# Centro de Ciencias de Benasque Pedro Pascual

Partial Differential Equations Optimal Design & Numerics

# **Dedicated to Vicent Caselles**

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# Variational Characterization of Diagonalization Operators & Eigenvalues



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#### Today's talk

Origin of the problem A global approach A global approach: infinite dimension Remarks

## Origin of the problem



## Origin of the problem

• We were interested in the determination of a system of orthonormal functions  $\psi := (\psi_m)_{m \ge 1}$  satisfying

(1.1) 
$$\begin{cases} i\partial_t \psi_m - \Delta \psi_m + (V + \widetilde{V}) \psi_m = 0 & \text{in } (0, T) \times \Omega \\ -\Delta V = \sum_{m=1}^{\infty} \alpha_m |\psi_m(x, t)|^2 & \text{in } (0, T) \times \Omega \\ \psi_m(0, x) = \psi_{0m}(x) & \text{in } \Omega \\ \psi_m(t, \sigma) = 0 & \text{on } [0, T] \times \partial \Omega \end{cases}$$

► A *standing wave solution* is an orthonormal system of functions  $(\varphi_m)_{m \ge 1}$  such that the family defined by

$$\psi_m(t,x) = \mathrm{e}^{\mathrm{i}\lambda_m t} \varphi_m(x)$$

satisfies (1.1).

For instance  $(\psi_{0m})_{m\geq 0}$  may be a Hilbert basis of  $L^2(\Omega)$  with each  $\psi_{0m} \in H^1_0(\Omega)$ .

## Origin of the problem

► The Schrödinger–Poisson system becomes: find a system of orthonormal functions  $\varphi := (\varphi_m)_{m \ge 1}$  and a sequence of real eigenvalues  $(\lambda_m)_{m \ge 1}$  satisfying

(1.2) 
$$\begin{cases} -\Delta \varphi_m + (V + \widetilde{V}) \varphi_m = \lambda_m \varphi_m & \text{in } \Omega \\ -\Delta V = \sum_{m=1}^{\infty} \alpha_m |\varphi_m(x)|^2 & \text{in } \Omega \\ \varphi_m(\sigma) = 0 & \text{on } \partial \Omega \end{cases}$$

• The coefficients  $\alpha_m$  are assumed to satisfy

$$\alpha_m > 0, \qquad \sum_{m=1}^{\infty} \alpha_m < \infty.$$

- Various types of domains  $\Omega$  and boundary conditions may be considered.
- The potential  $\widetilde{V}$  is given and may be singular.

## A global approach



# A global approach

- Even the linear case (that is dropping the second equation in (1.2) and setting  $V \equiv 0$ ) deserves a new approach... also in the finite dimensional case
- In other words: can one characterize the whole eigensystem of a linear operator through one variational problem?
- Consider a selfadjoint positive definite matrix  $A : H \longrightarrow H$  where H is an *n*-dimensional Hilbert space
- The eigenvalues of A can be found through the critical values of the Rayleigh quotient

(2.1)	(Au u)
	(u u)

# A global approach

Namely, for 
$$1 \le k \le n - 1$$
,

(2.2) 
$$\lambda_1 = \inf_{u \in H} \frac{(Au|u)}{(u|u)}, \qquad \lambda_{k+1} = \inf\left\{\frac{(Au|u)}{(u|u)} ; u \in \operatorname{span}\{e_1, \dots, e_k\}^{\perp}\right\}$$

where  $e_1, \ldots, e_k$  are eigenvectors for  $\lambda_1, \ldots, \lambda_k$ .

- In practice, one finds *n* critical values (or critical points), each depending on the previous ones.
- ▶ When  $H_0$  is a separable, infinite dimensional Hilbert space and (A, D(A)) is an unbounded positive self-adjoint operator such that the imbedding H := $D(A^{1/2}) \subset H_0$  is compact, then the above procedure (2.2) yields all the eigenvalues of A.

