

Long-time Behaviour of a Model of Rigid Structure Floating in a Viscous Fluid

G. Vergara-Hermosilla, M. Tucsnak, F. Sueur

Université de Bordeaux

VII Partial differential equations, optimal design and numerics
Benasque, Aug. 18 - Aug. 30, 2019



This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No 765579.



This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No 765579.



This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No 765579.

Visit www.conflex.org !

Outline

1. **A Model of rigid structure in a viscous fluid**
2. **Mittag-Leffler functions**
3. **Solutions unbounded case**
4. **Hurwitz and Anti-Hurwitz polynomials**
5. **Long-time behavior in viscous case**

The equilibrium problem

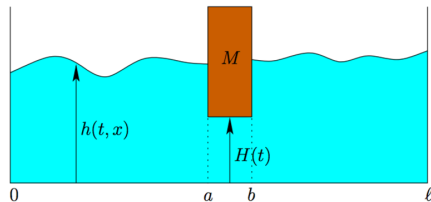


Figure 1: Configuration, Image from Maity, Tucsnak et al.

Notations

μ is the coefficient of viscosity of the fluid.

$$E = (0; a) \cup (b; a + b).$$

$$I = [a; b].$$

Equations Return to the Equilibrium

Proposition [Maity, Tucsna et al., 2018]

If $l = a + b$, then, the return to the equilibrium problem, the position of the solid is completely determined by the integro-differential equation

$$\begin{aligned} & \left(1 + \frac{(b-a)^3}{12} \right) H = H_0 \frac{j l j^2}{j E j^2} \left(\frac{(b-a)^2}{2} F H + (b-a)H + (b-a)H \right); \\ & H(0) = H_0; \quad H'(0) = 0; \end{aligned} \quad (1)$$

and with F such that $\hat{F}(s) = \rho \frac{1}{1+s} \tanh \rho \frac{sa}{1+s}$:

Unbounded case

Proposition [Maity, TucsnaK et al.,2018]

If $E = (1; a) [(b; 1)]$, then the position of the solid is completely determined by the integro-differential equation

$$\begin{aligned} AH + BF - H + CH + DH &= 0; \\ H(0) &= H_0; \quad H'(0) = H'_0; \end{aligned} \quad (2)$$

where $A = 1 + \frac{(b-a)^3}{12}$, $B = (b-a)^2$, $C = (b-a)$, $D = (b-a)$, and

$$F(t) = P - \frac{1}{2} P \frac{e^{-\frac{t}{a}}}{t^3} + D^{1=2} H_0$$

Unbounded case

Proposition [Maity, TucsnaK et al.,2018]

If $E = (1; a) [(b; 1)]$, then the position of the solid is completely determined by the integro-differential equation

$$\begin{aligned} AH + BF - H + CH + DH &= 0; \\ H(0) &= H_0; \quad H'(0) = H_0; \end{aligned} \quad (2)$$

where $A = 1 + \frac{(b-a)^3}{12}$, $B = (b-a)^2$, $C = (b-a)$, $D = (b-a)$, and

$$F(t) = P - \frac{1}{2} P \frac{e^{-t}}{t^3} + D^{1=2} 0;$$

Goal: Understand the long-time behavior of solutions $H(t)$ for the unbounded case

Mittag-Leffler functions

Mittag-Leffler functions

Definition

The two-parametric Mittag-Leffler function, is the complex-valued function defined by

$$E_{\alpha, \beta}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(k\alpha + \beta)} \quad \text{with } \alpha > 0; \beta \in \mathbb{C} \quad (3)$$

In the case when $\alpha = 1$ the function is known has the classical Mittag-Leffler function and denoted by $E(z)$.

Mittag-Leffler functions

Definition

The two-parametric Mittag-Leffler function, is the complex-valued function defined by

$$E_{\alpha, \beta}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(k\alpha + \beta)} \quad \text{with } \alpha > 0; \beta \in \mathbb{C}; \quad (3)$$

In the case when $\alpha = 1$ the function is known has the classical Mittag-Leffler function and denoted by $E(z)$.

