Scalar case $N = 1$: Extremum at x is the point $u(x)$:



Vector case $N > 1$: Extremum at x is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$ passing through the point $u(x)$:



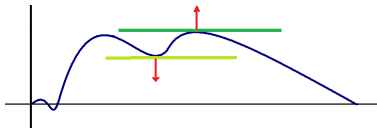
In the scalar case $\psi \equiv \text{constant}$.

Main Subject: Contact Solutions for systems of PDEs

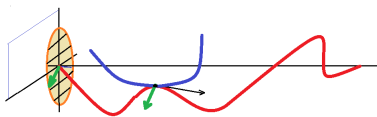
Peculiarities of the **Extremality Principle of Contact**:

Can not be characterized by ordering!

Scalar case $N = 1$: Maximum corresponds to $\xi = +1$ and minimum to $\xi = -1$



Vector case $N > 1$: Extremum in the direction $\xi \in \mathbb{S}^{N-1}$ is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$:



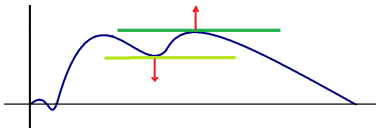
All the directions in the range need to be considered!

Main Subject: Contact Solutions for systems of PDEs

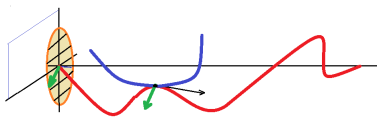
Peculiarities of the **Extremality Principle of Contact**:

Can not be characterized by ordering!

Scalar case $N = 1$: Maximum corresponds to $\xi = +1$ and minimum to $\xi = -1$



Vector case $N > 1$: Extremum in the direction $\xi \in \mathbb{S}^{N-1}$ is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$:



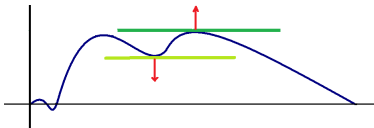
All the directions in the range need to be considered!

Main Subject: Contact Solutions for systems of PDEs

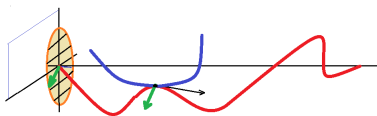
Peculiarities of the **Extremality Principle of Contact**:

Can not be characterized by ordering!

Scalar case $N = 1$: Maximum corresponds to $\xi = +1$ and minimum to $\xi = -1$



Vector case $N > 1$: Extremum in the direction $\xi \in \mathbb{S}^{N-1}$ is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

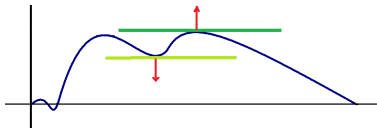


All the directions in the range need to be considered!

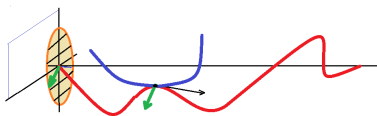
Peculiarities of the **Extremality Principle of Contact**:

Can not be characterized by ordering!

Scalar case $N = 1$: Maximum corresponds to $\xi = +1$ and minimum to $\xi = -1$



Vector case $N > 1$: Extremum in the **direction $\xi \in \mathbb{S}^{N-1}$** is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$:

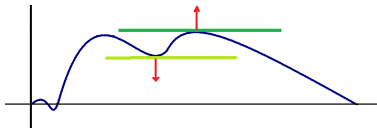


All the directions in the range need to be considered!

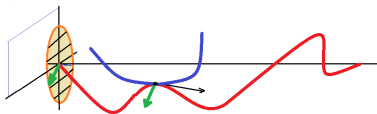
Peculiarities of the **Extremality Principle of Contact**:

Can not be characterized by ordering!

Scalar case $N = 1$: Maximum corresponds to $\xi = +1$ and minimum to $\xi = -1$



Vector case $N > 1$: Extremum in the **direction $\xi \in \mathbb{S}^{N-1}$** is the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R}^N$:



All the directions in the range need to be considered!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the **Extremality Principle of Contact**:

Has Order!

Scalar case $N = 1$: Let $u, \psi \in C^2(\mathbb{R}^n)$. Then

$$u - \psi \text{ has max at } x \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

Vector case $N > 1$: Let $u, \psi \in C^2(\mathbb{R}^n)^N$. Then

$$\psi \text{ is a 1st Order Extremal at } x \text{ along } \xi \implies D(u - \psi)(x) = 0$$

$$\psi \text{ is a 2nd Order Extremal at } x \text{ along } \xi \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

2nd order Contact is required to deduce appropriate Hessian inequality!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the **Extremality Principle of Contact**:

Has Order!

Scalar case $N = 1$: Let $u, \psi \in C^2(\mathbb{R}^n)$. Then

$$u - \psi \text{ has max at } x \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

Vector case $N > 1$: Let $u, \psi \in C^2(\mathbb{R}^n)^N$. Then

$$\psi \text{ is a 1st Order Extremal at } x \text{ along } \xi \implies D(u - \psi)(x) = 0$$

$$\psi \text{ is a 2nd Order Extremal at } x \text{ along } \xi \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

2nd order Contact is required to deduce appropriate Hessian inequality!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the **Extremality Principle of Contact**:

Has Order!

Scalar case $N = 1$: Let $u, \psi \in C^2(\mathbb{R}^n)$. Then

$$u - \psi \text{ has max at } x \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

Vector case $N > 1$: Let $u, \psi \in C^2(\mathbb{R}^n)^N$. Then

$$\psi \text{ is a 1st Order Extremal at } x \text{ along } \xi \implies D(u - \psi)(x) = 0$$

$$\psi \text{ is a 2nd Order Extremal at } x \text{ along } \xi \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

2nd order Contact is required to deduce appropriate Hessian inequality!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the **Extremality Principle of Contact**:

Has Order!

Scalar case $N = 1$: Let $u, \psi \in C^2(\mathbb{R}^n)$. Then

$$u - \psi \text{ has max at } x \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

Vector case $N > 1$: Let $u, \psi \in C^2(\mathbb{R}^n)^N$. Then

$$\psi \text{ is a 1st Order Extremal at } x \text{ along } \xi \implies D(u - \psi)(x) = 0$$

$$\psi \text{ is a 2nd Order Extremal at } x \text{ along } \xi \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

2nd order Contact is required to deduce appropriate Hessian inequality!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the **Extremality Principle of Contact**:

Has Order!

Scalar case $N = 1$: Let $u, \psi \in C^2(\mathbb{R}^n)$. Then

$$u - \psi \text{ has max at } x \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

Vector case $N > 1$: Let $u, \psi \in C^2(\mathbb{R}^n)^N$. Then

$$\psi \text{ is a 1st Order Extremal at } x \text{ along } \xi \implies D(u - \psi)(x) = 0$$

$$\psi \text{ is a 2nd Order Extremal at } x \text{ along } \xi \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

2nd order Contact is required to deduce appropriate Hessian inequality!

