Asymptotic analysis of partially and locally dissipated hyperbolic systems $^{\rm 1}$

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We consider *n*-component quasilinear hyperbolic systems of the form:

$$\frac{\partial U}{\partial t} + \sum_{j=1}^{d} A^{j}(U) \frac{\partial U}{\partial x_{j}} = \frac{BU}{\varepsilon}, \quad \text{where} \quad x \in \mathbb{R}^{d}, \varepsilon > 0 \quad \text{and} \quad U = \begin{pmatrix} u_{1} \\ \vdots \\ u_{n} \end{pmatrix}$$

where the matrices A^{i} and B are symmetric \rightarrow hyperbolicity of the system.

It models physical phenomena with finite speed of propagation or conservations laws, such as:

- The compressible Euler equation, Maxwell's equation, Einstein's equation, MHD equations, Yang-Mills equation, etc.
- Numerous applications: non-viscous fluid mechanics, kinetic theory, astrophysics, road traffic modelling, blood vessel circulation, etc.

Questions: When does the solution exists globally in time? And what happens when $\varepsilon \to 0?$

 \rightarrow There is a surprisingly strong connection between these questions and problems related to control theory and Villani's hypocoercivity theory.

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Role of the dissipation term

For that issue, the 0-th order term BU, that acts as a **dissipation** term, plays an essential role.

- In the case $B \equiv 0$, local-in-time strong solutions may develop singularities (shock waves) in finite time (A. Majda, D. Serre).
- If BU acts directly on each component i.e. B > 0

 \rightarrow global existence + convergence to the equilibrium exponentially fast. (T-T. Li)

- In practice, a more reasonable assumption is that the dissipation acts only on certain components of the system: $B + {}^{T}B \ge 0$.
- This can be written as:

$$BU = egin{pmatrix} 0_{\mathbb{R}^{n_1}}\ DU \end{pmatrix}$$
 where $D > 0, DU \in \mathbb{R}^{n_2}, n_1, n_2 \in \mathbb{N}$ and $n_1 + n_2 = n$.

• Main application: compressible Euler system with damping

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t u + u \cdot \nabla u + \nabla P(\rho) + \frac{u}{\varepsilon} = 0. \end{cases}$$

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Global-in-time existence of solutions

Q: Since the dissipation is only present in some equations of the system, how can one ensure the global existence of solutions?

As a toy-model, let us look at the damped p-system

$$\begin{cases} \partial_t u + \partial_x v = \mathbf{0}, \\ \partial_t v + \partial_x u + \mathbf{v} = \mathbf{0}. \end{cases}$$

For this simple system, performing standard energy estimates leads to:

$$rac{d}{dt} \|(u,v)\| + \|v\|_{L^2}^2 \leq 0 \rightarrow$$
 no time-decay information on u .

Idea: consider the following perturbed functional

$$\mathcal{L}^2 = \|(u, v, \partial_x u, \partial_x v)\|_{L^2}^2 + \int_{\mathbb{R}} v \partial_x u,$$

which allows to recover dissipation properties on all the components.

Indeed, after basic computations, one obtains

$$\frac{d}{dt}\mathcal{L}^2+\|\mathbf{v}\|_{L^2}^2+\|(\partial_{\mathbf{x}}\mathbf{u},\partial_{\mathbf{x}}\mathbf{v})\|_{L^2}^2\leq 0.$$

And since $\mathcal{L}^2 \sim ||(u, v, \partial_x u, \partial_x v)||_{L^2}^2$, one can derive time-decay estimates (depending on the frequencies!)

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SK condition, Kalman rank condition and Hypocoercivity

For the general system $\partial_t U + \sum_j A^j \partial x_j U + BU = 0$, the previous idea also holds under the following condition:

Definition (Shizuta-Kawashima '80s)

$$\forall \xi \in \mathbb{R}^d, \text{ ker } L \cap \{ \text{eigenvectors of } \sum_j A^j \xi_j \} = \{ 0 \}.$$
 (SK)

Actually such condition is equivalent to the Kalman rank condition for the couple $(\sum_{i} A^{i} \xi_{j}, B)$.