Examples

$$E_{1,1}(z) = e^z;$$

$$E_{2,1}(z) = \cosh(\sqrt{z});$$

$$E_{\frac{1}{2},1}(z) = e^{z^2} \operatorname{erfc}(\sqrt{z});$$

Mittag-Leffler functions

Theorem [Popov-Sedletskii, 2013]

For any $0 < \alpha < 1$; $z \in \mathbb{C}$, $p \in \mathbb{N}$, and $z \in L_{1-\alpha} = \{z \in \mathbb{C} : \arg z \in [0, \alpha)\}$, the following asymptotics hold

$$E_{\alpha, \beta}(z) = \frac{1}{\Gamma(\beta)} z^{1-\beta} e^{z^\alpha} \sum_{k=1}^{\infty} \frac{z^{-k}}{\Gamma(\beta - k)} + R_m^{[1]}(z; \alpha, \beta); \quad (4)$$

where the remainder $R_m^{[1]}$ admits the estimate

$$R_m^{[1]}(z; \alpha, \beta) \ll \begin{cases} \frac{2^{\frac{b+2}{2}} (b+1) e^{(\frac{5}{4}j - j)}}{jz^{p+1}}; & \text{if } b = (p+1) < 0 \\ (6 + \frac{2}{\alpha}) e^{(\frac{5}{4}j - j)} \\ jz^{p+1}; & \text{if } b < 0: \end{cases} \quad (5)$$

The first of estimates in (12) is valid for all $z \in L_{1-\alpha}$, and the second under the additional condition $\arg z \in [0, \alpha)$.

Mittag-Leffler functions

Theorem [Popov-Sedletskii, 2013]

For any $0 < \alpha < 1$; $z \in \mathbb{C}$, $p \in \mathbb{N}$ and $z \in L_{1=}$, $z \neq 0$; the following asymptotics formulas hold

$$E_{\alpha, \beta}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k + \beta)} + R_m^{[2]}(z; \alpha, \beta); \quad (6)$$

where the remainder $R_m^{[2]}$ admits the estimate

$$R_m^{[2]}(z; \alpha, \beta) \begin{cases} \ll \frac{2^{\frac{b+2}{2}} (b+1) e^{(\frac{3}{4}j = j)}}{jz^{p+1}}; & \text{if } b \geq 0 \\ \ll \frac{(6 + \frac{2}{\alpha}) e^{(\frac{3}{4}j = j)}}{jz^{p+1}}; & \text{if } b < 0: \end{cases} \quad (7)$$

The first of estimates in (7) is valid for all $z \in L_{1=}$, and the second under the additional condition $jz^j \geq 2$.

Laplace transform of Mittag Leffler functions

In this work we are interested in the case when $\alpha = \beta > 0$ and $z = \lambda t$, with $\lambda \in \mathbb{C}$ and $t \in \mathbb{R}$. For simplicity we introduce the notation

$$E(\lambda; t) := E_{\alpha, \alpha}(\lambda t):$$

Laplace transform of Mittag Leffler functions

In this work we are interested in the case when $\alpha = \beta > 0$ and $z = t$, with $\alpha \in \mathbb{C}$ and $t \in \mathbb{R}$. For simplicity we introduce the notation

$$E(\alpha; t) := E_{\alpha, \alpha}(t):$$

Lemma

The Laplace transform of $E(\alpha; t)$ is given by

$$L[t^{-1}E(\alpha; t)](s) = (s - \alpha)^{-1};$$

where $\operatorname{Re}(s) > \alpha$ and $j < \alpha < j + 1$.

