# An eigenvalue problem of Steklov type as $p ightarrow +\infty$

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Let  $\Omega \subseteq \mathbb{R}^n$ ,  $n \geq 2$ , be a bounded, connected, open set with Lipschitz boundary.

The first non-zero Steklov eigenvalue of  $\Omega$  is defined by

$$\sigma(\Omega) := \min\left\{\frac{\displaystyle\int_{\Omega} |\nabla v|^2 dx}{\displaystyle\int_{\partial\Omega} v^2 d\mathcal{H}^{n-1}} : v \in H^1(\Omega) \setminus \{0\}, \int_{\partial\Omega} v \, d\mathcal{H}^{n-1} = 0\right\}.$$

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Any minimizer satisfies

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ \\ \frac{\partial u}{\partial \nu} = \sigma(\Omega) u & \text{on } \partial \Omega. \end{cases}$$

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The sequence of Steklov eigenvalues

$$0 = \sigma_1(\Omega) < \sigma_2(\Omega) (= \sigma(\Omega)) \le \sigma_3(\Omega) \le \sigma_3(\Omega) \cdots 
earrow +\infty$$

starts with zero.

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The first non-trivial Steklov eigenvalue  $\sigma(\Omega)$  coincides with the value of the best constant in the Poincaré-Wirtinger trace inequality:

$$c_{\Omega}\int_{\partial\Omega}|u-\bar{u}_{\Omega}|^2 \ d\mathcal{H}^{n-1}\leq \int_{\Omega}|\nabla u|^2 \ dx,$$

for  $u \in W^{1,2}(\Omega)$ , where  $\bar{u}_{\Omega}$  is the average of the trace of u on  $\partial \Omega$ .

#### Motivation

• The Steklov eigenvalues can be interpreted as the eigenvalues of the Dirichlet-to-Neumann operator

$$D: H^{1/2}(\partial\Omega) \rightarrow: H^{-1/2}(\partial\Omega)$$

that maps a function  $f \in H^{1/2}(\partial \Omega)$  to  $Df = \frac{\partial Hf}{\partial \nu}$ , where Hf is the harmonic extension of f to  $\Omega$ .

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• The Steklov boundary condition is often considered in the more general form

$$\frac{\partial u}{\partial \nu} = \sigma \rho u,$$

where  $\rho \in L^{\infty}(\partial\Omega)$ . If  $\Omega \subset \mathbb{R}^2$ , the Steklov eigenvalues can be thought of as the squares of the natural frequencies of a vibrating free membrane with its mass concentrated along its boundary with density  $\rho$ .

Shape Optimization problem in dimension 2

# Shape Optimization problem in dimension 2

#### Theorem [Weinstock, J. Rational Mech. Anal., 1954]

If  $\Omega\subseteq \mathbb{R}^2$  is a bounded, Lipschitz simply connected open set, then

$$\sigma(\Omega)P(\Omega) \le \sigma(B)P(B),\tag{1}$$

where  $P(\Omega)$  stands for the perimeter of  $\Omega$  and  $B \subseteq \mathbb{R}^2$  is a ball. Equality holds if and only if  $\Omega$  is a ball.

In other words: "among all simply connected sets of  $\mathbb{R}^2$  with prescribed perimeter, the disc maximises the first non-zero Steklov eigenvalue".

#### Remark (Girouard-Polterovich, J. Spectral Theory, 2017)

Weinstock inequality fails for planar domains which are not simply connected. Namely, one can find an annulus  $\Omega_{\varepsilon} = B_1 \setminus \overline{B}_{\varepsilon}$ ,  $\varepsilon \approx 0$ , such that

 $\sigma(\Omega_{\varepsilon})P(\Omega_{\varepsilon}) > \sigma(B)P(B).$ 

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What about the *n*-dimensional case,  $n \ge 3$ ?