# A global approach: finite dimensional space

- Finding  $(\lambda_j)_j$  is equivalent to find a Hilbert basis  $(\widetilde{u}_j)_j$  such that  $A\widetilde{u}_j = \lambda_j \widetilde{u}_j$
- Fix  $(e_j)_{1 \le j \le n}$ , a Hilbert basis of *H* Denoting by *U* the matrix such that  $Ue_j = \tilde{u}_j$ , the problem is thus to find a unitary operator *U* such that

$$AUe_j = \lambda_j Ue_j \iff U^* AUe_j = \lambda_j e_j.$$

► For simplicity, assume *A* positive definite, and denote

 $\mathbb{S} := \{ U : H \longrightarrow H ; \ U^* U = I \}.$ 

and choose *n* numbers  $\alpha_j > 0$ , with  $\alpha_j \neq \alpha_k$  for  $j \neq k$ , and denote  $D := \text{diag}(\alpha_j)$ 

• Let  $J : S \longrightarrow \mathbb{R}$  be defined by

(2.3) 
$$J(U) := \operatorname{tr}(DU^*AU) = \sum_{j=1}^n \alpha_j(U^*AUe_j|e_j).$$

# A global approach: finite dimensional space

• We show the following

**Theorem.** The functional *J* is smooth and achieves its minimum on  $\mathbb{S}$ , at some  $U_0 \in \mathbb{S}$ . Moreover if  $u_j := U_0 e_j$ , then  $(u_j)_{1 \le j \le n}$  is the eigensystem of *A*.

## Finite dimension: Idea of proof

▶ Let *M* be skew-adjoint, that is  $M^* = -M$ . Then for all  $t \in \mathbb{R}$  we have

 $U(t) := \exp(tM) U_0 \in \mathbb{S}.$ 

- ► Thus for all  $t \in \mathbb{R}$  we have  $J(U_0) \leq J(U(t))$
- We conclude that

$$\left(\frac{d}{dt}J(U(t))\right)_{|t=0} = 0.$$

• This means that for all M such that  $M^* = -M$ 

 $\operatorname{tr}(DU_0^*MAU_0) = \operatorname{tr}(DU_0^*AMU_0).$ 

Setting  $B := U_0 D U_0^*$ , we have that for all M such that  $M^* = -M$ ,

 $\operatorname{tr}(M(AB - BA)) = 0$ 

## Finite dimension: Idea of proof

• This implies that BA = AB, that is

 $U_0 D U_0^* A = A U_0 D U_0^*.$ 

Set  $u_j := U_0 e_j$ , and apply the above operators to  $u_j$ 

 $(U_0 D U_0^*) A u_j = A U_0 D U_0^* u_j = A U_0 D e_j = \alpha_j A U_0 e_j = \alpha_j A u_j,$ 

• Thus 
$$U_0 D U_0^* A u_j = \alpha_j A u_j$$
, and

$$D(U_0^*Au_j) = \alpha_j(U_0^*Au_j).$$

Since  $\alpha_j$  is a simple eigenvalue of *D*, with a corresponding eigenvector  $e_j$ , and since  $Au_j \neq 0$  we conclude that

$$U_0^*Au_j = \lambda_j e_j \iff Au_j = \lambda_j u_j.$$

and finally  $U_0^*AU_0 = \operatorname{diag}(\lambda_1, \ldots, \lambda_n)$ .

A global approach: infinite dimension



## A global approach: infinite dimension

- ► Assumptions: *H* infinite dimensional, separable, complex Hilbert space, scalar product (·|·), norm || · ||.
- (A, D(A)) operator H, with  $D(A) \subset H$  dense and compact,  $A^* = A \ge 0$ .
- ▶  $(e_j)_{j\geq 1}$  a Hilbert basis of *H*, such that  $e_j \in D(A^{1/2})$  for each  $j \geq 1$ .
- $(\alpha_j)_{j\geq 1}$ , with  $\alpha_j > 0$ , such that

(3.1) 
$$\sum_{j\geq 1} \alpha_j \, \|e_j\|_{D(A^{1/2})}^2 < \infty,$$

and we denote by *D* the diagonal operator defined by  $De_j := \alpha_j e_j$  for  $j \ge 1$  (note that  $\alpha_j \rightarrow 0$  and *D* is compact).