Main Subject: Contact Solutions for systems of PDEs

Peculiarities of the **Extremality Principle of Contact**:

Has Order!

Scalar case $N = 1$: Let $u, \psi \in C^2(\mathbb{R}^n)$. Then

$$u - \psi \text{ has max at } x \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

Vector case $N > 1$: Let $u, \psi \in C^2(\mathbb{R}^n)^N$. Then

$$\psi \text{ is a 1st Order Extremal at } x \text{ along } \xi \implies D(u - \psi)(x) = 0$$

$$\psi \text{ is a 2nd Order Extremal at } x \text{ along } \xi \implies \begin{cases} D(u - \psi)(x) = 0 \\ D^2(u - \psi)(x) \leq 0 \end{cases}$$

2nd order Contact is required to deduce appropriate Hessian inequality!

Peculiarities of the **Extremality Principle of Contact**:

The Order has a consequence:

The Extremality imposes partial regularity of lower-dimensional projections of the function u :

ψ has 1st order Contact with u at $x \implies$

u has a $C^{1/2}$ regular codimension-1 projection near x

ψ has 2nd order Contact with u at $x \implies$

u has a $C^{0,1}$ regular codimension-1 projection near x

All are result of vectorial obstructions which disappear if $N = 1$.

Peculiarities of the **Extremality Principle of Contact**:

The Order has a consequence:

The **Extremality** imposes partial regularity of lower-dimensional projections of the function u :

ψ has 1st order Contact with u at $x \implies$

u has a $C^{1/2}$ regular codimension-1 projection near x

ψ has 2nd order Contact with u at $x \implies$

u has a $C^{0,1}$ regular codimension-1 projection near x

All are result of vectorial obstructions which disappear if $N = 1$.

Peculiarities of the **Extremality Principle of Contact**:

The Order has a consequence:

The **Extremality** imposes partial regularity of lower-dimensional projections of the function u :

ψ has 1st order Contact with u at $x \implies$

u has a $C^{1/2}$ regular codimension-1 projection near x

ψ has 2nd order Contact with u at $x \implies$

u has a $C^{0,1}$ regular codimension-1 projection near x

All are result of vectorial obstructions which disappear if $N = 1$.

Peculiarities of the **Extremality Principle of Contact**:

The Order has a consequence:

The **Extremality** imposes partial regularity of lower-dimensional projections of the function u :

ψ has 1st order Contact with u at $x \implies$

u has a $C^{1/2}$ regular codimension-1 projection near x

ψ has 2nd order Contact with u at $x \implies$

u has a $C^{0,1}$ regular codimension-1 projection near x

All are result of vectorial obstructions which disappear if $N = 1$.

Peculiarities of the **Extremality Principle of Contact**:

The Order has a consequence:

The **Extremality** imposes partial regularity of lower-dimensional projections of the function u :

ψ has 1st order Contact with u at $x \implies$

u has a $C^{1/2}$ regular codimension-1 projection near x

ψ has 2nd order Contact with u at $x \implies$

u has a $C^{0,1}$ regular codimension-1 projection near x

All are result of vectorial obstructions which disappear if $N = 1$.

Peculiarities of the **Extremality Principle of Contact**:

The Order has a consequence:

The **Extremality** imposes partial regularity of lower-dimensional projections of the function u :

ψ has 1st order Contact with u at $x \implies$

u has a $C^{1/2}$ regular codimension-1 projection near x

ψ has 2nd order Contact with u at $x \implies$

u has a $C^{0,1}$ regular codimension-1 projection near x

All are result of vectorial obstructions which disappear if $N = 1$.

Main Subject: Contact Solutions for systems of PDEs

The Extremality Principle of Contact: easily understood via Jets
Sets of Pointwise Generalized Derivatives.

Definition (2nd Order Contact Jets). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $x \in \mathbb{R}^n$
and $\xi \in \mathbb{S}^{N-1}$. Then,

$$(P, \mathbf{X}) \in J^{2,\xi} u(x)$$

iff

$$\xi \vee \left[u(z) - u(x) - P(z-x) - \frac{1}{2} \mathbf{X} : (z-x) \otimes (z-x) \right] \leq o(|z-x|^2)$$

as $z \rightarrow x$.

Here “ \leq ” is taken in Symmetric tensors of $\mathbb{R}^N \otimes \mathbb{R}^N$ and

$$a \vee b := \frac{1}{2} (a \otimes b + b \otimes a).$$

Equivalence:

$$J^{2,\xi} u(x) = \left\{ (D\psi(x), D^2\psi(x)) : \psi \text{ is a Contact } \xi\text{-function} \right\}.$$

Main Subject: Contact Solutions for systems of PDEs

The Extremality Principle of Contact: easily understood via Jets
Sets of Pointwise Generalized Derivatives.

Definition(2nd Order Contact Jets). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $x \in \mathbb{R}^n$
and $\xi \in \mathbb{S}^{N-1}$. Then,

$$(P, \mathbf{X}) \in J^{2,\xi} u(x)$$

iff

$$\xi \vee \left[u(z) - u(x) - P(z-x) - \frac{1}{2} \mathbf{X} : (z-x) \otimes (z-x) \right] \leq o(|z-x|^2)$$

as $z \rightarrow x$.

Here “ \leq ” is taken in Symmetric tensors of $\mathbb{R}^N \otimes \mathbb{R}^N$ and

$$a \vee b := \frac{1}{2} (a \otimes b + b \otimes a).$$

Equivalence:

$$J^{2,\xi} u(x) = \left\{ (D\psi(x), D^2\psi(x)) : \psi \text{ is a Contact } \xi\text{-function} \right\}.$$

Main Subject: Contact Solutions for systems of PDEs

The Extremality Principle of Contact: easily understood via Jets
Sets of Pointwise Generalized Derivatives.

Definition(2nd Order Contact Jets). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $x \in \mathbb{R}^n$
and $\xi \in \mathbb{S}^{N-1}$. Then,

$$(P, \mathbf{X}) \in J^{2,\xi} u(x)$$

iff

$$\xi \vee \left[u(z) - u(x) - P(z-x) - \frac{1}{2} \mathbf{X} : (z-x) \otimes (z-x) \right] \leq o(|z-x|^2)$$

as $z \rightarrow x$.

Here " \leq " is taken in Symmetric tensors of $\mathbb{R}^N \otimes \mathbb{R}^N$ and

$$a \vee b := \frac{1}{2} (a \otimes b + b \otimes a).$$

Equivalence:

$$J^{2,\xi} u(x) = \left\{ (D\psi(x), D^2\psi(x)) : \psi \text{ is a Contact } \xi\text{-function} \right\}.$$

Main Subject: Contact Solutions for systems of PDEs

The Extremality Principle of Contact: easily understood via Jets
Sets of Pointwise Generalized Derivatives.

