



Relativistic Stars in dRGT Massive Gravity

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Introduction

- About dRGT Massive Gravity
- Our Motivations

About dRGT Massive Gravity/ Our motivations



- It is the theory of ghost-free massive spin-2 field. [de Rham, Gabadadze, Tolley (2010)]
 - → The theory can be describe accelerated universe. The mass terms behave like cosmological constant. [A. Gümrükçüoğ, C. Lin, S. Mukohyama(2010)]
- Relativistic stars' structure, especially maximum mass, can be modified by non-linear effects, strong-field structure of the theory.
- Massive neutron star, whose mass is 2 solar mass, may be explained by the theory.
- We calculate the hydrostatic equilibrium and maximum mass numerically.

Action of dRGT Massive Gravity



$$S_{\mathrm{dRGT}} = \frac{1}{2\kappa^2} \int d^4x \sqrt{-\det(g)} \left[R - 2m_0^2 \sum_{n=0}^4 \beta_n e_n \left(\sqrt{g^{-1}f}\right) \right] + S_{\mathrm{matter}}$$

- $g_{\mu\nu}$, $f_{\mu\nu}$: Dynamical and Reference metric ■ $\kappa^2 = 8\pi G$: Gravitational coupling
- \blacksquare m_0, β_n : Parameters of the theory

$$\begin{pmatrix} \sqrt{g^{-1}f} \end{pmatrix}_{\rho}^{\mu} \left(\sqrt{g^{-1}f} \right)_{\nu}^{\rho} = g^{\mu\rho} f_{\rho\nu} [\mathbf{X}] := \operatorname{Tr}(\mathbf{X}), \quad e_0(\mathbf{X}) = 1, \quad e_1(\mathbf{X}) = [\mathbf{X}] e_2(\mathbf{X}) = \frac{1}{2} \left([\mathbf{X}]^2 - [\mathbf{X}^2] \right), \quad e_3(\mathbf{X}) = \frac{1}{6} \left([\mathbf{X}]^3 - 3[\mathbf{X}][\mathbf{X}^2] + 2[\mathbf{X}^3] \right), e_4(\mathbf{X}) = \frac{1}{24} \left([\mathbf{X}]^4 - 6[\mathbf{X}]^2[\mathbf{X}^2] + 3[\mathbf{X}^2]^2 + 8[\mathbf{X}][\mathbf{X}^3] - 6[\mathbf{X}^4] \right) = \det(\mathbf{X}), e_k(\mathbf{X}) = 0 \quad \text{for} \quad k > 4$$



Analysis on modified TOV equations

- A new constraint from mass terms
- Modified TOV equations

Our model / Assumptions



- minimal model : $\beta_0 = 3$, $\beta_1 = -1$, $\beta_2 = 0$, $\beta_3 = 0$
- graviton mass as cosmological constant : $m_0 = \frac{\hbar}{c} \sqrt{\Lambda} \sim 10^{-66} \mathrm{g}$
- Spherical and static dynamical metric

& flat reference metric

$$g_{\mu\nu}dx^{\mu}dx^{\nu} = -e^{2\phi}dt^{2} + e^{2\sigma}d\rho^{2} + D^{2}(\rho)(d\theta^{2} + \sin^{2}\theta d\varphi^{2})$$
$$f_{\mu\nu}dx^{\mu}dx^{\nu} = -dt^{2} + d\rho^{2} + \rho^{2}(d\theta^{2} + \sin^{2}\theta d\varphi^{2})$$
$$e^{-2\lambda(r)} \equiv 1 - \frac{2GM(r)}{r} \int D(\rho) \equiv r, \ \rho \equiv \chi(r), \ e^{2\sigma}(\chi'(r))^{2} \equiv e^{2\lambda}$$

$$g_{\mu\nu}dx^{\mu}dx^{\nu} = -e^{2\phi}dt^{2} + e^{2\lambda}dr^{2} + r^{2}(d\theta^{2} + \sin^{2}\theta d\varphi^{2})$$
$$f_{\mu\nu}dx^{\mu}dx^{\nu} = -dt^{2} + (\chi'(r))^{2}dr^{2} + \chi^{2}(r)(d\theta^{2} + \sin^{2}\theta d\varphi^{2})$$

