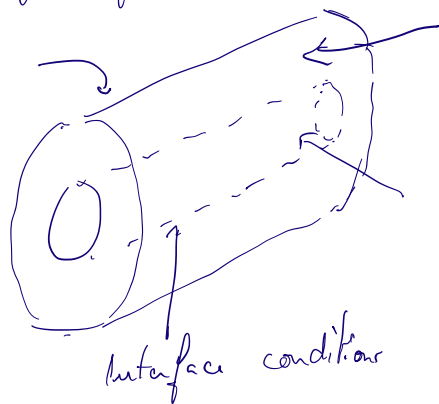


# Controllability and residual estimates for well-posed systems.

## ② Motivation

① A fluid-structure model.  
Modelling of a blood flow in an elastic vessel.

Contact:  
Force exerted  
on the boundary.



Vessel: Elasticity  
equations

Blood flow:  
Navier - Stokes eq  
(or more accurate  
rheology).

Controllability? Widely open.

In fact, even well-posedness is very delicate.

Many difficulties:

x Moving domains.  $\rightarrow$  Strong non-linearity

x Coupling of hyperbolic and parabolic  
equations

$\rightarrow$  Regularity properties do  
not match.

Ref for well-posedness: [Cortada Skokker 2005]

and more

② Simplified models

① Heat-Wave.



Wave equation

$$\partial_{tt} y - \Delta y = 0 \quad \text{in } (0, T) \times (\mathbb{B}(R_{ext}) \setminus \overline{\mathbb{B}(R_{in})})$$

Heat equation

$$\partial_t v - \Delta v = 0 \quad \text{in } (0, T) \times \mathbb{B}(R_{in})$$

Interface boundary conditions.

$$u = \partial_{tt} y \quad \text{in } (0, T) \times S(R_{in})$$

$$\partial_{\nu} v = \partial_{\nu} y$$

Contact  $u = v \quad \text{in } (0, T) \times S(R_{ext}).$

→ what are the contact properties of this model?

in 4d. [Zhang - Zuazua 2003]: Null-controllability properties hold if  $T > 2(R_{ext} - R_{in})$ .

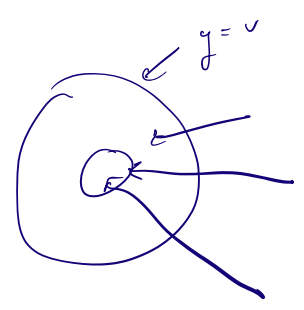
Proof by contact propagation of the energy.  
NB: Exact controllability cannot hold.

In multi-d [Raveli Zhang Zuoze = '05  
 Zhang Zuoze '07 Kanamori - <sup>2004</sup> ~~2004~~ <sub>2004</sub>]  
 the stability of the model (and variants)  
 is analyzed and is shown to depend  
 on the geometry of the wave domain  
 and of the heat domain.

Stab. controllability of the multi-d model  
 is open even in the simple above geometric  
 setting.

⑥ Simpler models: Waves with boundary conditions

- Replacing the heat by the Laplacian  
 (Low Reynolds  
 high viscosity)



$$\begin{aligned}
 \partial_x y - \Delta y &= 0. \\
 \left( \begin{aligned} \partial_t y &= u \\ \partial_\nu y &= \partial_\nu u. \end{aligned} \right. \\
 \Delta u &= 0.
 \end{aligned}$$

N.B. Solving  $\Delta u = 0$  in  $B(R_{int})$   
 $\partial_\nu u = g$  on  $S(R_{int})$

$$u|_{S(R_{int})} = -(-\Delta)^{1/2} g.$$

$\Rightarrow$  The interface conditions read

$$\left| \partial_t y = -(-\Delta)^{1/2} \partial_t y \right| \quad \left( \begin{array}{l} \text{Here } v \text{ goes} \\ \text{from the wave to} \\ \text{the heat} \end{array} \right)$$

Prob: if  $v=0$  (no contact).

$$\frac{d}{dt} \left( \frac{1}{2} \int (|\partial_t y|^2 + |y_t|^2) \right) - \int_{S(R_{int})} \partial_\nu y \partial_t y = 0.$$

$$\leadsto \frac{d}{dt} \left( \frac{1}{2} \int (|\partial_t y|^2 + |y_t|^2) \right) + \left\| (-\Delta_S)^{1/2} \partial_\nu y \right\|_{L^2(S)}^2 = 0.$$

→ Damped wave equation  
damping term on the boundary.

Contact properties? Approximate controllability holds -  
if  $T > 2(R_{ext} - R_{int})$ .  
(Holmgren or Spherical Harmonics + lateral propagation)

Not controllability = open pb.

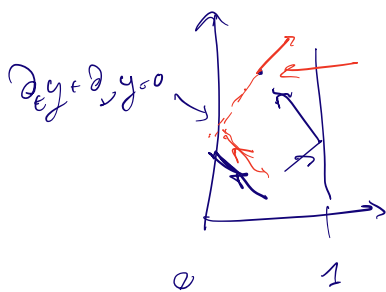
• A somewhat simpler and more classical model.

$$\left\{ \begin{array}{l} \partial_{tt} y - \Delta y = 0 \quad \text{in } (0, T) \times B(R_{ext}) \setminus B(R_{int}) \\ y = v \quad \text{on } (0, T) \times S(R_{ext}) \\ \partial_\nu y + \partial_\nu y = 0 \quad \text{on } (0, T) \times S(R_{int}) \end{array} \right.$$

• "Absorbing boundary conditions".  
(Engqvist - [Tajda 77])

Here, propagation of singularities with these boundary conditions is known: One can propagate only in one direction of time.

