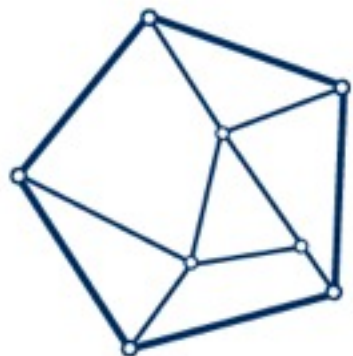


# Clustering Wedges: An Alternative Approach to Measuring $H(z)$ and $D_A(z)$

**Eyal Kazin**

In collaboration with:

Tamara **Davis**, Chris **Blake**, Ariel **Sánchez**



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- For the **non-expert**:
  - How we **measure** the **geometry** of the Universe with galaxy clustering
  - In other words: the Alcock-Paczynski test on the Baryonic Acoustic Feature to constrain  **$H(z)$ ,  $D_A(z)$**
- For the **expert**:
  - practical aspects of **binning** your correlation functions: Multipoles, **Wedges**,  $RR(\mu)$

For usage of data, mock catalogues:

Marc **Manera**, Cameron **McBride**, The Sloan Digital Sky Survey, The WiggleZ Dark Energy Survey

## The WiggleZ Group





For usage of data, mock catalogues:

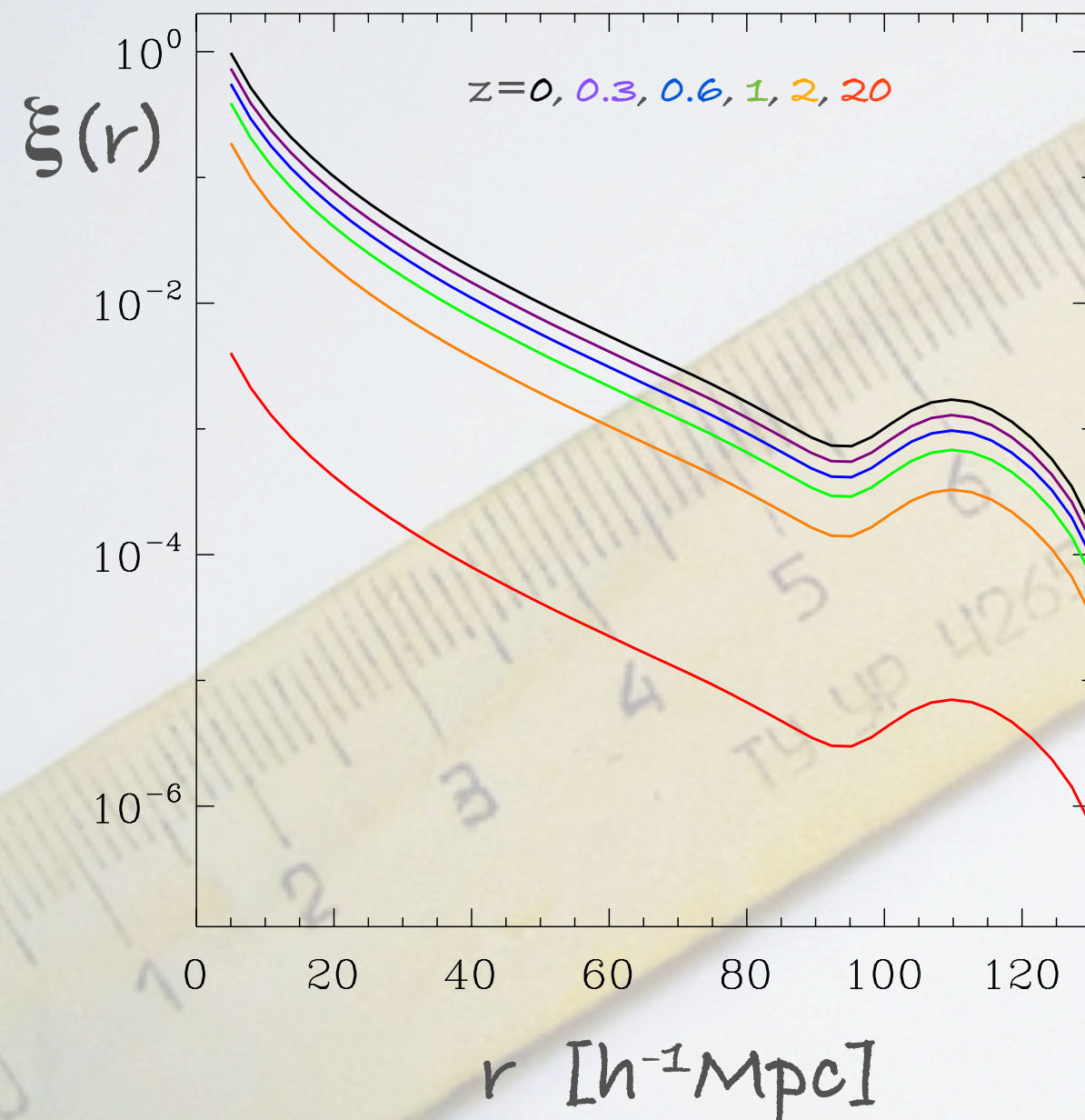
Marc **Manera**, Cameron **McBride**, The Sloan Digital Sky Survey, The WiggleZ Dark Energy Survey

## The Sloan Digital Sky Survey

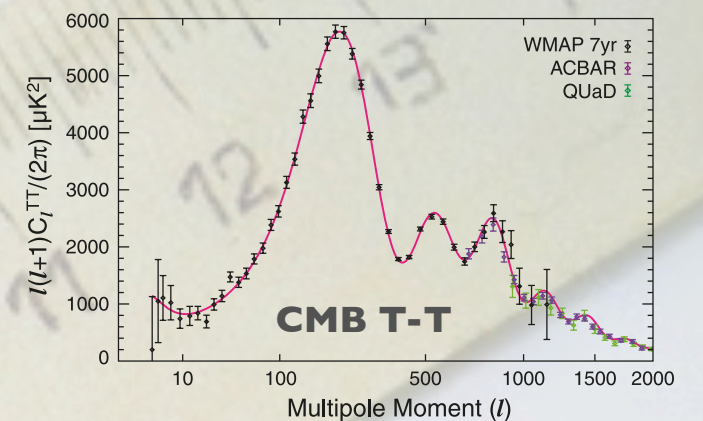




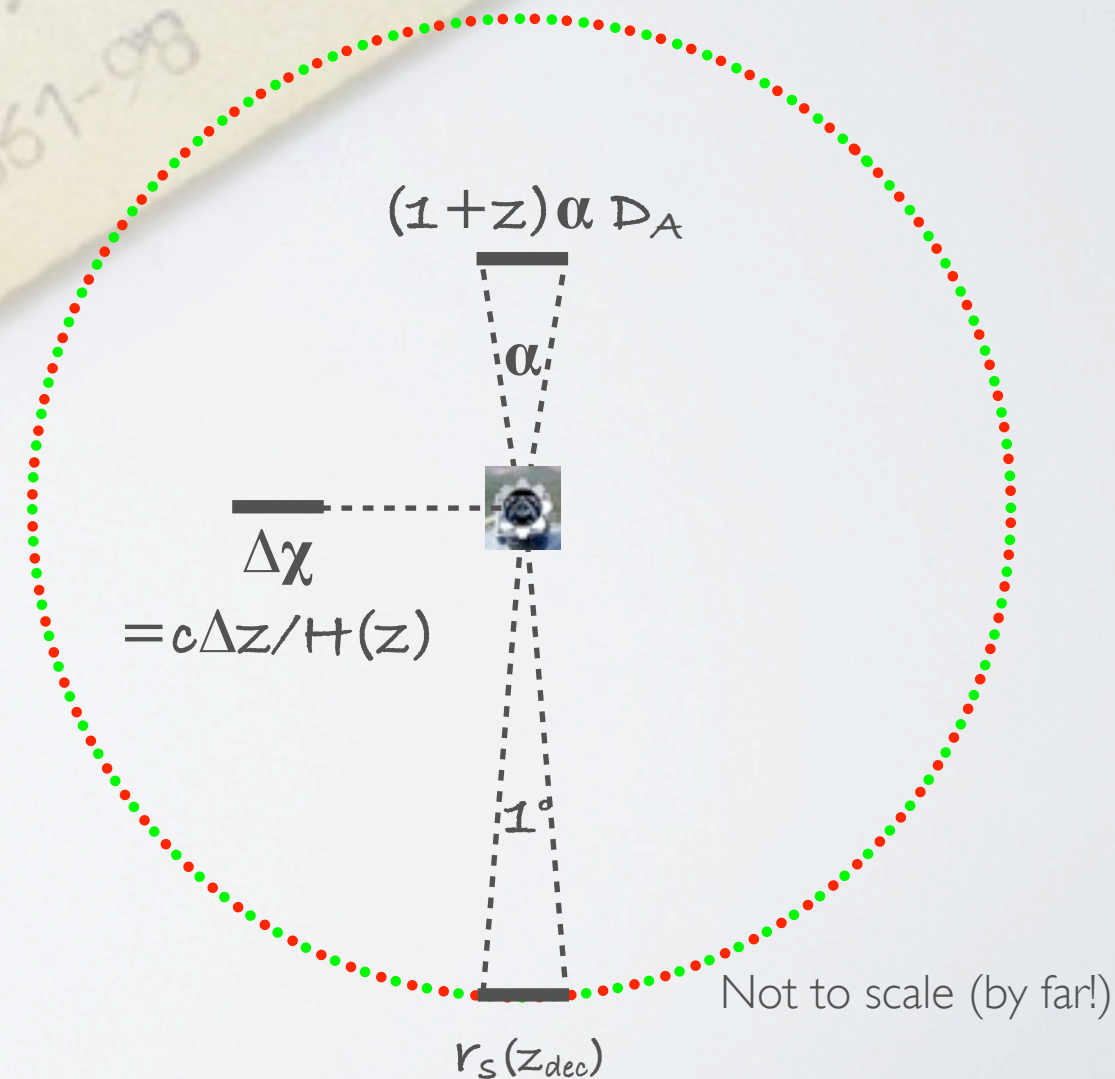
# The Baryonic Acoustic Feature as a Standard Ruler



Larson et al. (2010)



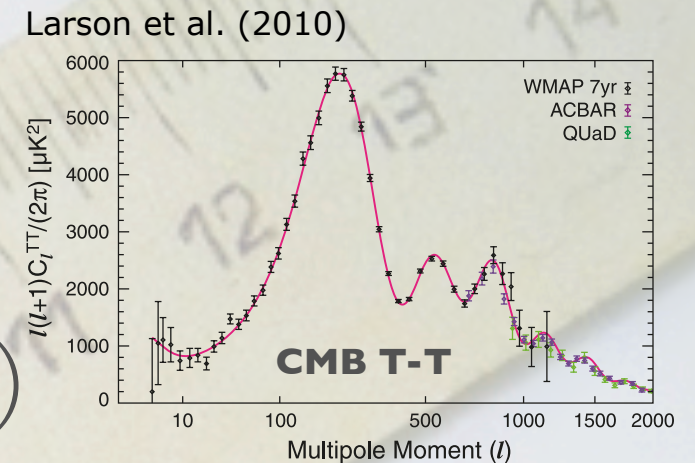
**Surface of last scattering  
 $z \sim 1100$**





# The Baryonic Acoustic Feature as a Standard Ruler

Early Universe ( $z_{\text{dec}} \sim 1090$ ):  
CMB temp fluctuations determines  
 $r_s \sim 147 \text{ Mpc}$  ( $\delta r_s / r_s \sim 1.3\%$ ; WMAP-5 Komatsu et al. 2009)

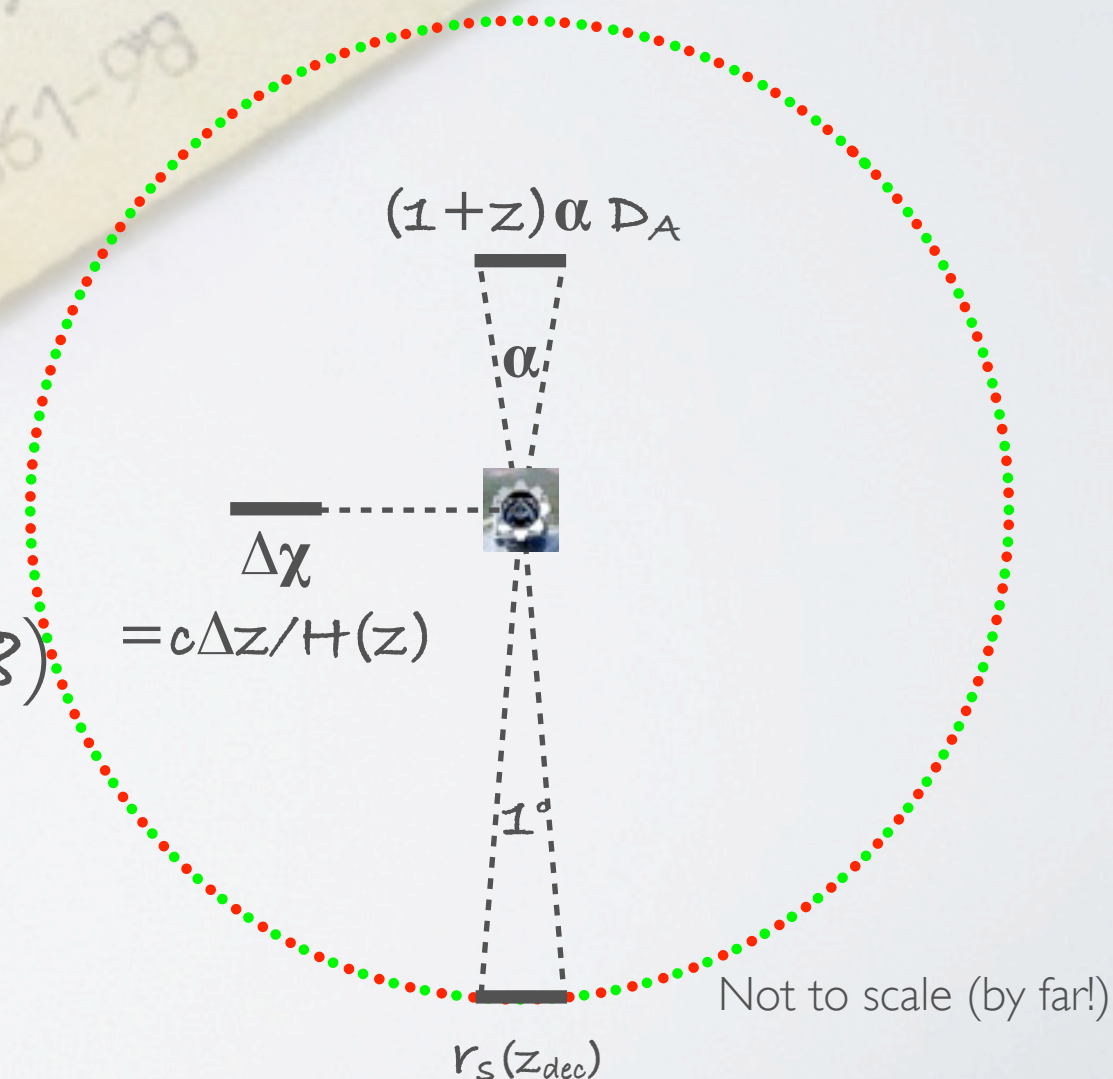


Late Universe :  
SDSS-II, -III  
LRGs ( $z \sim 0.3, 0.6$ )  
QSOs Lyman- $\alpha$  Forest ( $z > 2.5$ )

**Surface of last scattering  
 $z \sim 1100$**

Wiggle-Z  
Blue Galaxies ( $z \sim 0.2, 0.4, 0.6, 0.8$ )

Galaxy Clusters

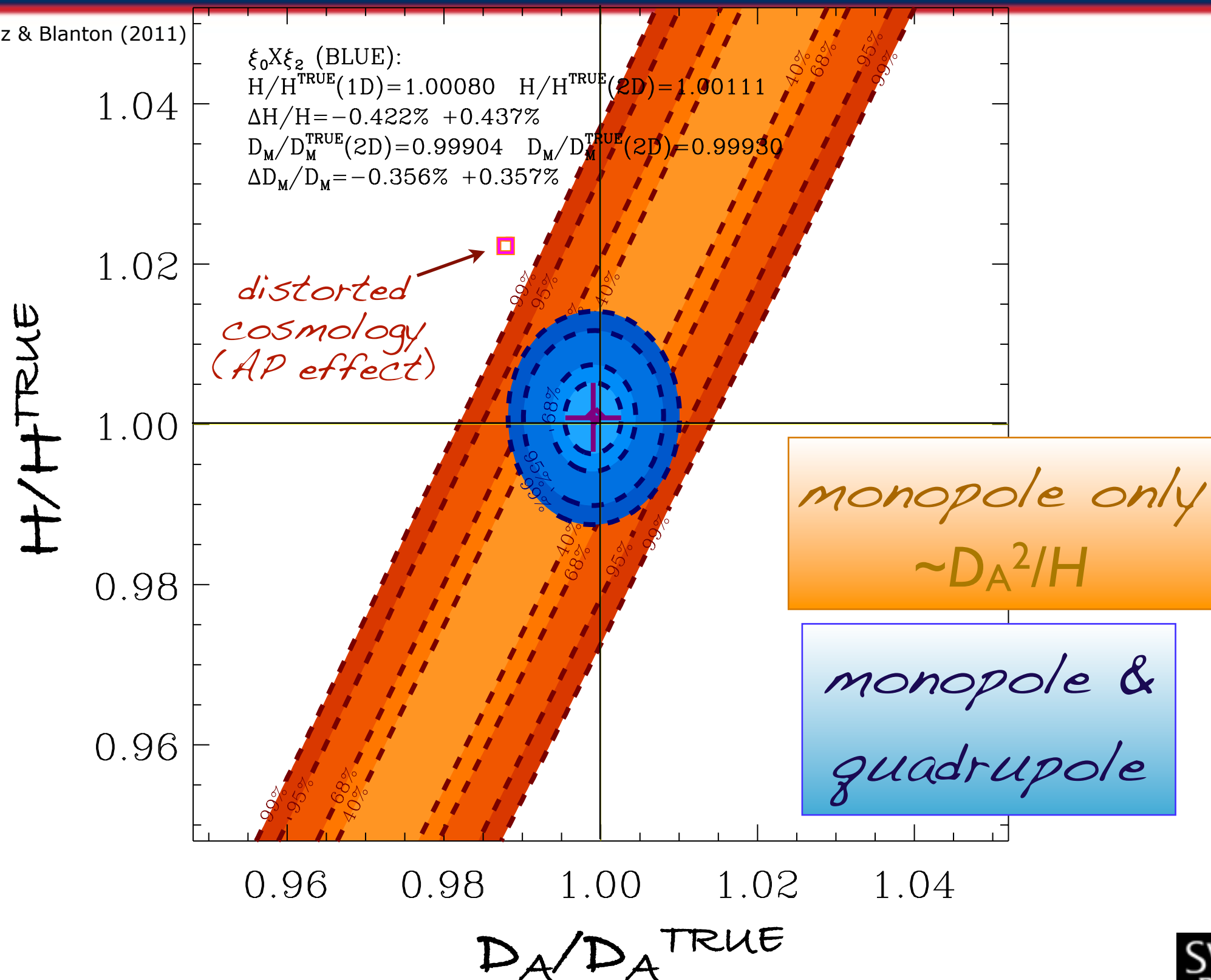




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# Beyond the Monopole: The Importance of Anisotropic Clustering