• Consider  $U: H \longrightarrow H$  such that

(3.2) 
$$U^*U = UU^* = I$$
,  $Ue_j \in D(A^{1/2})$  for  $j \ge 1$ ,  $\sum_{j\ge 1} \alpha_j(U^*AUe_j|e_j) < \infty$ .

## A global approach: infinite dimension

• Define the set  $\mathbb{S}$  by

$$\mathbb{S} := \{ U : H \longrightarrow H ; \text{ } U \text{ satisfies (3.2)} \}.$$

 $\mathbb{S} \neq \emptyset$  is non trivial: for  $\lambda > 0$ , one has  $e^{i\lambda A} \in \mathbb{S}$  and  $U_{\lambda} := (I + i\lambda A)(I - i\lambda A)^{-1} \in \mathbb{S}$ 

▶ For  $U \in S$  define  $J_0(U)$  by

(3.3) 
$$J_0(U) := \operatorname{tr}(DU^*AU) := \sum_{j \ge 1} \alpha_j(U^*AUe_j|e_j)$$

**Theorem.**  $J_0$  achieves its minimum on  $\mathbb{S}$ . There exists  $\widehat{U}_0 \in \mathbb{S}$  such that  $J_0(\widehat{U}_0) = \min_{U \in \mathbb{S}} J_0(U),$ 

and  $\widehat{U}_0$  is a diagonalization operator for A; more precisely, for each  $j \ge 1$ , the vector  $\varphi_j := \widehat{U}_0 e_j$  is an eigenvector of A corresponding to the eigenvalue  $\lambda_j := (A\varphi_j | \varphi_j)$ .

### Infinite dimension: idea of proof

• Consider 
$$b := \inf_{U \in \mathbb{S}} J_0(U) \ge 0$$
.

- ▶ Let  $(U_n)_{n\geq 1} \in \mathbb{S}$  be such that  $b \leq J(U_n) \leq b + 1/n \leq b + 1$ .
- ▶ For fixed  $j \ge 1$ , setting  $u_j^n := U_n e_j$ , we have for all  $n \ge 1$

$$||u_j^n||_{D(A^{1/2})}^2 = 1 + (Au_j^n|u_j^n) \le 1 + \frac{b+1}{\alpha_j}.$$

▶ By Cantor's diagonal scheme, one finds a subsequence (denoted by)  $(u_j^n)_n$  such that there exists a family  $(u_j)_j$  such that for  $j \ge 1$  fixed

 $u_j^n \rightarrow u_j =: U_0 e_j$  weakly in  $D(A^{1/2})$ ,  $u_j^n \rightarrow u_j =: U_0 e_j$  strongly in H.

- $U_0$  can be extended to H, and  $U_0^*U_0 = I$ .
- ▶ Finally, one shows that  $J_0(U_0) < \infty$  and  $U_0 \in S$  and that  $J_0(U_0) = b$ .

