

Global L^p Carleman estimates and applications

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Goal of the talk.

Discuss a global L^p Carleman estimates for the Laplace operator.

Keywords.

- Carleman estimates
- Laplace operator
- L^p estimates (Stein - Tomas theorem)

I Introduction let Ω be a smooth bounded domain of $\mathbb{R}^d$
 $(d \geq 3)$

$$\begin{cases} -\Delta u = f & \text{in } \Omega. \\ u = g & \text{on } \partial\Omega. \end{cases}$$

$$f \in H^{-1}(\Omega) \text{ \& } g \in H^{1/2}(\partial\Omega) \Rightarrow u \in H^1(\Omega).$$

$$f \in H^{-1}(\Omega)? \quad f = f_2 + f_{(2^*)'} + \operatorname{div} F$$

$$\text{with } f_2 \in L^2(\Omega), \quad F \in L^2(\Omega; \mathbb{R}^d)$$

$$f_{(2^*)}' \in L^{(2^*)}'(\Omega)$$

$$\left(\begin{array}{l} \text{Recall } H^1 \hookrightarrow L^{2^*}, \quad 2^* = \frac{2d}{d-2} \\ L^{(2^*)}' \hookrightarrow H^{-1} \quad (2^*)' = \frac{2d}{d+2} \end{array} \right)$$

Goal: Allow a source term $f = f_2 + f_{(2^*)}' + \operatorname{div} F$
with $f_2 \in L^2(\Omega)$, $f_{(2^*)}' \in L^{(2^*)}'(\Omega)$, $F \in L^2(\Omega; \mathbb{R}^d)$.

Qm u : Since $u \in H^1(\Omega)$, we want to estimate
 $u \in L^2(\Omega)$, $\nabla u \in L^2(\Omega; \mathbb{R}^d)$ and $u \in L^{2^*}(\Omega)$.

Interest to develop L^p estimates
(when L^p estimates are better than the ones obtained
by Sobolev's embedding).

Lower order perturbations of the Laplacian

$$\Delta u = \underbrace{Vu + w_1 \cdot \nabla u + \operatorname{div}(w_2 u)}_{\text{Lower order}} -$$

Lower order if this is better than H^{-1} $\int_{\Omega} u \in H^1(\Omega)$.

Critical scales. $V \in L^{\frac{d}{2}^+}(\Omega)$.

$$w_1 \in L^d(\Omega; \mathbb{R}^d).$$

$$w_2 \in L^d(\Omega; \mathbb{R}^d).$$

Unique continuation results for

$$-\Delta u = Vu + w_1 \cdot \nabla u + \operatorname{div}(w_2 u).$$

valid for $V \in L^{d/2^+}(\Omega)$, $w_1 \in L^d(\Omega; \mathbb{R}^d)$, $w_2 \in L^d(\Omega; \mathbb{R}^d)$.

~ [Koch-Tataru 2001.]

Key elements: L^p Carleman estimates - [Jerison - Kenig 1985]
[Barcelo - Kenig - Ruiz Sogge 1987, 88].
.....

• Wolff's argument [Wolff 1992]
~ Choose appropriate weights depending on the solution -

Rk. Even strong unique continuation holds.

Rk There are counterexamples to unique continuation if $V \in L^p$, with $p < \frac{d}{2}$.
[Koch-Tataru 2002]

However Precise quantifications of smallness
with respect to the norms of V, w_1, w_2
in sharp classes are, to our knowledge, missing.