Inspired by this fact and by the hypercoercivity theory, Beauchard and Zuazua constructed the following Lyapunov functional to recover decay estimates:

$$\mathcal{L} riangleq \|U\|_{L^2}^2 + \int_{\mathbb{R}^d} \min(\xi, \xi^{-1}) \mathcal{I} \quad ext{where} \quad \mathcal{I} riangleq \Im \sum_{k=1}^{n-1} arepsilon_k ig(L \mathcal{A}^{k-1}_{\omega} \widehat{U} \cdot L \mathcal{A}^k_{\omega} \widehat{U} ig).$$

Again, one obtains

$$\frac{d}{dt}\mathcal{L} + \kappa \min(1, |\xi|^2)\mathcal{L} \leq 0$$

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• With this estimate at hand, one deduces the global existence of small H^s solutions in the full space and

$$\begin{aligned} \|U^{h}(t)\|_{L^{2}(\mathbb{R}^{d},\mathbb{R}^{n})} &\leq Ce^{-\lambda t}\|U_{0}\|_{L^{2}(\mathbb{R}^{d},\mathbb{R}^{n})},\\ \|U^{\ell}(t)\|_{L^{\infty}(\mathbb{R}^{d},\mathbb{R}^{n})} &\leq Ct^{-\frac{d}{2}}\|U_{0}\|_{L^{1}(\mathbb{R}^{d},\mathbb{R}^{n})}\end{aligned}$$

where U^h and U^ℓ correspond, respectively, to the high and low frequencies of the solution.

- Moreover, the method developed by Beauchard and Zuazua allows to treat situation when the (SK) condition is not satisfied.
- However these hypercoercivity techniques do not give the full story of the behavior of the solution in the low frequency-regime and new considerations needs to be made to be able to study the limit $\varepsilon \to 0$.

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"New" observations

• Back to the damped *p*-system:

$$\begin{cases} \partial_t u + \partial_x v = 0, \\ \partial_t v + \partial_x u + \frac{v}{\varepsilon} = 0. \end{cases}$$
(1)

A spectral analysis of the matrix

$$\begin{pmatrix} 0 & i\xi \\ i\xi & \frac{1}{\varepsilon} \end{pmatrix}$$

shows that:

- In low frequencies $(|\xi| \ll \frac{1}{\varepsilon})$, there are two real eigenvalues $\frac{1}{\varepsilon}$ and $\varepsilon \xi^2$.
- In high frequencies ($|\xi| \gg \frac{1}{\varepsilon}$), two complex conjugate eigenvalues coexist, whose real parts are asymptotically equal to $\frac{1}{2\varepsilon}$.

• The threshold between low and high frequencies is at $\frac{1}{-}$

• ightarrow The behavior of solution depend on the relation between ξ and arepsilon.

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Insights from the spectral analysis

- There exists a damped mode in the low frequencies regime associated to the eigenvalue $\frac{1}{c} \rightarrow$ Crucial uniform estimates
- $\bullet\,$ The asymptotic behaviour of the solution when $\varepsilon \to 0$ is not so intuitive.
 - Naively, we expect that as the damping coefficient becomes larger the dissipation becomes more dominant.
 - However, the so-called *overdamping* effect occurs: the decay rate behavior is related to $(\varepsilon, 1/\varepsilon)$.



Low frequencies in a simple case

Our idea is to follow exactly what the spectral analysis tells us. This can be done using:

$$\|f\|^h_{\dot{\mathbb{B}}^s_{2,1}} \triangleq \sum_{j \geq \frac{1}{\epsilon}} 2^{j^s} \|\dot{\Delta}_j f\|_{L^2} \quad \text{and} \quad \|f\|^\ell_{\dot{\mathbb{B}}^{s'}_{p,1}} \triangleq \sum_{j \leq \frac{1}{\epsilon}} 2^{j^{s'}} \|\dot{\Delta}_j f\|_{L^p}.$$