Definition (2nd Order Contact Jets). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $x \in \mathbb{R}^n$
and $\xi \in \mathbb{S}^{N-1}$. Then,

$$(P, \mathbf{X}) \in J^{2,\xi} u(x)$$

iff

$$\xi \vee \left[u(z) - u(x) - P(z-x) - \frac{1}{2} \mathbf{X} : (z-x) \otimes (z-x) \right] \leq o(|z-x|^2)$$

as $z \rightarrow x$.

Here “ \leq ” is taken in Symmetric tensors of $\mathbb{R}^N \otimes \mathbb{R}^N$ and

$$a \vee b := \frac{1}{2} (a \otimes b + b \otimes a).$$

Equivalence:

$$J^{2,\xi} u(x) = \left\{ (D\psi(x), D^2\psi(x)) : \psi \text{ is a Contact } \xi\text{-function} \right\}.$$

Main Subject: Contact Solutions for systems of PDEs

The Extremality Principle of Contact: easily understood via Jets
Sets of Pointwise Generalized Derivatives.

Definition (2nd Order Contact Jets). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $x \in \mathbb{R}^n$
and $\xi \in \mathbb{S}^{N-1}$. Then,

$$(P, \mathbf{X}) \in J^{2,\xi} u(x)$$

iff

$$\xi \vee \left[u(z) - u(x) - P(z-x) - \frac{1}{2} \mathbf{X} : (z-x) \otimes (z-x) \right] \leq o(|z-x|^2)$$

as $z \rightarrow x$.

Here “ \leq ” is taken in Symmetric tensors of $\mathbb{R}^N \otimes \mathbb{R}^N$ and

$$a \vee b := \frac{1}{2} (a \otimes b + b \otimes a).$$

Equivalence:

$$J^{2,\xi} u(x) = \left\{ (D\psi(x), D^2\psi(x)) : \psi \text{ is a Contact } \xi\text{-function} \right\}.$$

Main Subject: Contact Solutions for systems of PDEs

The PDE notions for systems:

Definition(Contact Solutions). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$. Then u solves

$$F(\cdot, u, Du, D^2u) = 0$$

when $u \in C^0(\mathbb{R}^n)^N$ and

$$(P, \mathbf{X}) \in J^{2,\xi}u(x) \implies \xi^\top F(x, u(x), P, \mathbf{X}) \geq 0.$$

for all $x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1}$.

Reduction to the scalar case $N = 1$: $\mathbb{S}^0 = \{-1, +1\}$ and

$$(P, \mathbf{X}) \in J^{2,\pm}u(x) \implies F(x, u(x), P, \mathbf{X}) \begin{matrix} \geq \\ \leq \end{matrix} 0.$$

$J^{2,\pm}u(x)$ coincide with the scalar semijets.

Main Subject: Contact Solutions for systems of PDEs

The PDE notions for systems:

Definition(Contact Solutions). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$. Then u solves

$$F(\cdot, u, Du, D^2u) = 0$$

when $u \in C^0(\mathbb{R}^n)^N$ and

$$(P, \mathbf{X}) \in J^{2,\xi}u(x) \implies \xi^\top F(x, u(x), P, \mathbf{X}) \geq 0.$$

for all $x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1}$.

Reduction to the scalar case $N = 1$: $\mathbb{S}^0 = \{-1, +1\}$ and

$$(P, \mathbf{X}) \in J^{2,\pm}u(x) \implies F(x, u(x), P, \mathbf{X}) \begin{matrix} \geq \\ \leq \end{matrix} 0.$$

$J^{2,\pm}u(x)$ coincide with the scalar semijets.

Main Subject: Contact Solutions for systems of PDEs

The PDE notions for systems:

Definition(Contact Solutions). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$. Then u solves

$$F(\cdot, u, Du, D^2u) = 0$$

when $u \in C^0(\mathbb{R}^n)^N$ and

$$(P, \mathbf{X}) \in J^{2,\xi}u(x) \implies \xi^\top F(x, u(x), P, \mathbf{X}) \geq 0.$$

for all $x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1}$.

Reduction to the scalar case $N = 1$: $\mathbb{S}^0 = \{-1, +1\}$ and

$$(P, \mathbf{X}) \in J^{2,\pm}u(x) \implies F(x, u(x), P, \mathbf{X}) \begin{matrix} \geq \\ \leq \end{matrix} 0.$$

$J^{2,\pm}u(x)$ coincide with the scalar semijets.

Main Subject: Contact Solutions for systems of PDEs

The PDE notions for systems:

Definition(Contact Solutions). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$. Then u solves

$$F(\cdot, u, Du, D^2u) = 0$$

when $u \in C^0(\mathbb{R}^n)^N$ and

$$(P, \mathbf{X}) \in J^{2,\xi}u(x) \implies \xi^\top F(x, u(x), P, \mathbf{X}) \geq 0.$$

for all $x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1}$.

Reduction to the scalar case $N = 1$: $\mathbb{S}^0 = \{-1, +1\}$ and

$$(P, \mathbf{X}) \in J^{2,\pm}u(x) \implies F(x, u(x), P, \mathbf{X}) \begin{matrix} \geq \\ \leq \end{matrix} 0.$$

$J^{2,\pm}u(x)$ coincide with the scalar semijets.

Main Subject: Contact Solutions for systems of PDEs

The PDE notions for systems:

Definition(Contact Solutions). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$. Then u solves

$$F(\cdot, u, Du, D^2u) = 0$$

when $u \in C^0(\mathbb{R}^n)^N$ and

$$(P, \mathbf{X}) \in J^{2,\xi}u(x) \implies \xi^\top F(x, u(x), P, \mathbf{X}) \geq 0.$$

for all $x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1}$.

Reduction to the scalar case $N = 1$: $\mathbb{S}^0 = \{-1, +1\}$ and

$$(P, \mathbf{X}) \in J^{2,\pm}u(x) \implies F(x, u(x), P, \mathbf{X}) \begin{matrix} \geq \\ \leq \end{matrix} 0.$$

$J^{2,\pm}u(x)$ coincide with the scalar semijets.