Shape Optimization problem in  $\mathbb{R}^n$  with volume constraint

#### Theorem [Brock, ZAMM, 2001]

For every Lipschitz bounded open set  $\Omega \subseteq \mathbb{R}^n$ , it holds true

$$\sigma(\Omega)V(\Omega)^{\frac{1}{n}} \leq \sigma(B)V(B)^{\frac{1}{n}}.$$

The equality holds iff  $\Omega$  is a ball.

In other words: "Among all Lipschitz sets of  $\mathbb{R}^n$  with prescribed volume, balls maximise the first non-zero Steklov eigenvalue".

Shape Optimization problem in  $\mathbb{R}^n$  with perimeter constraint

Theorem [Bucur-Ferone-Nitsch-Trombetti, *J. Differential Geom.*, 2018]

Let  $\Omega$  be a bounded, open and convex set of  $\mathbb{R}^n$ . Then

$$\sigma(\Omega)P(\Omega)^{\frac{1}{n-1}} \leq \sigma(B)P(B)^{\frac{1}{n-1}}.$$

Equality holds only if  $\Omega$  is a ball.

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The above inequality cannot hold for simply connected sets in  $\mathbb{R}^n$ . Namely, one can find a spherical shell  $\Omega_{\varepsilon} = B_1 \setminus \overline{B}_{\varepsilon}$ ,  $\varepsilon \approx 0$ , ( $B_r$  denotes the ball of radius r centered at the origin) such that

$$\sigma(\Omega_{\varepsilon})P(\Omega_{\varepsilon})^{\frac{1}{n-1}} > \sigma(B)P(B)^{\frac{1}{n-1}}.$$

# The orthotropic *p*-Laplace operator

Let  $\Omega \subseteq \mathbb{R}^n$  be an open, bounded and convex set and let p > 1. We consider the orthotropic p-Laplace operator:

$$\widetilde{\Delta}_p u = \sum_{i=1}^n \left( |u_{x_i}|^{p-2} u_{x_i} \right)_{x_i}.$$

- For p = 2 it coincides with the Laplacian
- For  $p \neq 2$  it differs from the usual *p*-Laplacian, that is defined as  $\Delta_p u := \operatorname{div} (|\nabla u|^{p-2} \nabla u).$

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This operator has been considered by several authors:

- Visik, 1963
- Lions, 1969
- Belloni-Kawohl, 2004
- Rossi-Saez, 2007
- Brasco-Franzina, 2013

# Orthotropic *p*-Laplacian

Case of the *p*-Laplace operator: Suppose we are considering a non linear elastic membrane, fixed on a boundary  $\partial\Omega$  of a plane domain. If u(x) denotes its vertical displacements, its deformation energy is given by  $\int_{\Omega} |\nabla u|^p$  and a minimizer of the Rayleigh quotient

 $\frac{\int_{\Omega} |\nabla u|^p dx}{\int_{\Omega} |u|^p dx}$ 

on  $W_0^{1,p}(\Omega)$  satisfies the Euler-Lagrange equation in  $\Omega$ :

 $-\Delta_p u = \lambda_p |u|^{p-2} u$ 

#### Orthotropic *p*-Laplacian

Case of the orthotropic *p*-Laplace operator: If the membrane is woven out of elastic strings in a rectangular fashion, then its deformation energy is given by

$$\int_{\Omega}\sum_{i}|u_{x_{i}}|^{p}dx.$$

A minimizer of the Rayleigh quotient

$$\frac{\int_{\Omega} \sum_{i} |u_{x_{i}}|^{p} dx}{\int_{\Omega} |u|^{p} dx}$$

on  $W_0^{1,p}$ , if it exists, will satisfy

$$\widetilde{\Delta}_p u = \widetilde{\lambda}_p |u|^{p-2} u.$$

# Steklov problem for the orthotropic p-Laplacian

Let us consider the Steklov-eigenvalue problem for the pseudo p-Laplace operator:

$$\begin{cases} -\widetilde{\Delta}_{p}u = 0 & \text{on } \Omega\\ \sum_{j=i}^{n} |u_{x_{j}}|^{p-2} u_{x_{j}} \nu_{\partial\Omega}^{j} = \sigma |u|^{p-2} u \rho_{p} & \text{on } \partial\Omega, \end{cases}$$

where

• 
$$\nu_{\partial\Omega} = (\nu^1_{\partial\Omega}, \dots, \nu^n_{\partial\Omega})$$
 is the outer normal of  $\partial\Omega$ 