L^2 Carleman estimates

$$\Omega \subset \mathbb{R}^d, d \geq 3, \omega \subset \Omega.$$

Let $\varphi \in C^3(\bar{\Omega})$ s.t. $\varphi = 0$ on $\partial\Omega$, $\partial_n \varphi < 0$ on $\partial\Omega$

and $\exists \alpha, \beta > 0$, $\inf_{\Omega \setminus \bar{\omega}} |\nabla \varphi| \geq \alpha$

and $\forall x \in \bar{\Omega} \setminus \omega$, $\forall \xi \in \mathbb{R}^d$ with $|\nabla \varphi(x)| = |\xi|$ and $\nabla \varphi(x) \cdot \xi = 0$

$$\partial_{\xi\xi}^2 \varphi(x) (\nabla \varphi(x), \nabla \varphi(x)) + \partial_{\xi\xi}^2 \varphi(x) (\xi, \xi) \geq \beta |\nabla \varphi(x)|^2.$$

then $\exists C$, $\forall u \in H^1(\Omega)$ with $\Delta u = f_2 + \operatorname{div} F$, $f_2 \in L^2$, $F \in L^2$,

$$\forall \tau > 1,$$

$$\tau^{3/2} \|u e^{\tau\varphi}\|_{L^2} + \tau^{1/2} \|\nabla u e^{\tau\varphi}\|_{L^2} \lesssim \|e^{\tau\varphi} f_2\|_{L^2} + \tau \|e^{\tau\varphi} F\|_{L^2} \\ + \tau^{3/4} \|e^{\tau\varphi} u\|_{H^{1/2}(\partial\Omega)} + \tau^{3/2} \|e^{\tau\varphi} u\|_{L^2(\omega)}$$

— [Imanuv.lov - Puel 2003].

• Subellipticity condition (Necessary & Sufficient Condition, Hörmander)

$$\begin{aligned} & \exists \alpha, \beta > 0, \quad \inf_{\Omega \setminus \bar{\omega}} |\nabla \varphi| \geq \alpha \\ & \forall x \in \Omega \setminus \bar{\omega}, \quad \forall \xi \in \mathbb{R}^d \text{ with } |\nabla \varphi(x)| = |\xi| \text{ and } \nabla \varphi(x) \cdot \xi = 0 \\ & \mathcal{D}^2 \varphi (\nabla \varphi(x), \nabla \varphi(x)) + \mathcal{D}^2 \varphi_x(\xi, \xi) \geq \beta |\nabla \varphi(x)|^2. \end{aligned}$$

• Limitations with respect to lower order terms $\Delta u = Vu$.

By Carleman $\tau^{\frac{3}{2}-\theta} \|u e^{\tau \varphi}\|_{H^\theta} \lesssim \|Vu e^{\tau \varphi}\|_{L^2} + \text{observations}.$

as we can absorb $\|Vu e^{\tau \varphi}\|_{L^2}$ by the left hand side if

$$\|Vu e^{\tau \varphi}\|_{L^2} \leq C_v \|u e^{\tau \varphi}\|_{H^\theta} \text{ for some } \theta \in [0, \frac{3}{2}).$$

But $H^{3/2} \subset L^p$ with $p = \frac{1}{\frac{1}{2} - \frac{3}{2d}} = \frac{2d}{d-3} \Rightarrow \text{OK if } V \in L^{\frac{2d}{3}}(\Omega)$

Our result. [Dehman, Ervedoza, Theboulbi 2023]

L^p Carleman estimates $\Omega \subset \mathbb{R}^d$, $d \geq 3$, $\omega \subset \Omega$.

Same conditions on φ .

then $\exists C$, $\forall u \in H^1(\Omega)$ with $\Delta u = f_2 + \operatorname{div} F + f_{(2+)'}$
 with $f_2 \in L^2(\Omega)$, $F \in L^2(\Omega; \mathbb{R}^d)$, $f_{(2+)'}$ $\in L^{(2+)'(\Omega)}$.

$\forall \tau > 1$,

$$\tau^{3/2} \|u e^{\tau\varphi}\|_{L^2} + \tau^{1/2} \|\nabla u e^{\tau\varphi}\|_{L^2} \lesssim \|e^{\tau\varphi} f_2\|_{L^2} + \tau \|e^{\tau\varphi} F\|_{L^2} + \tau^{\frac{3}{4} - \frac{1}{2d}} \|e^{\tau\varphi} f_{(2+)}\|_{L^{(2+)'}} \\ + \tau^{3/4} \|e^{\tau\varphi} u\|_{H^{1/2}(\partial\Omega)} + \tau^{3/2} \|e^{\tau\varphi} u\|_{L^2(\omega)}$$