Main Subject: Contact Solutions for systems of PDEs

Contact Solutions completely compatible with Classical Solutions for Degenerate Elliptic systems:

Definition. The system $F(D^2u) = 0$ is Degenerate Elliptic when $[F(\mathbf{X}) - F(\mathbf{Y})]_{\alpha} [\mathbf{X} - \mathbf{Y}]_{\alpha ij} w_i w_j \geq 0$, $w \in \mathbb{R}^n$, i.e.

$$[F(\mathbf{X}) - F(\mathbf{Y})]^{\top} [\mathbf{X} - \mathbf{Y}] \geq 0$$

Example. (Quasi)linear case: $\mathbf{A} : D^2u = 0$, i.e.

$$\mathbf{A}_{\alpha i \beta j} : D_{ij}^2 u_{\beta} = 0.$$

D.E. $\iff \mathbf{A} : (\eta \otimes w) \otimes (\eta \otimes w) \geq 0 \iff \left\{ \begin{array}{l} \mathbf{A} \geq_{\otimes} 0 \\ \text{rank-1 positivity.} \end{array} \right.$

Example. A Fully nonlinear elliptic system:

$$F_{\alpha}(\cdot, u, Du, \sigma(D^2 u_{\alpha})) = 0.$$

Main Subject: Contact Solutions for systems of PDEs

Contact Solutions completely compatible with Classical Solutions for Degenerate Elliptic systems:

Definition. The system $F(D^2u) = 0$ is **Degenerate Elliptic** when $[F(\mathbf{X}) - F(\mathbf{Y})]_{\alpha} [\mathbf{X} - \mathbf{Y}]_{\alpha ij} w_i w_j \geq 0$, $w \in \mathbb{R}^n$, i.e.

$$[F(\mathbf{X}) - F(\mathbf{Y})]^{\top} [\mathbf{X} - \mathbf{Y}] \geq 0$$

Example. (Quasi)linear case: $\mathbf{A} : D^2u = 0$, i.e.

$$\mathbf{A}_{\alpha i \beta j} : D_{ij}^2 u_{\beta} = 0.$$

D.E. $\iff \mathbf{A} : (\eta \otimes w) \otimes (\eta \otimes w) \geq 0 \iff \left\{ \begin{array}{l} \mathbf{A} \geq_{\otimes} 0 \\ \text{rank-1 positivity.} \end{array} \right.$

Example. A Fully nonlinear elliptic system:

$$F_{\alpha}(\cdot, u, Du, \sigma(D^2 u_{\alpha})) = 0.$$

Main Subject: Contact Solutions for systems of PDEs

Contact Solutions completely compatible with Classical Solutions for Degenerate Elliptic systems:

Definition. The system $F(D^2u) = 0$ is **Degenerate Elliptic** when $[F(\mathbf{X}) - F(\mathbf{Y})]_{\alpha} [\mathbf{X} - \mathbf{Y}]_{\alpha ij} w_i w_j \geq 0$, $w \in \mathbb{R}^n$, i.e.

$$[F(\mathbf{X}) - F(\mathbf{Y})]^T [\mathbf{X} - \mathbf{Y}] \geq 0$$

Example. (Quasi)linear case: $\mathbf{A} : D^2u = 0$, i.e.

$$\mathbf{A}_{\alpha i \beta j} : D_{ij}^2 u_{\beta} = 0.$$

D.E. $\iff \mathbf{A} : (\eta \otimes w) \otimes (\eta \otimes w) \geq 0 \iff \left\{ \begin{array}{l} \mathbf{A} \geq_{\otimes} 0 \\ \text{rank-1 positivity.} \end{array} \right.$

Example. A Fully nonlinear elliptic system:

$$F_{\alpha}(\cdot, u, Du, \sigma(D^2 u_{\alpha})) = 0.$$

Main Subject: Contact Solutions for systems of PDEs

Contact Solutions completely compatible with Classical Solutions for Degenerate Elliptic systems:

Definition. The system $F(D^2u) = 0$ is **Degenerate Elliptic** when $[F(\mathbf{X}) - F(\mathbf{Y})]_{\alpha} [\mathbf{X} - \mathbf{Y}]_{\alpha ij} w_i w_j \geq 0$, $w \in \mathbb{R}^n$, i.e.

$$[F(\mathbf{X}) - F(\mathbf{Y})]^T [\mathbf{X} - \mathbf{Y}] \geq 0$$

Example. **(Quasi)linear case:** $\mathbf{A} : D^2u = 0$, i.e.

$$\mathbf{A}_{\alpha i \beta j} : D_{ij}^2 u_{\beta} = 0.$$

D.E. $\iff \mathbf{A} : (\eta \otimes w) \otimes (\eta \otimes w) \geq 0 \iff \left\{ \begin{array}{l} \mathbf{A} \geq_{\otimes} 0 \\ \text{rank-1 positivity.} \end{array} \right.$

Example. A Fully nonlinear elliptic system:

$$F_{\alpha}(\cdot, u, Du, \sigma(D^2 u_{\alpha})) = 0.$$

Main Subject: Contact Solutions for systems of PDEs

Contact Solutions completely compatible with Classical Solutions for Degenerate Elliptic systems:

Definition. The system $F(D^2u) = 0$ is **Degenerate Elliptic** when $[F(\mathbf{X}) - F(\mathbf{Y})]_{\alpha} [\mathbf{X} - \mathbf{Y}]_{\alpha ij} w_i w_j \geq 0$, $w \in \mathbb{R}^n$, i.e.

$$[F(\mathbf{X}) - F(\mathbf{Y})]^{\top} [\mathbf{X} - \mathbf{Y}] \geq 0$$

Example. (Quasi)linear case: $\mathbf{A} : D^2u = 0$, i.e.

$$\mathbf{A}_{\alpha i \beta j} : D_{ij}^2 u_{\beta} = 0.$$

D.E. $\iff \mathbf{A} : (\eta \otimes w) \otimes (\eta \otimes w) \geq 0 \iff \left\{ \begin{array}{l} \mathbf{A} \geq_{\otimes} 0 \\ \text{rank-1 positivity.} \end{array} \right.$

Example. A Fully nonlinear elliptic system:

$$F_{\alpha}(\cdot, u, Du, \sigma(D^2u_{\alpha})) = 0.$$

Main Subject: Contact Solutions for systems of PDEs

Contact Solutions completely compatible with Classical Solutions for Degenerate Elliptic systems:

Definition. The system $F(D^2u) = 0$ is **Degenerate Elliptic** when $[F(\mathbf{X}) - F(\mathbf{Y})]_{\alpha} [\mathbf{X} - \mathbf{Y}]_{\alpha ij} w_i w_j \geq 0$, $w \in \mathbb{R}^n$, i.e.

$$[F(\mathbf{X}) - F(\mathbf{Y})]^{\top} [\mathbf{X} - \mathbf{Y}] \geq 0$$

Example. (Quasi)linear case: $\mathbf{A} : D^2u = 0$, i.e.