Kazin, Sánchez & Blanton (2011)





*I am not going to  
show BOSS clustering Wedges  
results today. (but stay tuned ..)*

*Most of the plots here are from  
mock catalogues.*





- z-distortions in practice: a brief practical recap
- There is information in the Hexadecapole  $\xi_4(s)$
- In with the new (basis): Clustering Wedges  $\xi(\Delta\mu, s)$
- Time Permitting:  $N_{RR}(\mu) \neq \text{constant}$



# Redshift Distortions: Dynamical and Geometrical

*Dynamical: squashing (Kaiser 1987), Finger of God*

*comoving distance*

$$\chi(z) = c \int_0^{z_{\text{obs}}} \frac{dz'}{H(z', \Omega)}$$

*Geometrical: AP effect (Alcock & Paczynski 1979)*





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# The Alcock-Paczynski Effect

In the **anisotropic**  
Baryonic Acoustic Feature

$$H \times D_A$$

$$r_1 = c \Delta z / H(z)$$

$$r_2 = (1+z) D_A(z) \Theta$$

$$r_1 = r_2$$

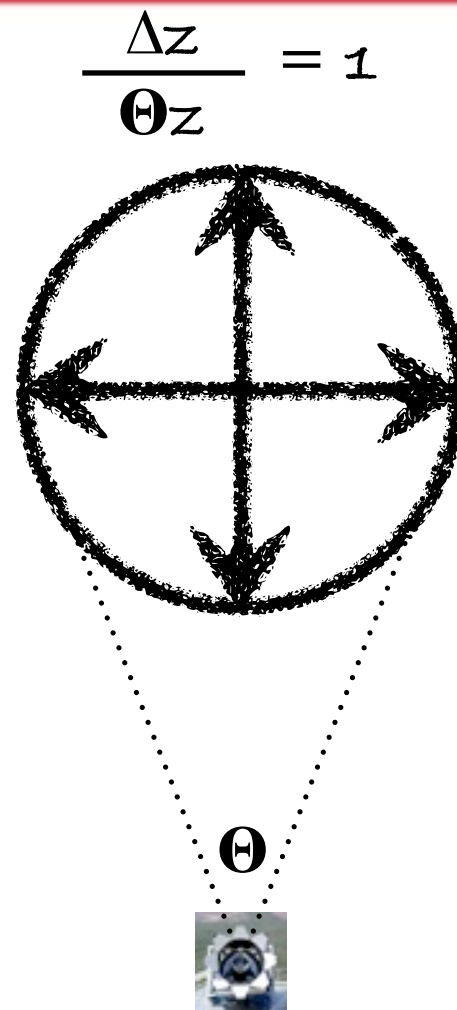
$$H \times D_A = c \Delta z / (1+z) / \Theta$$

In the **isotropic**  
Baryonic Acoustic Feature

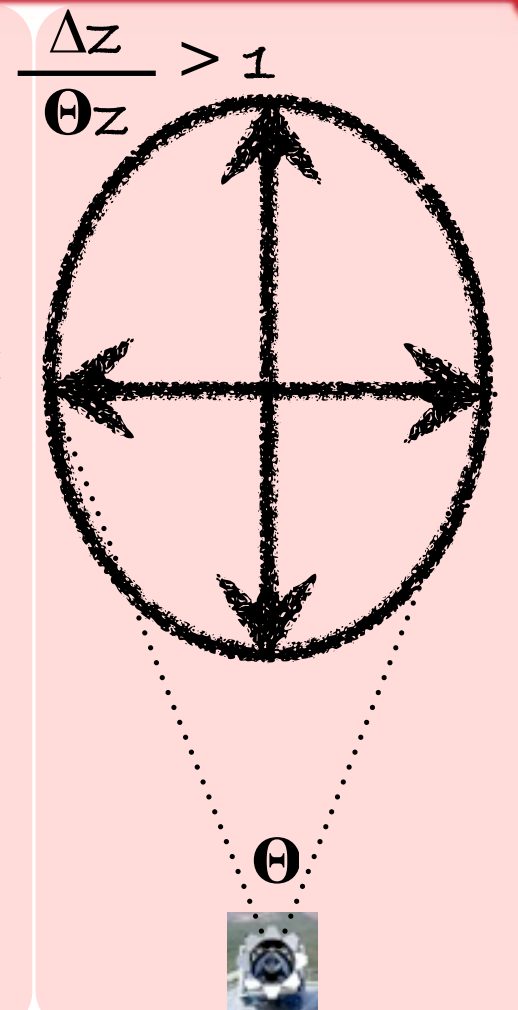
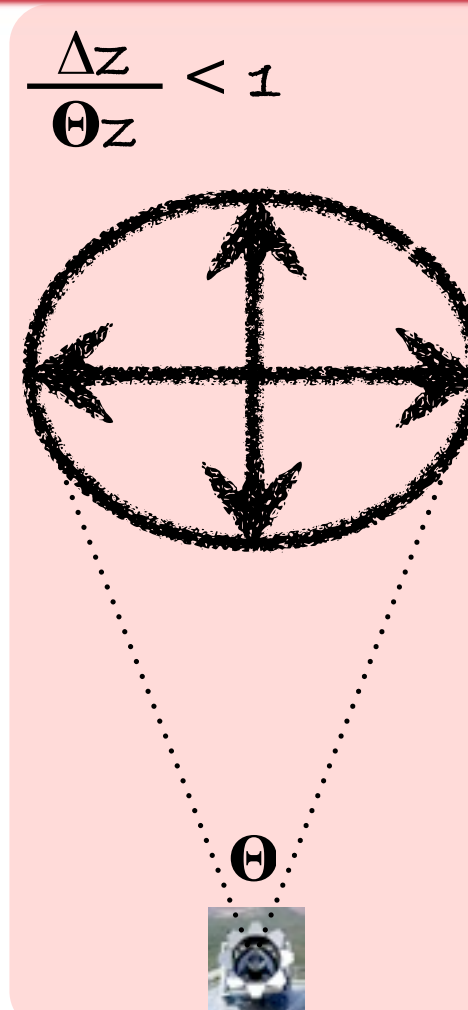
$$D_A^2 / H$$

$$d^3 s = \alpha d^3 s^D$$

$$\alpha = \left( \frac{H^D}{H} \right)^{1/3} \left( \frac{D_A}{D_A^D} \right)^{2/3}$$



Real Space



Redshift Space

$\longleftrightarrow \Theta z$   
 $\updownarrow \Delta z$

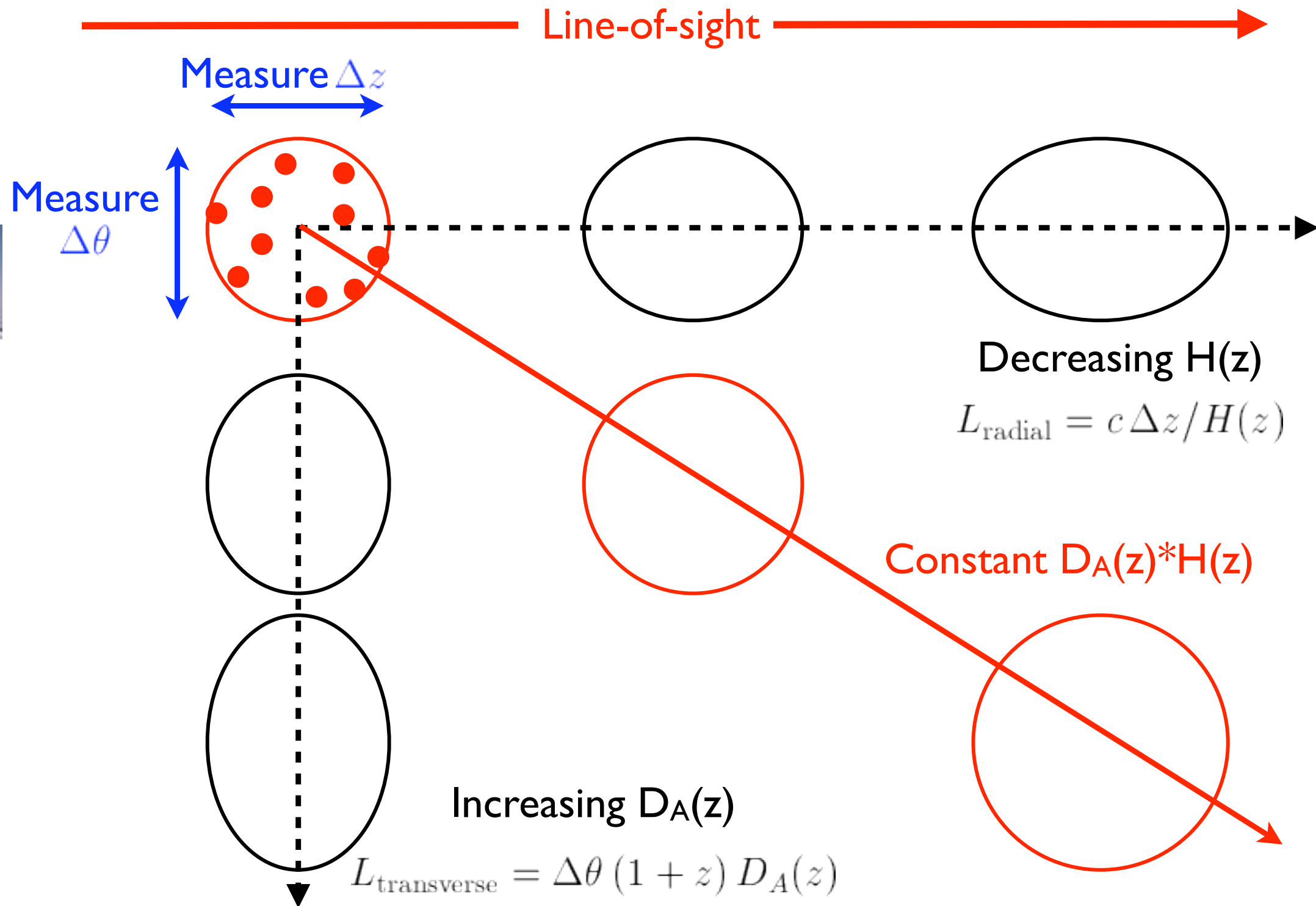
$$\frac{\Delta z}{\Theta z} = z^{-1} [\Omega_\Lambda + \Omega_{m0} (1+z)^3]^{1/2} \int_1^{z+1} dy (\Omega_\Lambda + \Omega_{m0} y^3)^{-1/2}$$



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# The Alcock-Paczynski Effect

Plot Credit: Chris Blake







*z-distortions: General term for both types of distortions. Not solely Dynamical!*

*Dynamical:*

*Squashing (Kaiser 1987), Non-linear etc..*

*Finger of God (velocity dispersion effect)*

*Geometrical:*

*Alcock-Paczynski effect (Alcock & Paczynski 1979)*


 $\xi(s \sim \text{BA feature scale})$ 

 $s \text{ [h}^{-1}\text{Mpc]}$ 


**LA**rge **S**uite of  
**DA**rk **MA**tter **S**ims



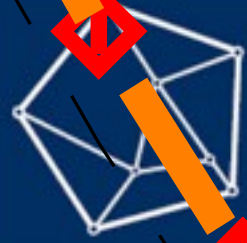
Emphasize on many  
observational effects



Results in **most**  
**realistic uncertainties**  
of clustering of the SDSS-II  
LRGs

public mocks: <http://lss.phy.vanderbilt.edu/lasdamas/>





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# Geometrical Distortion Effects on the 2-Pt Correlation Function

$\xi_0$

- Template (*here I use the true mock signal*)
- ◆ ``data'' (*here I use mock signal affected by AP*)
- - - fit (*here I fit Template to ``data'' varying  $H$  and  $D_A$* )

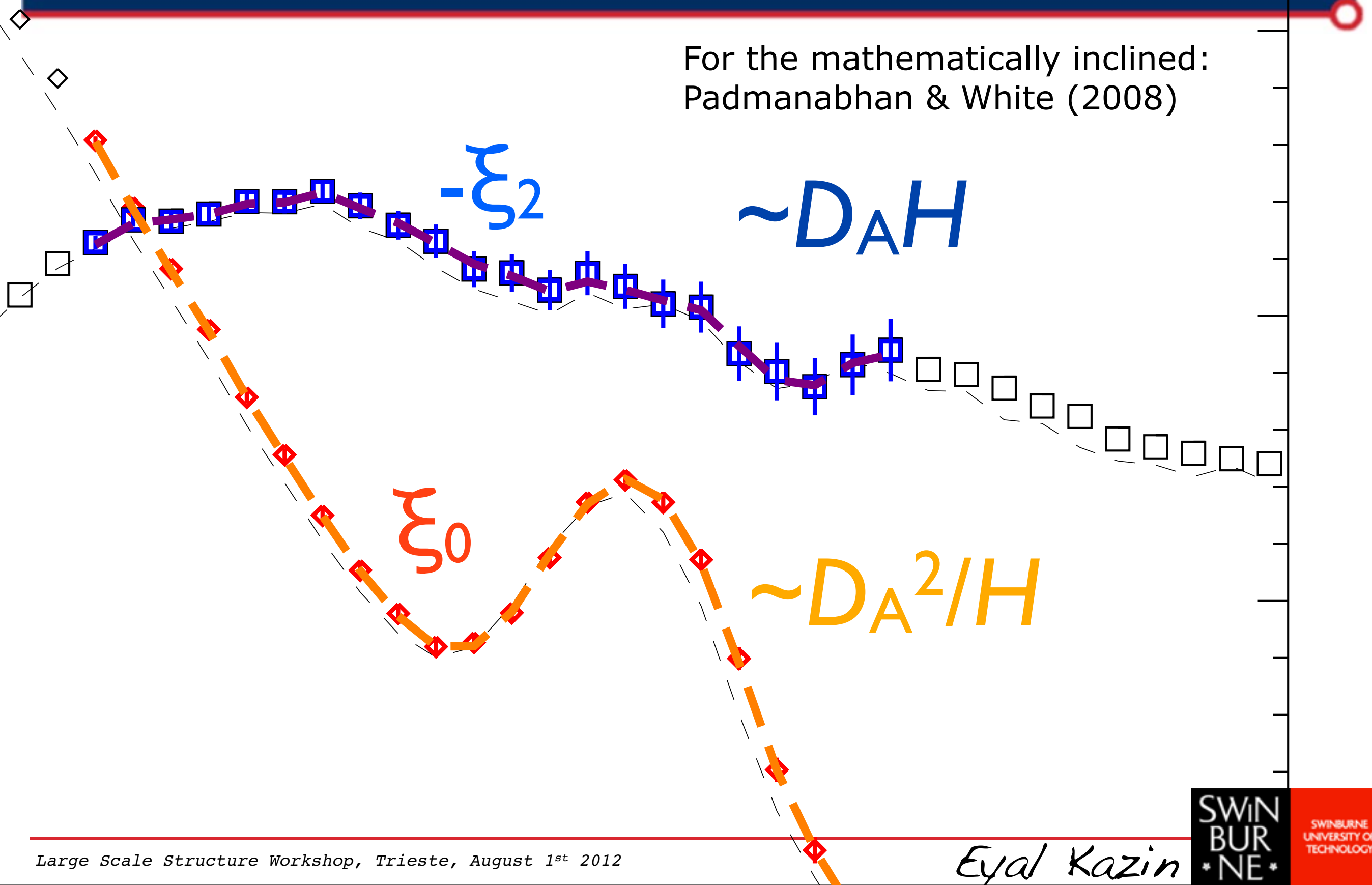


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# Geometrical Distortion Effects on the Clustering Multipoles

For the mathematically inclined:  
Padmanabhan & White (2008)



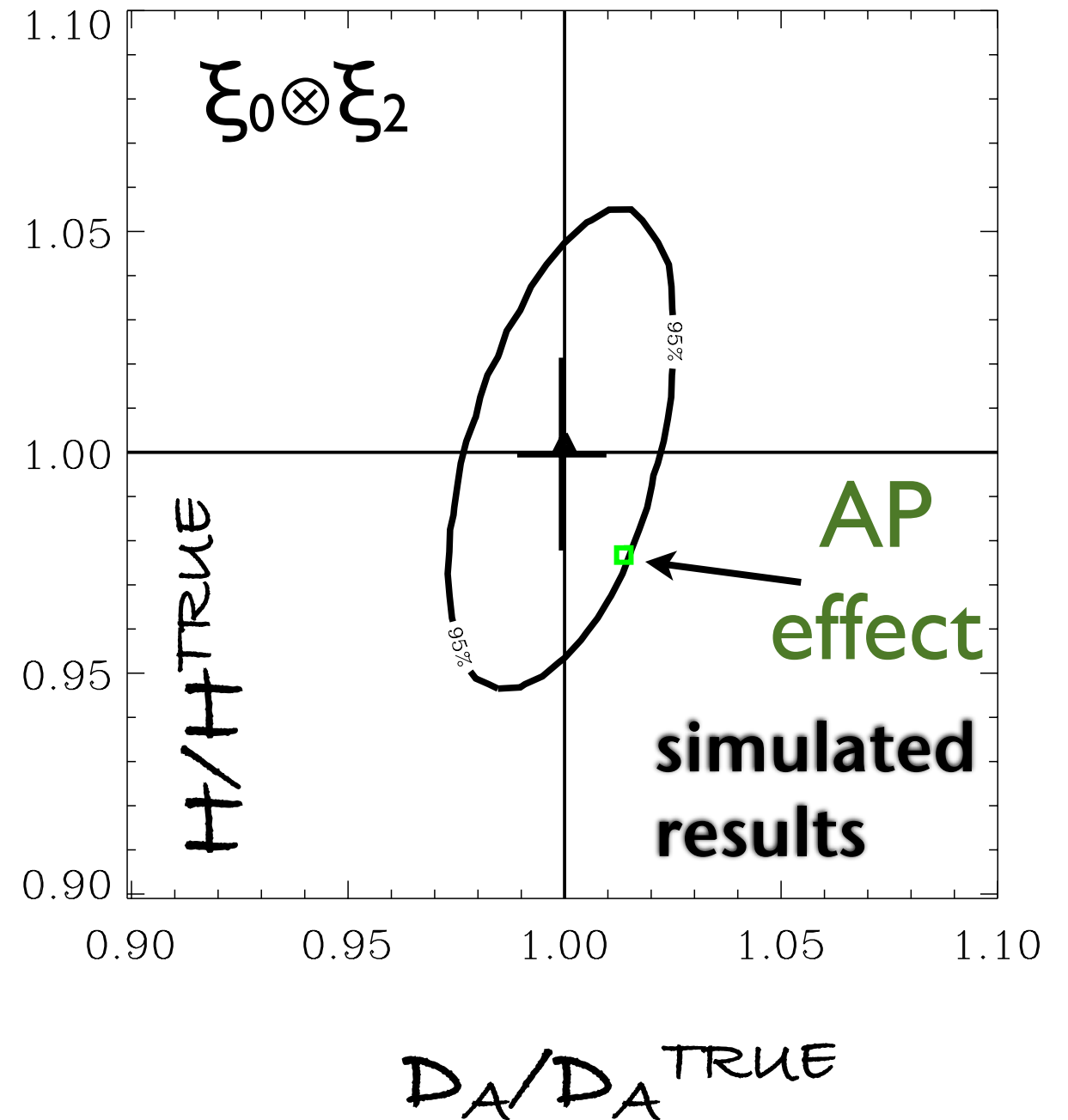
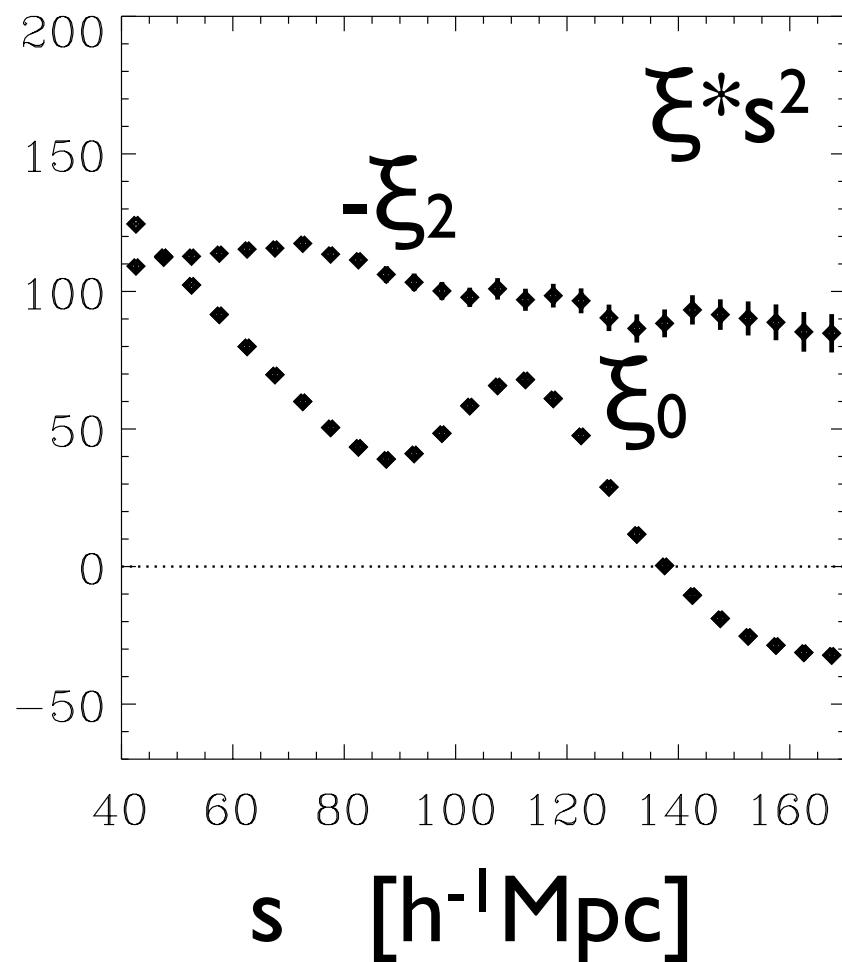