• 
$$\rho_p(x) = \|\nu_{\partial\Omega}(x)\|_{\ell^{p'}};$$

• p' is the coniugate exponent of p;

• 
$$||x||_{\ell^p}^p = \sum_{j=1}^n |x^j|^p$$
.

The real number  $\sigma$  is called Steklov eigenvalue whenever problem (2) admits a non-trivial weak  $W^{1,p}$  solution.

(2)

# Steklov problem for the orthotropic p-Laplacian

We can write

$$-\widetilde{\Delta}_{p}u = \operatorname{div}\left(\mathcal{A}_{p}(\nabla u)\right), \qquad \mathcal{A}_{p}(\nabla u) = \left(|u_{x_{1}}|^{p-2}u_{x_{1}}, \ldots, |u_{x_{n}}|^{p-2}u_{x_{n}}\right).$$

Let  $u \in W^{1,p}(\Omega)$ . We say that u is a weak solution of (2) if

$$\int_{\Omega} \langle \mathcal{A}_{p}(\nabla u), \nabla \varphi \rangle dx = \sigma \int_{\partial \Omega} |u|^{p-2} u \varphi \rho_{p} d\mathcal{H}^{n-1} \qquad \forall \varphi \in W^{1,p}(\Omega).$$

#### Some results

The following results are proved in [L. Brasco - G. Franzina, NoDEA, 2013].

- These Steklov eigenvalues form at least a countably infinite sequence of positive numbers diverging at infinity.
- The first eigenvalue is 0 and corresponds to constant eigenfunctions.
- Denoting by  $\Sigma^p_p(\Omega)$  the first non-trivial, it has the following variational characterization

$$\Sigma^{p}_{\rho}(\Omega) = \min\left\{\frac{\int_{\Omega} \|\nabla u\|^{p}_{\ell^{\rho}} dx}{\int_{\partial\Omega} |u|^{p} \rho_{\rho} d\mathcal{H}^{n-1}}, \ u \in W^{1,p}(\Omega), \ \int_{\partial\Omega} |u|^{p-2} u \rho_{\rho} d\mathcal{H}^{n-1} = 0\right\}.$$

#### Some results

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- These Steklov eigenvalues form at least a countably infinite sequence of positive numbers diverging at infinity.
- The first eigenvalue is 0 and corresponds to constant eigenfunctions.
- $\Sigma_p^p(\Omega)$  represents the optimal constant in the weighted trace-type inequality

$$\int_{\Omega} \|\nabla u\|_{\ell^{p}}^{p} dx \geq \Sigma_{p}^{p}(\Omega) \int_{\partial \Omega} |u|^{p} \rho_{p} d\mathcal{H}^{n-1}$$

in the class of Sobolev functions  $u \in W^{1,p}(\Omega)$ , such that

$$\int_{\partial\Omega}|u|^{p-2}u\rho_pd\mathcal{H}^{n-1}=0.$$

# The orthotropic $\infty-\text{Laplace}$ operator

#### Aim

We want to study the first non-trivial Steklov eigenvalue for the orthotropic  $p-{\rm Laplacian},$  as  $p\to+\infty:$ 

 $\lim_{p\to+\infty}\Sigma_p(\Omega).$ 

We define the following operator

$$\widetilde{\Delta}_{\infty} u(x) := \sum_{j \in I(\nabla u(x))} u_{x_j}^2(x) u_{x_j,x_j}(x),$$

where

$$I(x) := \{j \le n : |x_j| = ||x||_{\ell^{\infty}}\}, \quad ||x||_{\ell^{\infty}} = \max_{j=1,\dots,n} |x^j|.$$