Back (again) to the damped p-system:

$$\begin{cases} \partial_t u + \partial_x v = 0\\ \partial_t v + \partial_x u + \frac{v}{\varepsilon} = 0, \end{cases}$$

Defining the damped mode $w = v + \varepsilon \partial_x u$, the system can be rewritten

$$\begin{cases} \partial_t u - \varepsilon \partial_{xx}^2 u = -\partial_x w \\ \partial_t w + \frac{w}{\varepsilon} = -\varepsilon \partial_{xx}^2 v. \end{cases}$$

→ One directly get the uniform behaviour observed in the spectral analysis, not just heat effect as depicted in the previous references. → It is possible to study the two equations in L^p spaces in a decoupled way as the source terms can be absorbed in the low-frequency regime:

To sum-up

- The hypocoercivity approach does not give the full story of the low-frequency behavior.
- New low-frequency analysis + high frequencies computation à la Beauchard et Zuazua, leads to uniform global existence result for general hyperbolic system satisfying the (SK) condition.
- And from these uniform estimates with a threshold depending on ε we can justify the relaxation limit when $\varepsilon \to 0$ with an explicit convergence rate.
- Introducing the diffusive rescaling:

$$(\widetilde{\rho}^{\varepsilon},\widetilde{v}^{\varepsilon})(t,x)\triangleq(\rho,\frac{v}{\varepsilon})(\frac{t}{\varepsilon},x).$$

The Euler system rewrites:

$$\begin{cases} \partial_t \rho^{\varepsilon} + \operatorname{div}(\rho^{\varepsilon} v^{\varepsilon}) = 0, \\ \varepsilon^2 \partial_t (\rho^{\varepsilon} v^{\varepsilon}) + \varepsilon^2 \operatorname{div}(\rho^{\varepsilon} v^{\varepsilon} \otimes v^{\varepsilon}) + \nabla P(\rho^{\varepsilon}) + \rho^{\varepsilon} v^{\varepsilon} = 0. \end{cases}$$

Relaxation result

Theorem (Danchin, C-B, Math. Ann. 2022)

Let $d \ge 1$, $p \in [2, 4]$ and $\varepsilon > 0$.

- Let ρ be a strictly positive constant and (ρ ρ, v) be the solution of the compressible Euler system with damping (constructed with the previous arguments)
- Let N ∈ C_b(ℝ⁺; B^{d/p}_{p,1}) ∩ L¹(ℝ⁺; B^{d/p+2}_{p,1}) be the unique solution associated to the Cauchy problem:

$$\left\{egin{array}{l} \partial_t \mathcal{N} - \Delta P(\mathcal{N}) = 0 \ \mathcal{N}(0,x) = \mathcal{N}_0 \in \dot{\mathbb{B}}_{p,1}^{rac{d}{p}} \end{array}
ight.$$

If we assume that

$$\|\widetilde{\rho}_{0}^{\varepsilon} - \mathcal{N}_{0}\|_{\mathbb{B}^{\frac{d}{p}-1}_{p,1}} \leq C\varepsilon,$$

then

$$\left\|\widetilde{\rho}^{\varepsilon}-\mathcal{N}\right\|_{\mathcal{L}^{\infty}(\mathbb{R}_{+};\mathbb{B}^{\frac{d}{p}-1}_{\rho,1})}+\left\|\widetilde{\rho}^{\varepsilon}-\mathcal{N}\right\|_{\mathcal{L}^{1}(\mathbb{R}_{+};\mathbb{B}^{\frac{d}{p}+1}_{\rho,1})}+\left\|\frac{\nabla P(\widetilde{\rho}^{\varepsilon})}{\widetilde{\rho}^{\varepsilon}}+\widetilde{\nu}^{\varepsilon}\right\|_{\mathcal{L}^{1}(\mathbb{R}^{+};\mathbb{B}^{\frac{d}{p}}_{\rho,1})}\leq C\varepsilon.$$

Localized damping

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Damping active outside of a ball