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# Extra Information from the Hexadecapole

KAZIN, SANCHEZ & BLANTON (2011)

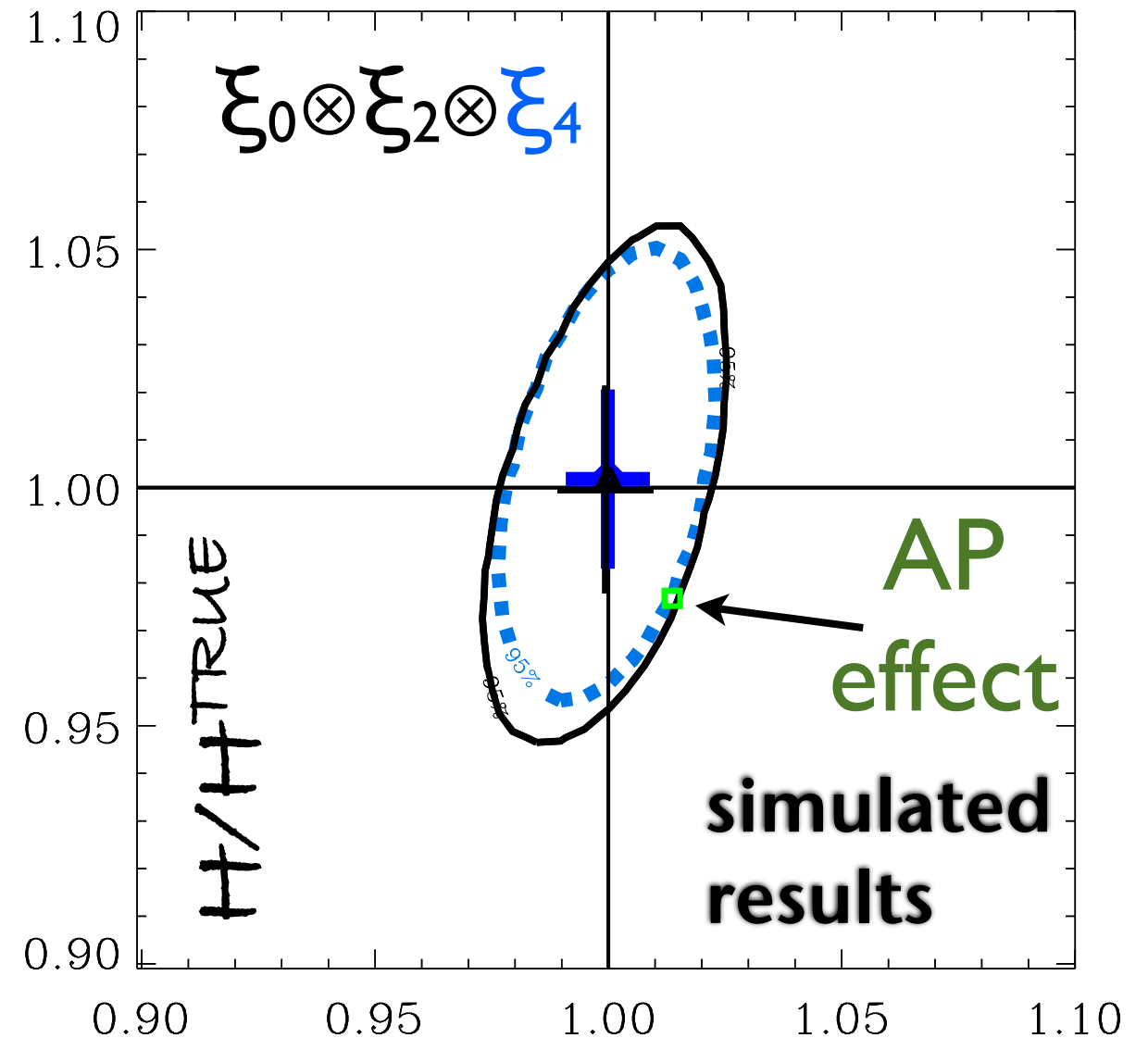
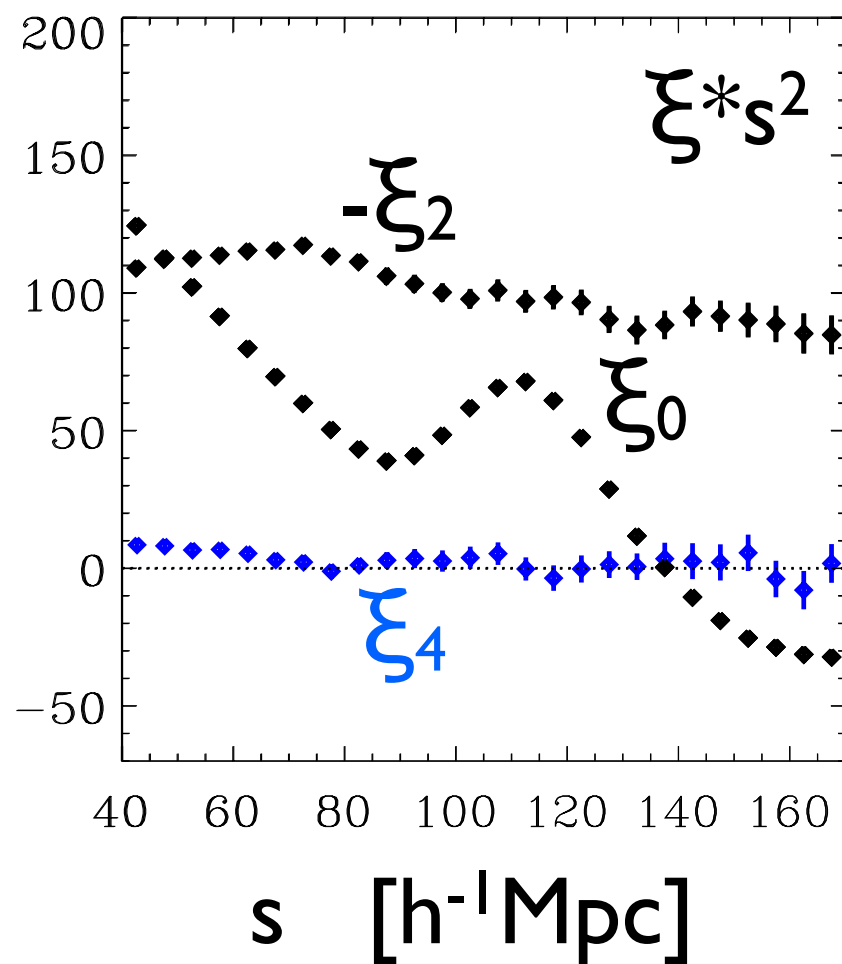




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# Extra Information from the Hexadecapole

KAZIN, SANCHEZ & BLANTON (2011)



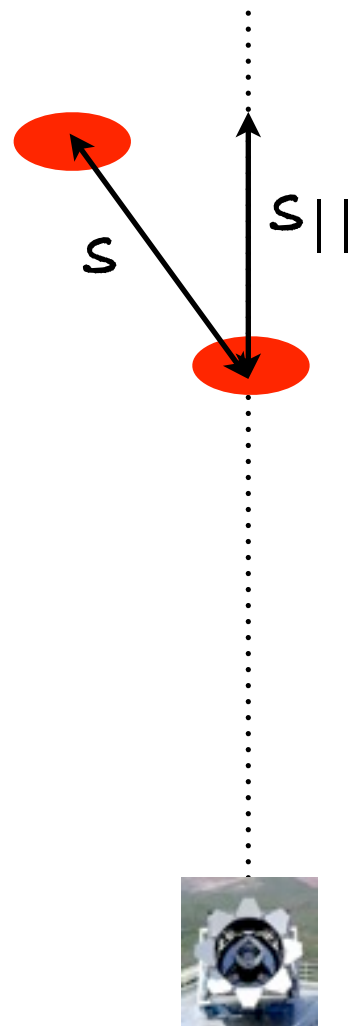
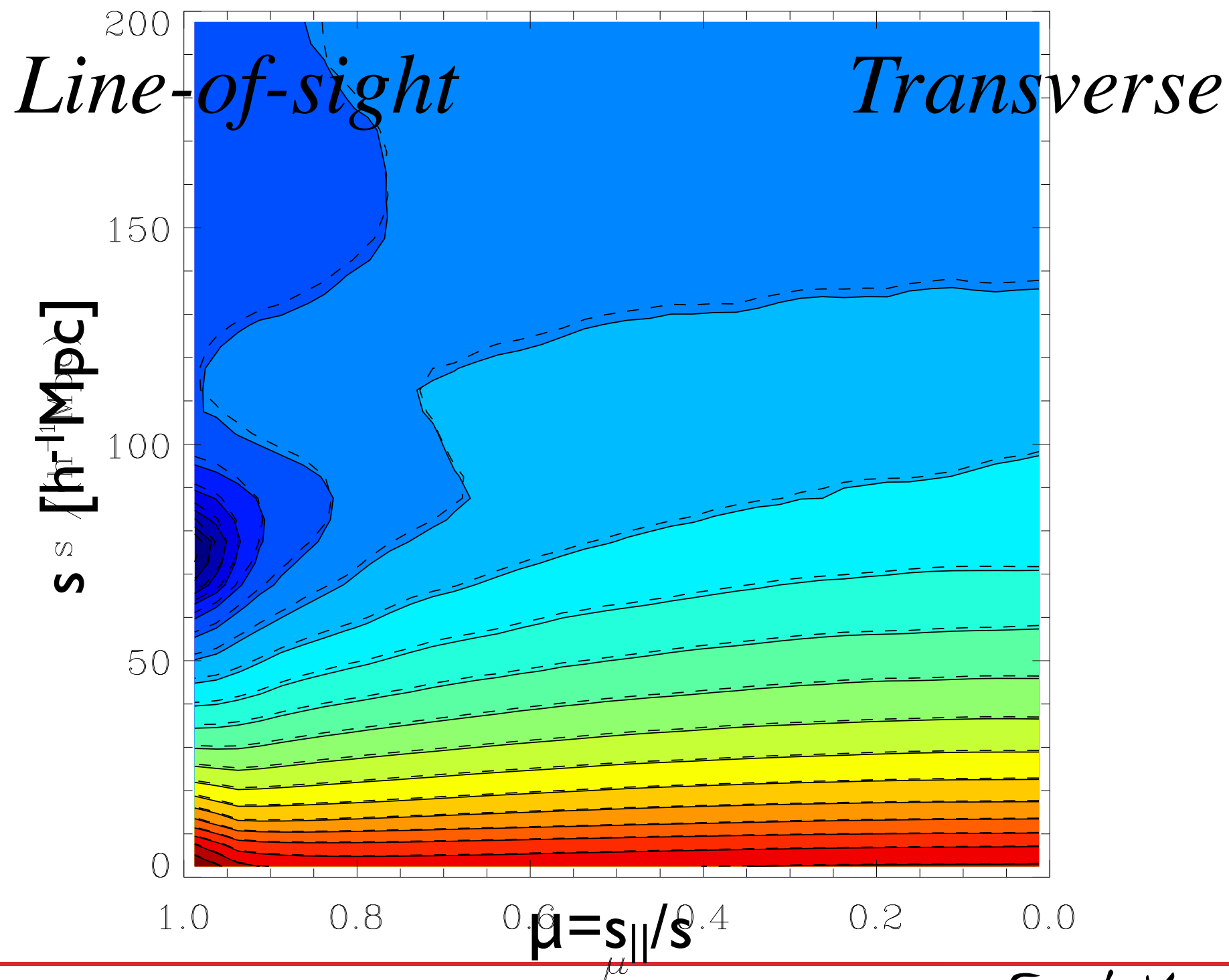
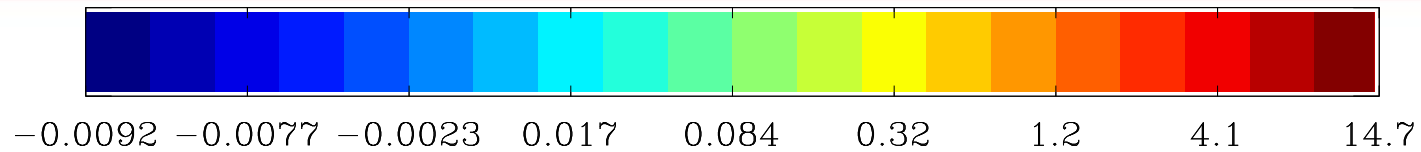
Hexadecapole  $\xi_4$  improves constraints  $D_A/D_A^{\text{TRUE}}$   
(See also Taruya et al. 2011)



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# The 2D Clustering Plane $\xi(\mu, s)$

Kazin, Sanchez & Blanton (2011)



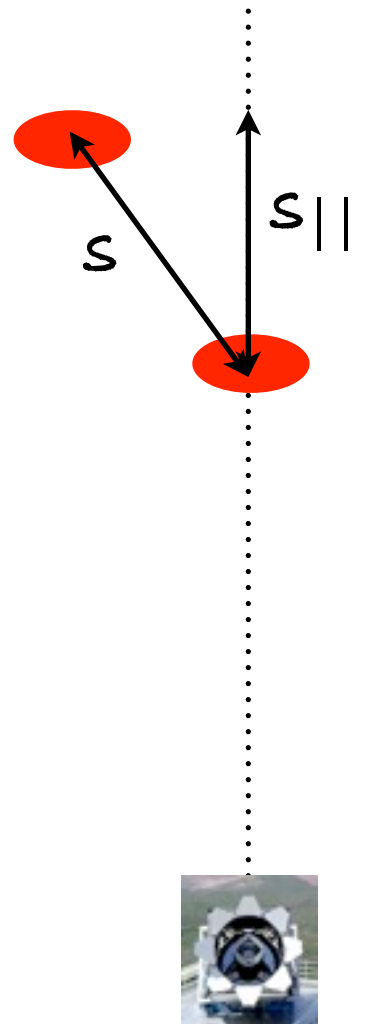
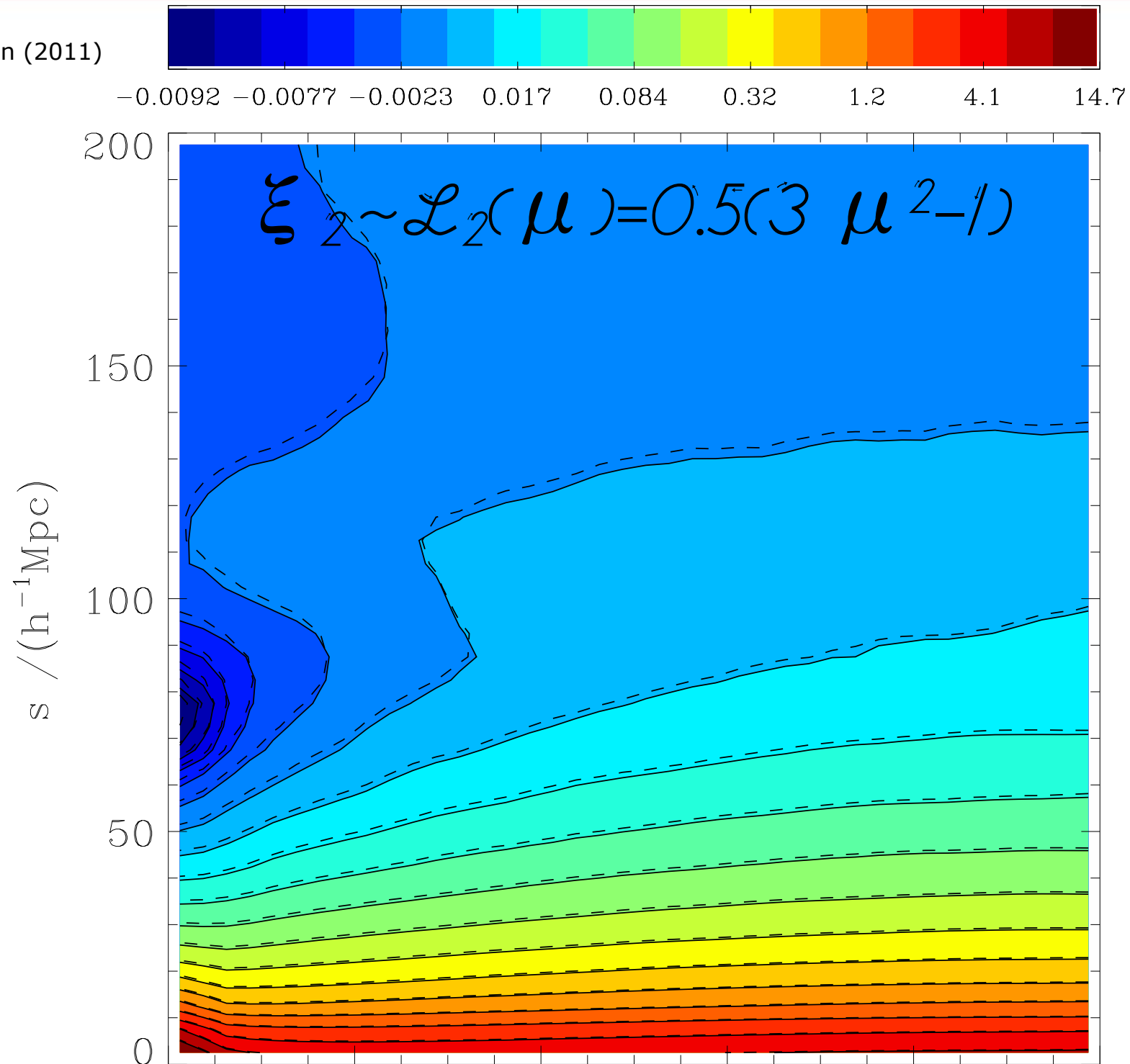