Some heuristics: the limit problem as  $p \to +\infty$ If we assume that  $u \in C^2$ , we can write

$$\widetilde{\Delta}_{p} u = (p-1) \sum_{j=1}^{n} |u_{x_j}|^{p-4} u_{x_j}^2 u_{x_j,x_j}.$$

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Dividing by  $(p-1) \| 
abla u \|_{\ell^\infty}^{p-4}$ , we achieve

$$\frac{\widetilde{\Delta}_{\rho} u}{(p-1) \|\nabla u\|_{\ell^{\infty}}^{p-4}} = \sum_{j=1}^{n} \left| \frac{u_{x_{j}}}{\|\nabla u\|_{\ell^{\infty}}} \right|^{p-4} u_{x_{j}}^{2} u_{x_{j},x_{j}}.$$

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Let us define

$$I(x) := \{j \le n : |x_j| = ||x||_{\ell^{\infty}}\}, \quad ||x||_{\ell^{\infty}} = \max_{j=1,\dots,n} |x^j|.$$

we can rewrite (3) as

$$\frac{\widetilde{\Delta}_{p} u}{(p-1) \|\nabla u\|_{\ell^{\infty}}^{p-4}} = \sum_{j \in I(\nabla u(x))} u_{x_{j}}^{2} u_{x_{j},x_{j}} + \sum_{j \notin I(\nabla u(x))} \left| \frac{u_{x_{j}}}{\|\nabla u\|_{\ell^{\infty}}} \right|^{p-4} u_{x_{j}}^{2} u_{x_{j},x_{j}}.$$

#### Some heuristics

Starting from

$$\frac{\widetilde{\Delta}_{p} u}{(p-1) \|\nabla u\|_{\ell^{\infty}}^{p-4}} = \sum_{j \in I(\nabla u(x))} u_{x_{j}}^{2} u_{x_{j}, x_{j}} + \sum_{j \notin I(\nabla u(x))} \left| \frac{u_{x_{j}}}{\|\nabla u\|_{\ell^{\infty}}} \right|^{p-4} u_{x_{j}}^{2} u_{x_{j}, x_{j}},$$

we take the limit as  $p \to +\infty$  and, since for any  $j \notin I(\nabla u(x))$  we have  $\left|\frac{u_{x_j}}{\|\nabla u\|_{\ell^{\infty}}}\right| < 1$ , we obtain

~ .

$$\widetilde{\Delta}_{\infty} u = \lim_{p \to +\infty} \frac{\overline{\Delta}_{p} u}{(p-1) \|\nabla u\|_{\ell^{\infty}}^{p-4}} = \sum_{j \in I(\nabla u(x))} u_{x_{j}}^{2} u_{x_{j}, x_{j}}.$$

#### Some new results

#### Theorem [Ascione-P., JMAA, 2021]

It holds

$$\lim_{\rho \to +\infty} \Sigma_{\rho}(\Omega) = \frac{2}{\operatorname{diam}_{1}(\Omega)} =: \Sigma_{\infty}(\Omega),$$

where  $\operatorname{diam}_1(E) := \sup_{x,y \in E} ||x - y||_{\ell^1}$ . Moreover, the following variational characterization holds:

$$\Sigma_{\infty}(\Omega) = \min \left\{ \frac{\|\|\nabla u\|_{\ell^{\infty}}\|_{L^{\infty}(\Omega)}}{\|u\|_{L^{\infty}(\partial\Omega)}}, \ u \in W^{1,\infty}(\Omega), \ \max_{x \in \partial\Omega} u(x) = -\min_{x \in \partial\Omega} u(x) \neq 0 \right\}.$$

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Notation:

• We denote by  $u_p$  an eigenfunction with related eigenvalue  $\Sigma_p^p(\Omega)$ , with the following normality condition

$$\frac{1}{V(\Omega)}\int_{\partial\Omega}|u_{\rho}|^{\rho}\rho_{\rho}d\mathcal{H}^{n-1}=1,$$

where  $V(\cdot)$  is the volume.