and

$$\tau^{\frac{3}{4} + \frac{1}{2d}} \|e^{\tau\varphi} u\|_{L^{2*}} \lesssim \|e^{\tau\varphi} f_2\|_{L^2} + \tau \|e^{\tau\varphi} F\|_{L^2} + \tau^{\frac{3}{4} + \frac{1}{2d}} \|e^{\tau\varphi} f_{(2+)}\|_{L^{(2+)'}} \\ + \tau^{3/4} \|e^{\tau\varphi} u\|_{H^{1/2}(\partial\Omega)} + \tau^{3/2} \|e^{\tau\varphi} u\|_{L^2(\omega)}$$

Corollary. $\Omega \subset \mathbb{R}^d$, $d \geq 3$, $\omega \subset \Omega$

$\exists C > 0$, $\forall u \in H_0^1(\Omega)$, $\Delta u = Vu + W_1 \cdot \nabla u$ in Ω

with $V \in L^{q_0}(\Omega)$, $W_1 \in L^{q_1}(\Omega; \mathbb{R}^d)$

$$q_0 > \frac{d}{2}$$

and

$$q_1 > \frac{3d-2}{2}$$

then

$$\|u\|_{L^2(\Omega)} \leq C e^{C \left(\|V\|_{L^{q_0}}^{\delta(q_0)} + \|W_1\|_{L^{q_1}}^{\delta(q_1)} \right)} \|u\|_{L^2(\omega)}.$$

with

$$\delta(q_0) = \begin{cases} \frac{1}{\frac{3}{2} \left(1 - \frac{d}{2q_0}\right) + \frac{1}{2q_0}} & \text{if } q_0 > d \\ \frac{1}{\left(\frac{3}{4} + \frac{1}{2d}\right) \left(2 - \frac{d}{q_0}\right)} & \text{if } q_0 \in \left(\frac{d}{2}, d\right] \end{cases}$$

$$\text{if } q_0 > d$$

$$\text{if } q_0 \in \left(\frac{d}{2}, d\right]$$

$$\text{and } \delta(q_1) = \frac{2}{1 - \frac{3d-2}{q_1}}$$

Rk. 1. Similar result for $\Delta u = Vu + \operatorname{div}(w_2 u)$.

— Mixing w_1 and w_2 gives unexpected complicated estimates due to the method.

Rk 2. $w_1 \in L^{q_1}(\Omega; \mathbb{R}^d) \rightarrow q_1 > d$ is the expected critical scale

$$q_1 > \frac{3d-2}{2}$$

but it is known from

[Kenig Ruiz Sogge '87] that one cannot do better using L^p Carleman estimates

$\leadsto$ Wolff's argument is needed

$\leadsto$ Ongoing work.

[Cano-Ervedoza-Thebault]

II

Strategy of the proof.

- × Consider the conjugate operator.
- × Localize at a rate depending on T
- × Change of variables into the case of a strip with a linear weight
- × Write the parametrix
- × Estimate the operators appearing in the parametrix
- × Glue all the estimates.

The conjugate operator.

$$\Delta u = f + \operatorname{div} F \quad \text{in } \Omega.$$

$\leadsto w = e^{\tau\phi} u$ satisfies

$$\Delta w = 2\tau \nabla\phi \cdot \nabla w + \tau^2 |\nabla\phi|^2 w - \tau \Delta\phi w$$

$$= \tilde{f} + \operatorname{div} \tilde{F} \quad \text{in } \Omega$$

where
$$\begin{cases} \tilde{f} = e^{\tau\phi} (f - \tau \nabla\phi \cdot F) \\ \tilde{F} = e^{\tau\phi} F. \end{cases}$$

Local estimate.

For $x_0 \in \Sigma \setminus \omega$, set $w_{x_0}(x) = \eta_{x_0}(x) w(x)$

with $\eta_{x_0}(x) = \eta(\tau^\alpha(x - x_0))$,

η radial, $\in C_c^\infty(B(1))$, $\eta = 1$ in $B(\frac{1}{2})$
Localisation in $B(x_0, \tau^{-\alpha})$.

