

The Obstacle Problem for the Total Variation

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The TV obstacle problem

Consider

- a bounded open set Ω in \mathbb{R}^n , n positive integer,
- an obstacle $\psi: \bar{\Omega} \rightarrow \mathbb{R}$ with $\psi \leq 0$ on $\partial\Omega$.

Obstacle problem: Minimize the total variation (TV)

$$\int_{\Omega} |\nabla u| \, dx$$

among functions $u: \bar{\Omega} \rightarrow \mathbb{R}$ with

$$u \equiv 0 \text{ on } \partial\Omega \quad \text{and} \quad u \geq \psi \text{ on } \Omega.$$

The generalized TV obstacle problem

Natural space for existence results (thanks to weak* compactness):

$$BV_0(\overline{\Omega}) := \left\{ u \in L^1(\mathbb{R}^n) : \begin{array}{l} \text{gradient } Du \text{ is finite measure on } \mathbb{R}^n \\ \text{and } u \equiv 0 \text{ a.e. on } \mathbb{R}^n \setminus \Omega \end{array} \right\}$$

(contains $W_{(0)}^{1,1}(\Omega)$, but also u with jumps along hypersurfaces in $\overline{\Omega}$).

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Generalized obstacle problem: Minimize the total mass of Du

$$|Du|(\bar{\Omega}) = |Du|(\Omega) + \underbrace{|Du|(\partial\Omega)}_{\approx \|\text{int trace}(u)\|_{L^1(\partial\Omega)}}$$

among

$$u \in BV_0(\bar{\Omega}) \quad \text{with } u \geq \psi \text{ a.e. on } \Omega.$$

Existence and duality for $W^{1,1}$ obstacles

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- For $\partial\Omega$ Lipschitz, $\psi \in W_0^{1,1}(\Omega)$, one has the duality formula

$$\begin{aligned} & \min\{|Du|(\bar{\Omega}) : u \in BV_0(\bar{\Omega}), u \geq \psi \text{ a.e. on } \Omega\} \\ &= \max\left\{ \int_{\Omega} \sigma \cdot \nabla \psi \, dx : \sigma \in \underbrace{S^\infty(\Omega, \mathbb{R}^n)}_{\text{sub-unit vector fields}}, \operatorname{div} \sigma \leq 0 \text{ in } \mathcal{D}'(\Omega) \right\}. \end{aligned}$$

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\rightsquigarrow to say more, need products $\sigma \cdot D\psi$ and $\sigma \cdot Du$ if merely $\psi, u \in BV$ (e.g. if ψ is a characteristic function).

The Anzellotti pairing

Consider:

- $u \in \text{BV}_{\text{loc}}(\Omega)$,
- a vector field $\sigma \in L^\infty_{\text{loc}}(\Omega, \mathbb{R}^n)$ (w.r.t. Lebesgue measure dx).

Can one define a product $[[\sigma, Du]]$?

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Can one define a product $[[\sigma, Du]]$? If $\text{div } \sigma$ is suitably good, yes:

Definition (Kohn & Temam '82/'83, Anzellotti '83, ...)

For u, σ as above, the distribution

$$[[\sigma, Du]] := \text{div}(\sigma u) - u \text{div } \sigma \in \mathcal{D}'(\Omega).$$

makes sense (and behaves reasonably) if ...

- ... either $u \in L^\infty_{\text{loc}}(\Omega)$, $\text{div } \sigma \in L^1_{\text{loc}}(\Omega)$
- ... or $\text{div } \sigma \in L^n_{\text{loc}}(\Omega)$ (then uses Sobolev's embedding).

A pairing for divergence-measure fields

But even if $\operatorname{div} \sigma \notin L^1_{\text{loc}}(\Omega)$, we still have:

Definition (a new Anzellotti type pairing, Scheven & S.)

For $u \in \text{BV}_{\text{loc}}(\Omega) \cap L^\infty_{\text{loc}}(\Omega)$ and $\sigma \in L^\infty_{\text{loc}}(\Omega, \mathbb{R}^n)$ such that $\operatorname{div} \sigma$ is Radon measure (in particular if $\operatorname{div} \sigma \leq 0$ in $\mathcal{D}'(\Omega)$), we define

$$[[\sigma, Du^+]] := \operatorname{div}(\sigma u) - u^+ \operatorname{div} \sigma \in \mathcal{D}'(\Omega).$$

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- makes sense because
 - $\operatorname{div} \sigma$ vanishes on \mathcal{H}^{n-1} -negligible sets (Chen & Frid '99),
 - u has \mathcal{H}^{n-1} -a.e. defined representatives u^\pm s.t., for \mathcal{H}^{n-1} -a.e. x , either $u^+(x) = u^-(x)$ is the Lebesgue value of u at x or $u^-(x) < u^+(x)$ are the approximate jump values of u at x .
- pairing $[[\sigma, Du^*]]$ with representative $u^* := \frac{u^+ + u^-}{2}$ already used by Mercaldo & Segura de León & Trombetti '09.

Properties of the pairing

Theorem (properties of $[[\sigma, Du^+]]$, Scheven & S.)