$$\mathbf{A}_{\alpha i \beta j} : D_{ij}^2 u_{\beta} = 0.$$

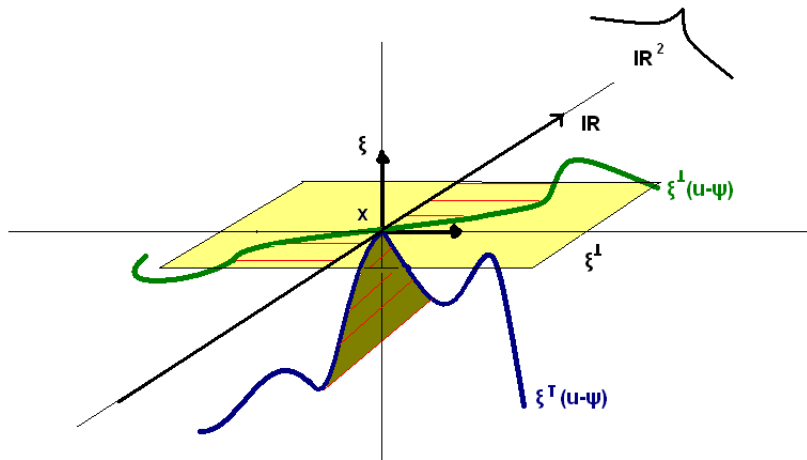
D.E. $\iff \mathbf{A} : (\eta \otimes w) \otimes (\eta \otimes w) \geq 0 \iff \left\{ \begin{array}{l} \mathbf{A} \geq_{\otimes} 0 \\ \text{rank-1 positivity.} \end{array} \right.$

Example. A Fully nonlinear elliptic system:

$$F_{\alpha}(\cdot, u, Du, \sigma(D^2u_{\alpha})) = 0.$$

Main Subject: Contact Solutions for systems of PDEs

Contact Jets *implicitly* Equivalent to Contact Functions.



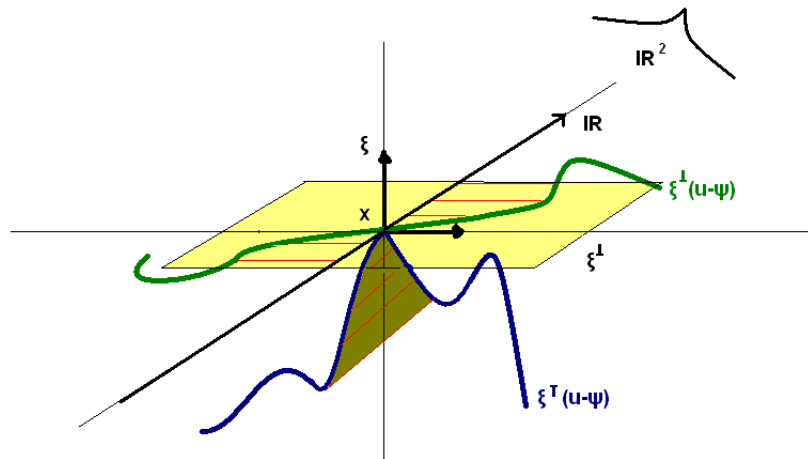
$\xi^T(u - \psi)$ has vanishing max at x

$\xi^\perp := I - \xi \otimes \xi$ ($\xi^\perp \equiv 0$ when $N = 1$, scalar case).

$|\xi^\perp(u - \psi)|$ controlled by $\xi^T(u - \psi)$ (through Cone functions)

Main Subject: Contact Solutions for systems of PDEs

Contact Jets *implicitly* Equivalent to Contact Functions.



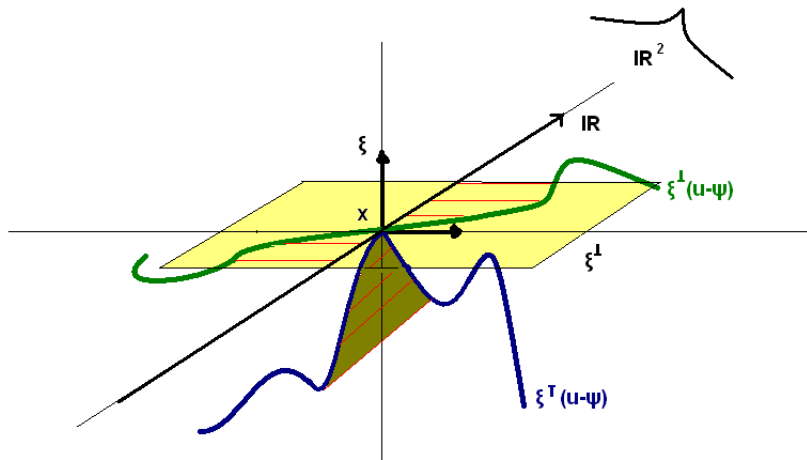
$\xi^T(u - \psi)$ has vanishing max at x

$\xi^\perp := I - \xi \otimes \xi$ ($\xi^\perp \equiv 0$ when $N = 1$, scalar case).

$|\xi^\perp(u - \psi)|$ controlled by $\xi^T(u - \psi)$ (through Cone functions)

Main Subject: Contact Solutions for systems of PDEs

Contact Jets *implicitly* Equivalent to Contact Functions.



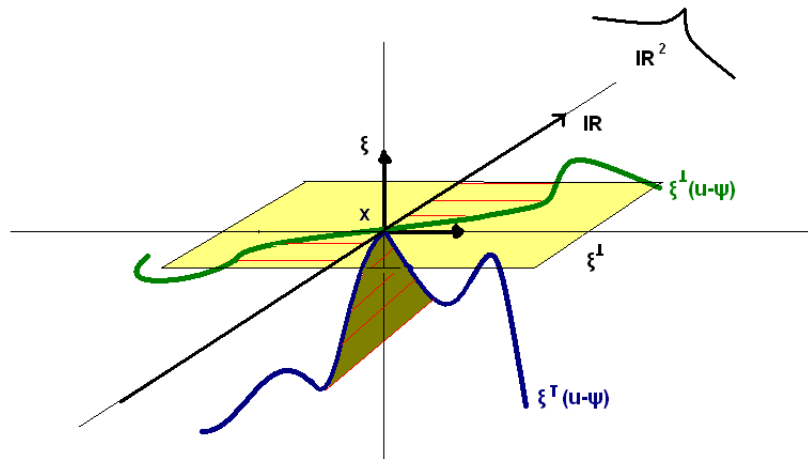
$\xi^T(u - \psi)$ has vanishing max at x

$\xi^\perp := I - \xi \otimes \xi$ ($\xi^\perp \equiv 0$ when $N = 1$, scalar case).

$|\xi^\perp(u - \psi)|$ controlled by $\xi^T(u - \psi)$ (through Cone functions)

Main Subject: Contact Solutions for systems of PDEs

Contact Jets *implicitly* Equivalent to Contact Functions.



$\xi^\top(u - \psi)$ has vanishing max at x

$\xi^\perp := I - \xi \otimes \xi$ ($\xi^\perp \equiv 0$ when $N = 1$, scalar case).