We consider the one-dimensional linear hyperbolic system

$$egin{aligned} &\partial_t U + A \partial_x U = -B U \mathbf{1}_\omega, & (t,x) \in (0,\infty) imes \mathbb{R}, \ &U(0,x) = U_0(x), & x \in \mathbb{R}, \end{aligned}$$

where $U = (u_1, u_2) \in \mathbb{R}^{n_1} \times \mathbb{R}^{n_2}$ and

 $\omega := \mathbb{R} \setminus B_R(0) = \{ x \in \mathbb{R} : \|x\| \ge R \} \quad \text{ for a fixed } R > 0.$

We assume:

•
$$B = \begin{pmatrix} 0 & 0 \\ 0 & D \end{pmatrix}$$
 with $D > 0$

• The matrix A is a *strictly hyperbolic matrix*, i.e. A has n real distinct eigenvalues

$$\lambda_1 < \lambda_p < \mathbf{0} < \lambda_{p+1} < \lambda_n.$$

• The couple (A, B) satisfies the (SK) condition.

In other words: we are in the same situation as before but the damping is only effective in ω (the complementary of a ball).

Goal: Quantify the decay as in the classical case.

Difficulties:

- Application of the Fourier transform to the term $1_{\omega} U$.
- Using a perturbed functional approached is not suitable to solve such problems, as it is known for the damped wave equations. equations.

Idea:

- The characteristic lines of the system spend only a finite time in the undamped region.
- When a characteristic is outside the undamped region, the solution decays as in the classical analysis.

This motivates us to develop a method involving only the consideration of the characteristics curves and a semigroup-wise decomposition.

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Presentation of the problem Main result Idea of proof

Propagation of characteristics and their location with respect to the region $\omega = \mathbb{R} \setminus B_R$ where the damping is active.



(a) **Case 1:** The initial support is in the damped region and the characteristics are going away from the un-damped region.



(c) Case 3: The initial support is in the undamped region

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(b) **Case 2:** The initial support is in the damped region and the characteristics cross the un-damped region



Reformulation of the system

As A is symmetric with n real distinct eigenvalues, there exists a matrix $P \in O(n, \mathbb{R})$ such that

$$P^{-1}AP = \Lambda$$
 where $\Lambda = diag(\lambda_1, ..., \lambda_n).$

Setting $V = P^{-1}U$, the system can be reformulated into

$$\begin{cases} \partial_t V + \Lambda \partial_x V = P^{-1} BPV \mathbf{1}_{\omega}(x), & (t, x) \in (0, \infty) \times \mathbb{R}, \\ V(0, x) = V_0(x), & x \in \mathbb{R}, \end{cases}$$
(2)

Decomposing $V = (v_1, \ldots, v_n)$, (2) is equivalent to the following system of coupled transport equations:

$$\begin{cases} \partial_t \mathbf{v}_1 + \lambda_1 \partial_x \mathbf{v}_1 &= \sum_{j=1}^n b_{1,j} \mathbf{v}_j \, \mathbf{1}_\omega(x) \\ &\vdots \\ \partial_t \mathbf{v}_n + \lambda_n \partial_x \mathbf{v}_n &= \sum_{j=1}^n b_{n,j} \mathbf{v}_j \, \mathbf{1}_\omega(x) \end{cases}$$

For all $1 \le i \le n$, the characteristic lines X_i of each equations passing through the point $(x_0, t_0) \in \mathbb{R} \times [0, T]$ are given by

$$X_i(t, x_0, t_0) := \lambda_i(t - t_0) + x_0, \quad t \in [0, T].$$

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Figure: Characteristics passing through a point $(x, t) \in \mathbb{R} \times \mathbb{R}_+$.



- The total time spend by all the characteristics in the undamped region is *finite*.
- Whenever one of the characteristic is in the undamped region, then the solution does not, in general, undergo any decay.