A new constraint from mass terms



 Perfect fluid's energy-momentum tensor & their conservation laws

$$T_{\mu\nu} = \operatorname{diag}\left(e^{2\phi}\rho, e^{2\lambda}P, r^2P, r^2\sin^2\theta P\right), \ \nabla^{\mu}T_{\mu\nu} = 0$$

Abstract structure of equation of motions in our models.

$$G_{\mu\nu} + m_0^2 I_{\mu\nu} = \kappa^2 T_{\mu\nu}, \ I_{\mu\nu} = \sum_{n=0}^{3} (-1)^n \beta_n g_{\mu\lambda} Y^{\lambda}_{(n)\nu}(\sqrt{g^{-1}f})$$

$$Y^{\mu}_{(n)\nu}(\mathbf{X}) = \sum_{r=0}^{n} (-1)^r \left(X^{n-r}\right)^{\lambda}_{\nu} e_r(\mathbf{X})$$

$$\nabla^{\mu} T_{\mu\nu} = 0 \text{ means a additional constraint.}$$

$$\nabla^{\mu} I_{\mu\nu} = 0 \Leftrightarrow \left(\frac{2}{r} - (P + \rho)^{-1} P'\right) \left(1 - \frac{2GM(r)}{r}\right)^{1/2} - \frac{2}{r} = 0$$

Modified TOV equations



For numerical calculations, equations should be written by dimensionless variables.

$$r_g \equiv GM_{\odot}, \ r \to rr_g, \ M \to mM_{\odot}, \ m_0 \to \alpha M_{\odot},$$
$$\rho \to \tilde{\rho}(M_{\odot}/r_g^3), \ P \to p(M_{\odot}/r_g^3)$$

 \blacksquare m(r) can be eliminated by the new constraint.

$$\nabla_{\mu}I^{\mu\nu} = 0 \Leftrightarrow \left(1 - \frac{2m(r)}{r}\right)^{1/2} = \left(1 - \frac{1}{2}\frac{p'(r)}{p(r) + \tilde{\rho}(r)}r\right)^{-1}$$

The hydrostatic equation become a higher order differential equation of $\rho(r)$, $p(\rho(r))$.

Modified TOV equations

- To solve the system, one more equation is needed. A equation of state (EoS) $p(r) = p(\tilde{\rho}(r))$, which is defined by hadron physics, should be used.
- After using EOS for eliminating p(r), TOV equations become very complicated forms. I show the abstract structures.
 - A 3rd order ODE of $\tilde{\rho}(r)$.

An algebraic equation.

$$m = m(r, \tilde{\rho}(r), \tilde{\rho}'(r))$$

Used boundary conditions

To compare results with the same central density and radius of GR case, boundary conditions become as follows.

• r = 0 : P'(r = 0) = 0 and $\rho(r = 0) = \rho_c$. (2 boundary conditions exist.)

- r = R s.t. P(r = R) = 0: The radius coincides with that in GR result of the same central density.
 (1 boundary condition exist.)
- The 3 boundary conditions are sufficient to solve the 3rd order ODE.



Numerical Results

- Quark stars (MIT bag model)
- Neutron stars (SLy Model)

The case of quark stars (MIT bag model)



Because graviton mass is very tiny, the distribution is nearly the same.

Mass-central density relations of quark stars







Mass-radius relations of quark stars



The masses are drastically changed by the new constraint.



The case of neutron stars (SLy model)



Summary / Future works



- The new constraint appears from divergence of mass terms
- Modified TOV equations are
 3rd order ODE and the new constraint.
- Numerical Results
 - The density distributions are mostly not changed because of very tiny mass.
 - The masses are drastically changed because of the new constraint.
- The same analysis of other parameters are needed. That of bigravity are also needed.