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# Splitting $\xi(\mu, s)$ to Multipoles $\xi_\ell(s)$

Kazin, Sanchez & Blanton (2011)



*Line-of-sight*  $\mu = s_{||} / s$

*Transverse*

*Eyal Kazin*

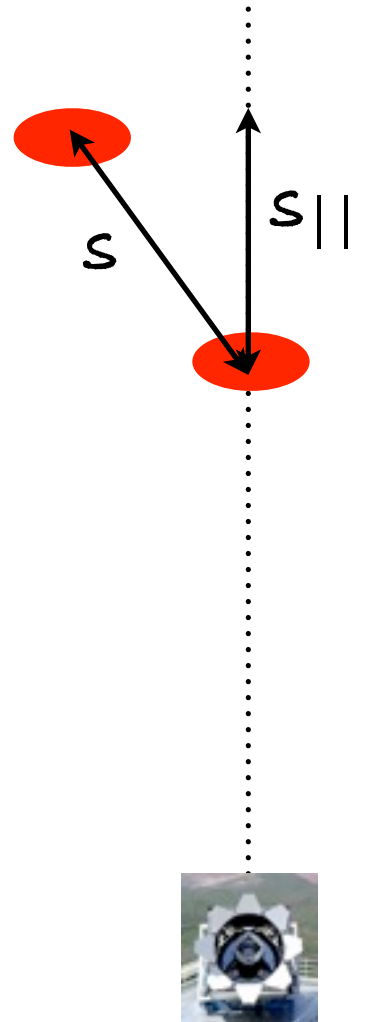
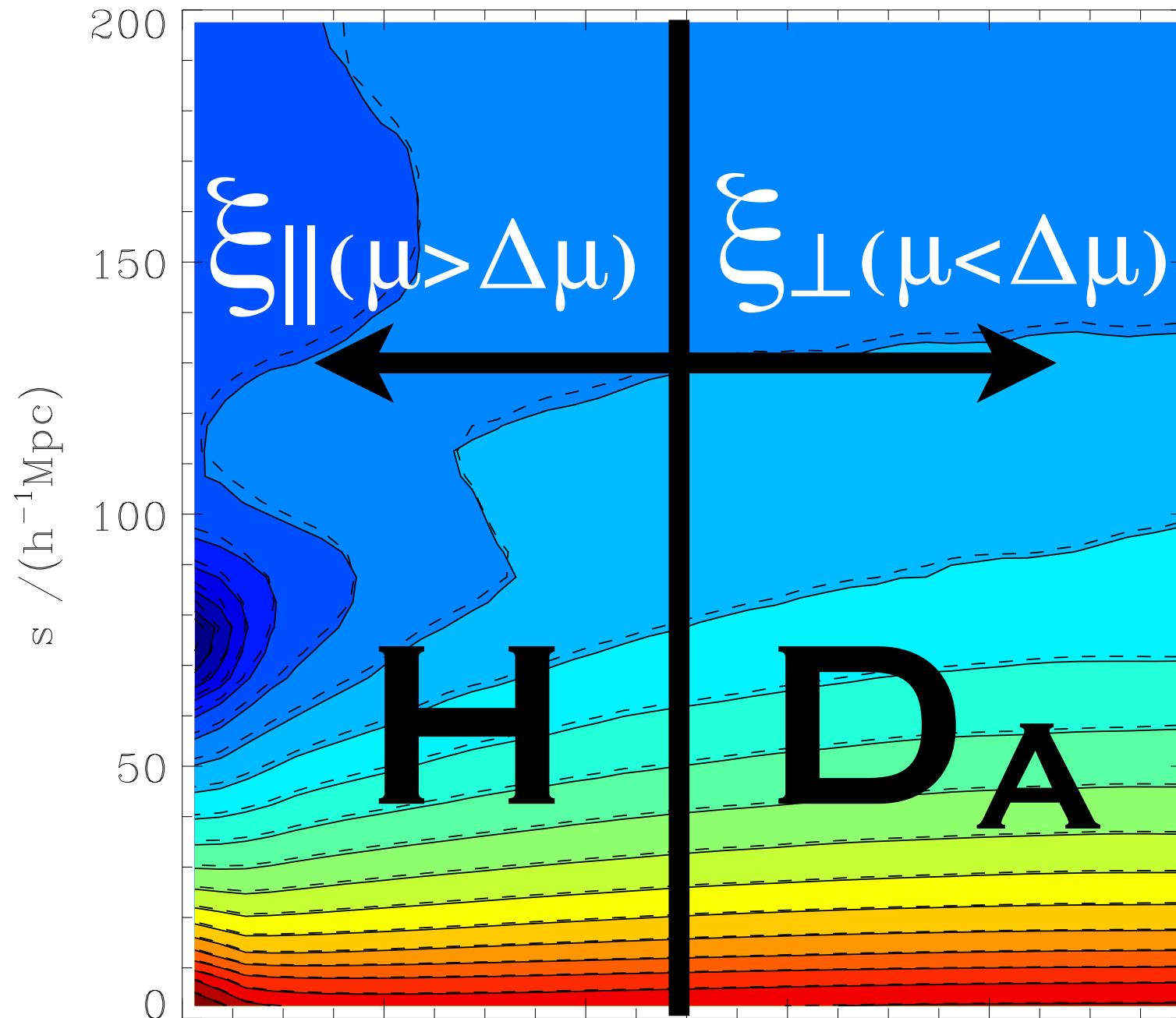
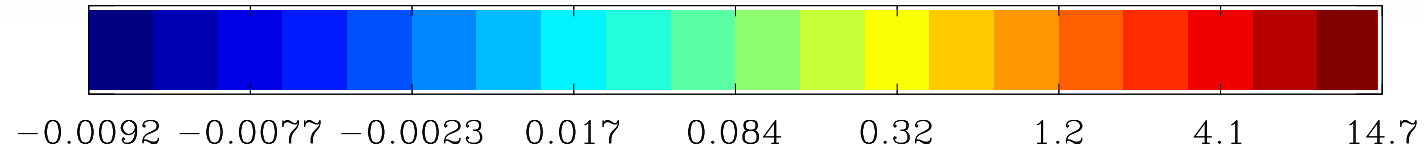




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# Splitting $\xi(\mu, s)$ to Wedges $\xi(\Delta\mu, s)$

Kazin, Sanchez & Blanton (2011)



*Line-of-sight*  $\mu = s_{||}/s$  *Transverse*

*Eyal Kazin*

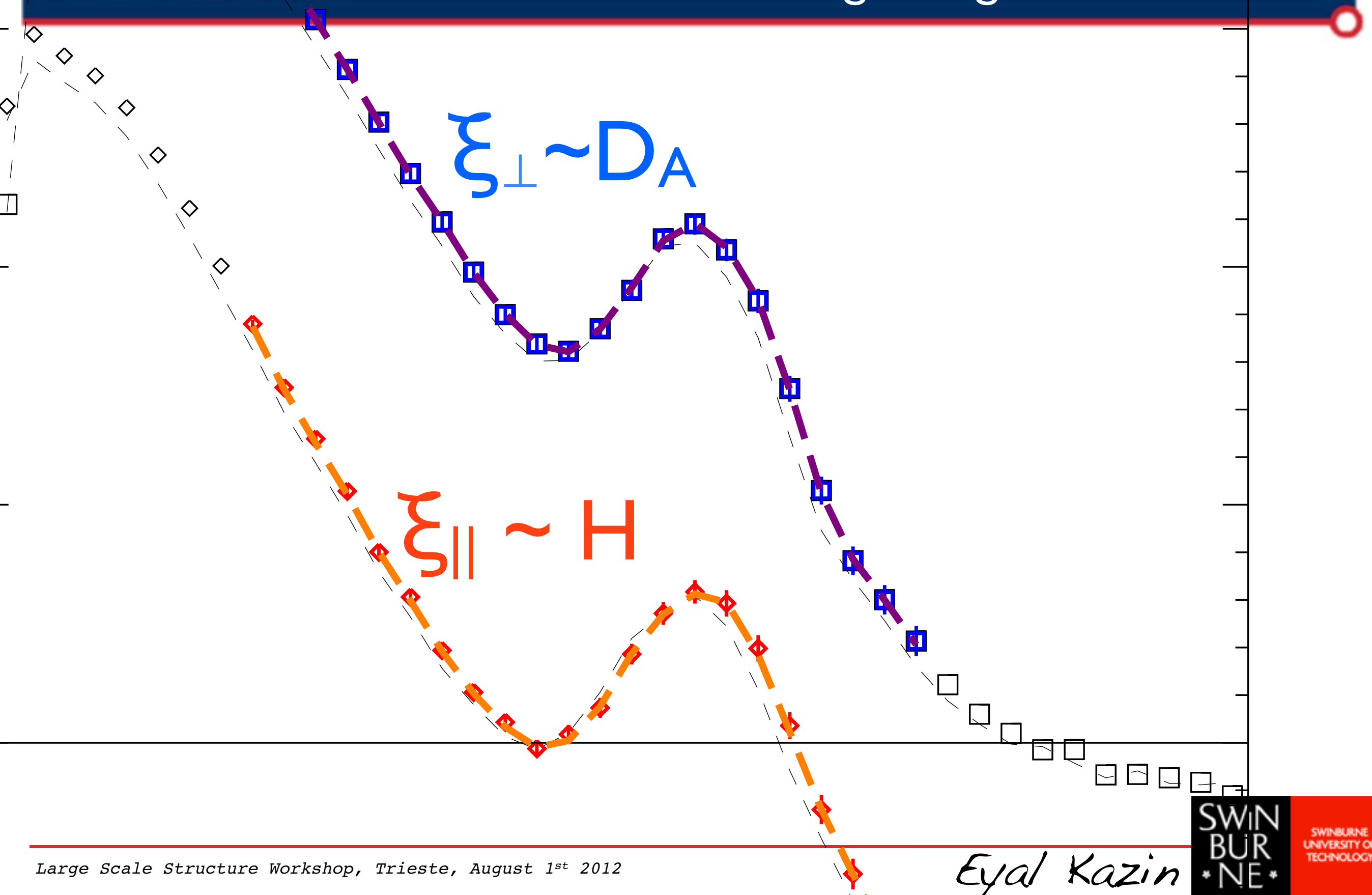
Large Scale Structure Workshop, Trieste, August 1<sup>st</sup> 2012





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# Geometrical Distortion Effects on the Clustering Wedges

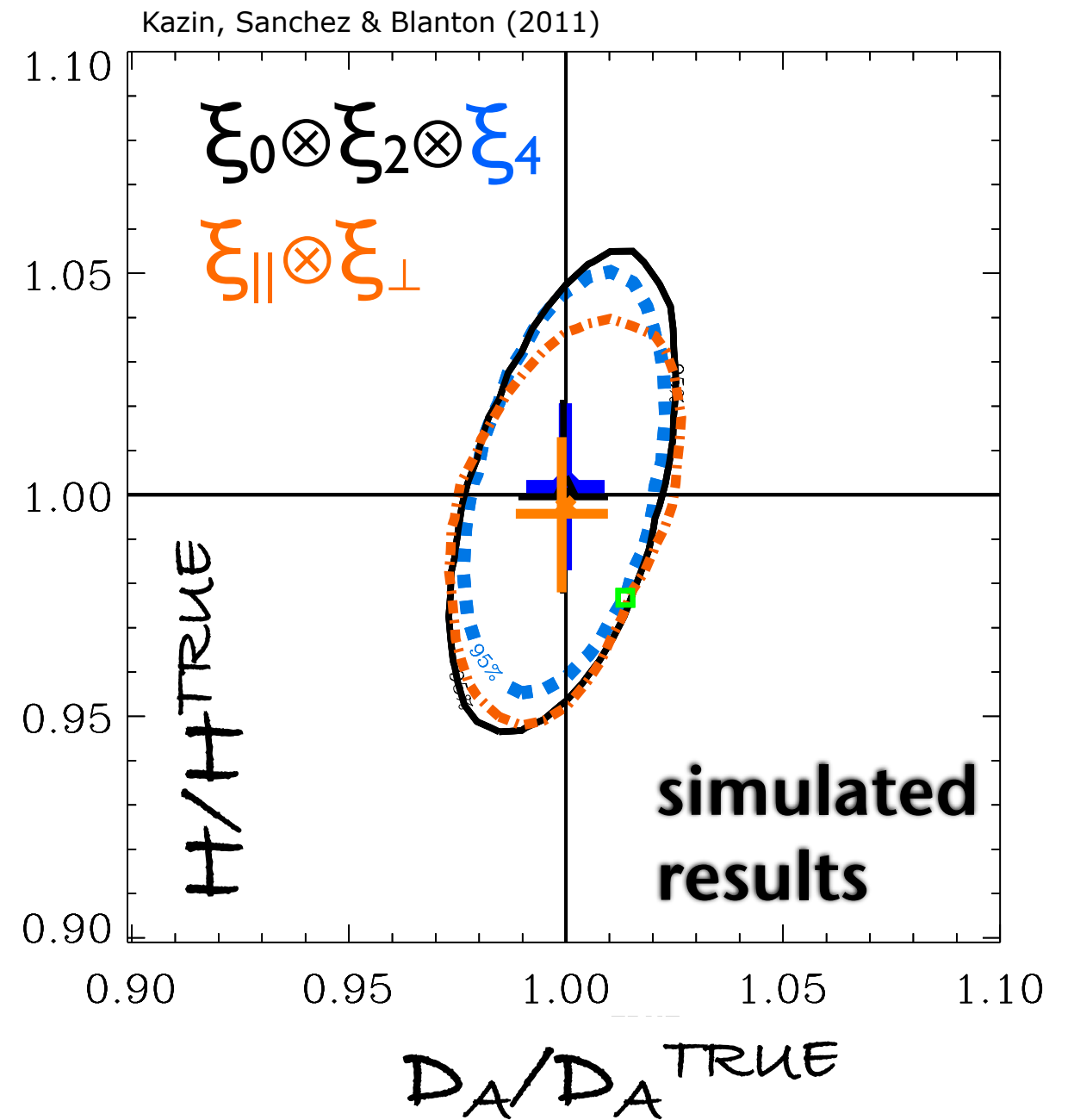
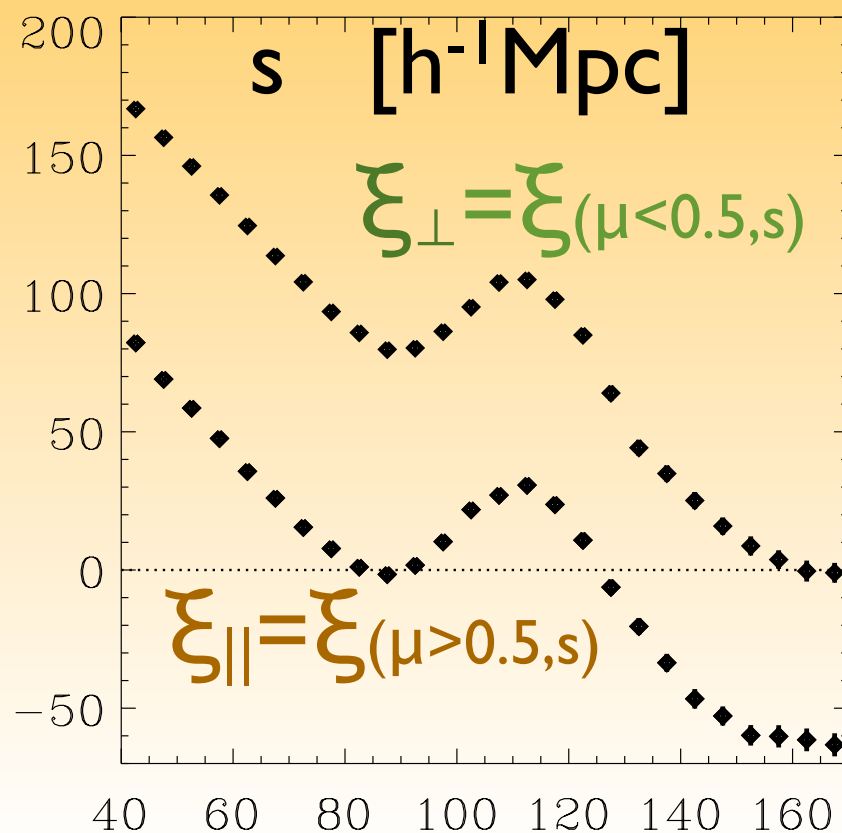
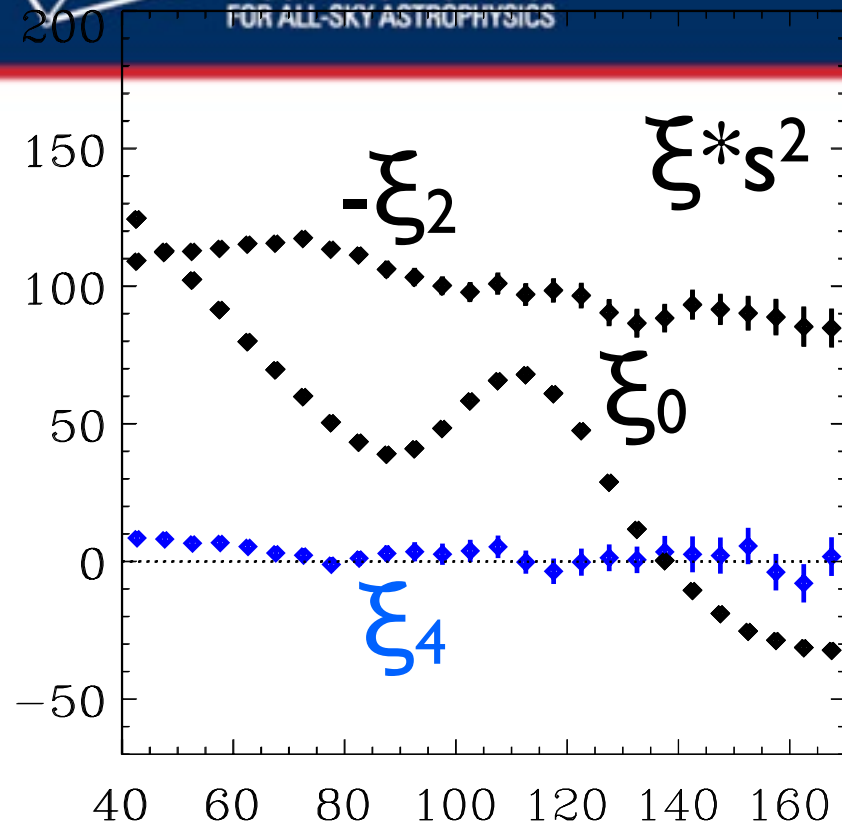