Main Theorem

Theorem (De Nitti-Zuazua-CB '22)

Assume that the matrix A is symmetric, strictly hyperbolic and does not admit the eigenvalue 0 and that the couple (A, B) satisfies the (SK) condition. Let $U_0 \in L^1(\mathbb{R}) \cap L^2(\mathbb{R})$. Then, there exists a constant C > 0 and a finite time $\overline{\tau} > 0$ such that for $t \ge \overline{\tau}$, the solution satisfies

$$\begin{split} \|U^{h}(\cdot,t)\|_{L^{2}(\mathbb{R})} &\leq C e^{-\gamma(t-\bar{\tau})} \|U_{0}\|_{L^{2}(\mathbb{R})}, \\ \|U^{\ell}(\cdot,t)\|_{L^{\infty}(\mathbb{R})} &\leq C(t-\bar{\tau})^{-1/2} \|U_{0}\|_{L^{1}(\mathbb{R})} \end{split}$$

where

$$\bar{\tau} = \max\left(\sum_{i=1}^{p} \frac{2R}{|\lambda_i|}, \sum_{i=p+1}^{n} \frac{2R}{|\lambda_i|}\right).$$

The decay estimates are delayed by the time each characteristic spend in the undamped region

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Idea of proof

For every $(x, t) \in \mathbb{R}^2$, there exists suitable times t_1, t_2 such that

 $v_i(x,t) = S_{d,i}(t)S_{c,i}(t_1)S_{d,i}(t_2)v_{i,0}(x),$

- S_d : dissipative semigroup associated to the equation with $\omega = \mathbb{R}$;
- S_c : conservative semigroup associated to the equation with $\omega = \emptyset$.



Difficulty: t_1 and t_2 depend on the point (x, t). But $t_{1} = t_2$ is unif bounded!

Other remarks/difficulties

Difficulties due to partial dissipation:

- It is only possible to obtain dissipation for the solution V if all the semigroups $S_{d,i}$ are active on a same time-interval i.e. the "full" semigroup $S_d = (S_{d,1}, \dots, S_{d,p})$ needs to be active.
- For instance, the action of S_{d,1} on the first component does not, in general, imply any time-decay properties for the component v₁.
- This means that if one of the conservative semigroups $S_{c,i}$ is active on a time-interval then the whole solution does not experience any decay on this time-interval;

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Recalling that $\forall i \in [1, p]$

$$v_i(x,t) = S_{d,i}(t)S_{c,i}(t_1)S_{d,i}(t_2)v_{i,0}(x).$$

With the previous considerations one ends up studying:

$$\mathcal{I}(x,t) = \bigcup_{i=1}^{p} [t_{1,i}(x,t), t_{2,i}(x,t)]$$
(3)

which corresponds to the union of time-interval where the dissipation is not active. $\rightarrow |\mathcal{I}|$ quantifies the delay. And, essentially, our theorem derives from

$$\sup_{x \ge R, t > 0} |\mathcal{I}(x, t)| \le \sum_{i=1}^{p} \frac{2R}{|\lambda_i|} = \bar{\tau}.$$
 (4)

And computations of the following type:

$$egin{aligned} \|v_1(.,t)\|_{L^2(\mathbb{R})} &= \|S_{d,1}(t)S_{c,1}(t_1)S_{d,1}(t_2)v_{1,0}\|_{L^2(\mathbb{R})} \ &\leq e^{-c(t-t_1)}\|S_{c,1}(t_1)S_{d,1}(t_2)v_{1,0}\|_{L^2} \ &\leq e^{-c(t-t_1)}\|S_{d,1}(t_2)v_{1,0}\|_{L^2} \ &\leq e^{-c(t-t_1)}e^{-c(t_2-0)}\|v_{1,0}\|_{L^2} \ &\leq e^{-c(t-(t_1-t_2))}\|v_{1,0}\|_{L^2} \end{aligned}$$

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Conclusion

For general hyperbolic system verifying the (SK) condition:

• Exhibiting a damped mode in low frequencies and using a suitable framework leads to new results concerning relaxation limit of such systems.

For locally damped linear hyperbolic systems, our characteristic argument yields:

- Accurate quantification of the delay appearing in decay rates depending on the size of the undamped region and the eigenvalues of the system.
- Possible generalizations to the half-line and to ω^c being finite union of bounded stripes.



Thank you for your attention!



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