$\alpha < \frac{1}{2} \rightarrow$ Allows to absorb the terms coming from the localization
 $\alpha > \frac{1}{4} \rightarrow$ Allows to approximate ϕ by its 2nd order approximation.

A suitable change of coordinates.

When localized in $B(x_0, \tau^{-\alpha})$ with $\frac{1}{4} < \alpha < \frac{1}{2}$,

$$\Delta w = 2\tau \nabla \varphi \cdot \nabla w + \tau^2 |\nabla \varphi|^2 w - \tau \Delta \varphi w$$

$$= f + \operatorname{div} F \quad \text{in } \Omega.$$

« Canonical Form ».

$$\begin{aligned} & \partial_{11}^2 \tilde{w} - 2\tau \partial_1 \tilde{w} + \tau^2 \tilde{w} \\ & + \sum_{j=2}^d (1 - \lambda_j x_{1j}) \partial_{x_j x_j} \tilde{w} = \tilde{f} + \operatorname{div} \tilde{F} \end{aligned}$$

in the strip $(-1, 1) \times \mathbb{R}^{d-1}$
 with $\lambda_j = \frac{2}{|\nabla \varphi(x_0)|^2} \left(\nabla^2 \varphi(x_0) (\nabla \varphi(x_0), \nabla \varphi(x_0)) + \nabla^2 \varphi(x_0) (L_j, L_j) \right) > 0$
 $L_j \cdot \nabla \varphi(x_0) = 0, |L_j| = |\nabla \varphi(x_0)|$ and $(L_2, \dots, L_d)$ basis of $\{\nabla \varphi(x_0)\}^\perp$.

Construction of a parametrix

$$\partial_{11} w - 2\tau \partial_1 w + \tau^2 w + \sum_{j=2}^d (1 - \lambda_j x_1) \partial_j w = f + \operatorname{div} F$$

in $(-1, 1) \times \mathbb{R}^{d-1}$.

→ Fourier transform $x' \rightarrow \xi'$.

$$\left[(\partial_1 - \tau)^2 - \Psi(x_1, \xi')^2 \right] \hat{w} = \hat{f} + \partial_1 \hat{F}_1 + \sum_{j=2}^d i \xi_j \hat{F}_j$$

with $\Psi(x_1, \xi')^2 = \sum_{j=2}^d (1 - \lambda_j x_1) \xi_j^2$.

$$(\partial_1 - \tau)^2 - \Psi(x_1, \xi')^2 = (\partial_1 - \tau - \Psi(x_1, \xi')) (\partial_1 - \tau + \Psi(x_1, \xi')) + \text{p.o.}$$

$$\rightsquigarrow w = K_{\tau,0} f + K_{\tau,1} f_1 + \sum_{j \geq 2} K_{\tau,j} f_j + \underbrace{Rw}_{\text{Remainder}}$$

with

$$\widehat{K_{\tau,0} f}(x_1, \varsigma') = \int_{y_1 \in (-1,1)} k_{\tau,0}(x_1, y_1, \varsigma') \widehat{f}(y_1, \varsigma') dy_1.$$

$$k_{\tau,0}(x_1, y_1, \varsigma') = -1_{\{\psi(x_1, \varsigma') > \tau\}} \int_{x_0}^{\min\{x_1, y_1\}} e^{-\tau(y_1 - x_1)} - \int_{x_1}^{\tilde{x}_1} \psi(\tilde{y}_1, \varsigma') d\tilde{y}_1 - \int_{\tilde{x}_1}^{y_1} \psi(\tilde{y}_1, \varsigma') d\tilde{y}_1 d\tilde{x}_1$$

$$+ 1_{\{\psi(x_1, \varsigma') \leq \tau\}} \int_{x_1}^{y_1} e^{-\tau(y_1 - x_1)} + \int_{x_1}^{\tilde{x}_1} \psi(\tilde{y}_1, \varsigma') d\tilde{y}_1 - \int_{\tilde{x}_1}^{y_1} \psi(\tilde{y}_1, \varsigma') d\tilde{y}_1 d\tilde{x}_1.$$

... $\rightsquigarrow$ Remains to estimate these operators --

Fourier restrictions theorems and applications.