#### Some new results

#### Theorem [Ascione-P., JMAA, 2021]

Let  $\Omega$  be a bounded open convex set such that  $\partial\Omega$  is  $C^1$ . There exists a sequence  $p_i \to +\infty$  such that  $u_{p_i}$  converges uniformly in  $\overline{\Omega}$  to  $u_{\infty}$ , that is solution of

$$egin{cases} -\widetilde{\Delta}_{\infty} u = 0 & ext{on } \Omega \ \Lambda(x,u,
abla u) = 0 & ext{on } \partial \Omega \end{cases}$$

in the viscosity sense, where, for  $(x, u, \eta) \in \partial\Omega \times \mathbb{R} \times \mathbb{R}^N$ , we set

$$\Lambda(x, u, \eta) = \begin{cases} \min\left\{ \|\eta\|_{\ell^{\infty}} - \Sigma_{\infty}(\Omega)|u|, \sum_{j \in I(\eta)} \eta_{j} \nu_{\partial\Omega}^{j}(x) \right\} & \text{if } u > 0\\ \max\left\{ \sum_{\infty}(\Omega)|u| - \|\eta\|_{\ell^{\infty}}, \sum_{j \in I(\eta)} \eta_{j} \nu_{\partial\Omega}^{j}(x) \right\} & \text{if } u < 0\\ \sum_{j \in I(\eta)} \eta_{j} \nu_{\partial\Omega}^{j}(x) & \text{if } u = 0. \end{cases}$$

# Shape Optimization results

Let  $p \in (1,\infty]$ . Let us recall that

$$\|x\|_{\ell^p}^p = \sum_{j=1}^n |x^j|^p, \quad \|x\|_{\ell^\infty} = \max_{j=1,\dots,n} |x^j|$$

and

$$\rho_p(x) = \|\nu_{\partial\Omega}(x)\|_{\ell^{p'}}.$$

We introduce the following notation:

• the ball relative to the  $\ell^p$  norm:

$$\mathcal{W}_{p} = \{x \in \mathbb{R}^{n} \mid ||x||_{\ell^{p}} \leq 1\};$$

• the perimeter relative to the  $\ell^p$  norm:

$$\mathcal{P}_{p}(\Omega) := \int_{\partial \Omega} \rho_{p}(x) d\mathcal{H}^{n-1}(x).$$

# Shape Optimization Results

#### Theorem [Ascione-P., JMAA, 2021]

Let  $\Omega \subset \mathbb{R}^n$  be an open bounded convex set and p > 1. Consider  $q \ge 0$  and  $r \in [0, n]$  such that  $\frac{p}{n} = q + \frac{r}{n}$ . Then, we have

$$\Sigma_p^p(\Omega) \, \mathcal{P}_p(\Omega)^{\frac{r-1}{n-1}} \, V(\Omega)^q \leq \mathcal{P}_p(\mathcal{W}_p)^{\frac{r-1}{n-1}} \, V(\mathcal{W}_p)^q.$$

#### Remarks and Corollaries:

• This result implies the Brock-Weinstock inequality proved in [Brasco-Franzina, 2013]:

$$\Sigma_{\rho}^{\rho}(\Omega)V(\Omega)^{\frac{\rho-1}{n}} \leq V(\mathcal{W}_{\rho})^{\frac{\rho-1}{n}}.$$

• If  $p \in (1, n]$ , we can choose r = p and q = 0, obtaining

$$\Sigma^p_{\rho}(\Omega) \mathcal{P}_{\rho}(\Omega)^{\frac{p-1}{n-1}} \leq \mathcal{P}_{\rho}(\mathcal{W}_{\rho})^{\frac{p-1}{n-1}}$$

# Shape Optimization Results

#### Theorem [Ascione-P., JMAA, 2021]

For any bounded open convex set  $\Omega \subseteq \mathbb{R}^n$ , it holds

$$\Sigma_{\infty}(\Omega)V(\Omega)^{rac{1}{n}} \leq \Sigma_{\infty}(\mathcal{W}_1)V(\mathcal{W}_1)^{rac{1}{n}}.$$