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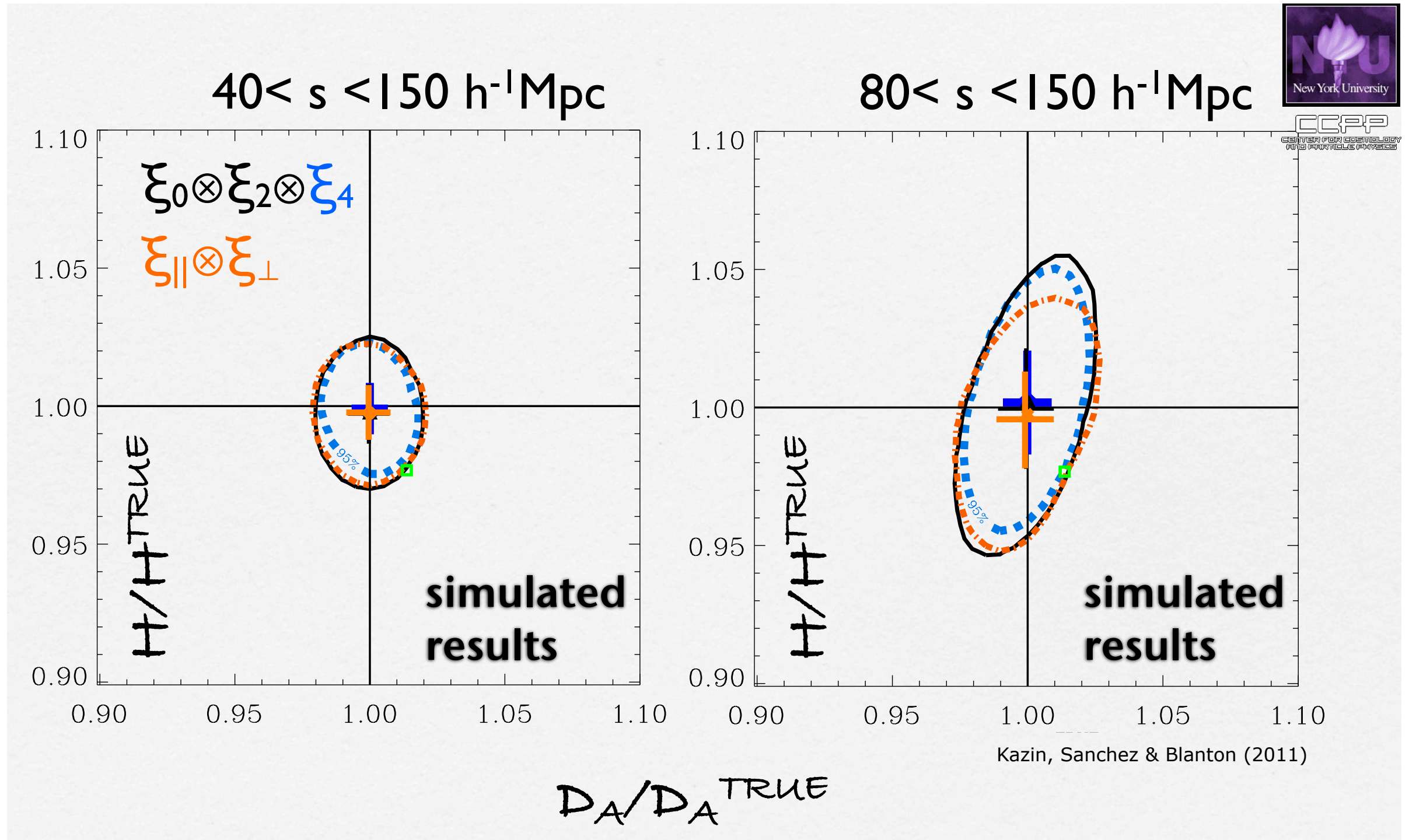
# Wedges $H$ , $D_A$ Performance





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# $H, D_A$ information in the $\xi$ Full Shape





# Wedges: Basic Equations

Definition:

$$\xi(\Delta\mu, s) \equiv \frac{\int_{\mu_{\min}}^{\mu_{\max}} \xi(\mu', s) d\mu'}{\int_{\mu_{\min}}^{\mu_{\max}} d\mu'}$$

Basis Transform From Multipoles:

$$\xi(\Delta\mu, s) = \xi_0 + \frac{1}{2} \left( \frac{\mu_{\max}^3 - \mu_{\min}^3}{\mu_{\max} - \mu_{\min}} - 1 \right) \xi_2$$

For  $\Delta\mu=0.5$ :

$$\begin{pmatrix} \xi_{||} \\ \xi_{\perp} \end{pmatrix} = \begin{pmatrix} 1 & \frac{3}{8} \\ 1 & -\frac{3}{8} \end{pmatrix} \begin{pmatrix} \xi_0 \\ \xi_2 \end{pmatrix}$$





$$\xi_{||}^{\mathcal{D}}(s) = \xi_{||} \left( \frac{H^{\mathcal{D}}}{H} s \right) + \mathcal{C}_{||}(\epsilon),$$

$$\xi_{\perp}^{\mathcal{D}}(s) = \xi_{\perp} \left( \frac{D_A}{D_A^{\mathcal{D}}} s \right) + \mathcal{C}_{\perp}(\epsilon),$$

**Inter-mixing terms** (not a pretty sight ...):

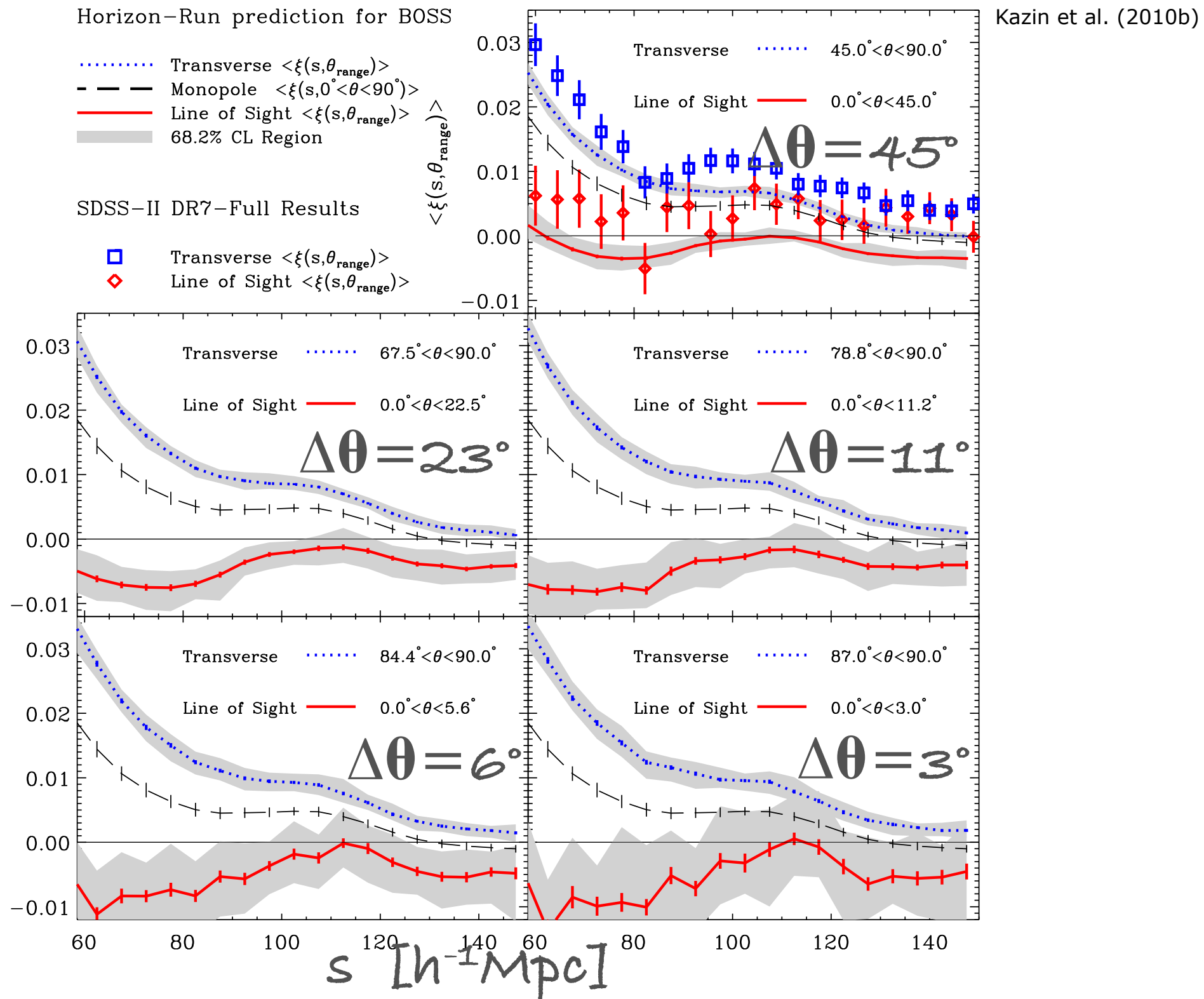
$$\mathcal{C}_{||}(\epsilon, \alpha) = \epsilon \left( -\frac{5}{4} \frac{d\xi_0(s)}{d \ln(s)} - \frac{19}{140} \frac{d\xi_2(s)}{d \ln(s)} + \frac{213}{140} \xi_2(\alpha s) \right)$$

$$\mathcal{C}_{\perp}(\epsilon, \alpha) = \epsilon \left( \frac{1}{4} \frac{d\xi_0(s)}{d \ln(s)} - \frac{53}{280} \frac{d\xi_2(s)}{d \ln(s)} + \frac{123}{140} \xi_2(\alpha s) \right)$$



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# BOSS 2014 Predicted Wedges $\xi(\Delta\mu, s)$



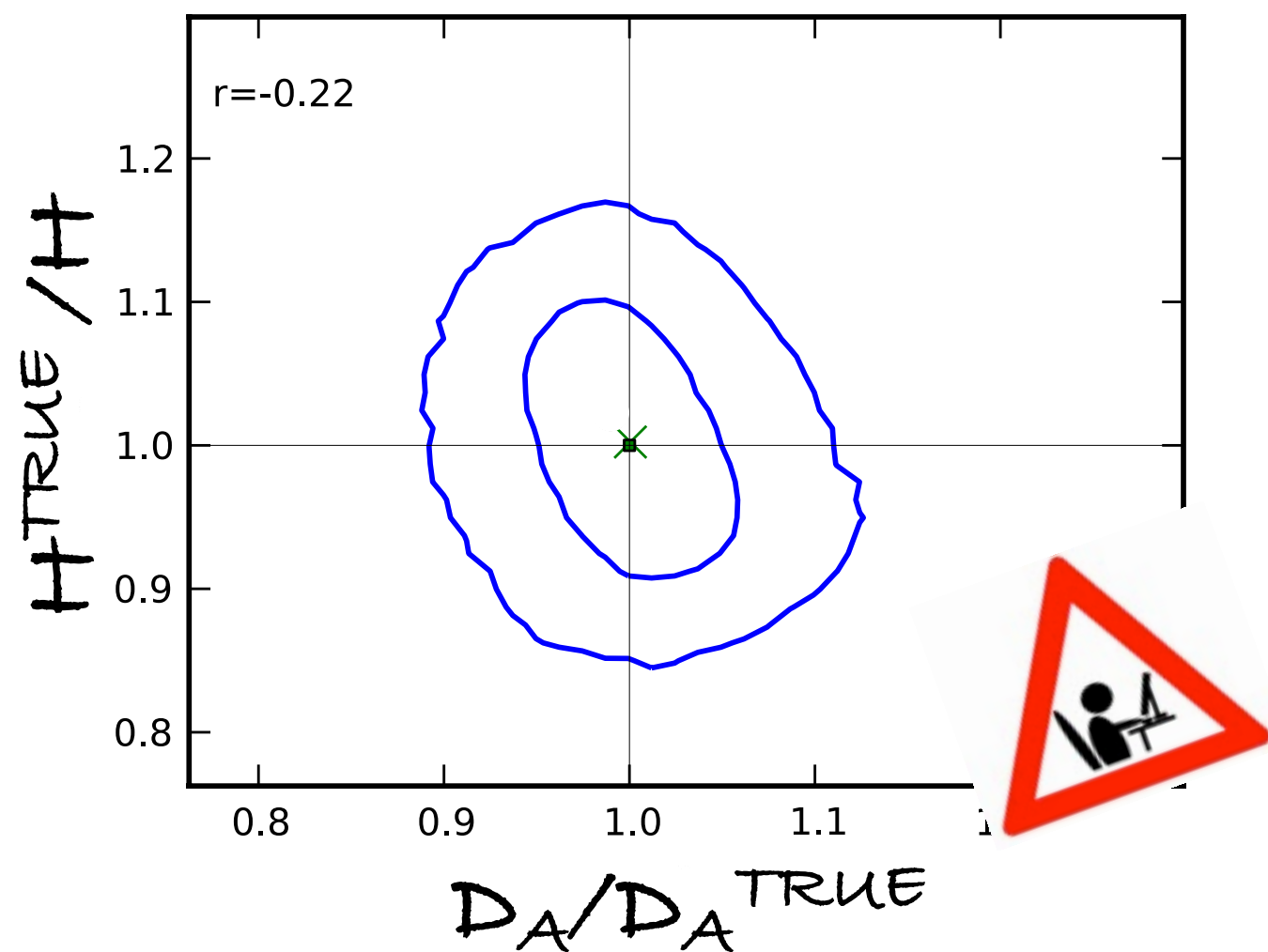
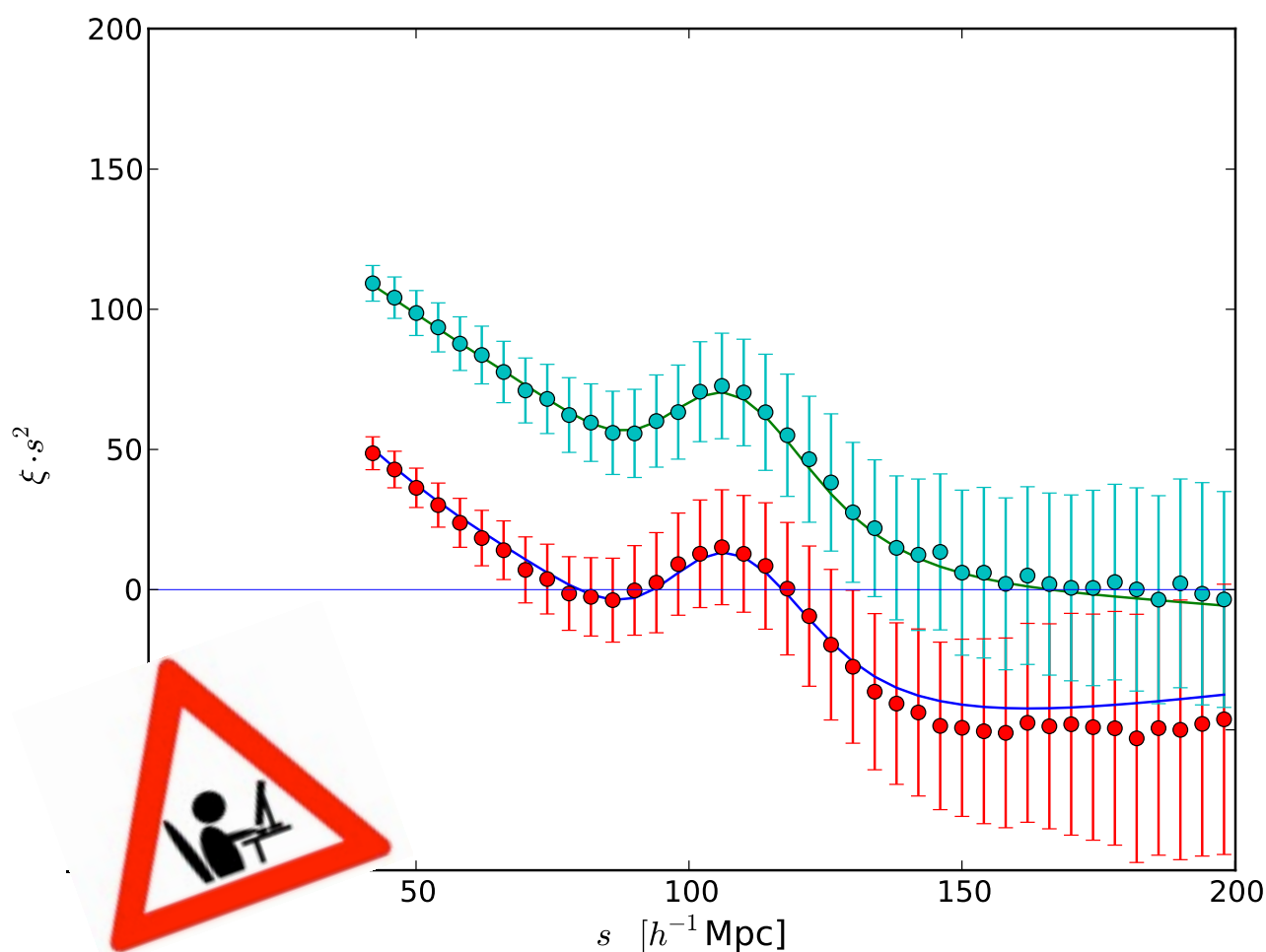


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# Testing Model on Mock Wedges

## Simulated Data: BOSS PTHalos (of Manera et al. 2012)

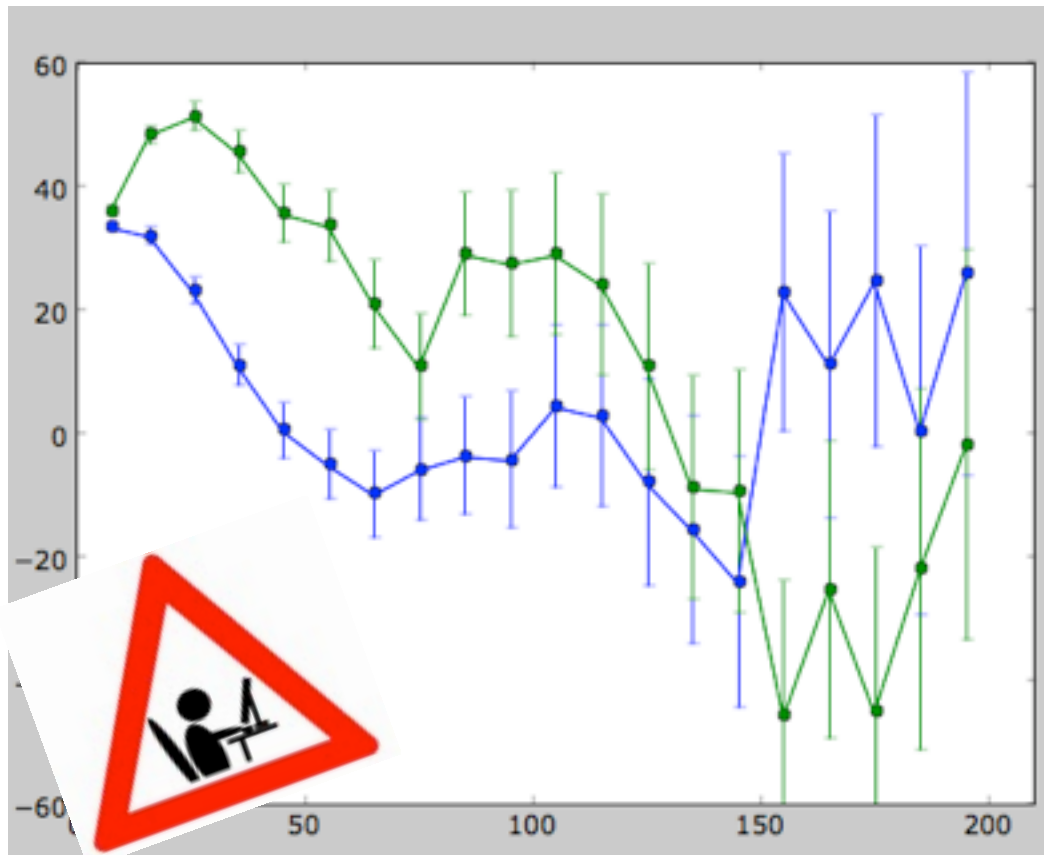
Kazin, Sánchez & the SDSS (in prep.)