Then (Stein - Tomas) Let $n \geq 2$, S^{n-1} the unit sphere of $\mathbb{R}^n$. Then the map

$$L^1(\mathbb{R}^n) \longrightarrow L^2(S^{n-1})$$

$$f \longmapsto \hat{f}|_{S^{n-1}}$$

can be extended by continuity on $L^{\frac{2(n+1)}{n+3}}(\mathbb{R}^n)$

and

$$\|\hat{f}\|_{L^2(S^{n-1})} \leq C \|f\|_{L^{\frac{2(n+1)}{n+3}}(\mathbb{R}^n)}.$$

What matters.

* Curvature of S^{n-1} .

$\leadsto$ Can be adapted to the ellipsoids

$$\Sigma_a = \{ \xi \in \mathbb{R}^n, \quad \Psi(a, \xi) = 1 \}$$

$$\text{where } \Psi(a, \xi)^2 = \sum_{j=1}^n (1 - a \lambda_j) \xi_j^2.$$

$$* \quad n \simeq d-1$$

$$\leadsto \frac{2(n+1)}{n+3} = \frac{2d}{d+2} = (2_*)'.$$

Based on this, if we consider an operator

$$K_{a,k} : L^2(\mathbb{R}^n) \rightarrow L^2(\mathbb{R}^n) \text{ given by}$$

$$\widehat{K_{a,k} f}(\xi) = k\left(\psi(a, \xi), \frac{\xi}{\psi(a, \xi)}\right) \widehat{f}(\xi),$$

we have

$\approx$ radial decomposition

$$\|K_{a,k}\|_{\mathcal{L}(L^2(\mathbb{R}^n))} \leq \|k\|_{L^\infty(\mathbb{R}_+, L^\infty(\Sigma_a))}$$

and

$$\|K_{a,k}\|_{\mathcal{L}\left(L^{2\left(\frac{n+1}{n+3}\right)}(\mathbb{R}^n), L^{2\left(\frac{n+1}{n-1}\right)}(\mathbb{R}^n)\right)} \leq C \int_0^\infty \|k(\lambda, \cdot)\|_{L^\infty(\Sigma_a)} \lambda^{\frac{n-1}{n+1}} d\lambda.$$

~> Allows to estimate the operators

$K_{\tau,0}$, $K_{\tau,j}$ as operators

$$\mathcal{L}(L^{(2^*)'}(\mathbb{R}^d), L^{(2^*)}(\mathbb{R}^d))$$

$$\mathcal{L}(L^{(2^*)'}(\mathbb{R}^d), L^2(\mathbb{R}^d)).$$

$$\mathcal{L}(L^2(\mathbb{R}^d), L^{(2^*)}(\mathbb{R}^d))$$

Prk. This step also use the (1d) Hardy - Littlewood - Sobolev thm.

$$\|K_{\tau,0} f\|_{L^{2*}} \leq \| \|K_{\tau,0} f(x_1, \cdot)\|_{L^{2*}_{x_1}} \|_{L^{2*}_{x_2}} \\ \leq \left\| \int_{-1}^1 \left(\int_{\lambda>0} \|h_{\tau,0}(x_1, y_1, \lambda, \cdot)\|_{L^\infty(\Sigma_{x_1})} \lambda^{1-\frac{2}{d}} d\lambda \right) \|f(y_1)\|_{L^{(2*)}_{y_1}} dy_1 \right\|_{L^{2*}_{x_2}}$$

$$\leq C \left\| \int_{-1}^1 \frac{1}{|x_1 - y_1|^{1-\frac{2}{d}}} \|f(y_1)\|_{L^{(2*)}_{y_1}} dy_1 \right\|_{L^{2*}_{x_2}}$$

$$\leq C \| \|f(y_1, \cdot)\|_{L^{(2*)}_{y_1}} \|_{L^{(2*)}_{y_2}}$$

$$\leq C \|f\|_{L^{(2*)}}.$$

Last Step: A Gluing argument.