For $u \in BV_{\text{loc}}(\Omega)$ and $\sigma \in L^\infty(\Omega, \mathbb{R}^n)$ with $\operatorname{div} \sigma \leq 0$ in $\mathcal{D}'(\Omega)$,

- $[[\sigma, Du^+]]$ is a Radon measure with product estimate

$$|[[\sigma, Du^+]]| \leq \|\sigma\|_{L^\infty(\Omega, \mathbb{R}^n)} |Du| \quad \text{on } \Omega,$$

- and its absolutely continuous part is the pointwise product, i.e.

$$[[\sigma, Du^+]]^a = (\sigma \cdot \nabla^a u) dx \quad \text{on } \Omega.$$

- In particular, $[[\sigma, Du^+]] = (\sigma \cdot \nabla u) dx$ trivializes for $u \in W_{\text{loc}}^{1,1}(\Omega)$.

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- Proofs based on fine (semi)continuity and capacity methods (e.g., since u^+ is *not* the limit of standard mollifications, need one-sided approximations of Carriero-Dal Maso-Leaci-Pascali '88).
- Up-to-the-boundary pairing $[[\sigma, Du^+]]_0$ on $\overline{\Omega}$ accounts for zero Dirichlet datum (on mildly regular $\partial\Omega$; cf. S. '15, Beck & S. '15).

Duality for BV obstacles

Theorem (duality for the TV obstacle problem, Scheven & S.)

For mildly regular $\partial\Omega$, $\psi \in \text{BV}_0(\overline{\Omega}) \cap L^\infty(\Omega)$ with $|D\psi|(\partial\Omega) = 0$:

$$\begin{aligned} & \min\{|Du|(\overline{\Omega}) : u \in \text{BV}_0(\overline{\Omega}), u \geq \psi \text{ a.e. on } \Omega\} \\ & = \max\{[\![\sigma, D\psi^+\]\!](\Omega) : \sigma \in \mathcal{S}^\infty(\Omega, \mathbb{R}^n), \text{div } \sigma \leq 0 \text{ in } \mathcal{D}'(\Omega)\}. \end{aligned}$$

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Two methods of proof (both rely on the properties of the pairing):

- Either look at obstacle problems for the p -Laplace in $W_0^{1,p}$ and pass $p \searrow 1$ (this way, if $\psi \in W_0^{1,1+\varepsilon}$, also get a convergence result for minimizers when $p \searrow 1$),

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- or deduce it from (abstract) convex duality.

BV optimality conditions

Heuristically, minimizers u should satisfy

$$\operatorname{div} \frac{\nabla u}{|\nabla u|} \leq 0,$$

and we can now make this precise:

Corollary (optimality conditions for the TV obstacle problem)

Every minimizer $u \in \text{BV}_0(\overline{\Omega})$ is super-1-harmonic on Ω in the sense that there exists some $\sigma \in S^\infty(\Omega, \mathbb{R}^n)$ with

$$\underbrace{\llbracket \sigma, Du^+ \rrbracket_0 = |Du| \text{ on } \overline{\Omega}}_{\text{BV-way of saying } \sigma = \frac{\nabla u}{|\nabla u|}} \quad \text{and} \quad \operatorname{div} \sigma \leq 0 \text{ in } \mathcal{D}'(\Omega).$$

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$$\underbrace{\llbracket \sigma, Du^+ \rrbracket_0}_{\text{BV-way of saying } \sigma = \frac{\nabla u}{|\nabla u|}} = |Du| \text{ on } \overline{\Omega} \quad \text{and} \quad \operatorname{div} \sigma \leq 0 \text{ in } \mathcal{D}'(\Omega).$$

Moreover, u is 1-harmonic away from the obstacle in the sense of

$$\operatorname{div} \sigma \equiv 0 \text{ on } \Omega \cap \{u^+ > \psi^+\}.$$

Extensions

We can also treat ...

- (much) more general obstacles:
 - thin and, most generally, quasi upper semicontinuous obstacles (then need additional tools: relaxation, De Giorgi's measure, ...),
 - obstacles which are positive up to $\partial\Omega$ (then need modified pairing),

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 - obstacles which are positive up to $\partial\Omega$ (then need modified pairing),
- the non-parametric area $\int_{\Omega} \sqrt{1+|\nabla u|^2} \, dx$ and similar functionals,
- general boundary values.

Related topics

Related work in progress concerns . . .

- *BV supersolutions* to 1-Laplace and minimal surface equations, in particular:
 - compactness results,
 - the question if simultaneous super- and sub-solutions are solutions (for the 1-Laplace surprisingly non-trivial, since σ is not unique \rightsquigarrow duality argument of possible interest; cf. Yan '11),

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 - the question if simultaneous super- and sub-solutions are solutions (for the 1-Laplace surprisingly non-trivial, since σ is not unique \rightsquigarrow duality argument of possible interest; cf. Yan '11),
- variational **existence results for measure data problems** to the 1-Laplace equation and the prescribed mean curvature equation (parametric or non-parametric; in the last case yields an alternative to the approach of Dai & Trudinger & Wang '12).