Equality holds if and only if  $\Omega$  is equivalent to  $W_1$  up to translations and scalings Moreover, if n = 2, it also holds

$$\Sigma_{\infty}(\Omega)P_{\infty}(\Omega) \leq \Sigma_{\infty}(\mathcal{W}_1)P(\mathcal{W}_1).$$

Equality holds if and only if  $\Omega$  is of constant width, i.e. if and only if  $\omega(v) \equiv \operatorname{diam}_1(\Omega)$  for every directions v.

Fix n = 2 and consider any bounded open convex set  $\Omega$ . For each direction v there exists two supporting lines  $r_1, r_2$  for  $\Omega$  that are orthogonal to v in the Euclidean sense. We call width of  $\Omega$  in the direction v the distance  $\omega(v) = d_1(r_1, r_2)$ .

# Thank you for your attention!

# Orthotropic *p*-Laplacian

Case of the *p*-Laplace operator: Suppose we are considering a non linear elastic membrane, fixed on a boundary  $\partial\Omega$  of a plane domain. If u(x) denotes its vertical displacements, its deformation energy is given by  $\int_{\Omega} |\nabla u|^p$  and a minimizer of the Rayleigh quotient

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on  $W_0^{1,p}(\Omega)$  satisfies the Euler-Lagrange equation in  $\Omega$ :

 $-\Delta_p u = \lambda_p |u|^{p-2} u$ 

#### Viscosity Solution

#### We denote

$$F_p: (\xi,X) \in \mathbb{R}^N imes \mathbb{R}^{N imes N} \mapsto -\sum_{j=1}^N (p-1) |\xi_j|^{p-2} X_{j,j}$$

and

$$B_{p}: (\sigma, x, u, \xi) \in \mathbb{R} \times \partial \Omega \times \mathbb{R} \times \mathbb{R}^{N} \mapsto \sum_{j=1}^{N} |\xi_{j}|^{p-2} \xi_{j} \nu_{\partial \Omega}^{j}(x) - \sigma |u|^{p-2} u \rho_{p}(x).$$

The Steklov problem can be formally rewritten as

$$\begin{cases} F_{p}(\nabla u, \nabla^{2} u) = 0, & \text{on } \Omega \\ B_{p}(\sigma, x, u, \nabla u) = 0, & \text{on } \partial\Omega. \end{cases}$$
(4)

Let *u* be a lower (upper) semi-continuous function on the closure  $\overline{\Omega}$  of  $\Omega$  and  $\Phi \in C^2(\overline{\Omega})$ . We say that  $\Phi$  is **touching from below** (**above**) *u* in  $x_0 \in \overline{\Omega}$  if and only if  $u(x_0) - \Phi(x_0) = 0$  and  $u(x) > \Phi(x)$  ( $u(x) < \Phi(x)$ ) for any  $x \neq x_0$  in  $\overline{\Omega}$ . A lower (upper) semi-continuous function *u* on  $\overline{\Omega}$  is said to be a **viscosity supersolution** (**subsolution**) of (4) if for any function  $\Phi \in C^2(\overline{\Omega})$  touching from below (above) *u* in  $x_0 \in \overline{\Omega}$  one has

$$F_{\rho}(\nabla \Phi(x_0), \nabla^2 \Phi(x_0)) \ge (\le) 0$$
  $x_0 \in \Omega;$ 

 $\max\{F_{\rho}(\nabla\Phi(x_0),\nabla^2\Phi(x_0)),B_{\rho}(\sigma,x_0,\Phi(x_0),\nabla\Phi(x_0))\} \ge (\le)0 \qquad x_0 \in \partial\Omega.$ 

Finally, we say that a continuous function u on  $\overline{\Omega}$  is a **viscosity solution** if it is both viscosity subsolution and supersolution.