We have estimates on each

$$w_{x_0}(x) = \eta(\tau^\alpha(x - x_0)) w(x), \quad x_0 \in \overline{\Omega} \setminus \omega$$

We then integrate in $x_0 \in \overline{\Omega} \setminus \omega$.

$\leadsto$ Yield the global estimate.

N.B. The boundary term does not yield

any specific difficulty in this argument since
the boundary is a level set of the weight function.

III

Application

with

Quantification of Unique Continuity
respect to lower order terms.

($w_2 = 0$)

$$V \in L^{q_0} \rightarrow V = \underbrace{V_{d/2}}_{\cap L^{d/2}} + \underbrace{V_d}_{\cap L^d} + \underbrace{V_\infty}_{\cap L^\infty}$$

$q_0 > d/2$

$$w_1 \in L^{q_1} \rightarrow w_1 = \underbrace{w_{1,d}}_{\cap L^d} + \underbrace{w_{1,\infty}}_{\cap L^\infty}$$

$q_1 > \frac{3d-2}{2}$

$$\Delta u = V_u + W_1 \cdot \nabla u, \quad u \in L^1 \cap L^{2+}, \quad \nabla u \in L^2.$$

$$\leadsto f_{(2+)' } = V_{d/2} u + V_d u + W_{1,d} \nabla u$$

$$f_2 = V_\infty u + W_{1,\infty} \cdot \nabla u.$$

$$\Rightarrow \tau^{3/2} \|u e^{\tau \phi}\|_{L^2} + \tau^{1/2} \|\nabla u e^{\tau \phi}\|_{L^2}$$

$$\lesssim \|V_\infty\|_{L^\infty} \|u e^{\tau \phi}\|_{L^2} + \|W_{1,\infty}\|_{L^\infty} \|\nabla u e^{\tau \phi}\|_{L^2}$$

$$+ \tau^{\frac{3}{4} - \frac{1}{2d}} \|V_d\|_{L^d} \|u e^{\tau \phi}\|_{L^2} + \tau^{\frac{3}{4} - \frac{1}{2d}} \|W_{1,d}\|_{L^d} \|\nabla u e^{\tau \phi}\|_{L^2}.$$

$$+ \tau^{\frac{3}{4} - \frac{1}{2d}} \|V_{d/2}\|_{L^{d/2}} \|u e^{\tau \phi}\|_{L^{2+}} + \text{observations}.$$

Provided

$$\left\{ \begin{array}{l} \|V_\infty\|_{L^\infty} + \tau^{\frac{3}{4} - \frac{1}{2d}} \|V_d\|_{L^d} \ll \tau^{3/2} \\ \|W_{1,\infty}\|_{L^\infty} + \tau^{\frac{3}{4} - \frac{1}{2d}} \|W_{1,d}\|_{L^d} \ll \tau^{1/2} \end{array} \right.$$

$$\begin{aligned} & \tau^{3/2} \|v e^{\tau\varphi}\|_{L^2} + \tau^{1/2} \|\nabla v e^{\tau\varphi}\|_{L^2} \\ & \lesssim \tau^{3/4 - 1/2d} \|V_{d/2}\|_{L^{d/2}} \|v e^{\tau\varphi}\|_{L^{2d}} + \text{observations.} \end{aligned}$$

Similarly,

$$\tau^{\frac{3}{4} + \frac{1}{2d}} \|ue^{\tau\phi}\|_{L^{2d}}$$

$$\lesssim \|V_\infty\|_{L^\infty} \|ue^{\tau\phi}\|_{L^2} + \|W_{2,\infty}\|_{L^\infty} \|\nabla u e^{\tau\phi}\|_{L^2}$$

$$+ \|V_d\|_{L^d} \|ue^{\tau\phi}\|_{L^{2d}}$$

$$+ \tau^{\frac{3}{4} + \frac{1}{2d}} \left(\|V_{d/2}\|_{L^{d/2}} \|ue^{\tau\phi}\|_{L^{2d}} + \|W_{1,d}\|_{L^d} \|\nabla u e^{\tau\phi}\|_{L^2} \right) + \text{observations}$$