$|\xi^\perp(u - \psi)|$ controlled by $\xi^\top(u - \psi)$ (through Cone functions)

Main Subject: Contact Solutions for systems of PDEs

- **Equivalence** between J^2 and Extremality notions is **deeper** (Extremality contains partial regularity info, J^2 does not).
- **Extremality** is characterized by the “**Contact**” **Principle calculus**: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $\exists Du(x), D^2u(x)$ & $\psi \in C^2(\mathbb{R}^n)^N$

$$\psi \text{ is 2nd order Contact } \Leftrightarrow \begin{cases} D(u - \psi)(x) = 0 \\ \xi \vee D^2(u - \psi)(x) \leq_{\otimes} 0 \end{cases}$$

- Similarities with scalar case **formal**. Finer structure exists:

$F(\cdot, u, Du) = 0$ requires $C^{1/2}$ codimension-1 partial regularity,
 $F(\cdot, u, Du, D^2u) = 0$ requires $C^{0,1}$ codimension-1 partial regularity.



Only “1/2” of the derivatives can be interpreted weakly,
the rest “1/2” must exist classically.

If $N = 1$ obstructions disappear, only C^0 required (Viscosity).

Main Subject: Contact Solutions for systems of PDEs

- **Equivalence** between J^2 and Extremality notions is **deeper** (Extremality contains partial regularity info, J^2 does not).
- **Extremality** is characterized by the **"Contact" Principle calculus**: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $\exists Du(x), D^2u(x)$ & $\psi \in C^2(\mathbb{R}^n)^N$

$$\psi \text{ is 2nd order Contact } \xi\text{-Function of } u \text{ at } x \Leftrightarrow \begin{cases} D(u - \psi)(x) = 0 \\ \xi \vee D^2(u - \psi)(x) \leq_{\otimes} 0 \end{cases}$$

- Similarities with scalar case **formal**. Finer structure exists:

$F(\cdot, u, Du) = 0$ requires $C^{1/2}$ codimension-1 partial regularity,
 $F(\cdot, u, Du, D^2u) = 0$ requires $C^{0,1}$ codimension-1 partial regularity.



Only "1/2" of the derivatives can be interpreted weakly,
the rest "1/2" must exist classically.

If $N = 1$ obstructions disappear, only C^0 required (Viscosity).

Main Subject: Contact Solutions for systems of PDEs

- **Equivalence** between J^2 and Extremality notions is **deeper** (Extremality contains partial regularity info, J^2 does not).
- **Extremality** is characterized by the **“Contact” Principle calculus**: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $\exists Du(x), D^2u(x)$ & $\psi \in C^2(\mathbb{R}^n)^N$

$$\psi \text{ is 2nd order Contact } \xi\text{-Function of } u \text{ at } x \Leftrightarrow \begin{cases} D(u - \psi)(x) = 0 \\ \xi \vee D^2(u - \psi)(x) \leq_{\otimes} 0 \end{cases}$$

- Similarities with scalar case **formal**. Finer structure exists:

$F(\cdot, u, Du) = 0$ requires $C^{1/2}$ codimension-1 partial regularity,
 $F(\cdot, u, Du, D^2u) = 0$ requires $C^{0,1}$ codimension-1 partial regularity.



Only “1/2” of the derivatives can be interpreted weakly,
the rest “1/2” must exist classically.

If $N = 1$ obstructions disappear, only C^0 required (Viscosity).

Main Subject: Contact Solutions for systems of PDEs

- **Equivalence** between J^2 and Extremality notions is **deeper** (Extremality contains partial regularity info, J^2 does not).
- **Extremality** is characterized by the **“Contact” Principle calculus**: if $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$, $\exists Du(x), D^2u(x)$ & $\psi \in C^2(\mathbb{R}^n)^N$

$$\psi \text{ is 2nd order Contact } \Leftrightarrow \begin{cases} D(u - \psi)(x) = 0 \\ \xi \vee D^2(u - \psi)(x) \leq_{\otimes} 0 \end{cases}$$

- Similarities with scalar case **formal**. Finer structure exists:

$F(\cdot, u, Du) = 0$ requires $C^{1/2}$ codimension-1 partial regularity,
 $F(\cdot, u, Du, D^2u) = 0$ requires $C^{0,1}$ codimension-1 partial regularity.



Only “1/2” of the derivatives can be interpreted weakly,
the rest “1/2” must exist classically.

If $N = 1$ obstructions disappear, only C^0 required (Viscosity).

Application 1: Fundamental Solutions of Δ_∞ are Eikonal

- **Fundamental Solutions** of scalar Δ_∞ for $N = 1$: **Cones**.
- **Fundamental Solutions** of vector Δ_∞ for $N > 1$: **Generalized “Twisted Cones”**:

Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ be radial. Then, $\Delta_\infty u = 0$ iff

$$u(z) := u_0 + L \int_0^{|z-x|} \nu(t) dt,$$

$u_0 \in \mathbb{R}^N$, $L \geq 0$ $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ curve in the sphere.

Fundamental Solutions of Δ_∞ are non-differentiable (at the “vertex” x) **Contact Solutions of the Eikonal PDE:**

$$|Du|^2 - L^2 = 0$$

If $N = 1$ then $\nu \equiv \pm 1$ and $u(z) = u_0 \pm L|z - x|$.
Cones are Viscosity Solutions of $|Du|^2 - L^2 = 0$.

Application 1: Fundamental Solutions of Δ_∞ are Eikonal

- Fundamental Solutions of scalar Δ_∞ for $N = 1$: Cones.
- Fundamental Solutions of vector Δ_∞ for $N > 1$: Generalized “Twisted Cones”:

Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ be radial. Then, $\Delta_\infty u = 0$ iff

$$u(z) := u_0 + L \int_0^{|z-x|} \nu(t) dt,$$

$u_0 \in \mathbb{R}^N$, $L \geq 0$ $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ curve in the sphere.

Fundamental Solutions of Δ_∞ are non-differentiable (at the “vertex” x) Contact Solutions of the Eikonal PDE:

$$|Du|^2 - L^2 = 0$$

If $N = 1$ then $\nu \equiv \pm 1$ and $u(z) = u_0 \pm L|z - x|$.
Cones are Viscosity Solutions of $|Du|^2 - L^2 = 0$.

Application 1: Fundamental Solutions of Δ_∞ are Eikonal

- Fundamental Solutions of scalar Δ_∞ for $N = 1$: Cones.
- Fundamental Solutions of vector Δ_∞ for $N > 1$: Generalized “Twisted Cones”:

Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ be radial. Then, $\Delta_\infty u = 0$ iff

$$u(z) := u_0 + L \int_0^{|z-x|} \nu(t) dt,$$

$u_0 \in \mathbb{R}^N$, $L \geq 0$ $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ curve in the sphere.

Fundamental Solutions of Δ_∞ are non-differentiable (at the “vertex” x) Contact Solutions of the Eikonal PDE:

$$|Du|^2 - L^2 = 0$$

If $N = 1$ then $\nu \equiv \pm 1$ and $u(z) = u_0 \pm L|z - x|$.
Cones are Viscosity Solutions of $|Du|^2 - L^2 = 0$.