In 1d



If this point of phase space has positive energy then the bicharacteristic before has positive energy

This is not enough to prove well-posedness  
 indeed: [Bardos - Lebeau - Rauch] requires propagation of singularities + well-posedness in both directions of time (in particular in the compactness) and all proofs I know use <sup>argument</sup> at some point that the eq can be solved backward in time!!  
 Not the case here.

→ Even the well-posedness of his model seems to be open.

Rk: In all the above models, due to the specific geometric setting, it is reasonable to hope for precise resolvent estimates. (see e.g. [Bardoni-Dardó E. Tercedo 2022]).

## II Abstract setting and resolvent estimates.

Abstract setting.

$$\begin{cases} y' = Ay + Bv. \\ y(0) = y_0. \end{cases}$$

•  $A$  generates a  $C^0$  semi-group on  $X$ .

•  $B \in \mathcal{L}(U, \mathcal{D}(A)')$

and  $B$  admissible.

$$\left( \begin{array}{l} \exists t > 0, v \mapsto \int_0^t e^{(t-s)A} Bv(s) ds. \\ \mathcal{L}^2_{loc}(t; U) \longrightarrow X \end{array} \right).$$

All the above linearized equations fit this framework.

Q: Can we read null-controllability from resolvent estimates?

Some partial answer is known.

② Necessary and sufficient condition for null exact controllability when  $\boxed{A^* = -A}$

→ Hautus test. (Tiller '04, Tucsmak - We-55 book).

$\exists m, \tau > 0, \forall \omega \in \mathbb{R}, \forall y \in \mathcal{D}(A),$

$$\|y\|_X \leq \tau \|(A - i\omega)y\|_X + m \|B^*y\|_U.$$

→ Weave packets criterion. [Ramezani - Takahashi - Tenenbaum]   
 Tucsmak  
if  $A$  has compact resolvent.  $\exists$  basis of orthonormal functions  $(\phi_j)_{j \in \mathbb{N}}$  with corresponding eigenvalues  $(i\lambda_j)_{j \in \mathbb{N}}$

$\exists \delta, \epsilon > 0, \forall \omega \in \mathbb{R}, \forall (a_j) \in \ell^2(\mathbb{N}),$

$$\|B^* \left( \sum_{|\lambda_j - \omega| < \epsilon} a_j \phi_j \right)\|_U \geq \delta \left\| \sum_{|\lambda_j - \omega| < \epsilon} a_j \phi_j \right\|_X$$

Rk: In both cases, the time of controllability provided by these techniques is not sharp.

Can be adapted to the case  $(e^{tA})_{t \geq 0}$  generates a group [Jacobowitz '05].

② Parabolic case  $A^* = A < 0$ .

cf [Deyckaerts Miller JFA '12]

• Sufficient conditions for null-controllability

Then if  $\exists \eta > 0, \forall v \in \mathcal{D}(A), \forall \omega > 0,$   
 $\exists \delta \in (0, 1),$   
 $\|v\|^2 \leq \eta^2 \omega^\delta \left( \frac{1}{\omega} \|(A - \omega)v\|^2 + \|B^*v\|^2 \right).$

Then null-controllability holds  
 with cost  $\leq c e^{c/T}$ .

• A necessary condit.

then: if null-cont. holds in | some time any time  
 with cost  $e^{c/T}$ .

then  $\exists a > 0, \forall v \in \mathcal{D}(A), \forall \lambda \in \mathbb{C}$  with  $\operatorname{Re} \lambda > 0$   
 $\|v\|_\lambda^2 \leq a e^{a(\operatorname{Re} \lambda)^{1/2}} \left( \|(A - \lambda)v\|_\lambda^2 + \|B^*v\|_\lambda^2 \right)$   
 $a e^{a(\operatorname{Re} \lambda)}$



Ab Sometimes close to a necessary  
and sufficient condit. of adding  
additional spectral estimates

f [Ammar - Khodja Benabdellah  
Gonzalez Burgos Toranzo 2019].

N.B. For parabolic equation

Lebeau - Robbiano spectral estimates  
 $\Rightarrow$  Null-controllability.

f [Lebeau - Robbiano '86, Tiller '06].

③ Mixed hyperbolic parabolic models -  
more general models.

N.B. One can prove

controllability results for  
several models of mixed  
hyperbolic - parabolic behavior.

[Lebean - Zuzue 1986] thermoelasticity

[Albano - Tetao 1992] thermoelasticity

[Chaves Silva - Rosa - Zuzue]  
viscoelasticity  
moving control.

[Kruif, Quenero '12, '16] -  
+ Poel  
Comp. Newton - Shkes.

[Beauchand LeBelich Koenig 2020]

Still no characterized in  
terms of resultant for  $\mathcal{F}^d$  models -