We require

$$\|V_d\|_{L^d} \ll \tau^{\frac{3}{4} + \frac{1}{2d}}$$

$$\text{and } \|V_{d/2}\|_{L^{d/2}} \ll 1$$

$$\leadsto \tau^{\frac{3}{4} + \frac{1}{2d}} \|u e^{\tau \phi}\|_{L^{2d}}$$

$$\lesssim \|V_\infty\|_{L^\infty} \|u e^{\tau \phi}\|_{L^2} + \|W_{1,\infty}\|_{L^\infty} \|\nabla u e^{\tau \phi}\|_{L^2} \\ + \tau^{\frac{3}{4} + \frac{1}{2d}} \|W_{2,d}\|_{L^d} \|\nabla u e^{\tau \phi}\|_{L^2} + o_b s$$

Combine with

$$\tau^{3/2} \|u e^{\tau \phi}\|_{L^2} + \tau^{1/2} \|\nabla u e^{\tau \phi}\|_{L^2}$$

$$\lesssim \tau^{3/4 - 1/2d} \|V_{d/2}\|_{L^{d/2}} \|u e^{\tau \phi}\|_{L^{2d}} + \text{observations.}$$

Provided

$$\|V_\infty\|_{L^\infty} \ll \tau^{3/2}, \quad \|V_d\|_{L^d} \ll \tau^{\frac{3}{4} + \frac{1}{2d}}, \quad \|W_{1,\infty}\|_{L^\infty} \ll \tau^{1/2}, \quad \|W_{2,d}\|_{L^d} \ll \tau^{-\frac{1}{4} + \frac{1}{2d}} \\ \|V_{d/2}\|_{L^{d/2}} \ll 1.$$

$$w_{1,\infty} = w_1 \mathbb{1}_{|w_1| \leq \lambda_1}, \quad w_{1,d} = \mathbb{1}_{|w_1| > \lambda_1} w_1.$$

$$V_\infty = V \mathbb{1}_{|v| \leq \lambda_0}, \quad V_d = V \mathbb{1}_{|v| > \lambda_0}, \quad V_{d/2} = 0 \quad \text{if } q_0 \geq d$$

OR

$$V_\infty = 0, \quad V_d = V \mathbb{1}_{|v| \leq \lambda_0}, \quad V_{d/2} = V \mathbb{1}_{|v| > \lambda_0} \quad \text{if } q_0 \in \left(\frac{d}{2}, d\right).$$

+ Optimize in λ_0, λ_1 .

IV

Further comments.

- Adapt Wolff's argument to get quantitative estimates for $w_1, w_2 \in L^{d+}(\Omega; \mathbb{R}^d)$.

→ Work in progress Caro, SE, Thebault

- These L^p Carleman estimates can in principle be adapted to the case of an interface
[Le Rousseau - Robbiano, Le Rousseau - Lerner].

- What about elliptic metrics?

$\operatorname{div}(A(x) \nabla \cdot)$ instead of Δ ?

• Parabolic equations? [Koch - Tataru].

• Discussing the optimality of the integrability conditions for the unique continuation property for the stationary Stokes pb

$$\begin{cases} -\Delta u + \bar{y} \cdot \nabla u + (u \cdot \nabla) \bar{y} + \nabla p = 0. \\ \operatorname{div} u = 0 \end{cases}$$

[Fabre - Lebeau '96].

Condition on $\bar{y}$?

Thank you for your attention!

Ref: L^p Carleman estimates for elliptic boundary value problems and applications to the quantification of unique continuation,

Belhassen Dehman, Sylvain Ervedoza, Lotfi Thabouti, to appear in Annales Henri Lebesgue.