Solutions unbounded case

Inviscid case

If we consider $\nu = 0$ in equation (2), the model is reduced to

$$\begin{aligned} AH'' + BH' + DH &= 0; \\ H(0) &= H_0; \quad H'(0) = H'_0; \end{aligned}$$

Applying Laplace transform to the equation above, and after simplifications, we obtain

$$\hat{H}(s) [As^2 + Bs + D] = H_0 [As + B] + AH'_0$$

Solutions of the model, inviscid case

Proposition [V-H, Sueur, Tucsna, 2019]

The solution $H(t)$ of equation (2) with $\gamma = 0$ is given by

$$\begin{aligned}
 H(t) = & e^{-\frac{Bt}{2A}} \left[H_0 \cosh\left(\frac{t}{A} \sqrt{\frac{B^2}{4} - AD} \right) + \frac{B \sinh\left(\frac{t}{A} \sqrt{\frac{B^2}{4} - AD} \right)}{2 \sqrt{\frac{B^2}{4} - AD}} \right] \\
 & + H_0 \frac{2A \sin\left(\frac{t}{2A} \sqrt{4AD - B^2} \right)}{4AD - B^2} ; \quad :
 \end{aligned}$$

Viscous case

Proposition [V-H, Sueur, TucsnaK, 2019]

The solution of the equation (2) with $\gamma > 0$ is given by

$$H(t) = e^{-\frac{\gamma}{2}t} \sum_{i=1}^4 X^4 h_i H_0 r_i + H_0 r_{\perp} E_{\frac{1}{2}}(\gamma_i; t);$$

where each γ_i is a root of the polynomial

$$p(\gamma) = A \gamma^4 + \bar{B} \gamma^3 + C \frac{2A}{\gamma^2} \bar{B} + \frac{A}{\gamma^2}; \quad (8)$$

and the parameters γ_i and r_{\perp} depends of the roots.

Hurwitz and Anti-Hurwitz polynomials

Hurwitz polynomials

A polynomial $f(X)$ is said to be Hurwitz if the real part of all its complex roots is negative, that is $\operatorname{Re}(u) < 0$ for all $u \in \mathbb{C}$ such that $f(u) = 0$.

Hurwitz polynomials

A polynomial $f(X)$ is said to be Hurwitz if the real part of all its complex roots is negative, that is $\operatorname{Re}(u) < 0$ for all $u \in \mathbb{C}$ such that $f(u) = 0$.

Theorem (Stodola condition)

If a polynomial with real coefficients is Hurwitz, then all its coefficients are of the same sign.

Anti-Hurwitz polynomials

A polynomial $f(X)$ is said to be Anti-Hurwitz if the real part of all its complex roots is negative, that is $\operatorname{Re}(u) < 0$ for all $u \in \mathbb{C}$ such that $f(u) = 0$.

Theorem [V-H, Luca, 2019]

Let $f(X) = a_0X^n + a_1X^{n-1} + \dots + a_{n-1}X + a_n$ be a polynomial with coefficients in \mathbb{R} and degree ≥ 3 . Then, $f(X)$ is anti-Hurwitz polynomial, if and only if it satisfies the following conditions:

1. $(-1)^i a_i > 0$ for all $i \in \{0, \dots, n\}$.
2. $(-1)^{[i]} \Delta_i > 0$, for all $i \in \{1, \dots, n\}$.

Long-time Behavior Viscous Case

Long-time Behavior Viscous Case

In this section we denote by $\lambda = \lambda_1; \lambda_2; \lambda_3; \lambda_4$ the set of roots of the polynomial $P(\lambda)$ in eq. (8).

Long-time Behavior Viscous Case

In this section we denote by $\lambda = \lambda_1; \lambda_2; \lambda_3; \lambda_4$ the set of roots of the polynomial $P(\lambda)$ in eq. (8).