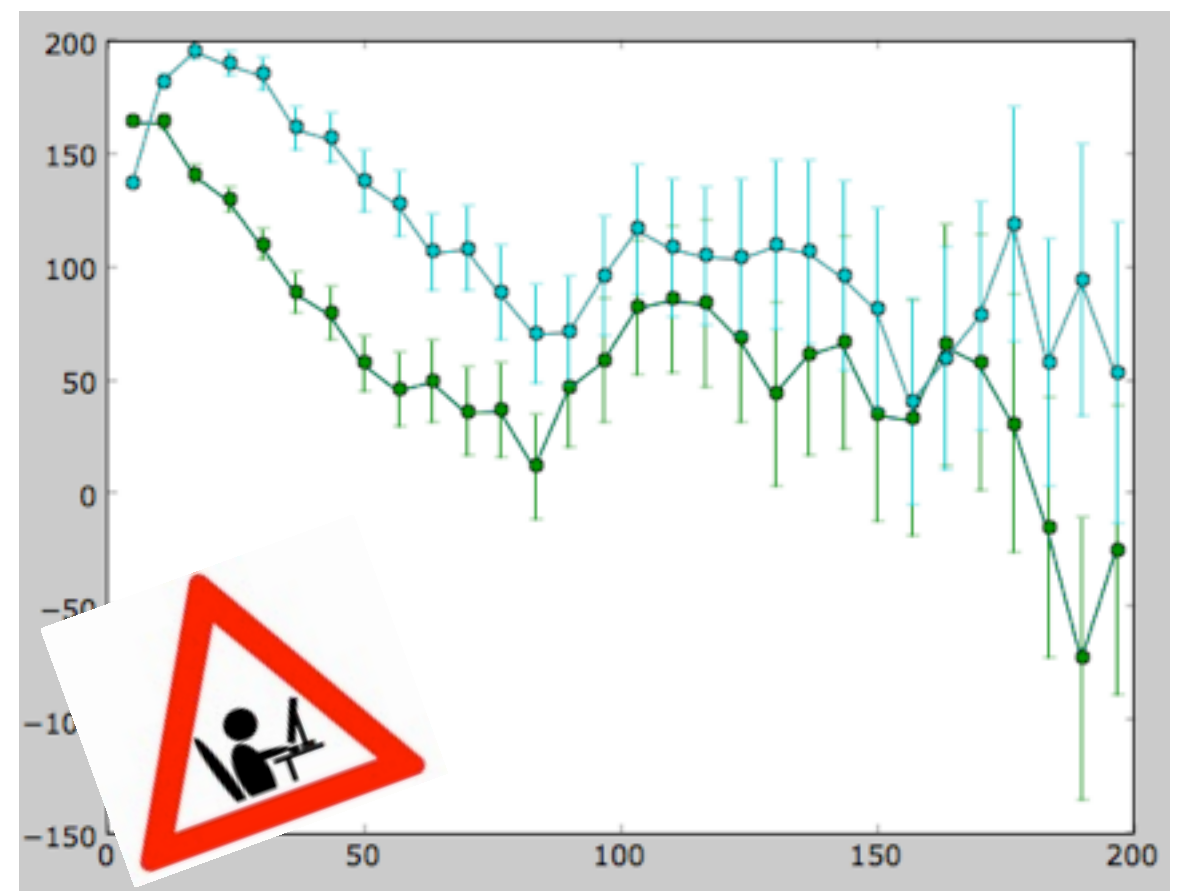
# Clustering Wedges in the Data

Davis, Kazin & the WiggleZ (in prep.)



**WiggleZ ( $0.2 < z < 1$ )**  
(bias  $\sim 1$ )

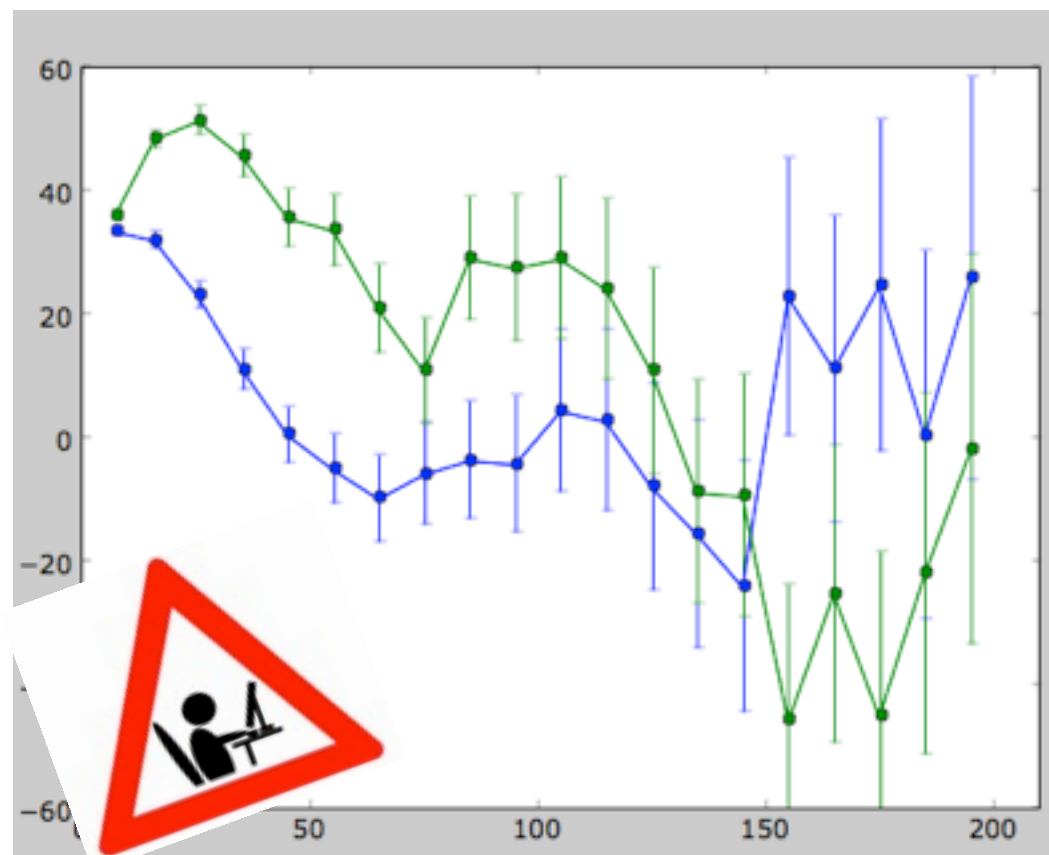
**SDSS-II LRGs ( $0.16 < z < 0.44$ )**  
(bias  $\sim 2.2$ )



Sánchez & Kazin (in prep.)

# Clustering Wedges in the Data

Davis, Kazin & the WiggleZ (in prep.)



**WiggleZ ( $0.2 < z < 1$ )**  
(bias  $\sim 1$ )

**SDSS-II LRGs ( $0.16 < z < 0.44$ )**  
(bias  $\sim 2.2$ )

Credit for reconstructed data: **Nikhil Padmanabhan**



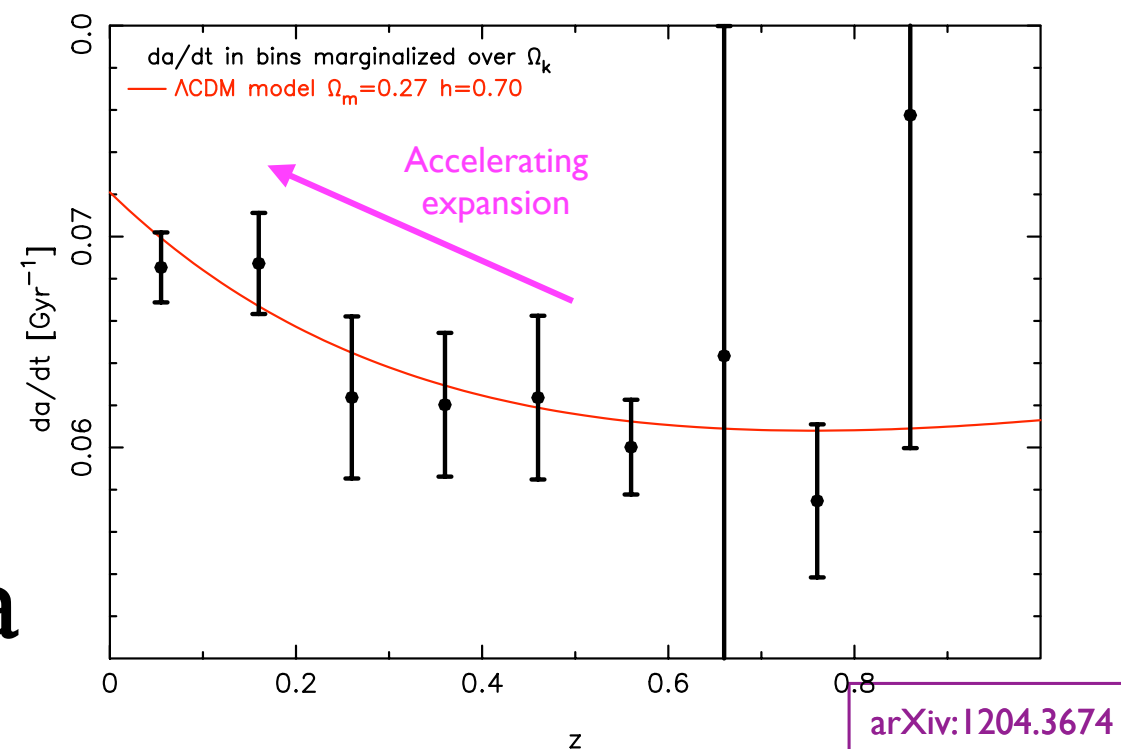
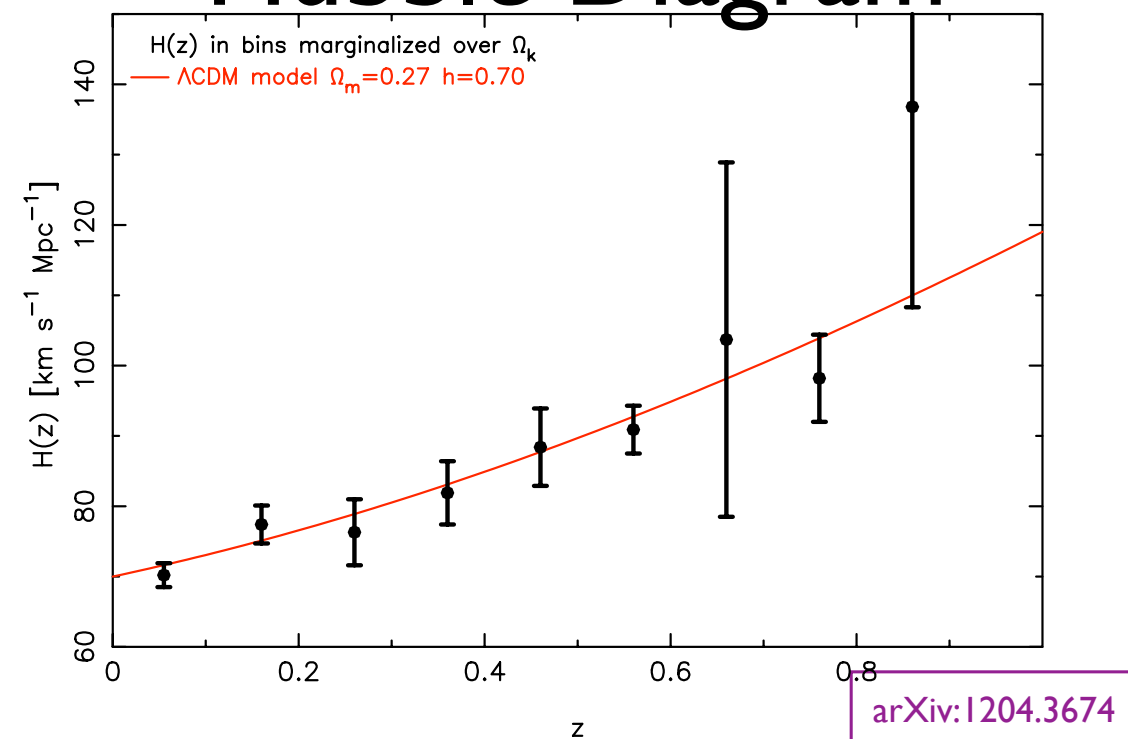
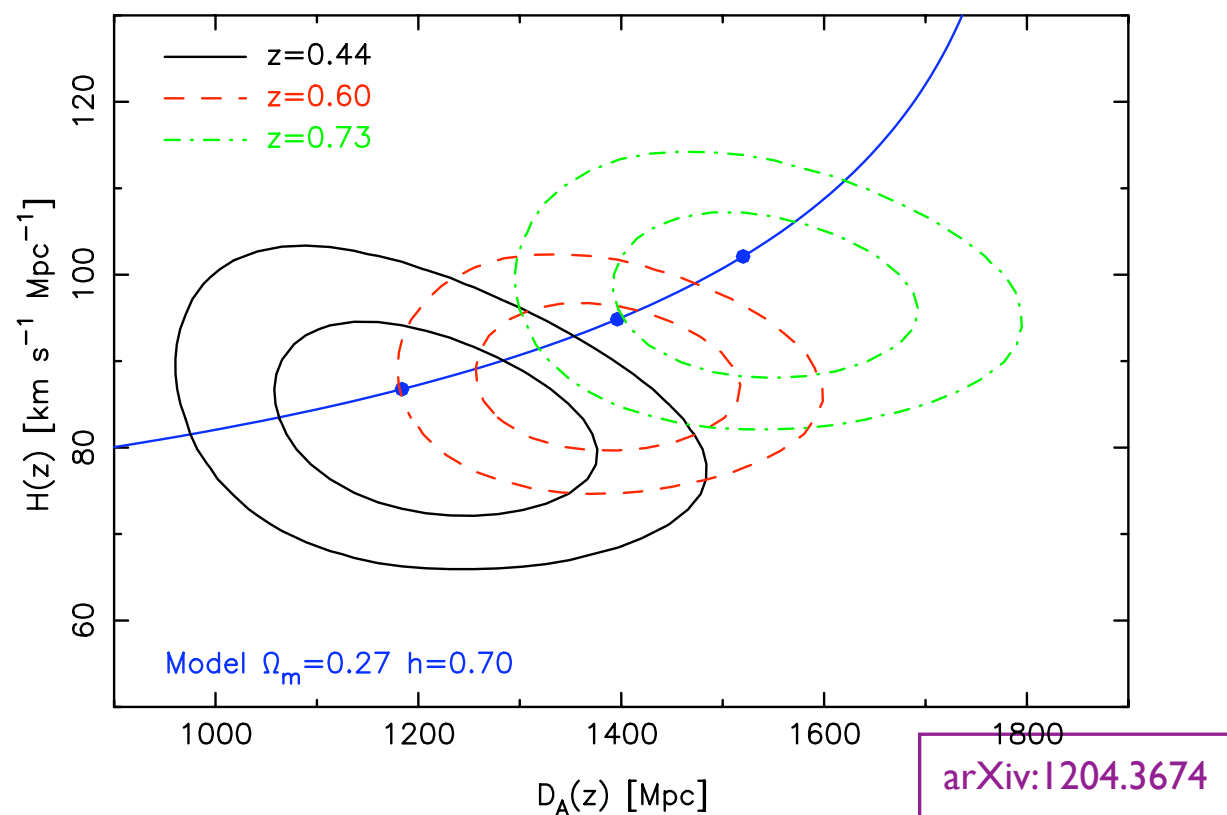
**Reconstructed**

Sánchez & Kazin (in prep.)

# WiggleZ $H$ - $D_A$ Results

Blake & the WiggleZ (2012)

## Hubble Diagram



Same-same but  
different:  $da/dt = H \cdot a$



- $\xi(\Delta\mu, s)$  wedges more practical than 2D  $\xi(\mu, s)$  plane because:
  - Higher S/N
  - Much cheaper (=easier) covariance matrix
- Compared to multipoles  $\xi_\ell(s)$  in constraining  $H, D_A, f$ :
  - Is one basis better than the other?
  - Are two peaks more useful than one?
  - to be continued ...



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# Warning!

slides contain  
t might not be  
individuals  
periodic box.

The following  
information that  
appropriate for  
that live inside a



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# Warning!

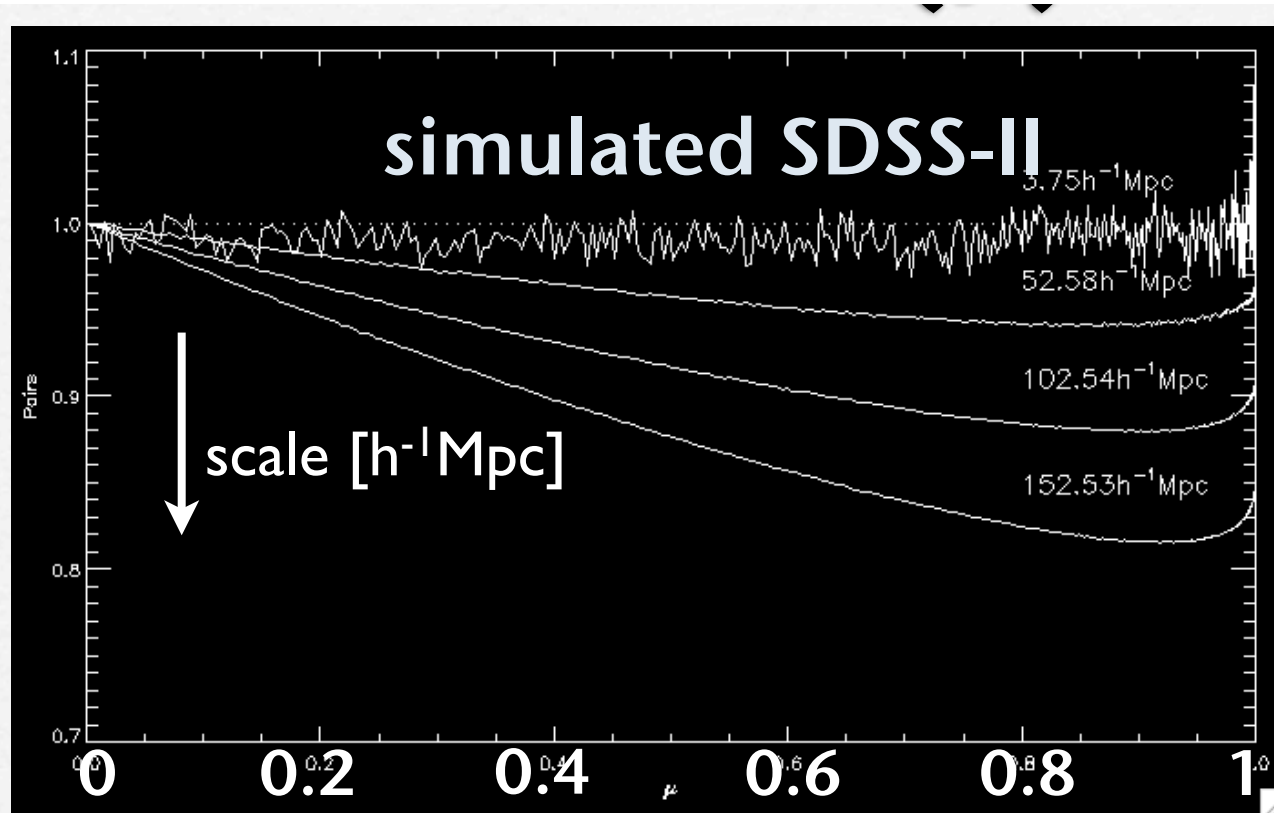
The following slides contain information that might not be appropriate for individuals that live inside a periodic box.