Application 1: Fundamental Solutions of Δ_∞ are Eikonal

- Fundamental Solutions of scalar Δ_∞ for $N = 1$: Cones.
- Fundamental Solutions of vector Δ_∞ for $N > 1$: Generalized “Twisted Cones”:

Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ be radial. Then, $\Delta_\infty u = 0$ iff

$$u(z) := u_0 + L \int_0^{|z-x|} \nu(t) dt,$$

$u_0 \in \mathbb{R}^N$, $L \geq 0$ $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ curve in the sphere.

Fundamental Solutions of Δ_∞ are non-differentiable (at the “vertex” x) Contact Solutions of the Eikonal PDE:

$$|Du|^2 - L^2 = 0$$

If $N = 1$ then $\nu \equiv \pm 1$ and $u(z) = u_0 \pm L|z - x|$.
Cones are Viscosity Solutions of $|Du|^2 - L^2 = 0$.

Application 1: Fundamental Solutions of Δ_∞ are Eikonal

- Fundamental Solutions of scalar Δ_∞ for $N = 1$: Cones.
- Fundamental Solutions of vector Δ_∞ for $N > 1$: Generalized “Twisted Cones”:

Let $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ be radial. Then, $\Delta_\infty u = 0$ iff

$$u(z) := u_0 + L \int_0^{|z-x|} \nu(t) dt,$$

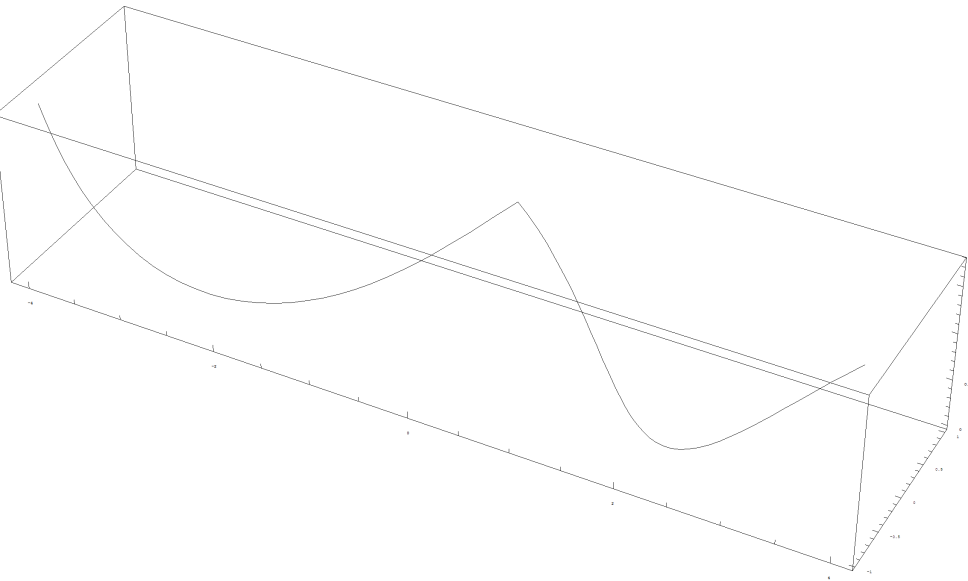
$u_0 \in \mathbb{R}^N$, $L \geq 0$ $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ curve in the sphere.

Fundamental Solutions of Δ_∞ are non-differentiable (at the “vertex” x)
Contact Solutions of the Eikonal PDE:

$$|Du|^2 - L^2 = 0$$

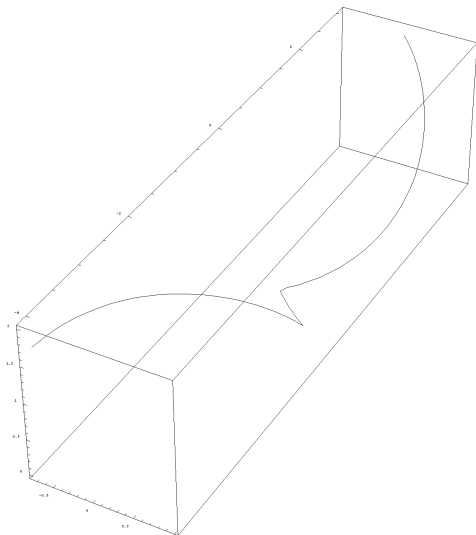
If $N = 1$ then $\nu \equiv \pm 1$ and $u(z) = u_0 \pm L|z - x|$.
Cones are Viscosity Solutions of $|Du|^2 - L^2 = 0$.

Application 1: Fundamental Solutions of Δ_∞ are Eikonal



The simplest Fundamental Solution $u : \mathbb{R} \rightarrow \mathbb{R}^2$ of Δ_∞ .

Application 1: Fundamental Solutions of Δ_∞ are Eikonal



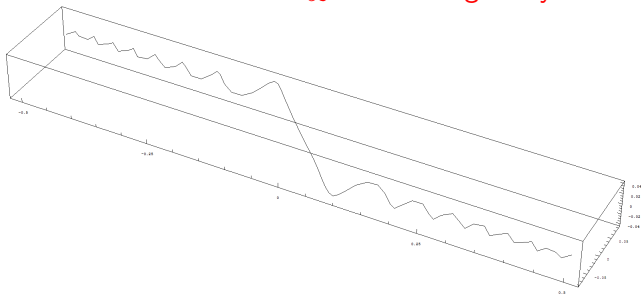
The simplest Fundamental Solution $u : \mathbb{R} \rightarrow \mathbb{R}^2$ of Δ_∞ .

Application 2: A class of $C^{1, \frac{1}{2}+}$ ∞ -Harmonic Functions

If $w \in \mathbb{R}^n$, $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ Lipschitz curve in the sphere,
 $K \in C^{\frac{1}{2}+}(\mathbb{R})$, then

$$u(z) := \int_0^{w^T z} \nu(K(t)) dt$$

defines a Contact solution of $\Delta_\infty u = 0$ of regularity $C^{1, \frac{1}{2}+}(\mathbb{R})^N$.



For appropriate K , $C^{1, \frac{1}{2}+}$ is the optimal possible regularity!

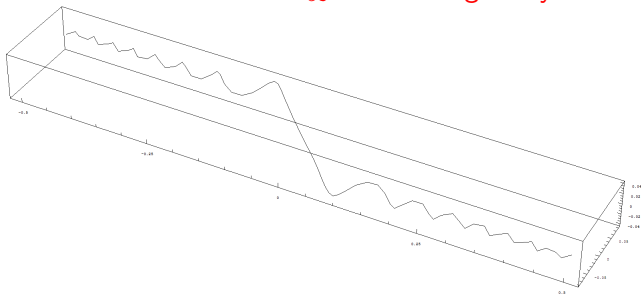
Arise as classical solutions of Eikonal PDE $|Du|^2 - 1 = 0$.