## Infinite dimension: idea of proof

▶ Let  $M : H \longrightarrow H$  be bounded, skew-adjoint, that is  $M^* = -M$ , and moreover  $M : D(A^{1/2}) \longrightarrow D(A^{1/2})$  continuous. Then for all  $t \in \mathbb{R}$  we have

 $U(t) := \exp(tM)U_0 \in \mathbb{S}.$ 

- ► Thus for all  $t \in \mathbb{R}$  we have  $J(U_0) \leq J(U(t)) =: g_0(t)$ . We conclude that  $g'_0(0) = \operatorname{tr}(DU_0^*MAU_0) \operatorname{tr}(DU_0^*AMU_0) = 0$ .
- Since  $\operatorname{tr}(DU_0^*MAU_0) = -\sum_j \alpha_j(Au_j|Mu_j)$  and  $\operatorname{tr}(DU_0^*AMU_0) = \sum_j \alpha_j(Mu_j|Au_j)$  this means

(3.4) 
$$\operatorname{Re}\sum_{j\geq 1}\alpha_j(Au_j|Mu_j) = 0$$

• Choosing M := iL with  $L^* = L$ , one gets

(3.5) 
$$\operatorname{Im}\sum_{j\geq 1}\alpha_j(Au_j|Lu_j)=0.$$

#### Infinite dimension: idea of proof

• Let  $n \neq k$  and let the operators *M* and *L* be defined by:

 $Mu_k := u_n$ ,  $Mu_n := -u_k$ ,  $Lu_k := u_n$ ,  $Lu_n := u_k$ ,  $Lu_j = Mu_j = 0$  if  $j \notin \{k, n\}$ .

Using (3.4) and (3.5), we conclude that

$$(\alpha_n - \alpha_k)(Au_n|u_k) = 0.$$

• Thus if  $\alpha_n \neq \alpha_k$ , we have

$$0 = (Au_n | u_k) = (U_0^* A U_0 e_n | e_k).$$

▶ Assume for instance for all  $n \neq k$  one has  $\alpha_n \neq \alpha_k$ . Then the above means that

$$U_0^* A U_0 e_n \in \operatorname{span}\{e_n\} \iff \exists \lambda_n \in \mathbb{R}, \quad A u_n = \lambda_n u_n.$$

#### Remarks



### Remarks

- ▶ When in (2.3) one chooses  $\alpha_j > \alpha_{j+1}$  for all  $j \ge 1$ , then one can check that the eigenvalues  $\lambda_j$  are ordered in a non decreasing order.
- ▶ In the infinite dimenional case, a typical example of application is the case

$$Au := -\Delta u + Vu, \quad \text{for } u \in D(A),$$

with

$$D(A) := \left\{ u \in H_0^1(\Omega) ; -\Delta u + Vu \in L^2(\Omega) \right\}.$$

- Here  $\Omega \subset \mathbb{R}^N$  is bounded, and  $V^+ \in L^1_{loc}(\Omega)$  while  $V^- \in L^p(\Omega)$  for some p > N/2.
- ► In the case of  $\Omega = \mathbb{R}^N$ , one can adapt the above method if one assumes that there exists a sequence  $(e_j)_{j\geq 1}$  which is total in  $L^2(\mathbb{R}^N)$  and such that

$$\int_{\mathbb{R}^N} e_j(x)\overline{e_k}(x)dx = \delta_{kj}, \text{ and for all } j \ge 1, \quad \int_{\mathbb{R}^N} \left( |\nabla e_j|^2 + V|e_j(x)|^2 \right) dx < 0.$$

## Remarks

Bob Kohn mentioned to us a result due to J. von Neumann which states that for two *n* × *n* matrices *A* and *B* 

$$|\operatorname{tr}(AB)| \le \sum_{j=1}^n \sigma_j(A)\sigma_j(B)$$

where  $(\sigma_j(A))_{1 \le j \le n}$  and  $(\sigma_j(B))_{1 \le j \le n}$  denote the decreasing singular values of *A* and *B* respectively.

From this L. Mirsky (1975) points out that one can conclude another result due to J. von Neumann, stating that:

$$\sup_{U,V} |\operatorname{tr}(BUAV)| = \sum_{j=1}^n \sigma_j(A)\sigma_j(B).$$

Our result, which is specialized to self-adjoint matrices, can be interpreted as another proof of the above result in that particular case, and also characterizes the diagonalization matrice by a variational method.