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$$N_{RR}(\mu) \neq \text{constant}$$



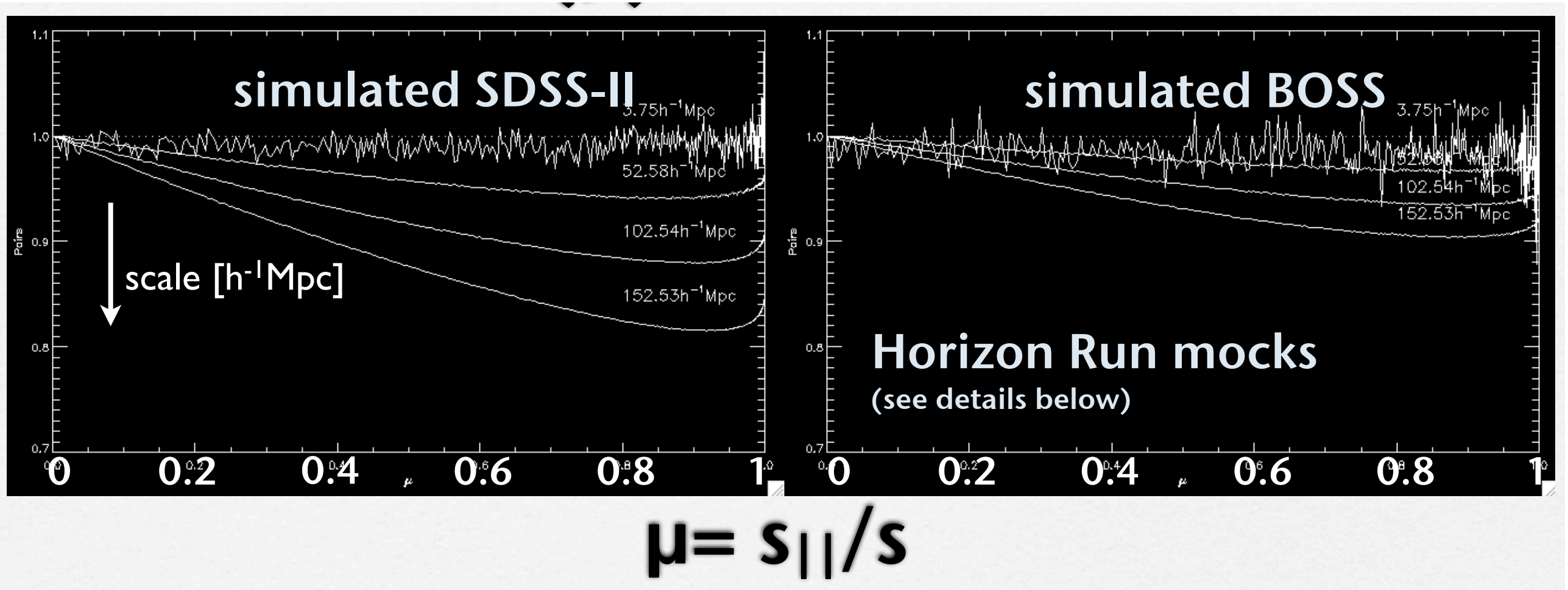
$$\mu = s_{||}/s$$

**LasDamas (SDSS-II geometry)**  
**0.16 < z < 0.44** volume limited  
**8000 deg<sup>2</sup>, SDSS sky-coverage**



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$$N_{RR}(\mu) \neq \text{constant}$$



**LasDamas (SDSS-II geometry)**  
**0.16 < z < 0.44** volume limited  
**8000 deg<sup>2</sup>, SDSS sky-coverage**

**Horizon Run (~BOSSish 2014)**  
**0.16 < z < 0.6** volume limited  
**10,300 deg<sup>2</sup> (π str) BOX**



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# BOSS Advertisement

*Now in your nearest browser!*

*More than 800,000 spectra in over 3,000 deg<sup>2</sup>*

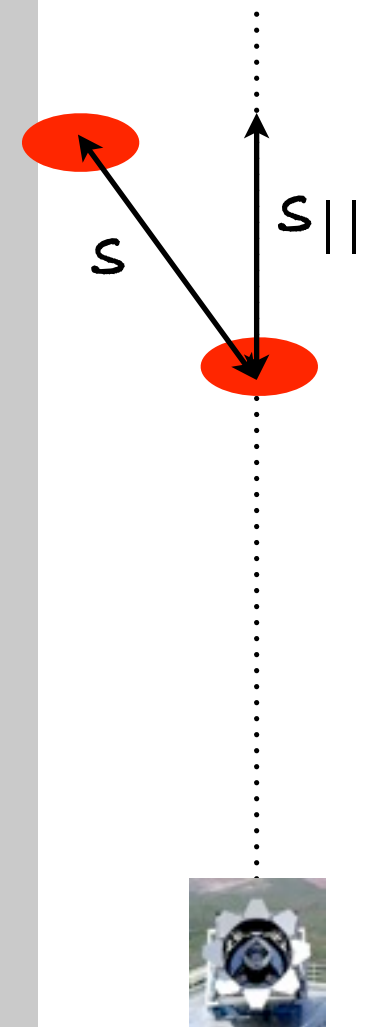
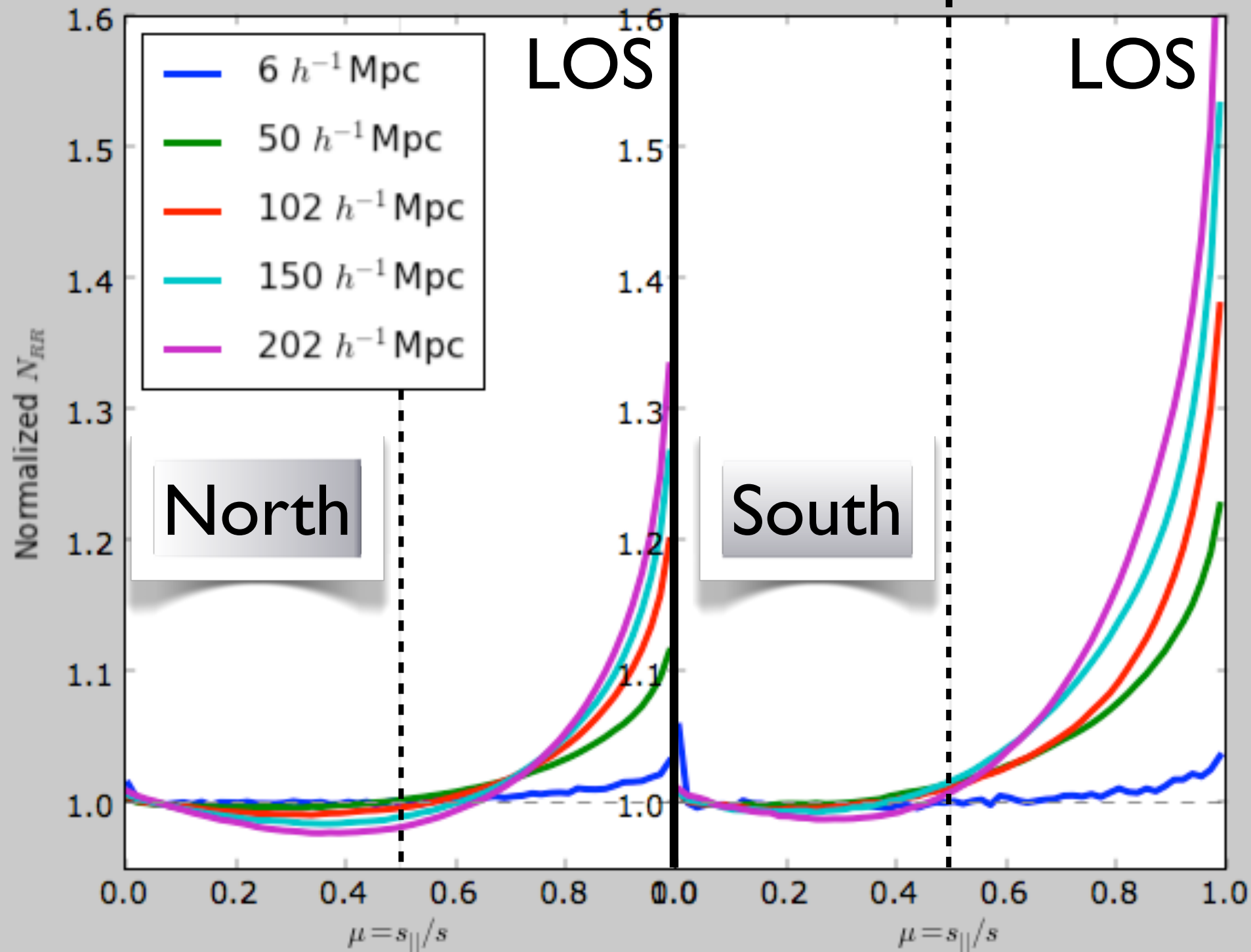
<http://sdss3.org/dr9/>



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$$N_{RR}(\mu) \neq \text{constant}$$

**BOSS CMASS DR9- now public!**







## $\xi$ Estimators: Direct vs Integrated

$$\mathcal{P}_0 = 1$$
$$\mathcal{P}_2 = \frac{1}{2} (3\mu^2 - 1)$$

**[up to  $(2\ell+1)/2$ ]**

$$\xi_\ell \equiv \int_{-1}^{+1} d\mu \mathcal{P}_\ell(\mu) \xi(\mu, s) = \int_{-1}^{+1} d\mu \mathcal{P}_\ell(\mu) \frac{DD(\mu, s) - RR(\mu, s)}{RR(\mu, s)}$$



# $\xi$ Estimators: Direct vs Integrated

## $\xi$ INTEGRATED

$$\mathcal{P}_0 = 1$$

$$\mathcal{P}_2 = \frac{1}{2} (3\mu^2 - 1)$$

**[up to  $(2\ell+1)/2$ ]**

$$\xi_\ell \equiv \int_{-1}^{+1} d\mu \mathcal{P}_\ell(\mu) \xi(\mu, s) = \int_{-1}^{+1} d\mu \mathcal{P}_\ell(\mu) \frac{DD(\mu, s) - RR(\mu, s)}{RR(\mu, s)}$$



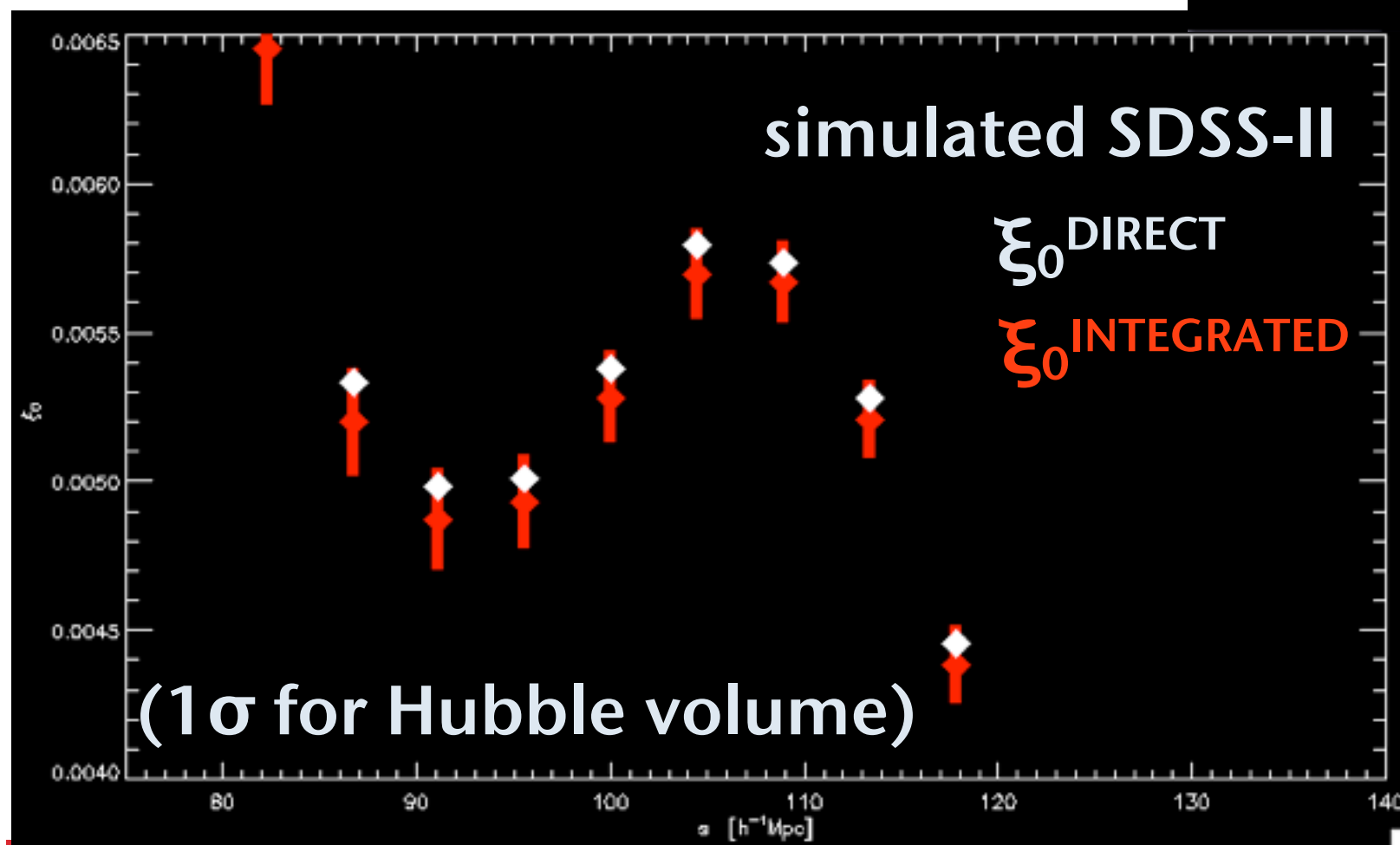
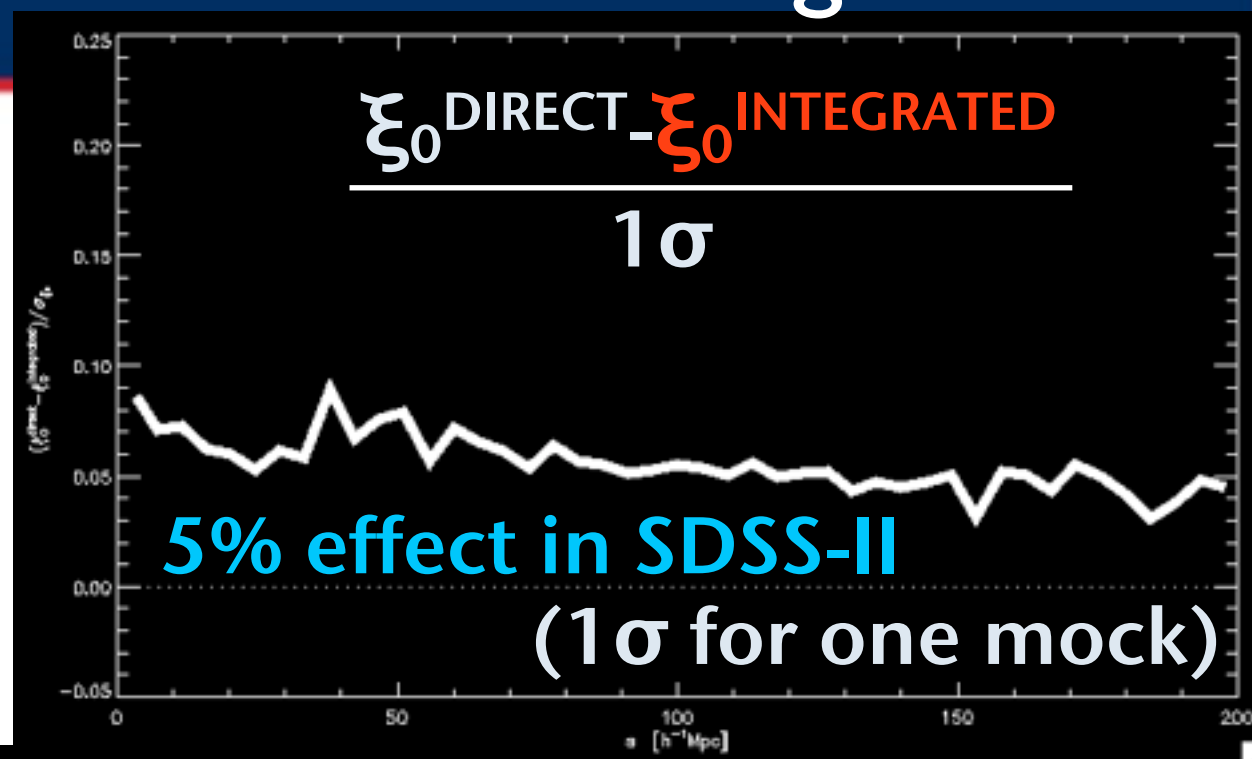
$$\xi_0(s) = \frac{DD(s) - RR(s)}{RR(s)} \neq \int_{-1}^{+1} d\mu \frac{DD(\mu, s) - RR(\mu, s)}{RR(\mu, s)}$$