Remark

Since the coefficients of the polynomial $P(\lambda)$ in eq. (8) admit different signs, we conclude that

$$\lambda_1 \in \mathbb{R}^+, \text{ and}$$

$$\lambda_2, \lambda_3, \lambda_4 \in \mathbb{C}.$$

Long-time Behavior Viscous Case

In this section we denote by $\lambda = \lambda_1; \lambda_2; \lambda_3; \lambda_4$ the set of roots of the polynomial $P(\lambda)$ in eq. (8).

Remark

Since the coefficients of the polynomial $P(\lambda)$ in eq. (8) admit different signs, we conclude that

$$\lambda_1 \in \mathbb{R}^-, \text{ and}$$

$$\lambda_2, \lambda_3, \lambda_4 \in \mathbb{C} \setminus \mathbb{R}.$$

Idea: Combine results of Popov-Sedletskii and solution of eq. (2)

Long-time Behavior Viscous Case

Conjecture

Let $H_i = (H_{0i} + H_{0i})$ for $i = 1; 2; 3; 4$; and let $\Gamma = L_2 \setminus \dots$. For all $p \in \mathbb{N}$, the following asymptotic formula hold:

$$H(t) = \sum_{i=2}^4 \frac{H_i}{2} e^{-\frac{p}{2} t} (e^{-\frac{p}{2} t})^2 + \sum_{i=1}^4 e^{-\frac{p}{2} t} \sum_{k=1}^p \frac{H_k}{2} e^{-\frac{k}{2} t} + R_p; \quad (9)$$

where the remainder R_p admits the estimate

$$|R_p| \leq e^{-\frac{p}{4} t} \sum_{i=2}^4 \frac{1}{2} \frac{2^{\frac{p+8}{4}} (1 + p=2)}{j^p t^{p+1}}; \quad (10)$$

Long-time Behavior Viscous Case

Conjecture

Let $H_i = (H_{0i} + H_{0i})$ for $i = 1; 2; 3; 4$; and let $\Gamma = L_2 \setminus \dots$. For all $p \in \mathbb{N}$, the following asymptotic formula hold:

$$H(t) = \sum_{i=2}^{\infty} \frac{H_i}{2} e^{-\frac{p}{2} t} (i^p t)^2 + \sum_{i=1}^{\infty} e^{-\frac{p}{2} t} \sum_{k=1}^{\infty} \frac{H_i}{2} \frac{t^k}{2} + R_p; \quad (11)$$

where the remainder R_p admits the estimate

$$|R_p| \leq e^{-\frac{p}{2} t} \sum_{j=2}^{\infty} \frac{2^{\frac{p+8}{4}} (1 + p=2)}{j^p t^{p+1}} \sum_{j=2}^{\infty} \frac{1}{j^j t^{p+1}}; \quad (12)$$

Remark

If $\epsilon > 0$ is such that

$$\operatorname{Re}(\lambda_\epsilon)^2 > \operatorname{Im}(\lambda_\epsilon)^2 - \frac{1}{\epsilon};$$

the conjecture follows.

Remark

If $i \in \mathbb{Z}$ is such that

$$\operatorname{Re}(i)^2 = \operatorname{Im}(i)^2 = \frac{1}{i};$$

the conjecture follow.

Perspectives

1. Solve the question

$$L_2 \setminus \mathbb{Z} \subset \mathbb{C} : \operatorname{Re}(i)^2 = \operatorname{Im}(i)^2 = \frac{1}{i} \quad ?$$

Remark

If $\lambda \in \mathbb{C}$ is such that

$$\operatorname{Re}(\lambda)^2 = \operatorname{Im}(\lambda)^2 = \frac{1}{\lambda};$$

the conjecture follow.

Perspectives

1. Solve the question

$$L_2 \setminus \mathbb{C} : \operatorname{Re}(\lambda)^2 = \operatorname{Im}(\lambda)^2 = \frac{1}{\lambda} \quad ?$$

2. If 1 does not follow, look for a set

$$(\lambda; \lambda) \in \mathbb{R}^+ \times \mathbb{R}^+ : \text{the conjecture follow} \quad :$$

Thanks for your attention !