Application 2: A class of $C^{1, \frac{1}{2}+}$ ∞ -Harmonic Functions

If $w \in \mathbb{R}^n$, $\nu : (0, \infty) \rightarrow \mathbb{S}^{N-1}$ Lipschitz curve in the sphere,
 $K \in C^{\frac{1}{2}+}(\mathbb{R})$, then

$$u(z) := \int_0^{w^T z} \nu(K(t)) dt$$

defines a Contact solution of $\Delta_\infty u = 0$ of regularity $C^{1, \frac{1}{2}+}(\mathbb{R})^N$.



For appropriate K , $C^{1, \frac{1}{2}+}$ is the optimal possible regularity!

Arise as classical solutions of Eikonal PDE $|Du|^2 - 1 = 0$.

Application 3: Pseudo-Gradient Flows for Δ_∞

Smooth Case. Let $u \in C^2(\mathbb{R}^n)^N$. Then, $\Delta_\infty u = 0$ iff $\forall x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1} \exists$ maximal curve

$$\begin{cases} \dot{\gamma}(t) = \xi^\top Du(\gamma(t)), \\ \gamma(0) = x, \end{cases}$$

such that

$$\begin{cases} |Du(\gamma(t))| = |Du(x)|, \quad t \in \mathbb{R}, \\ t \mapsto \xi^\top u(\gamma(t)) \text{ increasing.} \end{cases}$$

Follows from

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} (|Du(\gamma(t))|^2) &= \xi^\top \Delta_\infty u(\gamma(t)), \\ \frac{d}{dt} (\xi^\top u(\gamma(t))) &= |\xi^\top Du(\gamma(t))|^2. \end{aligned}$$

Application 3: Pseudo-Gradient Flows for Δ_∞

Smooth Case. Let $u \in C^2(\mathbb{R}^n)^N$. Then, $\Delta_\infty u = 0$ iff $\forall x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1} \exists$ maximal curve

$$\begin{cases} \dot{\gamma}(t) = \xi^\top Du(\gamma(t)), \\ \gamma(0) = x, \end{cases}$$

such that

$$\begin{cases} |Du(\gamma(t))| = |Du(x)|, \quad t \in \mathbb{R}, \\ t \mapsto \xi^\top u(\gamma(t)) \text{ increasing.} \end{cases}$$

Follows from

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} (|Du(\gamma(t))|^2) &= \xi^\top \Delta_\infty u(\gamma(t)), \\ \frac{d}{dt} (\xi^\top u(\gamma(t))) &= |\xi^\top Du(\gamma(t))|^2. \end{aligned}$$

Application 3: Pseudo-Gradient Flows for Δ_∞

Smooth Case. Let $u \in C^2(\mathbb{R}^n)^N$. Then, $\Delta_\infty u = 0$ iff $\forall x \in \mathbb{R}^n$, $\xi \in \mathbb{S}^{N-1} \exists$ maximal curve

$$\begin{cases} \dot{\gamma}(t) = \xi^\top Du(\gamma(t)), \\ \gamma(0) = x, \end{cases}$$

such that

$$\begin{cases} |Du(\gamma(t))| = |Du(x)|, \quad t \in \mathbb{R}, \\ t \mapsto \xi^\top u(\gamma(t)) \text{ increasing.} \end{cases}$$

Follows from

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} (|Du(\gamma(t))|^2) &= \xi^\top \Delta_\infty u(\gamma(t)), \\ \frac{d}{dt} (\xi^\top u(\gamma(t))) &= |\xi^\top Du(\gamma(t))|^2. \end{aligned}$$

Application 3: Pseudo-Gradient Flows for Δ_∞

Also, if $\eta \in \mathbb{S}^{N-1}$:

$$\frac{1}{2} \frac{d^2}{dt^2} \left(\xi^\top u(\gamma(t)) \right) = \xi^\top \Delta_\infty u(\gamma(t)),$$

$$\frac{d}{dt} \left(\eta^\top u(\gamma(t)) \right) = \left(\xi \otimes \eta : Du(Du)^\top \right) (\gamma(t)),$$

$$\frac{d^2}{dt^2} \left(\eta^\top u(\gamma(t)) \right) = D(\xi^\top u)^\top D \left(\xi \otimes \eta : Du(Du)^\top \right) (\gamma(t)).$$

General Case. Let $u \in C^0(\mathbb{R}^n)^N$. Then,

$\Delta_\infty u = 0$ in Contact sense iff similar pseudo-gradient flows exist.

They characterize ∞ -Harmonicity.

Also, if $\eta \in \mathbb{S}^{N-1}$:

$$\frac{1}{2} \frac{d^2}{dt^2} \left(\xi^\top u(\gamma(t)) \right) = \xi^\top \Delta_\infty u(\gamma(t)),$$

$$\frac{d}{dt} \left(\eta^\top u(\gamma(t)) \right) = \left(\xi \otimes \eta : Du(Du)^\top \right) (\gamma(t)),$$

$$\frac{d^2}{dt^2} \left(\eta^\top u(\gamma(t)) \right) = D(\xi^\top u)^\top D \left(\xi \otimes \eta : Du(Du)^\top \right) (\gamma(t)).$$

General Case. Let $u \in C^0(\mathbb{R}^n)^N$. Then,

$\Delta_\infty u = 0$ in Contact sense iff similar pseudo-gradient flows exist.

They characterize ∞ -Harmonicity.

Existence of ∞ -Harmonic Vector Functions with prescribed boundary values:

- **Problem:** Exists a Lipschitz Contact Solution $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ to the Dirichlet Problem for the ∞ -Laplacian

$$\begin{cases} \Delta_{\infty} u = 0, & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

for $\Omega \subset \subset \mathbb{R}^n$ and g Lipschitz.

- **Method:** Employ stability under limits, interpret p -Harmonic functions as Contact solutions and employ $\Delta_p \rightarrow \Delta_{\infty}$ as $p \rightarrow \infty$.

Existence of ∞ -Harmonic Vector Functions with prescribed boundary values:

- **Problem:** Exists a Lipschitz Contact Solution $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ to the Dirichlet Problem for the ∞ -Laplacian

$$\begin{cases} \Delta_{\infty} u = 0, & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

for $\Omega \subset \subset \mathbb{R}^n$ and g Lipschitz.

- **Method:** Employ stability under limits, interpret p -Harmonic functions as Contact solutions and employ $\Delta_p \rightarrow \Delta_{\infty}$ as $p \rightarrow \infty$.

Existence of ∞ -Harmonic Vector Functions with prescribed boundary values:

- **Problem:** Exists a Lipschitz Contact Solution $u : \mathbb{R}^n \rightarrow \mathbb{R}^N$ to the Dirichlet Problem for the ∞ -Laplacian

$$\begin{cases} \Delta_\infty u = 0, & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

for $\Omega \subset \subset \mathbb{R}^n$ and g Lipschitz.

- **Method:** Employ stability under limits, interpret p -Harmonic functions as Contact solutions and employ $\Delta_p \rightarrow \Delta_\infty$ as $p \rightarrow \infty$.

THANK YOU !!!