## $\xi$ DIRECT



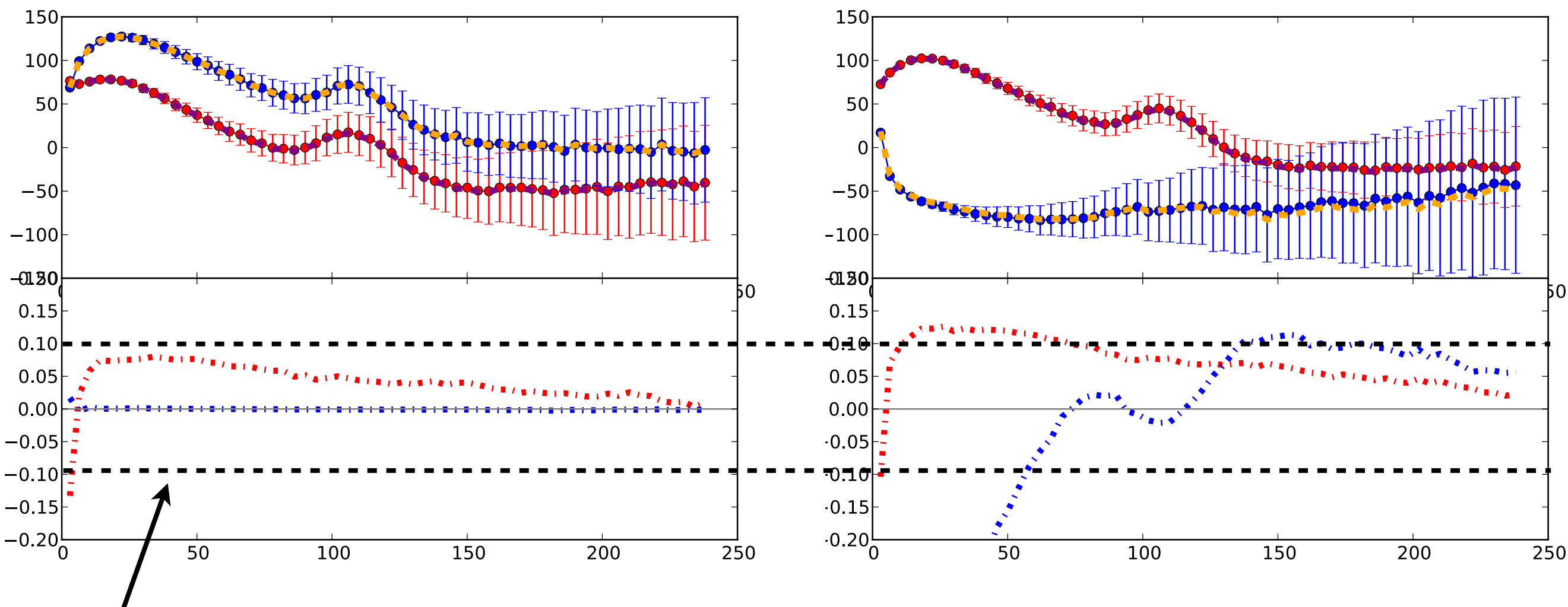
$$\xi_0(s) = \frac{DD(s) - RR(s)}{RR(s)} = \int_{-1}^{+1} d\mu \frac{DD(\mu, s) - RR(\mu, s)}{RR(\mu, s)} \cdot \frac{RR(\mu, s)}{RR(s)}$$

# $\xi$ Estimators: Direct vs Integrated



# $\xi$ Estimators: Direct vs Integrated Investigating 610 BOSS Mocks

$$(\xi^{\text{INTEGRATED}} - \xi^{\text{DIRECT}}) / \sigma_{\xi}$$



10% of  $1\sigma_{\xi}$  line: indicating **wedges are less sensitive to method of estimator**



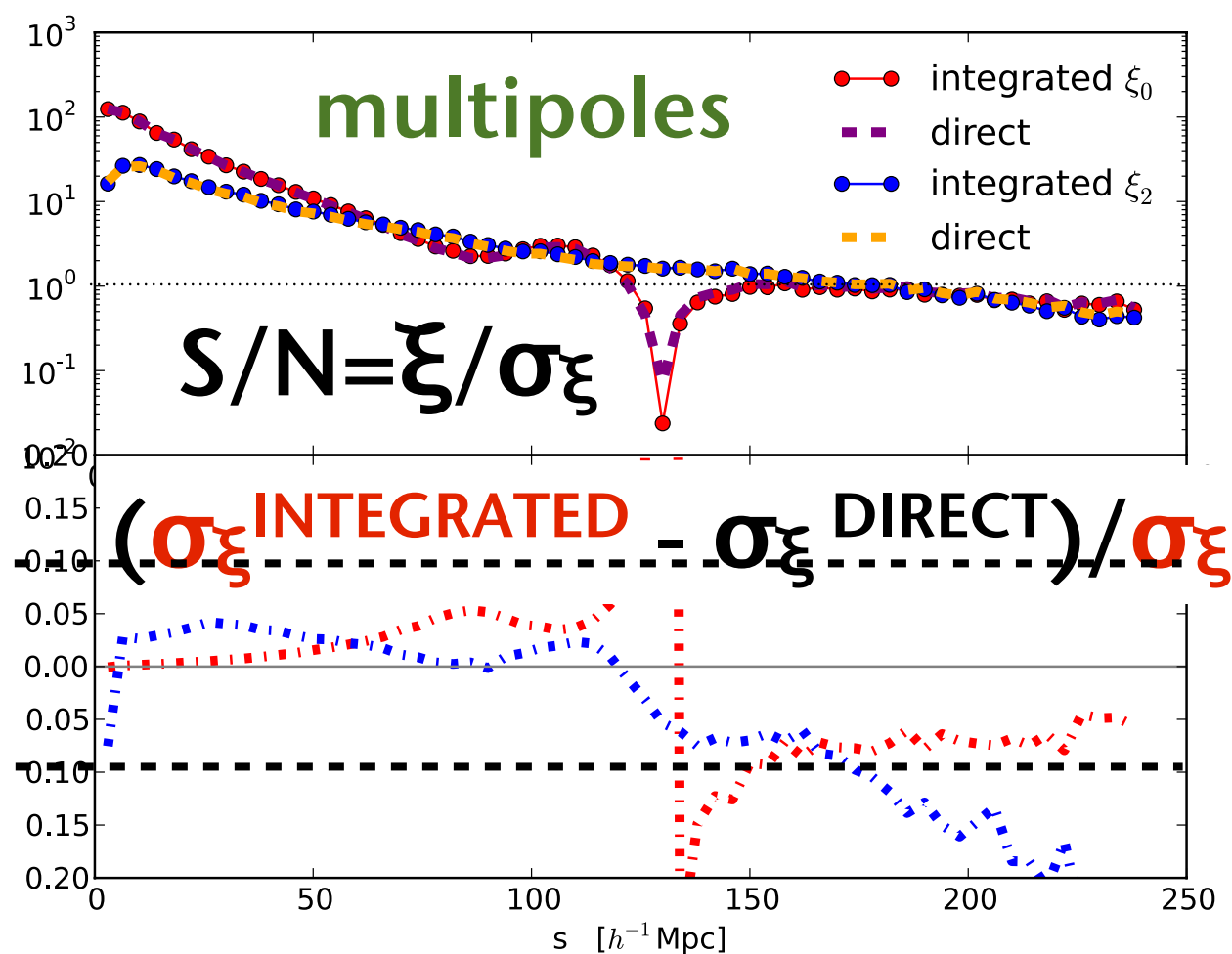
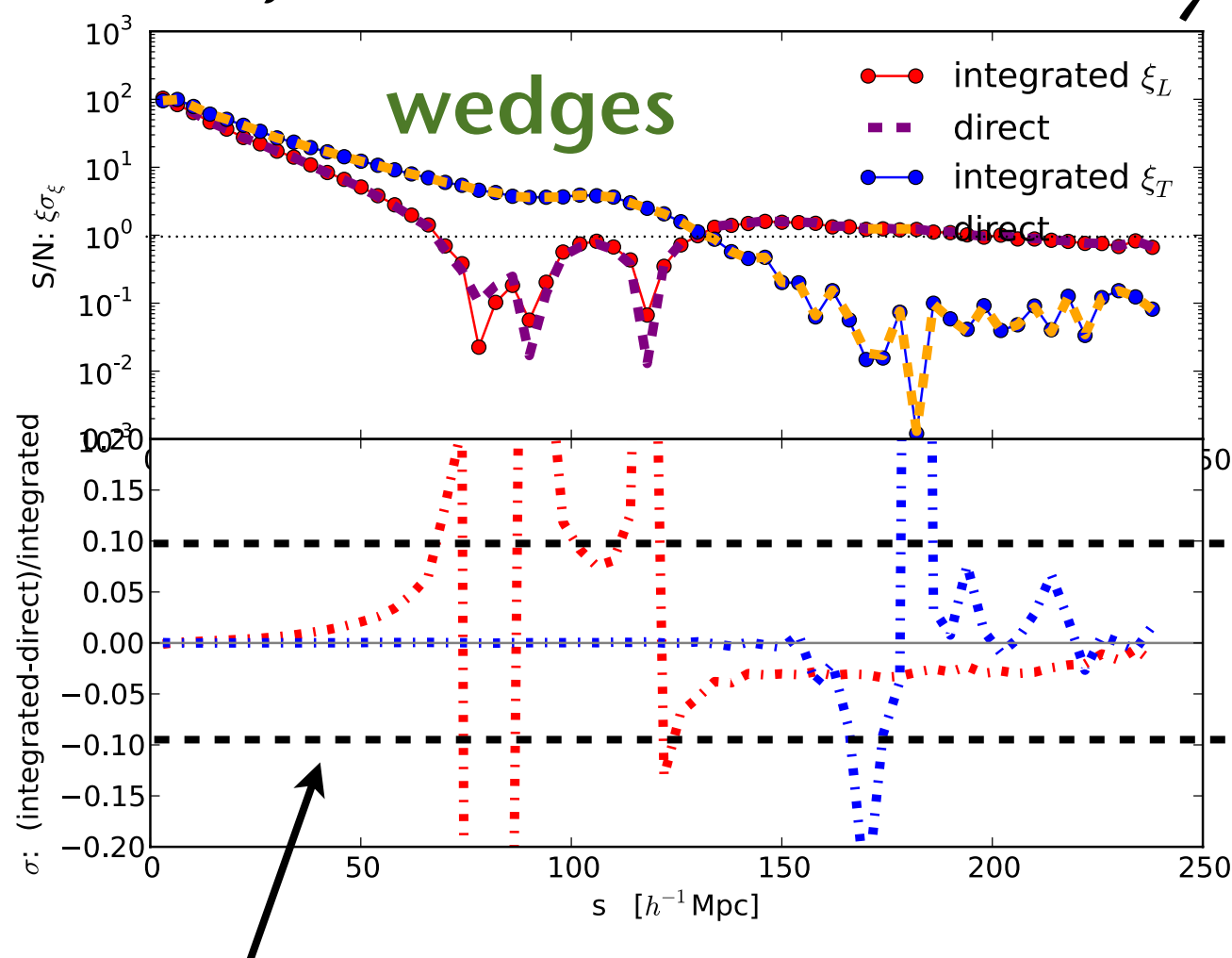


*But, don't you degrade  
the  $C_{ij}$ ,  
when integrating  
over noisy data bins?*

# $\xi$ Estimators: Direct vs Integrated

## Investigating 610 BOSS Mocks

*increase in noise?*  
*no, not too shabby (on most scales)...*



**10% of  $1\sigma_\xi$  line: indicating wedges are less sensitive to method of estimator**

# Clustering Wedges (temporary) Summary

- $\xi(\Delta\mu, s)$  wedges more practical than 2D  $\xi(\mu, s)$  plane because:
  - Higher S/N
  - Much cheaper (=easier) covariance matrix
- Comparing  $\xi(\Delta\mu)$  wedges to  $\xi_\ell(s)$  multipoles in constraining  $H, D_A, f$

3D  $\rightarrow$  2D  $\rightarrow$  1D

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- Con  
to  $\xi$   
cons



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  - Higher S/N
  - Much cheaper (=easier) covariance matrix
- Compared to multipoles  $\xi_\ell(s)$  in constraining  $H, D_A, f$ :
  - Is one basis better than the other?
  - Are two strong peaks more useful than one?
  - to be continued ...

*Thank You!*



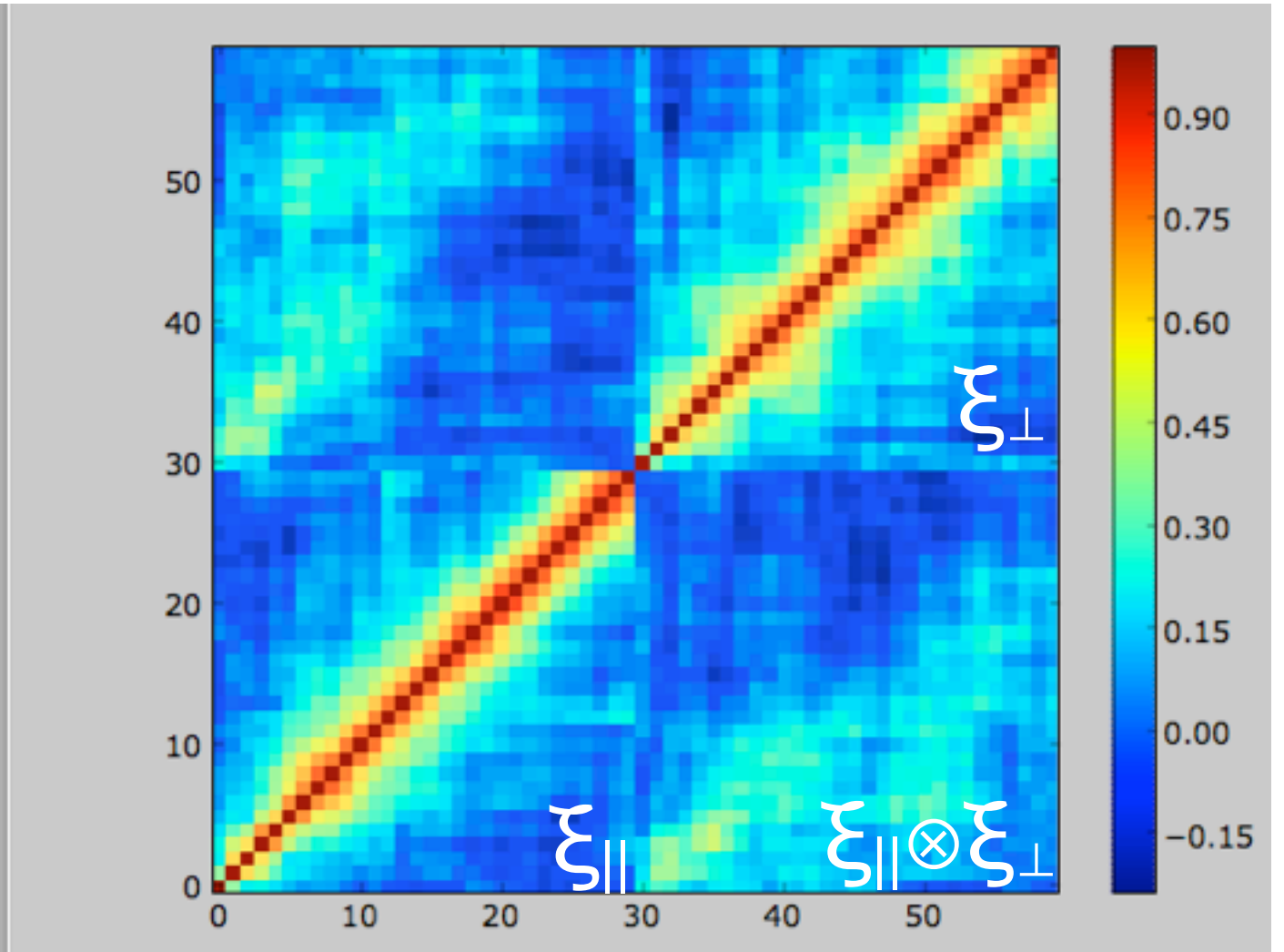
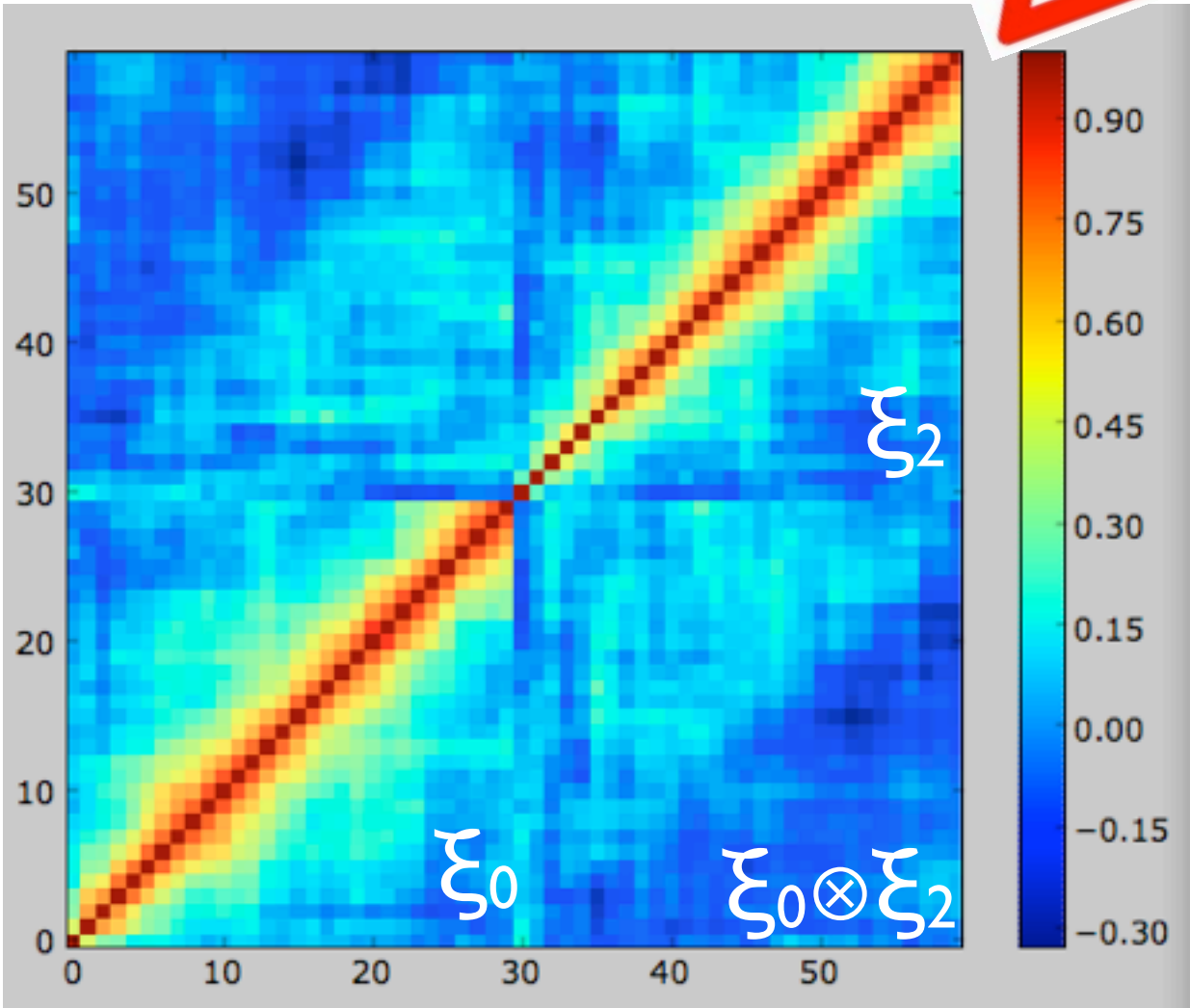
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# Covariance Matrix Comparison (Normalized)



$\xi_\ell(s)$

$\xi(\Delta\mu, s)$



5 100 200 5 100 200  
 $h^{-1} \text{Mpc}$

5 100 200 5 100 200  
 $h^{-1} \text{Mpc}$

$C_{ij}$  from LasDamas  $0.16 < z < 0.44$  (of McBride et al. in prep)

$\Delta s = 6.7 h^{-1} \text{Mpc}$  range 5-197  $h^{-1} \text{Mpc}$